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Automated characterization of magnetic reconnection using particle distributions

06 May 2020

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EGU 2020 – ST 1.9 "Theory and Simulation of Solar System plasmas"

Magnetic reconnection





Magnetic Reconnection

Complex physical phenomenon

- Break of the frozen-in magnetic field
- Magnetic energy release
- Transport mechanism, particle acceleration
- Magnetic Electron Diffusion Region (EDR)

Occurring in many plasma environments

– Sun: flares, CME

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- Earth's magnetosphere: magnetopause, magnetotail
- MMS mission







Detection of reconnection

- EDR is very small
 - The precise detection is hard
 - Use of indirect signatures
- Usually two groups
 - Field quantities
 - Statistical moments







Detection of reconnection

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Third approach: using directly the distribution





Particle distributions

- Rich part of the information
 - MMS mission: crescent shape
 - Electron dynamics dominates
 - Beams, power law, top-hat
- But very large data
 - 3D velocity space
 - Spatial space
 - Temporal aspect



Burch et al. 2016





Particle distributions

- Rich part of the information
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Burch et al. 2016

Extract automatically information from the particle distributions





Machine learning





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Supervised vs. unsupervised

- Supervised learning
 - Regression
 - Classification



- Unsupervised learning
 - Clustering
 - Dimension reduction
 - Density estimation



Related work

- Automated classification of plasma regions using 3D particle energy distribution. MMS mission: crescent shape, Olshevsky V. et al, 2019
- Automatic Detection of Magnetospheric Regions around Saturn using Cassini Data, Yeakel, K et al., 2017
- Automatic detection of magnetopause reconnection diffusion regions, Garnier P. et al.

Table 2. Training Dataset

Label	Region	# examples	percentage
-1	Unknown	0	0
0	Solar Wind	12, 135	42.4
1	Foreshock	7,351	25.7
2	Magnetosheath	7,009	24.5
3	Magnetosphere	2,146	7.5
	Total	28,641	100

We want to privilege unsupervised approaches





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Building an estimate of the probability density function





Building an estimate of the probability density function

- Non-parametric methods
 - Histogram
 - Kernel Density Estimation

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Building an estimate of the probability density function

Non-parametric methods

- Histogram
- Kernel Density Estimation

- Parametric methods
 - Fitting given distributions
 - Gaussian Mixture Models (GMM)



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Building an estimate of the probability density function

Non-parametric methods

- Histogram
- Kernel Density Estimation



Fitting given distributions

– Gaussian Mixture Models (GMM)





Gaussian Mixture models

Gaussian probability distribution

$$\mathcal{N}(\boldsymbol{x}|\boldsymbol{\mu},\,\boldsymbol{\Sigma}) = \frac{1}{\sqrt{(2\pi)^d |\boldsymbol{\Sigma}|}} exp\left(-\frac{(\boldsymbol{x}-\boldsymbol{\mu})\boldsymbol{\Sigma}^{-1}(\boldsymbol{x}-\boldsymbol{\mu})}{2}\right)$$





Gaussian Mixture models

Gaussian probability distribution

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• Sum of Gaussians (mixture)

$$p(\boldsymbol{x}|\boldsymbol{\Phi}) = \sum_{k=1}^{K} w_k \mathcal{N}(\boldsymbol{x}|\boldsymbol{\theta}_k)$$

Parameters to find

$$\boldsymbol{\theta}_{\boldsymbol{k}} = (w_k, \boldsymbol{\mu}_{\boldsymbol{k}}, \boldsymbol{\Sigma}_{\boldsymbol{k}})$$





Gaussian Mixture models

Gaussian probability distribution

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- Sum of Gaussians (mixture) $p(\boldsymbol{x}|\boldsymbol{\Phi}) = \sum_{k=1}^{K} w_k \, \mathcal{N}(\boldsymbol{x}|\boldsymbol{\theta_k})$ Number of components
- Parameters to find

$$\boldsymbol{\theta}_{\boldsymbol{k}} = (w_k, \boldsymbol{\mu}_{\boldsymbol{k}}, \boldsymbol{\Sigma}_{\boldsymbol{k}})$$





