



## **Sequential method of satellite navigation systems measurement integration**

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The sequential method of integrating navigational parameters obtained from non-simultaneous navigational measurements is presented. The proposed algorithm of position coordinates estimation is general and includes two modes of data processing – from simultaneous and non-simultaneous measurements. It can be used in hybrid receivers of radionavigation systems integrating non-homogenous position lines or in integrated navigation systems, particularly in receivers combining the measurements of various satellite navigation systems.