



Koninklijk Nederlands  
Meteorologisch Instituut  
*Ministerie van Verkeer en Waterstaat*

***R. Roebeling, E. Wolters, and H. Leijnse***

Thanks to:

I. Holleman, H. Deneke, and J. F. Meirink (KNMI)

**TRIPLE COLLOCATION OF PRECIPITATION RETRIEVALS FROM SEVIRI  
WITH GRIDDED RAIN GAUGE DATA AND WEATHER RADAR  
OBSERVATIONS OVER EUROPE**



## Introduction

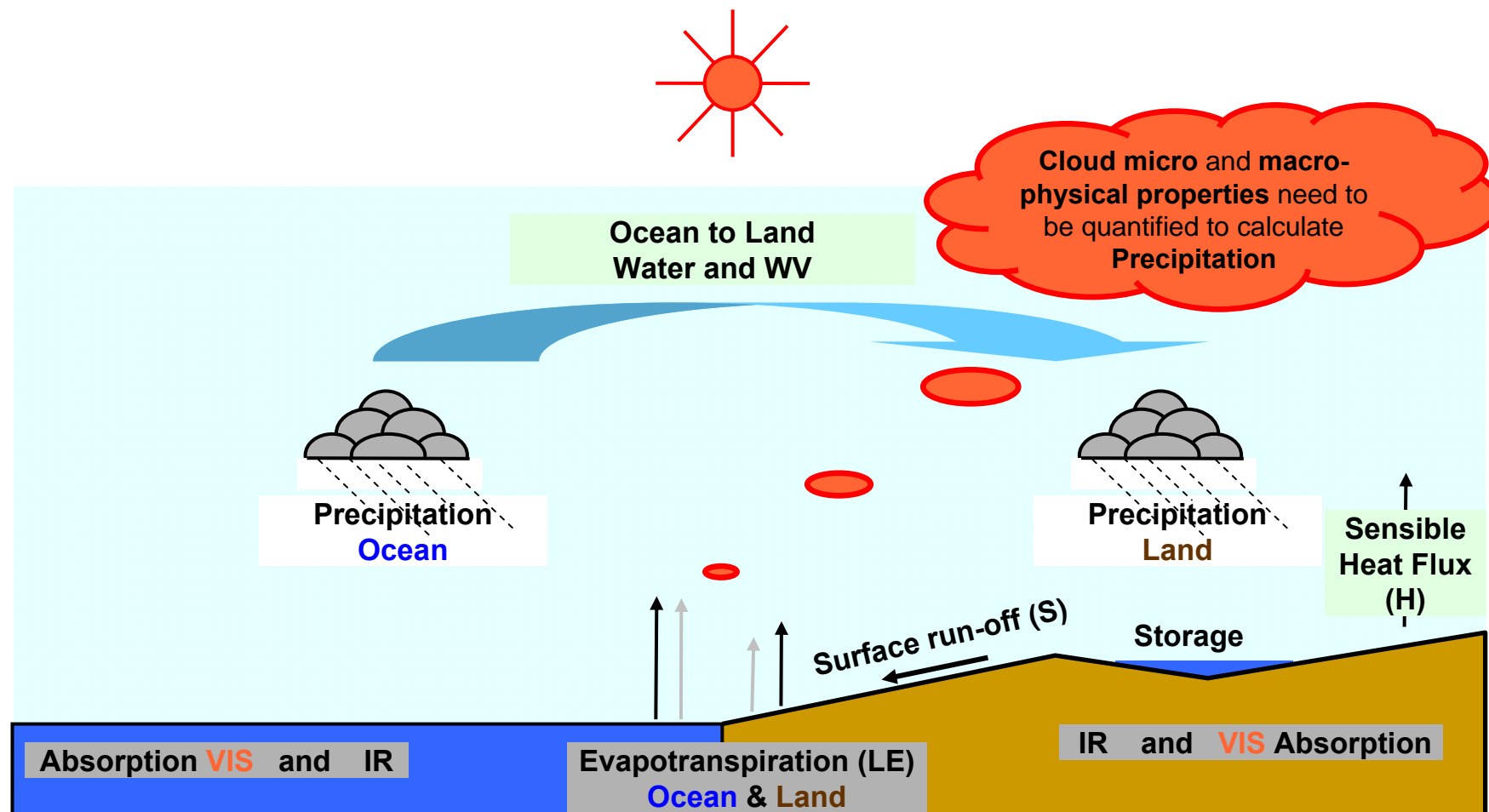
- ❖ **Motivation**
- ❖ **Cloud microphysics based precipitation retrieval**
- ❖ **Triple collocation**
- ❖ **Conclusions**



