

# Mountain Search and Rescue with Remotely Piloted Aircraft Systems

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## A. Motivation and Opportunities

Increasing number of people practicing winter sports in backcountry areas
Avalanches are one of the greatest hazards

RPAS can contribute to save lives by means of:

- Autonomous search of ARTVA signal
- Visual (visible/IR) Search&Rescue
- Aid Kit deployment

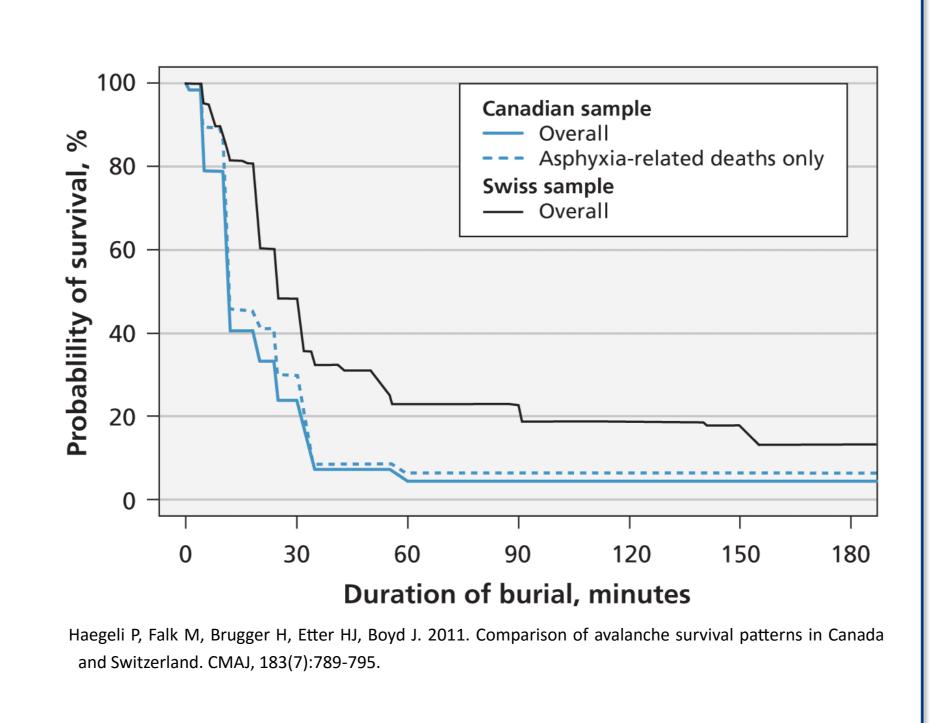
#### B. Rescue Mission

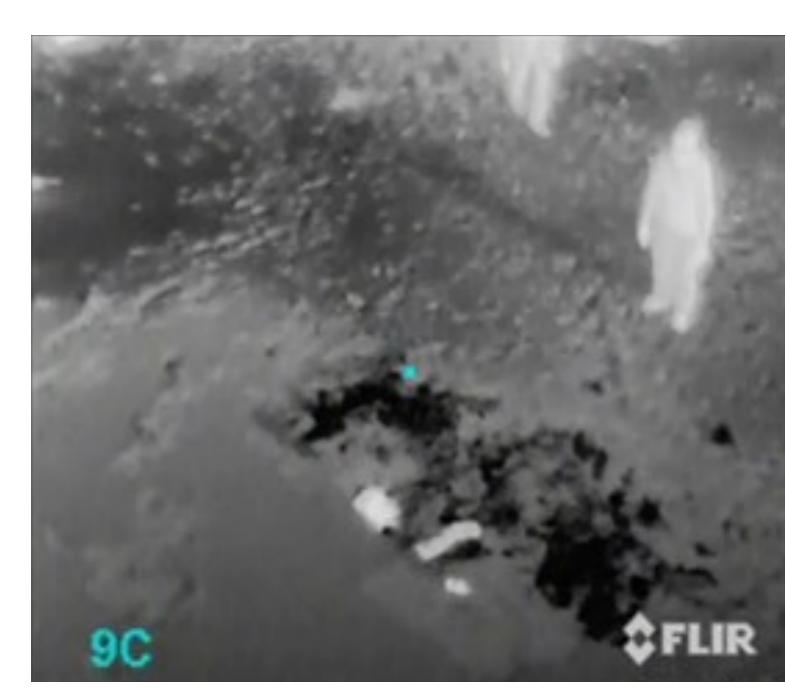
Follows the typical ARTVA search path Minimal RPAS deployment time (to T.O.) No need of flight programming and sensors calibration

