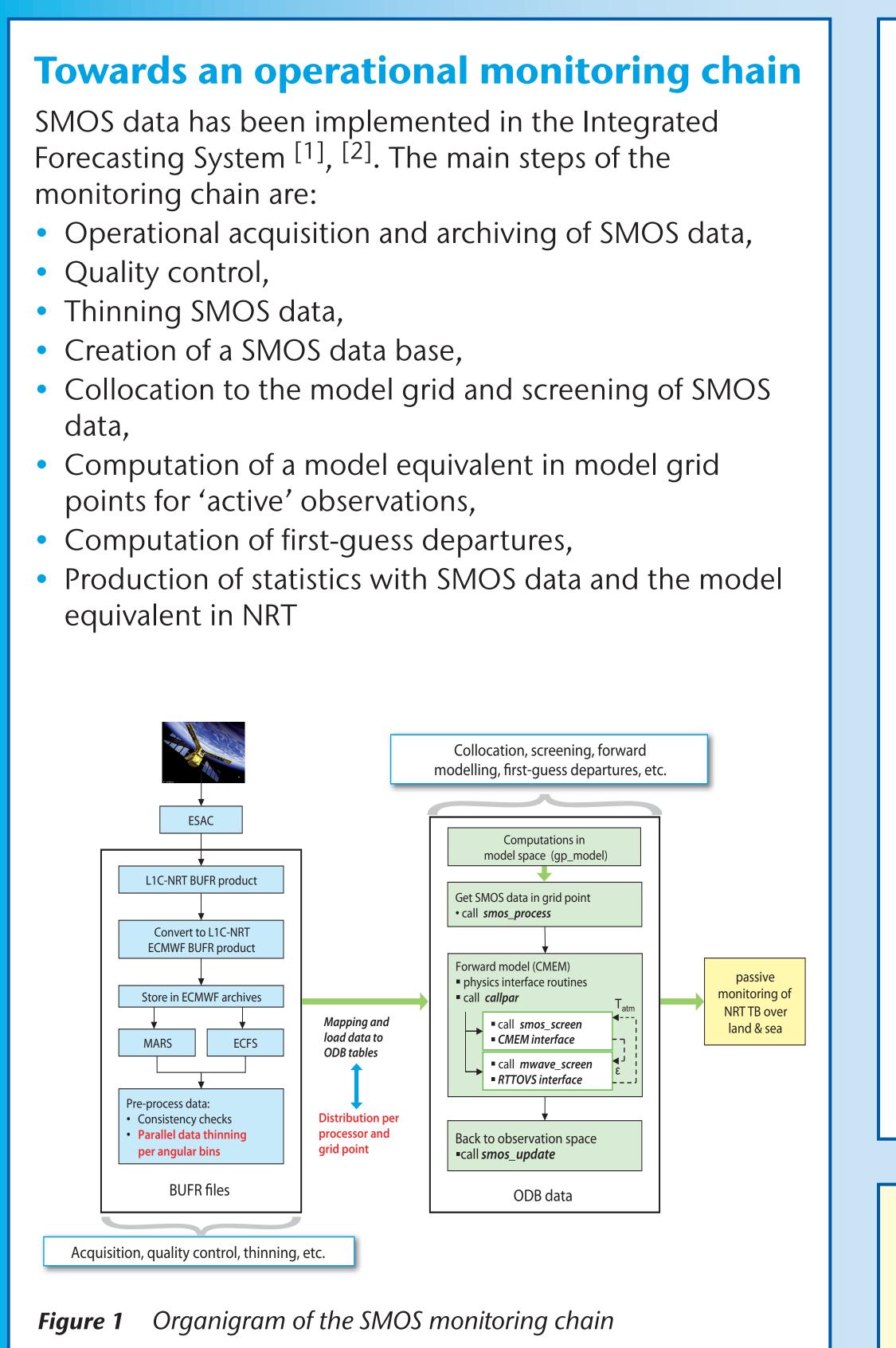
Monitoring SMOS data at ECMWF

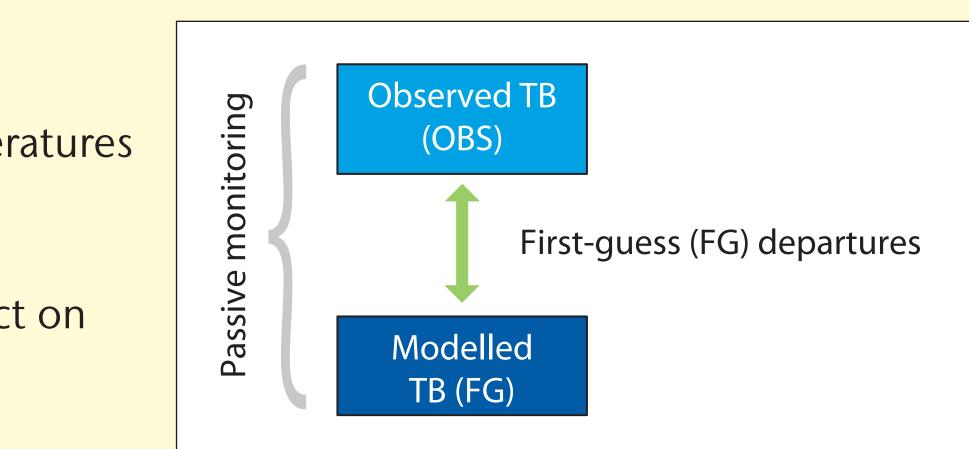
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Main objectives

- **1** Global monitoring of Near Real Time brightness temperatures at the satellite antenna reference frame.
- **2** Assimilation of SMOS brightness temperatures in the Integrated Forecasting System \rightarrow investigate the impact on the forecast skill.



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Monitoring products and support to CAL/VAL teams

Since the launch of SMOS, continuous monitoring of global brightness temperatures at incidence angles of 10, 20, 30, 40, 50 and 60 degrees and for the XX and YY polarization states.

Available at: http://www.ecmwf.int/research/ESA_ projects/SMOS/monitoring/smos_monitor.html

- Since Nov. 2011 statistics between SMOS brightness temperatures and a model equivalent are also available in NRT, and separately for land and oceans.
- Statistical products:
- Time series of area averages,
- Time-averaged geographical mean fields,
- Hovmoeller zonal mean fields,
- First-guess departures as function of the incidence angle
- Support to CAL/VAL teams by producing time series of statistical variables over targeted areas at:
- SCAN sites: Lancaster, Chase, Nemaha, Darlington, Little River, Little Washita, Reynolds Creek,
- Australia: AACES,
- ESA sites: VAS, Danube catchment,
- Antarctica: Dome-C,
- France: SMOSmania, SMOSREX,
- Finland: Sodankylae,
- Denmark: HOBE,
- Africa: Niamey (Niger), Loueme (Benin)

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- 2 Sabater, J.M., P. de Rosnay & A. Fouilloux, 2010: Operational Pre-processing chain, Collocation software development and Offline monitoring suite. M2TNP1/2/3 ESA Technical Reports. http://www.ecmwf.int/publications/library/do/references/show?id=89972
- **B** Drusch M., K. Scipal, P. de Rosnay, G. Balsamo, E. Andersson, P. Bougeault, P. Viterbo, 2009: Towards a Kalman Filter based soil moisture analysis system for the operational ECMWF Integrated Forecast System, Geophys. Res. Lett., 36, L10401, doi:10.1029/2009GL037716.



