



Bridging the gap – linking GRACE and GRACE-Follow On by hISST and SLR

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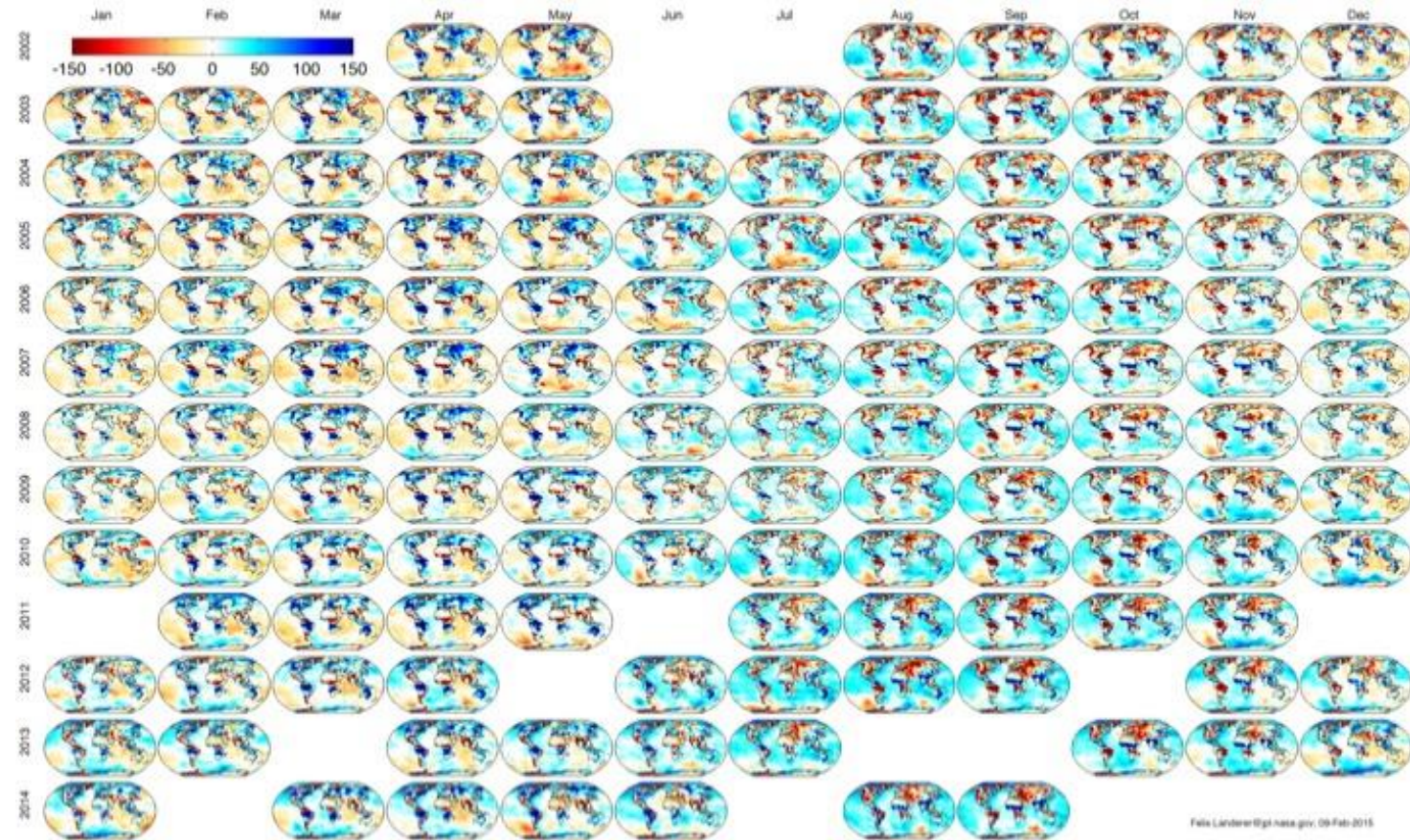
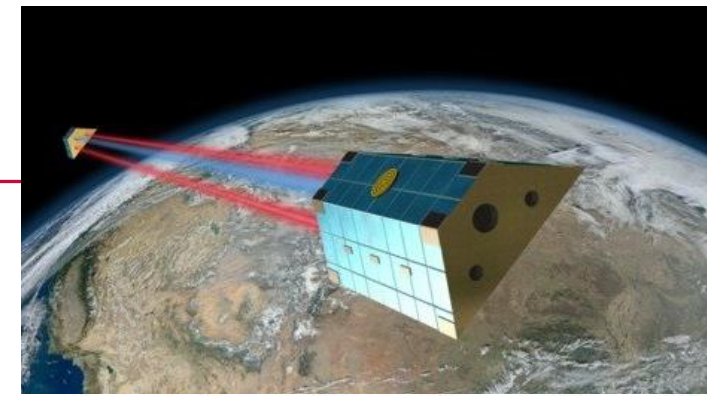
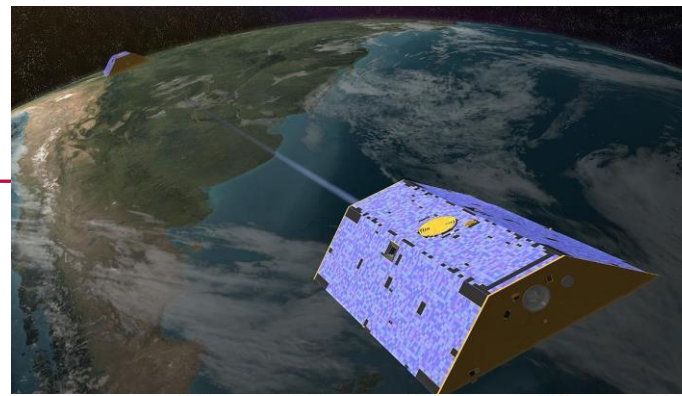
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2) Astronomical Institute, University Bern