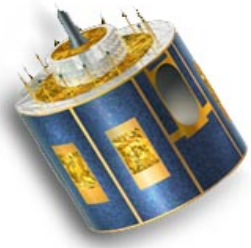
# *Motivation*



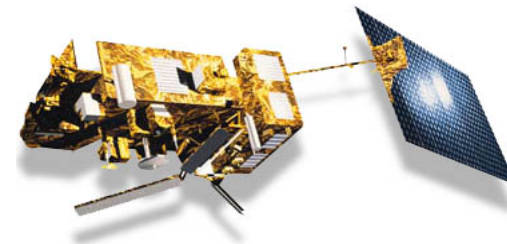
## Role of clouds in water balance



**Figure:** Schematic representation of the role of clouds in the water balance

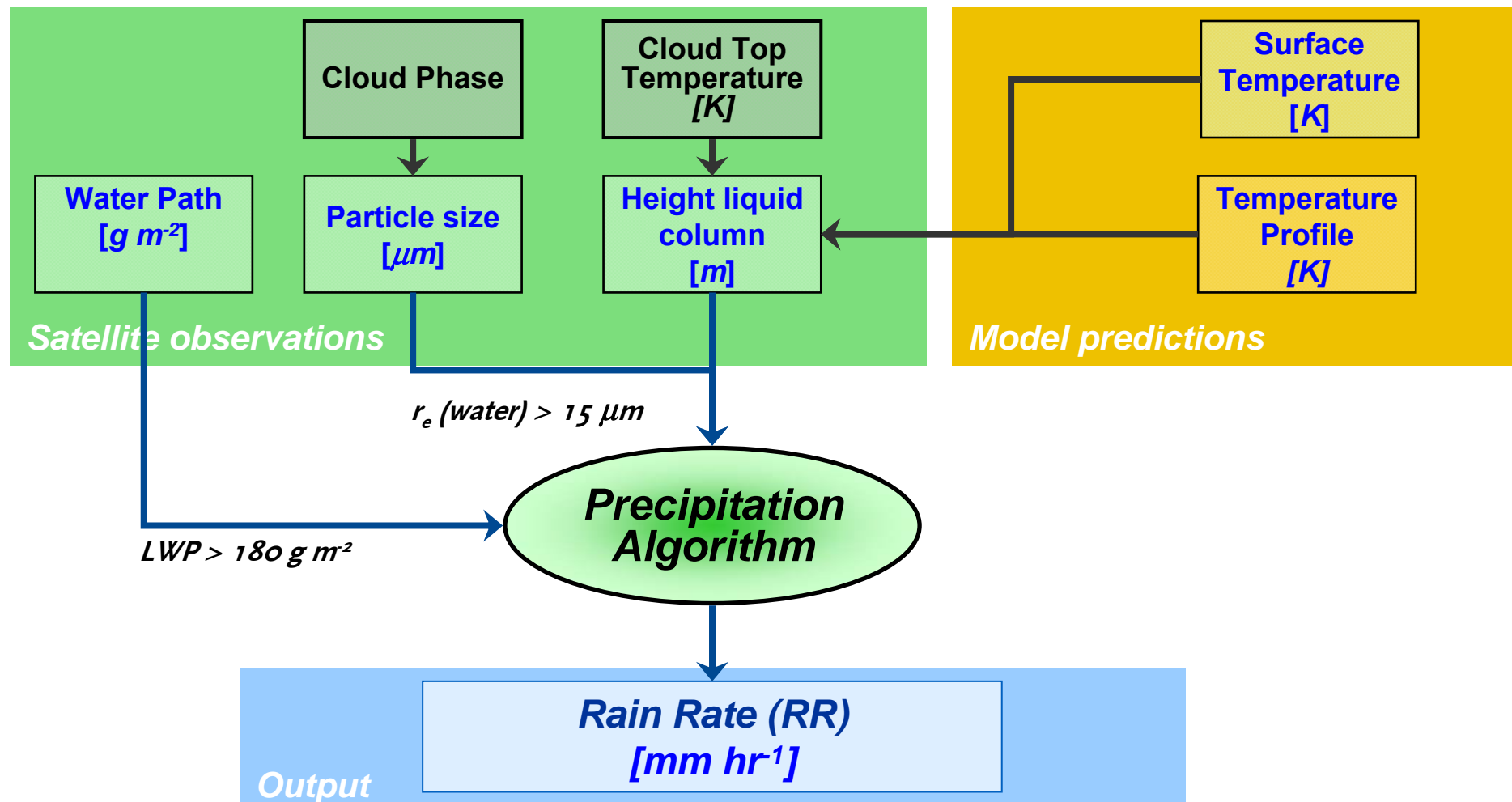


# *Cloud microphysics based precipitation retrieval*





## PP-VNIR: Retrieval (1)





## PP-VNIR: Retrieval (2)

### 1) Rain Rate retrieval

Based rain rate retrieval approach for SSM/I (*Wentz and Spencer, 1998*), and modified *Roebeling and Holleman (2009)* for SEVIRI.

$$LWP = 125 (1 + (H(R - \Delta R))^{0.6})$$

### 2) Correction for Cloud column height

$$H = \frac{(CTT_{max} - CTT_{pix})}{6.5} + \Delta H$$

#### Where

$LWP$	: Liquid Water Path	[g m <sup>-2</sup> ]
$R$	: Rain Rate	[mm hr <sup>-1</sup> ]
$H$	: Height of rain column	[km]
$CTT$	: Cloud Top Temperature	[K]
$\Delta R$	: Offset rain rate	[mm hr <sup>-1</sup> ]
$\Delta H$	: Offset height rain column	[km]

### 3) Correction for below cloud evaporation

The approach of *Petty (2001)* is used to calculate evaporation of rainfall below cloud base ( $R_r$ ):

$$R_r(z + dz) = R_r(z)e^E$$

where  $E$  is defined as:

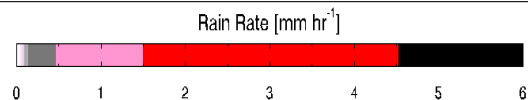
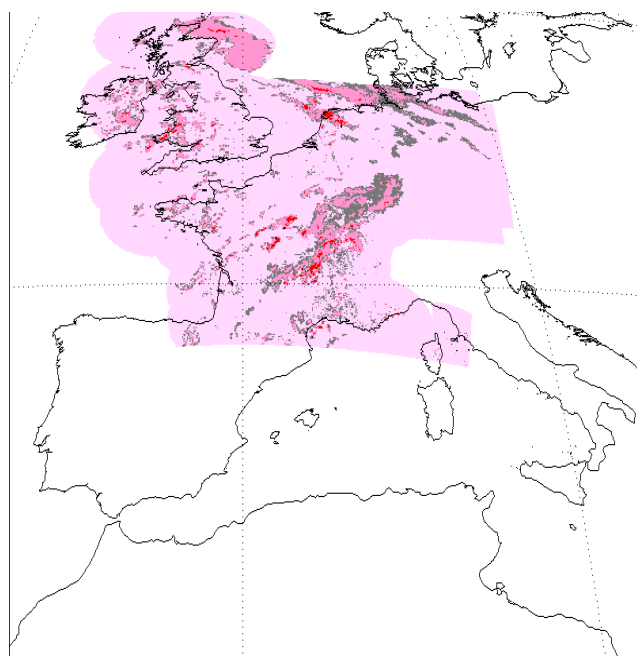
$$E = C_{ev}(-2.25R_r - 0.2)(1 - f)dz$$

#### Where

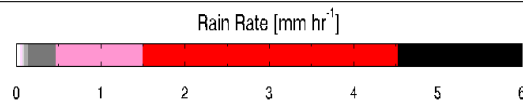
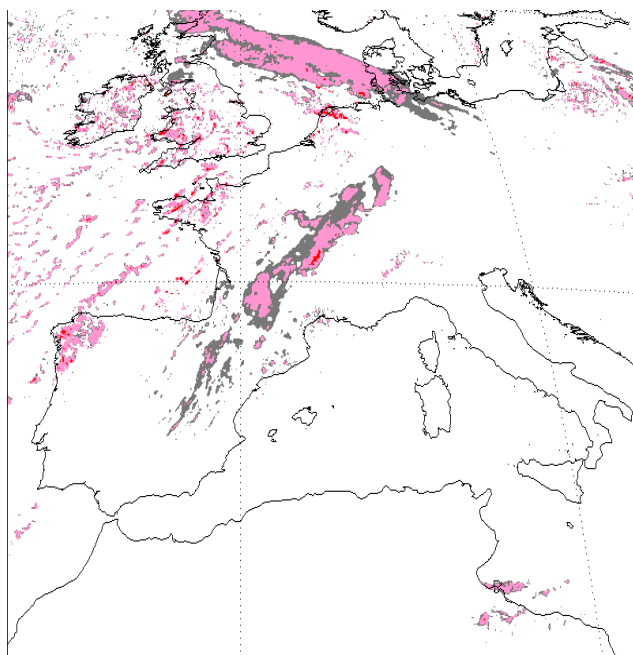
$z$	: altitude	[km]
	(from CTT and COT);	
$C_{ev}$	: effective evap. efficiency	[-]
	(0.5 from Austin 1987)	
$f$	: profile of relative humidity	[%]
	(from MERIS WV product).	



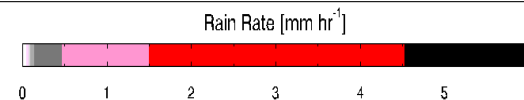
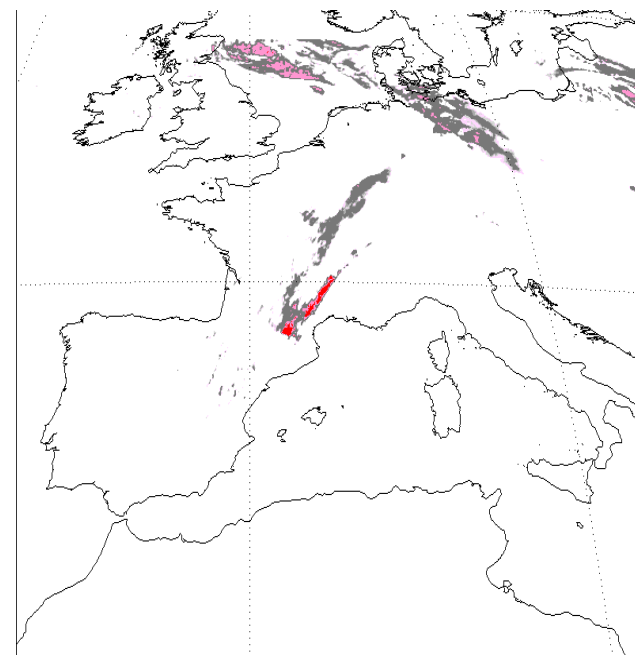
## Example: Comparison PP-VNIR v.s. Weather Radar



***Weather Radar***



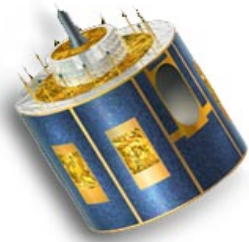
***MSG/PP-VNIR***



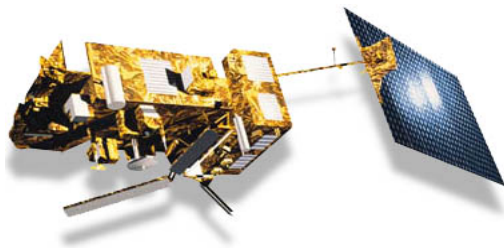
***MSG/MPE***

*(diurnal cycle 1 July 2007)*





# *Triple Collocation*





## Validation: Triple-collocation (1)

### Objective

To quantify spatial and temporal consistency of the SEVIRI precipitation product over Europe.