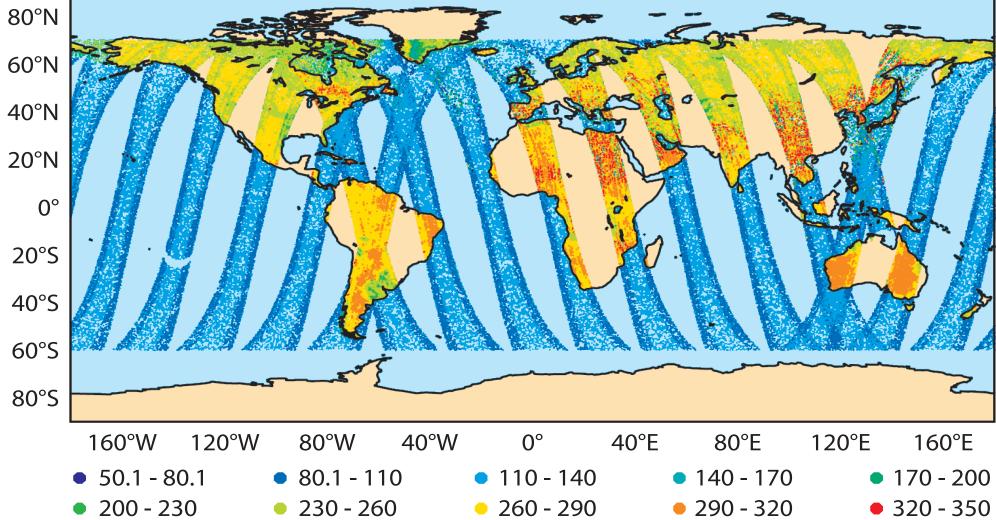
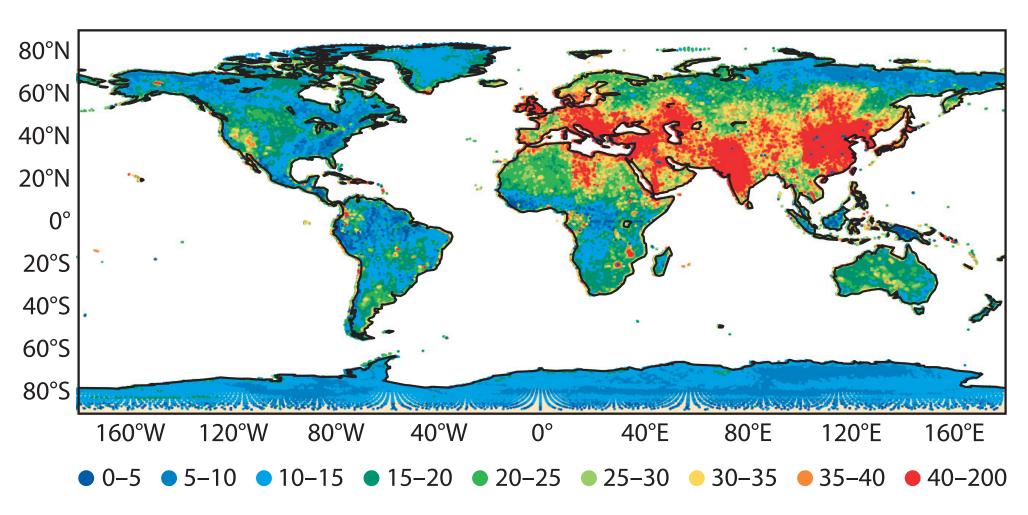




Figure 2 Observed SMOS brightness temperatures at 50 degrees incidence angle and YY polarisation on a) 28 November 2009, b) 20 December 2009. The data in a) is presented as very noisy, whereas the quality of the data has clearly improved everywhere in b) after a calibration event took place in December 2009.

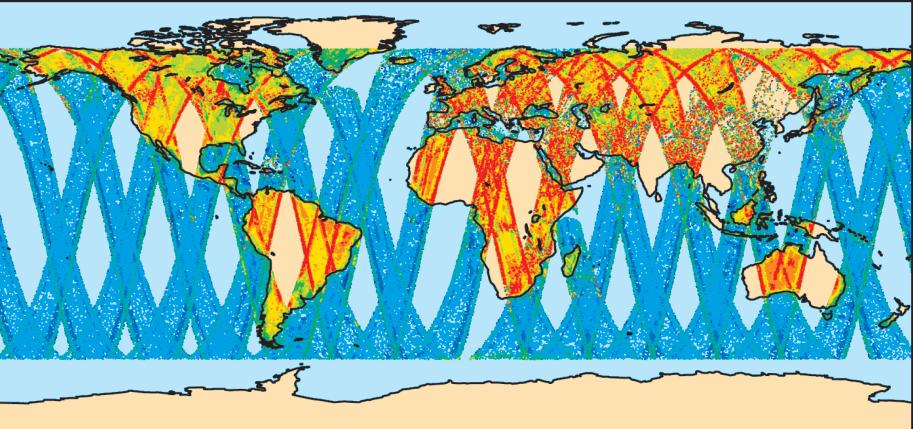
Radio Frequency Interference



Monitoring results

Daily monitoring of brightness temperatures

a 28 November 2009



160°E 120°E **b** 20 December 2009

Figure 3 Average standard deviation of the SMOS observed brightness temperatures the first week of October 2010 at XX polarization and 40 degrees incidence angle. Data in dark red presents abnormal strong variation over one week. Despite being L-band a protected band, illegal emissions in this band and contamination from fixed and mobile emissions in neighbouring bands, significantly perturb the SMOS signal in several areas of Europe and Asia. This phenomenon is called Radio Frequency Interference (RFI) and it is currently the biggest problem affecting the SMOS signal.