Motivation

- Bridging the gap between GRACE and GRACE-FO
- Bridging the gaps of GRACE
- Cross-validating GRACE and GRACE Follow-On
- Combination of gravity fields from various sources for improved recovery
- Study multi-mission multi-satellite environments



courtesy Felix Landerer using JPL mascons – Watkins et al. 2015



hISST data processing

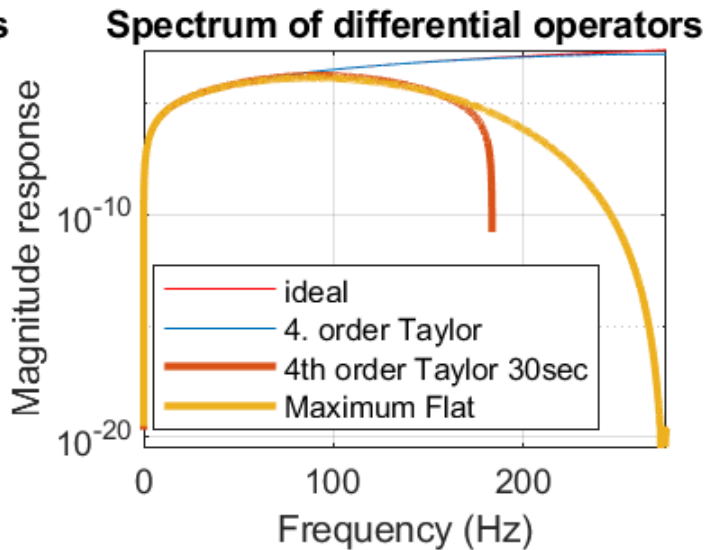
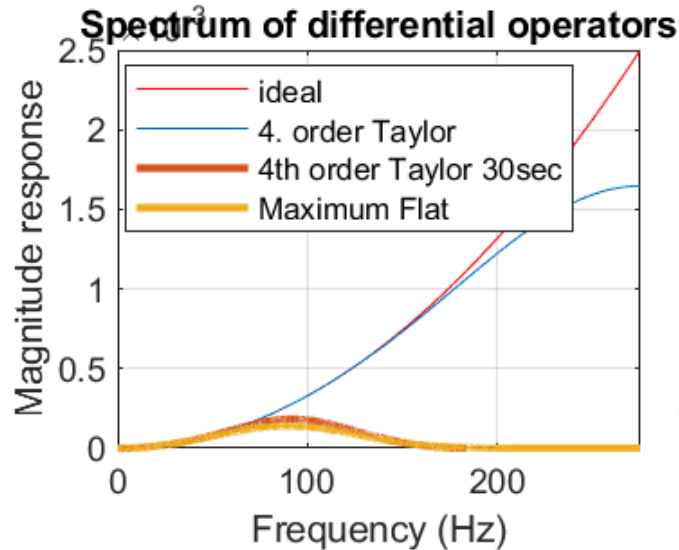