### Method

Triple-collocation is used to estimate error structures of three (or four) independent datasets. The spatial and temporal error structures are evaluated.

Domain: Europe

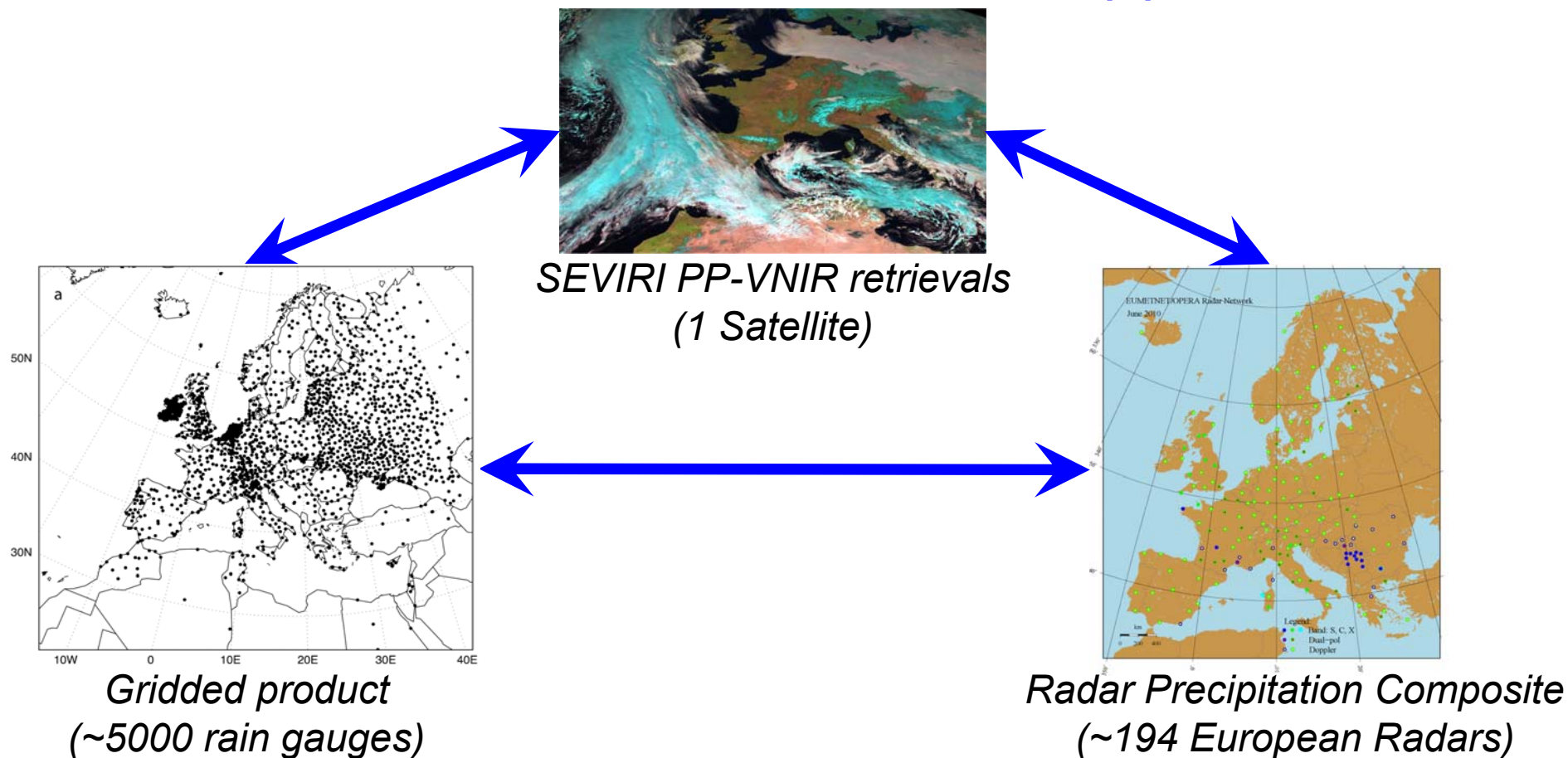
Period: Summer months (M,J,J,A) 2004, 2005 and 2006

Datasets: **GPCC**, **ECA&D**, **OPERA** and **PP-VNIR**(SEVIRI)

Nr Obs.: GPCC (monthly sums), ECA&D (daily sums), OPERA (5 mn. 24 hr/day) and PP-VNIR(SEVIRI) (15 mn. ~ 9 hr/day)



