

The VARION algorithm for moving GNSS receivers: preliminary tests and results

Mattia Crespi (1), Michela Ravanelli (1), and Giorgio Savastano (2)

(1) Geodesy and Geomatics Division, DICEA, Sapienza University of Rome, Rome, Italy, (2) Ionospheric and Atmospheric Remote Sensing Group, Jet Propulsion Laboratory, California Institute of Technology, Pasadena, California, USA

The VARION (Variometric Approach for Real-Time Ionosphere Observation) algorithm is a valid instrument to analyse TIDs (Travelling ionospheric disturbances), since it is able to estimate slant TEC (sTEC) variations in real-time [1]. In this work, the first application of VARION to moving GNSS receivers is presented. This usage is made possible since VARION algorithm is based on the geometry-free combination: the receiver motion does not affect the sTEC estimation process. In particular, GNSS observations coming from a ship, moving in the Greenland sea, were used. They were then compared to observations from GNSS permanent receivers both situated in Greenland [2] and in Iceland [3], which served as reference.

The GNSS permanent receivers were chosen in a such way the distance between the ship and the stations was within 200-300 km. In detail, sTEC time series related to the nearest IPP tracks are compared.

The first results show a good agreement both with the selected permanent stations and with the ship-based GNSS receiver. The noise level is also similar and well below the threshold chosen to highlight significant perturbations, like those induced by earthquakes and tsunamis. Furthermore, a passband filter was adopted to cut frequencies ranging from 0.5 to 3.3 mHz, corresponding to wave periods of 5 to 30 seconds. These frequencies were selected to consider only variations in sTEC with periods similar to that of the ocean tsunami itself. The filter was applied both to ship-based GNSS data and to GNSS permanent stations. The reference and the ship data display a better coherence also in this case. The developed methodology, although preliminary, can thus represent a new real-time and costeffective ionosphere monitoring tool, which does not require the installation of complex infrastructures in open sea, but leverages the ships already present in the seas. In conclusion, ship-based GNSS receivers could also be used to increase the ionosphere monitoring coverage over the oceans and, hence, to enhance tsunami early warning system.

References

- [1] Savastano, G., Komjathy, A., Verkhoglyadova, O., Mazzoni, A., Crespi, M., Wei, Y., & Mannucci, A. J. (2017). Real-time detection of tsunami ionospheric disturbances with a stand-alone GNSS receiver: A preliminary feasibility demonstration. *Scientific reports*, 7, 46607. doi: 10.1038/srep46607
- [2] IGS, International GNSS service <http://www.igs.org/network>
- [3] National Survey of Iceland, <http://www.lmi.is/en/>