



DEM generation from high resolution satellite stereopairs for hydraulic hazard analysis

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possible use of High Resolution Satellite Stereopairs to generate DSMs useful for hydraulic hazard analysis

alternative / integration to classic techniques:

- > Aerial photogrammetry
- > LiDAR
- > GNSS

Pros

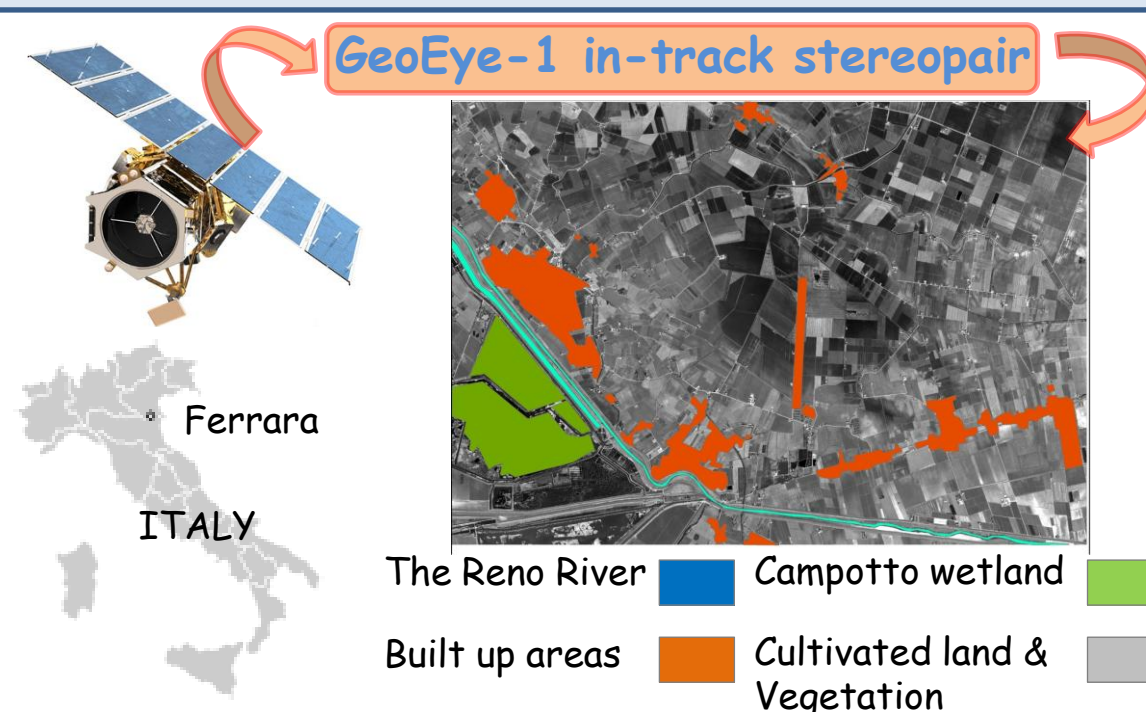
- ✓ costs reduction
- ✓ fast acquisition
- ✓ fast elaboration

Cons

- ✗ lower precision
- ✗ matching errors
- ✗ acquisition

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DATASET



Software used

- > **OrthoEngine v.10.3** (PCI Geomatica)
- > **SISAR**, developed by the team of Geodesy and Geomatic Area at La Sapienza University of Rome, Prof. M. Crespi

