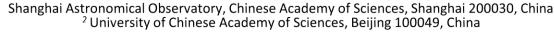


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Possibility Study of common tropospheric parameters as another 'local ties' of TRF

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Abstract:

The terrestrial reference frame (TRF) is commonly realized by a combination of space geodetic techniques. During the combination 'global ties', i.e. common global parameters, like the Earth Orientation Parameters (EOP), can be directly used, while 'local ties', i.e. common coordinates at colocation sites, have to consider the distances between the reference points of the various devices. The all observation of ground-based space geodetic techniques is through the atmosphere and consequently common atmospheric parameters for colocation sites might be used to link the techniques as well. But what are the common atmospheric parameters? We study the systematic errors between tropospheric parameters obtained by different techniques. By tropospheric parameters estimates and comparison of SLR/GNSS/VLBI/DORIS colocation sites we check what make the tropospheric differences of 4-technique colocation sites so that we can apply the ties better. We hope to find a method to apply tropospheric ties for a combination of the space geodetic techniques.

Tropospheric model for radio techniques

 $d_h^z = (0.0022768 \pm 0.000005) \frac{\Gamma_s}{f(\omega, H)}$

 $d_{nh}^z = 0.0022768 \times (\frac{1255}{t} + 0.05) \times e_s$

 $\mathbf{m}(\epsilon) = \frac{1 + \frac{a_2}{1 + a_3}}{\sin\epsilon + \frac{a_1}{\sin\epsilon + \frac{a_2}{\sin\epsilon + a_2}}} + v_i \quad (i = h, \omega)$

 $v_h = \left[\frac{1}{\sin\epsilon} - \frac{1 + \frac{b}{1+c}}{\sin\epsilon + \frac{a}{\sin\epsilon + \frac{b}{1+c}}}\right] \cdot h_{station}$

The zenith hydrostatic delay:

The zenith hydrostatic delay:

VMF1 mapping function

Where:

Keywords: terrestrial reference frame ; the space geodetic techniques ; local ties; tropospheric parameters ;

Theory and Methodology:

Tropospheric model for optical techniques The zenith hydrostatic delay: $d_h^z = 0.00002416079 \frac{f_h(\lambda)}{f(\varphi,H)} P_S (1)$ Where: $f_h(\lambda) = 10^{-6} [k_1^* \frac{(k_0 + \sigma^2)}{(k_0 - \sigma^2)^2} + k_3^* \frac{(k_2 + \sigma^2)}{(k_2 - \sigma^2)^2}] C_{CO_2},$ $f(\varphi, H) = 1 - 0.0026 cos 2\varphi - 0.00028H,$ $P_S \text{ is the surface barometric pressure}$ The zenith hydrostatic delay:

$$\begin{split} d_{nh}^{z} &= 10^{-6} (5.316 f_{nh}(\lambda) - 3.759 f_{h}(\lambda)) \frac{e_{s}}{f(\varphi, H)} \\ \text{Where:} \\ f_{nh}(\lambda) \\ &= 0.003101 (\omega_{0} + 3\omega_{1}\sigma^{2} + 5\omega_{2}\sigma^{4} + 7\omega_{3}\sigma^{6}) \end{split}$$

The FCULa mapping function:

$$n(\epsilon) = \frac{1 + \frac{a_1}{a_2}}{\sin\epsilon + \frac{a_1}{\sin\epsilon + \frac{a_2}{\sin\epsilon + \frac{a_1}{\sin\epsilon + \frac{a_1}{\sin\epsilon$$

Where:

$$a_i = a_{i0} + a_{i1}t_s + a_{i2}\cos\varphi + a_{i3}H$$
, $(i = 1,2,3)$

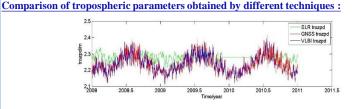


Figure 1 VLBI, SLR, GNSS zenith delay at colocation site WETZ

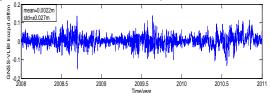


Figure 2 the zenith delay difference between VLBI and GNSS and spectrum analysis (WETZ)

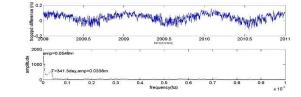
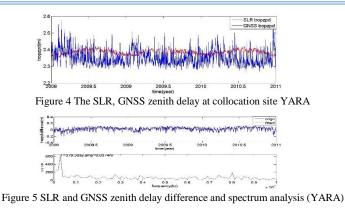
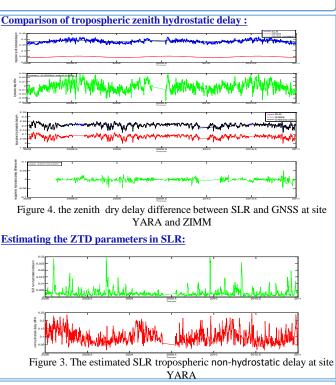


Figure 3 the zenith delay difference between SLR and GNSS and spectrum analysis (WETZ)





Conclusion:

VLBI tropospheric zenith delay is approximately consistent with GNSS

There exits a constant term and a long period (about 1 year) term in the tropospheric zenith delay difference between SLR and GNSS.

SLR tropospheric zenith hydrostatic delay is approximately consistent with GNSS (exiting a scaling factor).

it is the estimated GNSS tropospheric zenith non-hydrostatic delay parameter that cause the difference between SLR and GNSS, since SLR doesn't work when it rains. Next step, we should find the variation law of the difference so that we can apply tropospheric ties for a combination of the space geodetic techniques.