Gaussian Mixture Model

- $l(oldsymbol{\phi};oldsymbol{X})$ = $\sum_{i=1}^n \ln f(oldsymbol{X_i},oldsymbol{\phi})$
- How to infer the best parameters ? Maximum likelihood estimation

$$l(\boldsymbol{\phi}; \boldsymbol{X}) = \sum_{i=1}^{n} \ln \left[\sum_{k=1}^{K} w_k \mathcal{N}(\boldsymbol{x}_i | \boldsymbol{\theta}_k) \right]$$

estimation
problem
$$\frac{\partial l}{\partial \boldsymbol{\mu}_k} = 0 \qquad \frac{\partial l}{\partial \boldsymbol{\Sigma}_k} = 0 \qquad \frac{\partial l}{\partial \boldsymbol{w}_k} = 0 \quad s.t. \sum_{k=1}^{K} w_k = 1$$

- Maximizing the likelihood estimation
 - Non linear maximization problem
 - No closed form

• Need to find numerical local maximum: Expectation Maximization



• Very effective for models with unobserved latent variables







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• Very effective for models with unobserved latent variables







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• How to determine the number of components K?





• How to determine the number of components K?

- Information theory
 - Aikaike Information Criterion
 - Bayesian Information Criterion

$$AIC = 2k - 2\ln(L)$$
$$BIC = \ln(n)k - 2\ln(L)$$





• How to determine the number of components K?

- Information theory
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Complexity

Goodness of fit





• How to determine the number of components K?

- Information theory
 - Aikaike Information Criterion
 - Bayesian Information Criterion



Complexity

Goodness of fit

- Various interpretation to the number of components K
 - Beams/electron subpopulation
 - Complex distribution
 - Deviation from a Gaussian (tail, mode width, etc.)



Simulations





Simulations

- Access to the complete description of the plasma over all the spatial grid
- 2.5D collisionless Particle In Cell simulations
 - iPic3D (Markidis et al.)
 - Double Harris sheet case, weak guide field
 - Grid: 769 x 1025 (30di x 40 di)
 - 196,000,000 particles (~250 particles/cell)
 - Weighted particle injection

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B-field-aligned basis

$$e_{\parallel} := \widehat{B}, \text{ where } \widehat{B} = \frac{B}{\|B\|}$$

 $e_{\perp 1} := \widehat{B} \times e_{z}$
 $e_{\perp 2} := \widehat{B} \times e_{\perp 1} = -\widehat{B}^2 e_{z} + (e_{z}.\widehat{B})\widehat{B}$















(†)

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Analyzing the mixtures

• Thermal energy of the distribution

$$E_{thermal} = \frac{1}{N_p} \sum_{i=1}^{3} \left[\sum_{p} \left(\mathbf{V_p} - \langle \mathbf{V_p} \rangle \right)^2 \right]_i, \text{ with } \langle \mathbf{V_p} \rangle = \sum_{p} \frac{\mathbf{V_p}}{N_p}$$





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• Variance of the mixture:

$$(\sigma^2)^{(K)} = \sum_{i=1}^3 \left[\sum_{k=1}^K w_k^2 (\boldsymbol{\sigma}_k)^2 + \sum_{k=1}^K w_k (\boldsymbol{\mu}_k)^2 - \left(\sum_{k=1}^K w_k (\boldsymbol{\mu}_k) \right)^2 \right]_i$$





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Analyzing the mixtures: energy drop and deviation

• Thermal energy of the distribution

$$E_{thermal} = \frac{1}{N_p} \sum_{i=1}^{3} \left[\sum_{p} \left(\mathbf{V_p} - \langle \mathbf{V_p} \rangle \right)^2 \right]_i, \text{ with } \langle \mathbf{V_p} \rangle = \sum_{p} \frac{\mathbf{V_p}}{N_p}$$

Variance of the mixture: $(\sigma^2)^{(K)} = \sum_{i=1}^3 \left(\sum_{k=1}^K w_k^2 \left(\boldsymbol{\sigma}_k \right)^2 \right) + \left(\sum_{k=1}^K w_k \left(\boldsymbol{\mu}_k \right)^2 - \left(\sum_{k=1}^K w_k \left(\boldsymbol{\mu}_k \right) \right)^2 \right)$ **Diagnostic quantities** $E_{thermal}^{(K)}$ $E_{dev}^{(K)}$ $E_{dev} =$ $E_{dev}^{(K)}$ $E_{drop} = \frac{E_{thermal}}{E}$ Ð EGU 2020 06 May 2020

Analyzing the mixtures: energy drop and deviation









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Next steps

• Simulation: focus on less documented cases

- 2D turbulent reconnection
- 3D reconnection
- Other kind of simulations
- Observation: distributions from in situ space missions
 - MMS data
 - Reconstruction of the particle sampling

• Machine learning: potential improvement

- Convolutional methods and auto encoder
- Dual problem with kernel method



MMS observation: day side 2015

- Reconnection event: 16 October 2015-13:07:02.235 (Burch et al.)
 - Gap due to low energy channels
 - Complex preprocessing pipeline
 - Identify crescent shape

- Auto encoder may help (Olshevsky et al)
 - Extract 3D features
 - Use the PDF directly







Turbulent simulation

Identification of potential current layers •





Turbulent simulation

Identification of potential current layers •



1th4 out

Conclusion

• GMM is able to identify complex distributions in various cases

- Reconnection with weak and strong guide fields
- Help to analyze and identify reconnection
- No real physical interpretation and no unique solution

• GMM as a start in applying ML on simulations and particles

- Other ML methods are considered
- Auto encoder, SOM, etc.