Stereopair characteristics

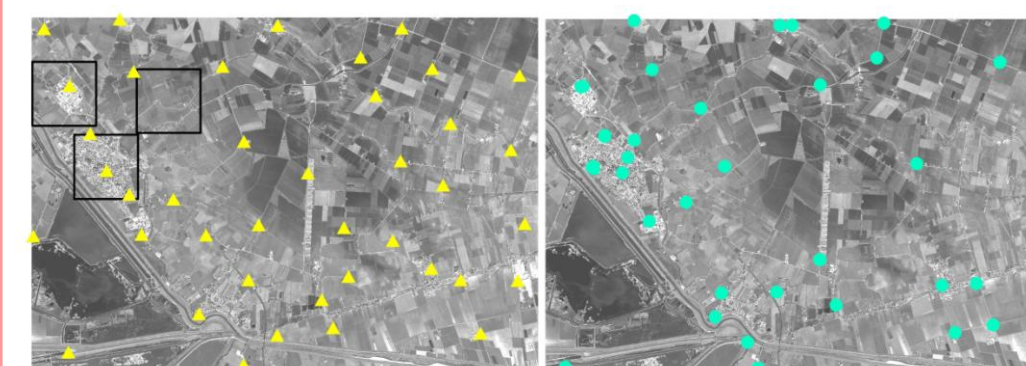
Acquisition date	28-03-10
Acquisition time	11.30 GMT
GSD	0.5 m
Scan direction	Reverse
Bits per pixel per band	11bits
Intersection angle	46°.4784
B/H	0.8
Pixel (row x col)	16604x23804

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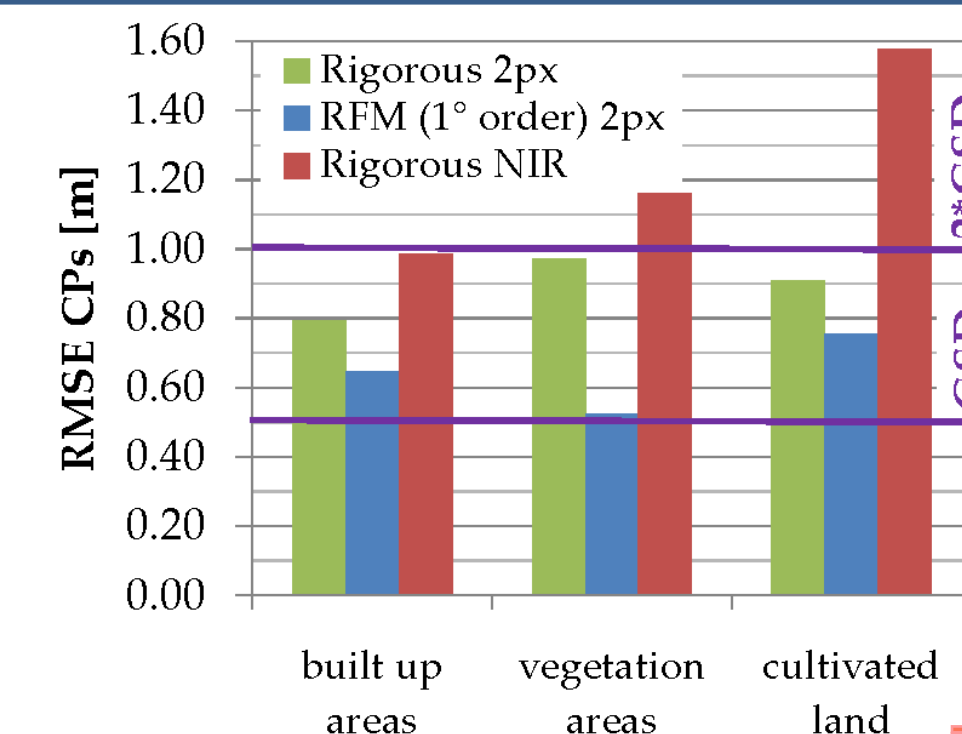
IMAGERY ORIENTATION

removal of spatial and radiometric distortions of the raw data:

- > Rigorous model
- > RFM
- > RPC improvement using SISAR



- > 78 GPs surveyed by stop&go GNSS, with 3D accuracy 3D of about 0.1m:
 - ✗ 40 GCPs used to execute orientation tests (▲)
 - ✗ 38 CPs used to validate orientation's accuracy (●)
- > orthometric heights (ITALGEO99) calculated using VERTO3 software provided by IGM (Istituto Geografico Militare)



- ✓ good accuracy achievable
- ✓ accuracy stabilization with few GCPs (~20 for 100km²)
- ✓ comparable results with rigorous model and RFM
- ✗ dependence on points' distribution
- ✗ dependence on GCPs' image recognition
- ✗ NO improvement using TPs
- ✗ NO improvement with RPC refinement