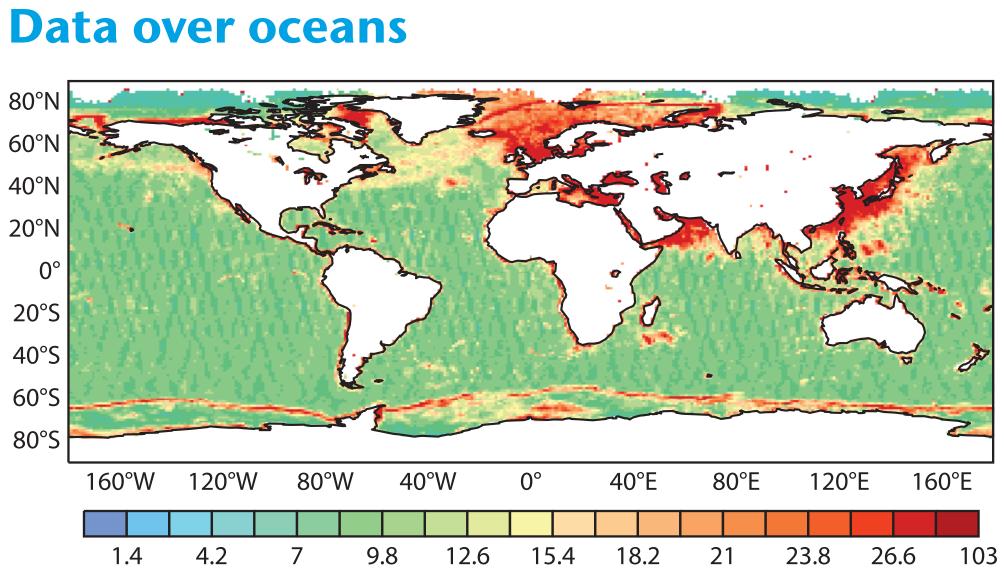


Figure 4 Average standard deviation of the SMOS observed brightness temperatures the first week of October 2010 at XX polarisation and 40 degrees incidence angle. RFI sources over land can contaminate the SMOS signal several hundred kilometres off-shore, as it can be observed in several areas of the East-Asian coast and the Mediterranean Sea. The interface between frozen and open sea water is clearly seen in the South Pole, presenting strong dynamics.

Support to CAL/VAL teams

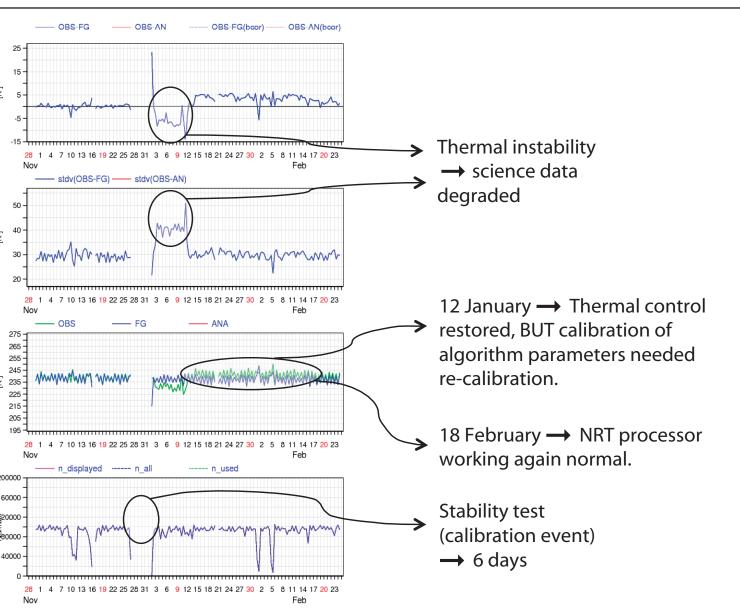
First-guess departures	Γ¥
Standard deviation of first-guess departures	[K]
Observed and modelled brightness temperatures	[K]
Number of observations	2 1 Numper

Figure 5 Time series of statistical variables at global scale for the XX polarisation state. Data corresponds to the period 28 November 2010 – 28 February 2011. In this example perturbations of the time series are explained by routine calibration tests performed by ESA. This tool generates the time series in near-real-time.

Т	ho	way
		vay

- SMOS data,
- Development of a bias correction scheme,
- Investigate the potential benefit of assimilating SMOS data within the EKF [3].
- Assimilation of SYNOP and SMOS data to correct the soil moisture state,
- Feedback to the atmosphere \rightarrow impact on the forecast skill.





forward

Development of an approach to reduce noise from