*P*-wave tomographic model from local bulletin data for improved seismic location in and around Israel

**Session SM4.3**: Imaging, modeling and inversion to explore the Earth's lithosphere

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**Ministry of Aliyah and Integration** 





Vienna | Austria | 3–8 May 2020



• No reliable **3-D velocity model** for Israel

source locations using various 1-D regional & local models

- Required for local Earthquake Early Warning System Dead Sea fault and network geometry, topography in Dead Sea Basin and Sea of Galilee
- Necessary to improve **CTBT monitoring**

integration into a regional model for the Eastern Mediterranean and Middle East region (EMME)





## **Research plan**

• Building of **local travel time database** 

revision of existing bulletin data, collection of unpublished data

- **Identification** of events with high **ground-truth** (GT) accuracy GTo (known location) explosions, GT5 (location error < 5 km) earthquakes and explosions
- Joint relocation of different types of seismic sources explosion data for better coverage, GT locations used as references
- Assembling of a **starting model** for Israel

compilation of geophysical data, crustal structure, etc.

- **Tomographic** inversion for a **crustal model** of Israel *FMTOMO*, P-wave earthquake and explosion data
- Using the crustal model as starting point for regional model RSTT method (CTBT), designed to allow real-time travel-time calculations

Schardong et al. (to be submitted)

**Future work** 





# **Revision of the bulletin data**

- **Irregularities** in the bulletin data clocking errors, missing station location history, etc.
- Large uncertainties on source locations various 1-D reference models, local or regional
- Review of online station catalogues <u>ISC, IRIS, FDSN, EMSC</u>, etc.
- Assembling of new station catalogue correction of station activity periods, locations, code names, etc.

Azimuth discrepancy is the difference between reported azimuth and recalculated azimuth based on available station catalogue Numerical precision of azimuth in bulletin is 1°

### Figure 3:

Wetzler & Kurzon (2016)

Event-to-station azimuth discrepancy before and after revision at RTMI for each **seismic phase**: **Pg**, **Pn**, **Sg**, **Sn** 





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- **GTO**: explosions with known location calibration explosions, old ammunition detonations, etc.
- GT5: event with GT accuracy greater than 5 km

based on network coverage parameters as defined by Bondár et al. (2004)

Figure 4: Station coverage of (a) earthquakes and (b) explosions. **Colour** gives primary azimuthal gap; size gives number of stations. Symbols depend on source type.





A seismic source is GT5 if:

more than 10 recording stations within 250 km

primary azimuthal gap (g<sub>p</sub>) of less than 110°

secondary azimuthal gap
(g<sub>s</sub>) of less than 160°

at least one station within 30 km

36°E



## **Event relocation**



- Multiple-event seismic locator BayesLoc apply TT correction to account for systematic errors, check phase labels
- Origin priors depending on source location accuracy GTo locations fixed, little variations around GT5 locations
- Selection of sources with best network coverage

>5 recording stations, primary azimuthal gap <90°

	Source type	N <sub>s</sub>	N <sub>A</sub>
	EQ	369	4,784
	EXP	2,150	19,878
	GT5	1,412	27,677
5	GTo	200	2,873
	Total	4,131	55,212





Table 2: Origin priors for each source type							
	EQ	EXP	GT5	GTO			
Epicentre [km]	10	10	2.5	0.01			
Depth [km]	10	0.1	2	0.01			
Origin time [s]	15	_	10	0.25			

**Table 1:** Number of **sources**  $(N_s)$ and **arrivals**  $(N_A)$  for each **source type** 



Crotwell et al. (1999) Kennett et al. (1995)

• Arrival-time variance reduction of 50-80%

elimination of outliers and mislabelled phases

• TT corrections eliminate systematic errors

arrivals align with theoretical curves (TauP with ak135)





## **New source locations**

• Most sources relocated <5 km from initial location

GT5 source locations vary much less than allowed

• 96-99% of non-GT5 sources have uncertainty <5 km

new GT5's can be used to improve even less accurately-located sources









• Moho depth variations

extracted from new compilation of crustal thickness maps in the EMME

• Starting velocity model

#### compilation of geological and geophysical data from the Geological Survey of Israel



Gvirtzman *et al.* (2016)

ط<sup>س</sup> <u>GSI</u>



• Forward modelling uses Fast Marching Method (FFM)

simplified ray tracing at any scale

• Wide variety of input **data types** and **seismic phases** 

possibility to combine local and teleseismic data

Model parameterisation allows complex structures

3-D starting model for velocity and crustal thickness

- **Vertical** grid spacing of 5 km (-35 to +5 km)
- **Horizontal** grid spacing of 0.25° (7.5°x6.5°)







# **Regional tomographic model of the EMME**



- **RSTT:** software and regional model designed for real-time travel time calculations
- **Global** tessellation of nodes every 1°

1-D profiles interpolated to build 3-D model of crust and upper mantle

• Ultimate goal is **global model** to predict **regional phases** 

studies already conducted in Eurasia and North America









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# THANKS! Any questions?

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