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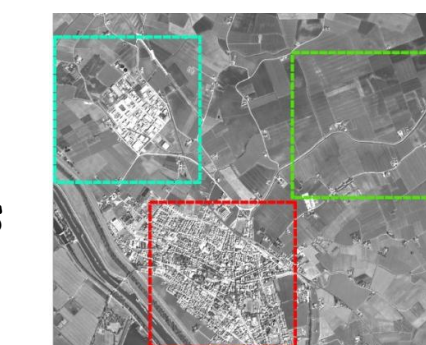
IMAGE MATCHING & DSM EXTRACTION

identification of all the corresponding features using **Area Based Matching** (cross correlation) and regular GRID creation

estimated parameters

- > software (commercial / scientific)
- > GCPs number and distribution
- > TPs
- > orientation model (rigorous / RFM)
- > spectrum information (Pan / multispectral)
- > grid spacing of the final DSM
- > editing needed

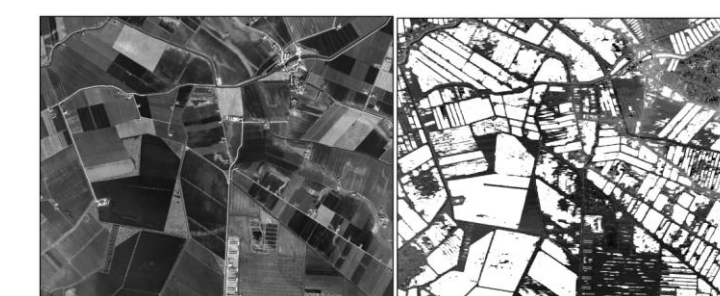
using **SISAR**.....
3 homogeneous tiles (urban, rural, mix)



using **OrthoEngine v.10.3**.....whole image

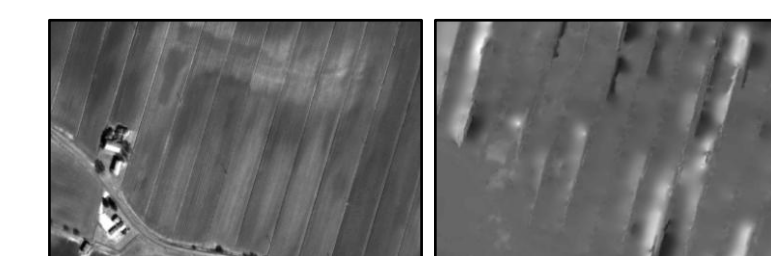
only 40% of the image **matched** successfully:

- ✓ streets, dirty tracks & built up areas
- ✗ cultivated land



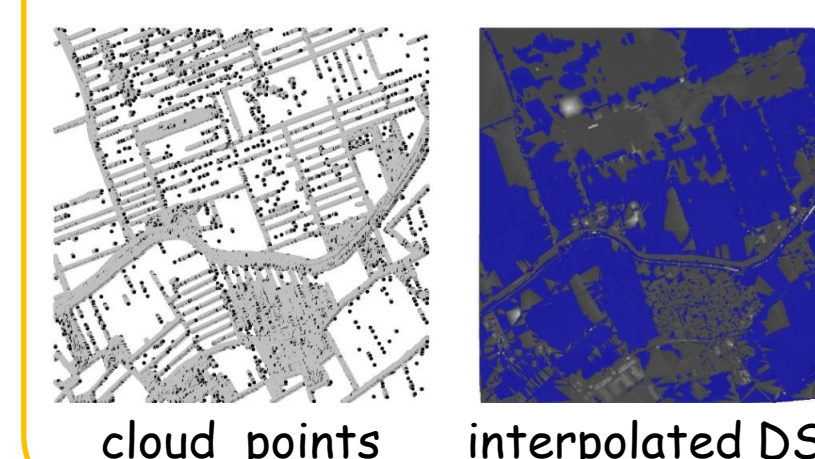
1) automatic fill procedures:

- a. OrthoEngine: Geocode DEM
- b. ArcMap: Spatial Analyst Tools | Hydrology



- ✗ height variations in already matched areas
- ✗ peaks & holes (>2m) due to objects near No data zones (OrthoEngine)

- ✓ matching parameters optimized for each tile
- ✓ easy outliers filtering
- ✓ correct height range
- ✗ some problems in the rural area
- ✗ simple point triangulation



2) semi-automatic procedure implemented in ArcMap:

- ✗ buffer of each No data zone
- ✗ field height value = mean of pixels value in the buffer area

...approximation but...