## Validation: Triple-collocation (2)



### Gridded datasets:

**ECA&D:** European Climate Assessment and Data set of KNMI

**GPCC:** Global Precipitation Climatology Centre of DWD



## Validation: Triple-collocation (3)

### ***Triple –collocation principles***

The method presented in Stoffelen et al. (1998); Jansen et al. (2006) or Scipal et al (2008). Triple-collocation aims to estimate the RSME which expresses the variance of the residual errors ( $r_x$ ):

$$X = \alpha_X + \beta_X R + r_X$$

$$Y = \alpha_Y + \beta_Y R + r_Y$$

$$Z = \alpha_Z + \beta_Z R + r_Z$$

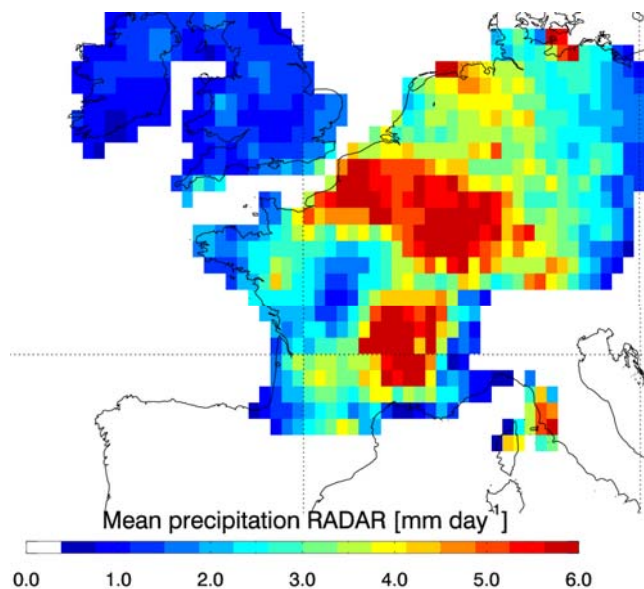
Where:

- $R$ : true values
- $X, Y, Z$ : retrieval values of the datasets
- $\alpha$  and  $\beta$ : calibration constants (offset and gain)
- $r$ : residual errors

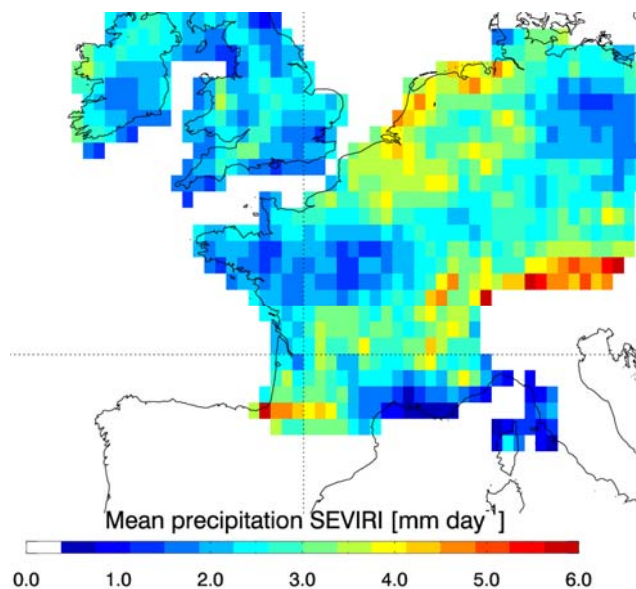


## Validation: Triple-Collocation (4)

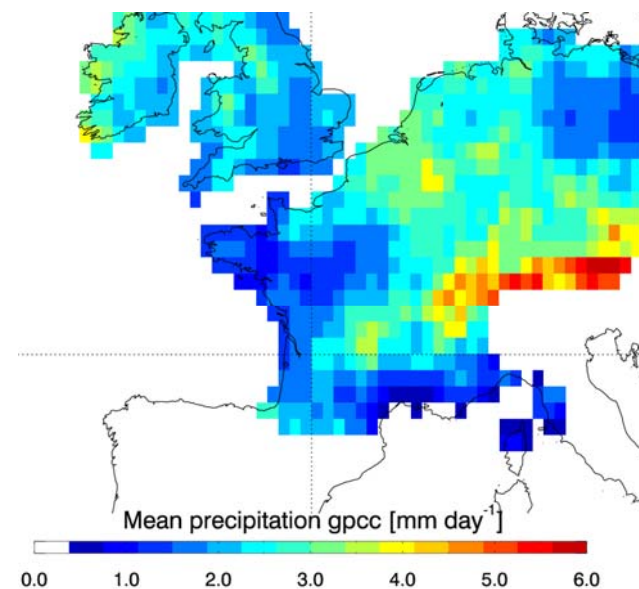
Weather Radars EU



SEVIRI (PP-VNIR)



GPCC



*Fig: Comparison of Weather Radars, SEVIRI and GPCC mean daily precipitation during May-August 2006*