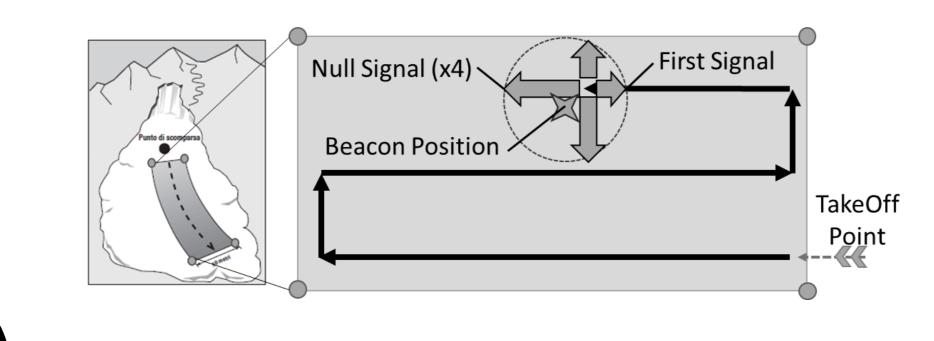
Full Automatic flight (no remote piloting)
Typical search path with

- GRID
- CROSS

Automatic Landing on Identified Target (opt. GPS coordinate)









## C. Proposed Solution and Devices

Small commercial quadcopter RPAS with:

- Customizable SW
- Calibrated Sensors
- Full Autonomous capabilities

Retractable ARTVA Antenna

- Compact design for easy transport/ deploy
- Proper distance from Avionics/Power
- Minimize wind and manoeuvres effects

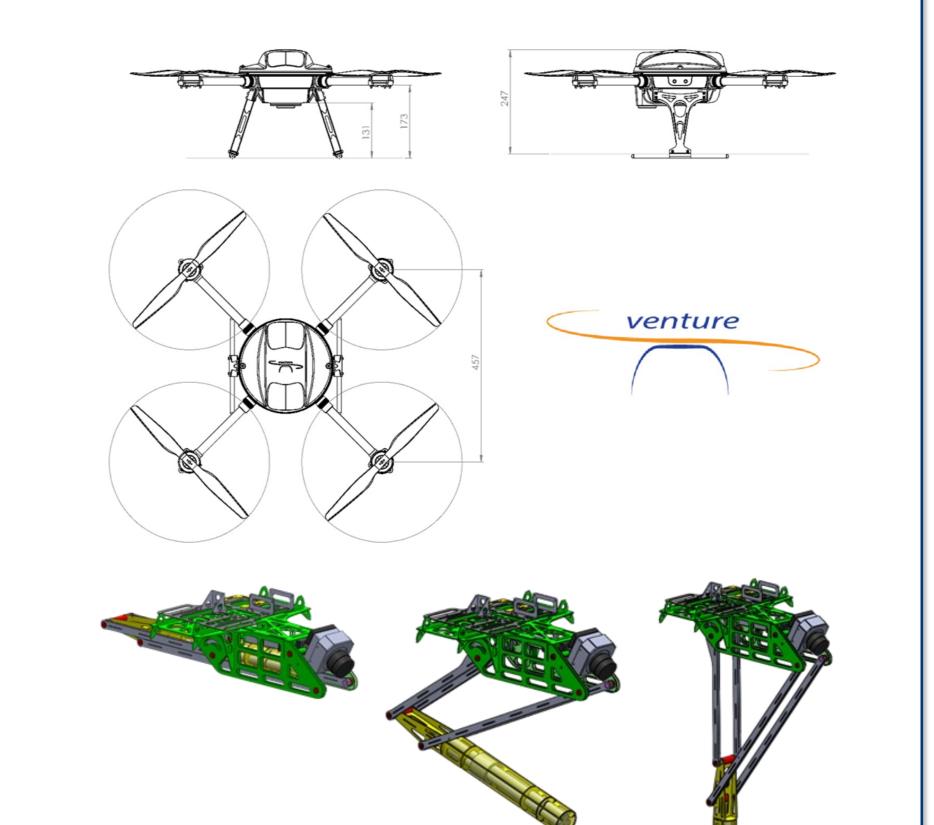
Automatic Terrain Following

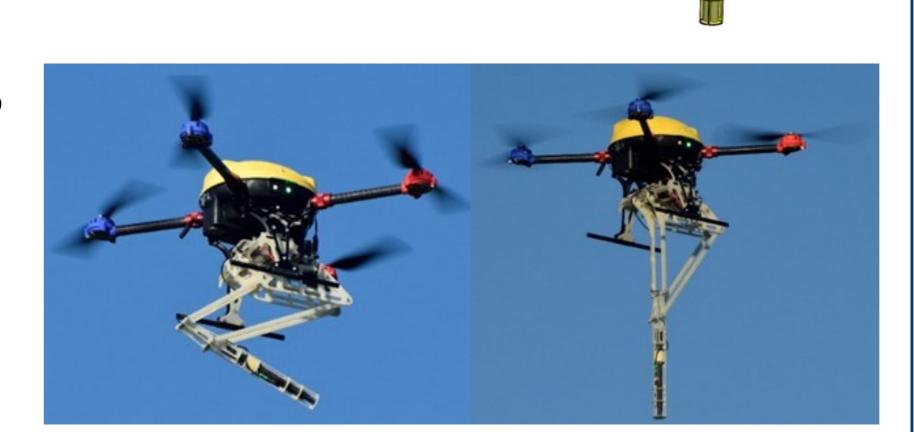
- Cope with mountain orography
- Constant ground-antenna distance
- Landing time optimization