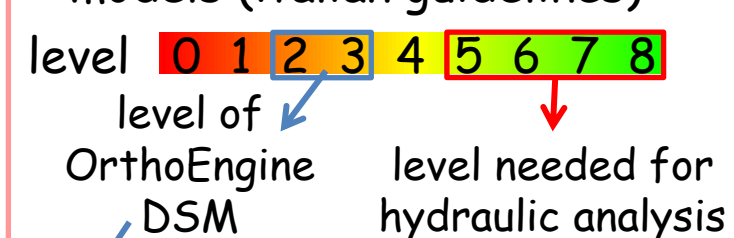
studied area: strongly flat area, differences between fields and dirty tracks < 0.5m



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analysis of the outflow of water after the **Reno river flood**

accuracy levels for digital models (italian guidelines)



- level of OrthoEngine DSM
- level needed for hydraulic analysis
- suitable for:
 - > environmental analysis (of cultivated land and low density built up areas)
 - > orthophotos (1:5000)

model implementation and simulation run with **Mike FLOOD** (DHI)

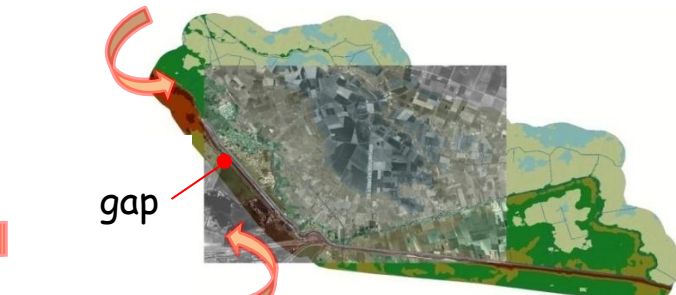
- > evaluation of flood's effects on:
 - Consortium buildings & instruments
 - emergency plan and evacuation
 - urban planning
- > accuracy dependent on:
 - barriers and reliefs
 - drains network
 - ground isolated points



collaboration with the land reclamation consortium of Ferrara

- > hydraulic analysis:
 - critical rate of flow
 - characteristics of the banks
 - position and formation of the gap
- > reference model:
 - GNSS survey of land and reliefs
 - land points from Regional Maps (analysis of the subsidence)
 - drains network

2 technicians for 6 months



- > GeoEye-1 DSM:
 - PAN 4px OrthoEngine

1 technician for 10 days

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DSM VALIDATION



- > ~12000 points collected with kinematic GNSS with 3D accuracy of about 0.3m:
 - cultivated land (~10000)
 - built up areas (~500)
 - vegetation (~1250)

> orthometric heights (ITALGEO99) computed using VERTO3

- > grid of x2m derived by a photogrammetric flight executed in July 2008 (GSD of each image about 0.43 m)
- > manual editing of areas with low correlation
- > validation by sample comparison with a kinematic GNSS survey
- > change detection analysis



- ✓ accuracy of about 2 pixel in the open area
- ✓ accuracy of 3 pixel in the urban area (SISAR)
- ✓ good results with matching in homogeneous areas
- ✓ possible use of NIR band (NO RGB)

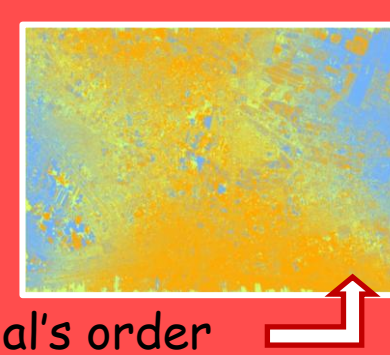
- ✗ matching errors
- ✗ points interpolation