*GPCC: Global Precipitation Climatology Centre of DWD*



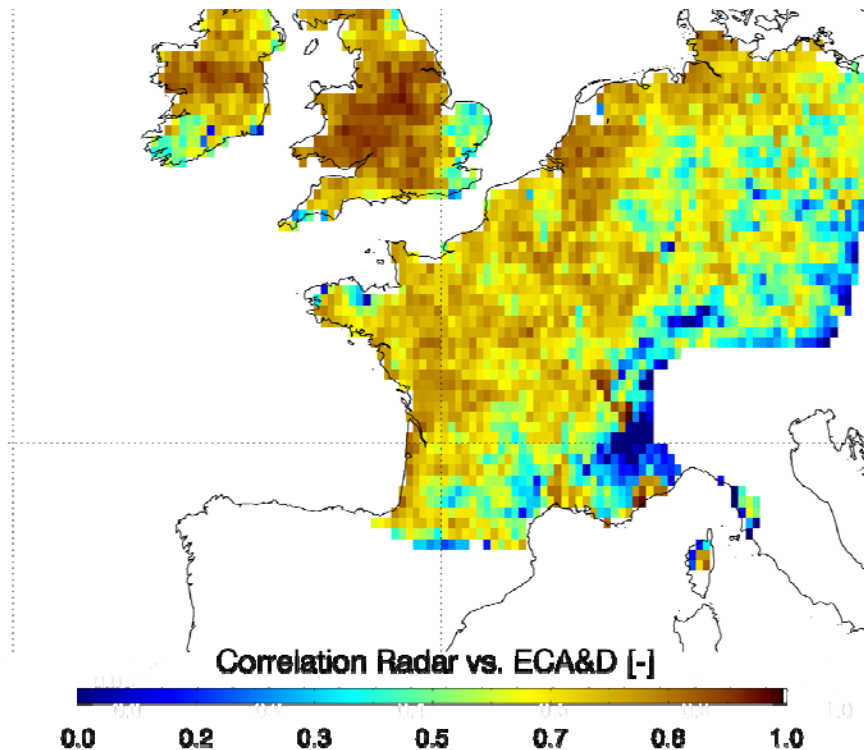
## Validation: Triple-collocation (5)

<i>Instr</i>	<i>Mean</i>	<i>Max</i>	<i>Std</i>	<i>Err</i>	<i>True Var.</i>	<i>Correl</i>
<b>2005</b>						
<b>GPCC</b>	2.19	6.82	0.91	0.70	2.55	1.00
<b>RADAR</b>	3.03	29.71	1.97	65.10	2.55	0.02
<b>SEVIRI</b>	2.89	7.58	1.00	0.96	2.55	0.82
<b>2006</b>						
<b>GPCC</b>	2.35	6.43	0.88	0.79	2.70	1.00
<b>RADAR</b>	3.28	21.10	1.85	2.69	2.70	0.30
<b>SEVIRI</b>	2.84	6.98	0.96	0.35	2.70	0.72
<b>2007</b>						
<b>GPCC</b>	3.32	7.84	0.94	0.89	3.25	1.00
<b>RADAR</b>	4.17	15.25	2.02	4.72	3.25	0.21
<b>SEVIRI</b>	2.95	10.28	1.08	0.19	3.25	0.74

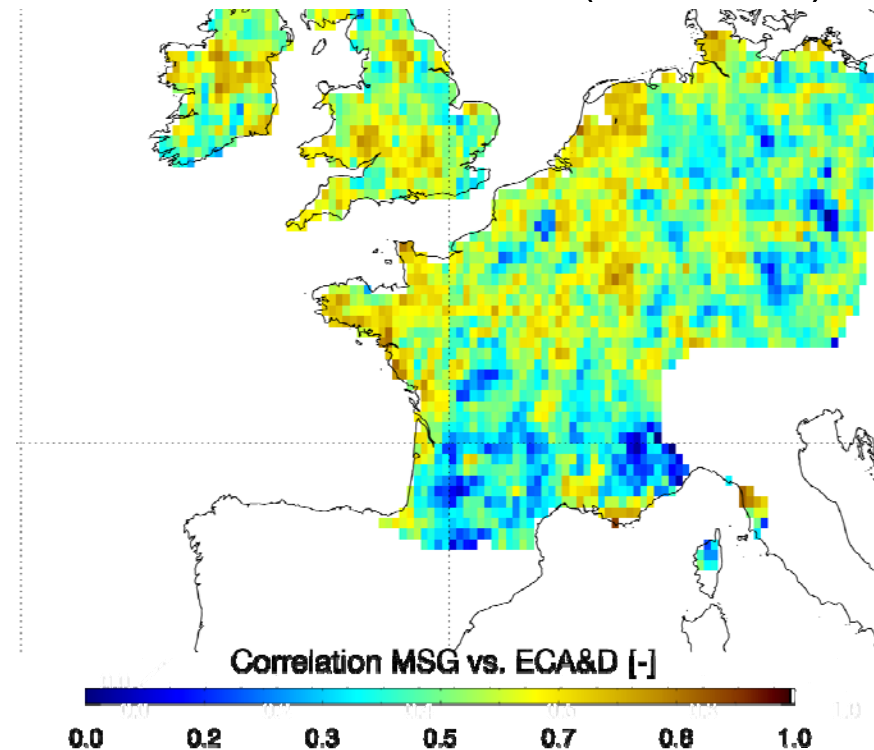


## Validation: Triple-Collocation (6)

ECA&D vs. EU RADAR



ECA&D vs. SEVIRI (PP-VNIR)