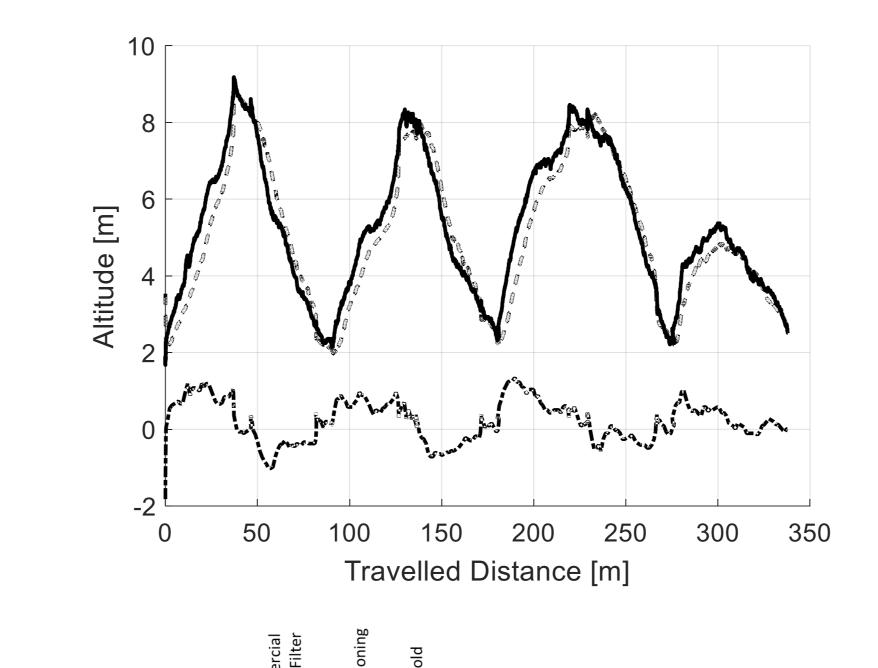
Full Autonomous Mission

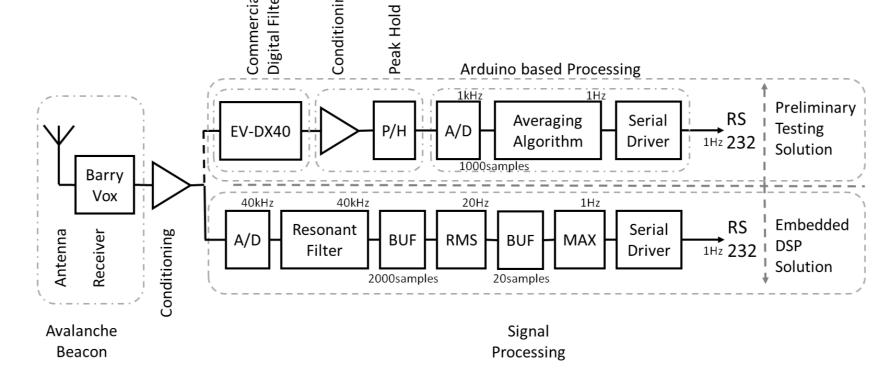
- Auto Heading / Avalanche size selection
- Automatic in-flight reprogramming by detected ARTVA signals

DSP based ARTVA signal processing
Optional GCS monitoring/communication



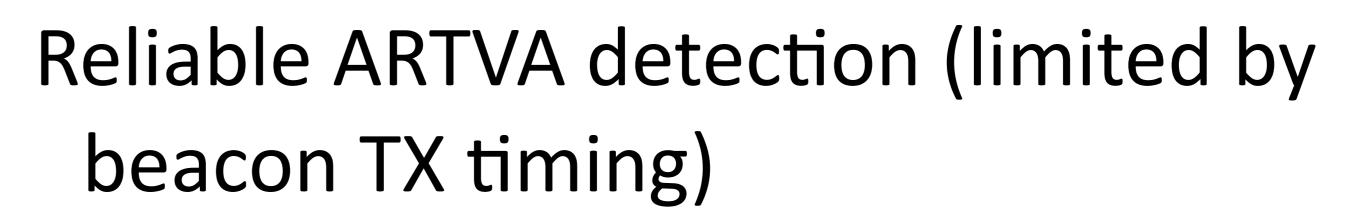






### D. Results

TOW: 3.5kg (incl. ARTVA, IR, 6s4.6Ah LiPo battery)
Reliable flight in mountain: altitude/
temperature/wing/terrain
Flight time optimization (turns/landing)
Navigation accuracy 1-2m (GPS+IMU,
5m/s wind gust)



Detection ranking for additional refinement

Flight Speed: min 4m/s (GRID), typ. 2m/s (CROSS)

Typical buried identification accuracy less than 1m

## E. Conclusions

Tests performed in backcountry terrain show the effectiveness of RPAS for:

- ARTVA search of buried people
- Visible/IR search of partially buried people