SISAR

- ✗ matching errors
- ✗ too much noise
- ✗ problems in buildings recognition
- ✗ dependence on GCPs distribution
- ✗ NO advantages using TPs
- ✗ RFM: high dependence on polynomial's order

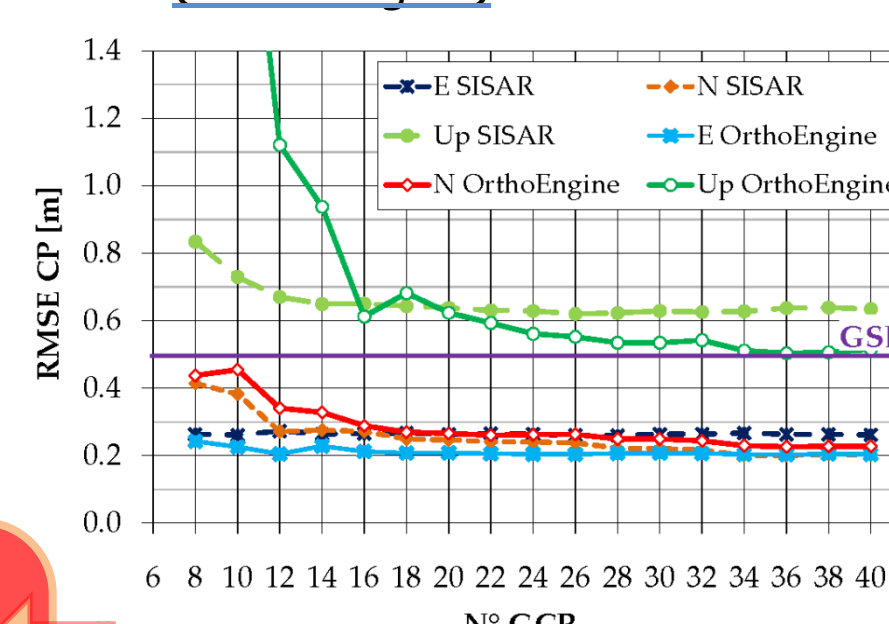
OrthoEngine v.10.3

advantages with GSD reduction

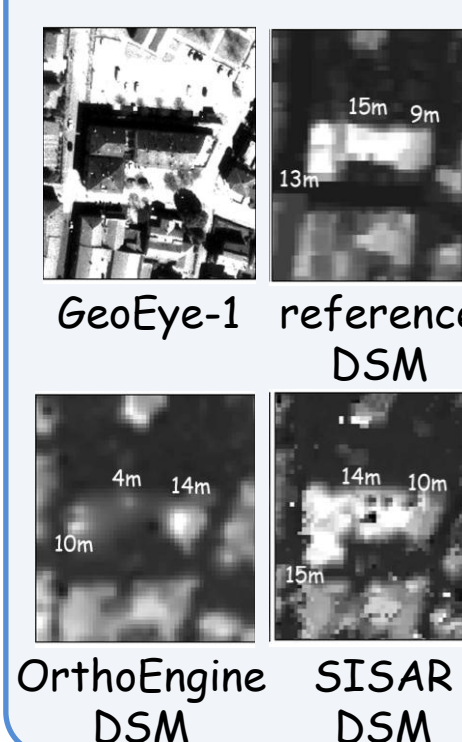


REFERENCE DATA

> comparisons with GNSS check points (LE95): RMSE Up (OrthoEngine)



buildings detection



> comparisons with the reference DSM (LE95): RMSE Up

DSM	rural area			urban area			mix area		
	Bias [m]	σ [m]	RMSE Up [m]	Bias [m]	σ [m]	RMSE Up [m]	Bias [m]	σ [m]	RMSE Up [m]
SISAR	-0.17	0.97	0.98	-0.78	1.27	10.49	-0.14	1.53	1.53
OE Pan	-0.39	0.62	0.73	0.69	1.69	1.82	0.75	1.15	1.37
OE NIR	-0.15	2.17	2.17	0.53	2.22	2.28	0.69	2.01	2.13

better results with semi-automatic procedure

RasterValue - ReferenceValue