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Thank you for your attention

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Gaussian Mixture Model

• How to infer the best parameters ?

$$\begin{aligned} \mathcal{U}(\boldsymbol{\phi}|\boldsymbol{X},\boldsymbol{Z}) &= \sum_{i=1}^{n} \ln \left[\sum_{k=1}^{K} w_k \mathcal{N}(\boldsymbol{x_i}|\boldsymbol{\theta_k}) \right] \\ \text{estimation} \\ \text{problem} \\ \frac{\partial l}{\partial \boldsymbol{\mu_k}} &= 0 \\ \frac{\partial l}{\partial \boldsymbol{\Sigma_k}} &= 0 \\ \frac{\partial l}{\partial \boldsymbol{\Sigma_k}} &= 0 \\ \frac{\partial l}{\partial w_k} &= 0 \\ s.t. \\ \sum_{k=1}^{K} w_k &= 1 \end{aligned}$$

- Maximizing the likelihood estimation
 - Non linear maximization problem
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• Need to find numerical local maximum: Expectation Maximization



EM Algorithm

$$\gamma(z_k) = \frac{w_k \mathcal{N}(\boldsymbol{x}|\boldsymbol{\theta}_k)}{\sum_{j=1}^K w_j \mathcal{N}(\boldsymbol{x}|\boldsymbol{\theta}_j)}.$$

Expectation Step

$$\boldsymbol{\mu}_{\boldsymbol{k}} = \frac{\sum_{i=1}^{n} \gamma(z_{ik}) \boldsymbol{x}_{i}}{\sum_{i=1}^{n} \gamma(z_{ik})}, \quad \forall k \in [1, \cdots, K],$$
$$\boldsymbol{\Sigma}_{\boldsymbol{k}} = \frac{\sum_{i=1}^{N} \gamma(z_{ik}) (\boldsymbol{x}_{i} - \boldsymbol{\mu}_{\boldsymbol{k}}) (\boldsymbol{x}_{i} - \boldsymbol{\mu}_{\boldsymbol{k}})^{T}}{\sum_{i=1}^{N} \gamma(z_{ik})}, \quad \forall k \in [1, \cdots, K],$$
$$w_{k} = \frac{1}{n} \sum_{i=1}^{n} \gamma(z_{ik}), \quad \forall k \in [1, \cdots, K].$$

Maximization Step





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```
Data: particles coordinates X and velocities V, mesh \Omega with n_x cells by n_y cells Result: distribution function f_i
```

1 begin

 $\mathbf{2}$

merge cells to increase the number of particles by subset, new mesh Ω' is of size $\frac{n_x}{r} \times \frac{n_y}{r}$

$$\mathbf{3} \quad | \quad \mathbf{for} \ i \in \Omega' \ \mathbf{do}$$

```
for k = 1 to k = 6 do
 \mathbf{4}
               GMM_k = GMM(V_i; k);
 \mathbf{5}
               BIC_k = BIC(GMM_k);
 6
           end
 7
           K = \arg\max_{k \in [1,6]} BIC_k;
 8
           f_i = GMM_K;
 9
10
       end
\mathbf{11}
12 end
```





Data: particles coordinates X and velocities V, mesh Ω with n_x cells by n_y cells **Description** function f

Result: distribution function f_i

1 begin

2 | merge cells to increase the number of particles by subset, new mesh Ω' is of size $\frac{n_x}{r} \times \frac{n_y}{r}$

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3 for $i \in \Omega'$ do

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12 end





Data: particles coordinates X and velocities V, mesh Ω with n_x cells by n_y cells **Result:** distribution function f_i

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 $\mathbf{2}$

merge cells to increase the number of particles by subset, new mesh Ω' is of size $\frac{n_x}{r} \times \frac{n_y}{r}$

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4
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6
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8
9
11
end
11
for
$$i \in \Omega'$$
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 $GMM_k = GMM(V_i; k);$
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end
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12 end