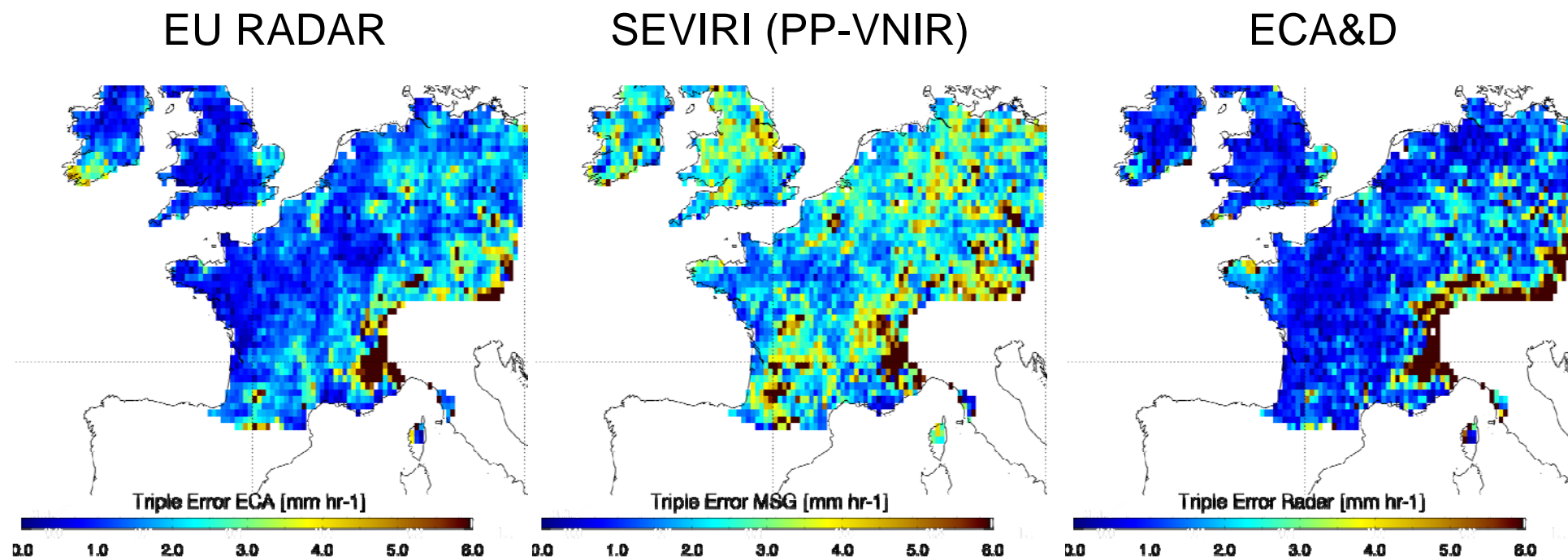
*Fig: Temporal correlation between ECA&D and Weather Radars (Left) and SEVIRI (right) using decadal precipitation rates for the summer months of 2005, 2006 and 2007*

*ECA&D: European Climate Assessment and Data set of KNMI*





## Validation: Triple-Collocation (7)



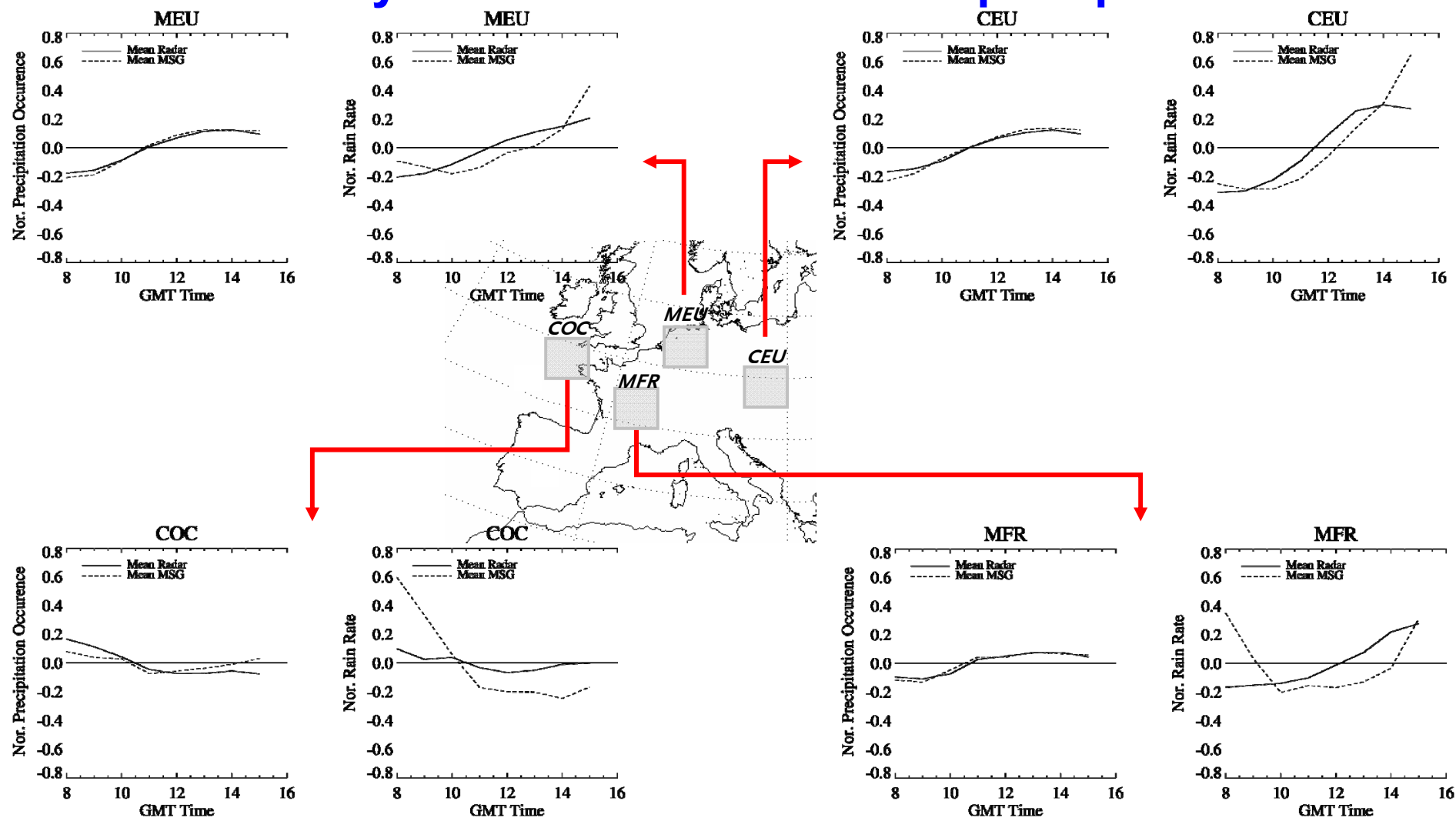
*Fig: Triple collocation errors of Weather Radars, SEVIRI and ECA decadal precipitation rates for the summer months of 2005, 2006 and 2007*

*ECA&D: European Climate Assessment and Data set of KNMI*





## Diurnal cycles Radar and PP-VNIR precipitation





# *Conclusions*

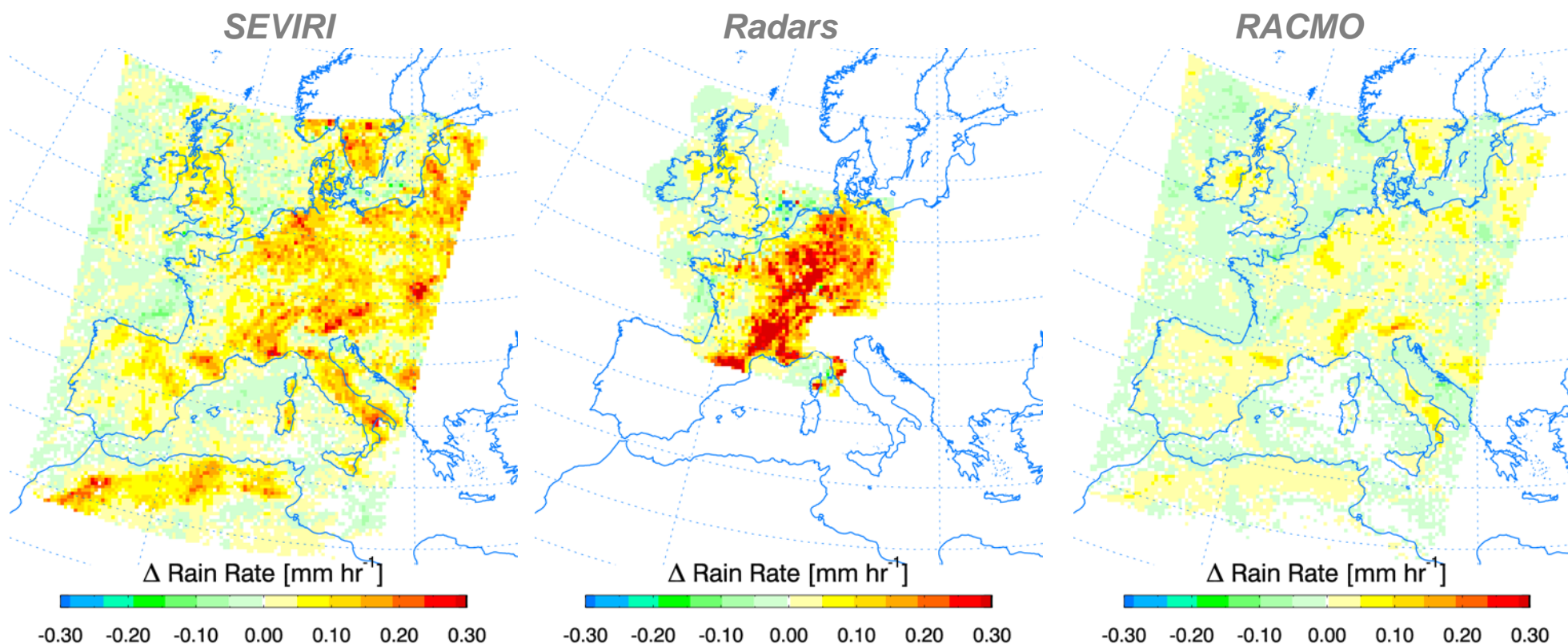


## Conclusions

- ❖ Triple collocation is good manner to find artefacts in different datasets;
- ❖ SEVIRI detects spatial and temporal variations in precipitation realistically;
- ❖ In its current form the EU RADAR composite is not suited to detects spatial variations in precipitation, whereas temporal variations are well detected;  
***!! OPERA aims to improve on this situation !!***
- ❖ GPCC and ECA&D deviate most from SEVIRI and EU RADAR in under sampled areas;
- ❖ SEVIRI & Radar show comparable diurnal cycles in occurrence and intensity of precipitation.



## Future: diagnoses precipitation parameterizations



*Fig: Difference between noon and morning rain rates for SEVIRI, Weather Radars and RACMO during May – Sept 2006*



Thank you!