Acceleration approach and background models

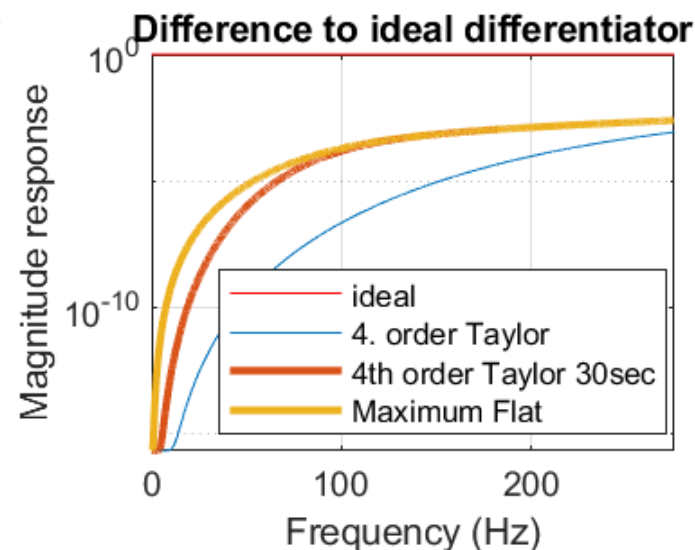
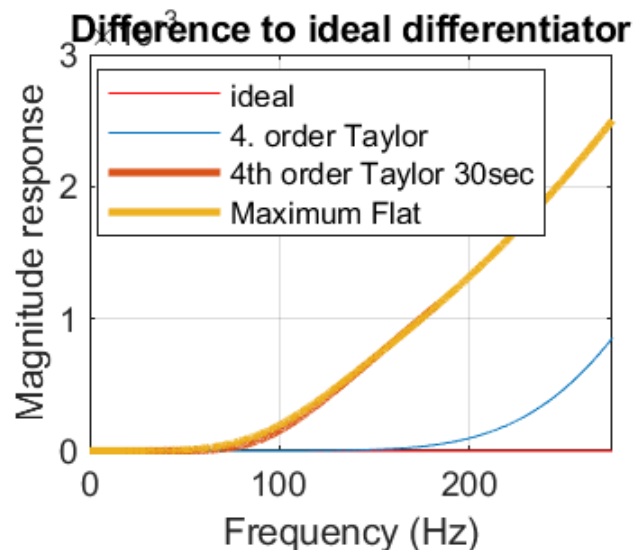
- Kinematic orbits from
 - Astronomical Institute, University Bern
 - Institute for Geodesy, Graz
 - Institute for Geodesy, Hannover
 - European Space Agencytotalling to 41 kinematic orbit products from 27 satellites.
- Accelerometer data used for CHAMP, GRACE and GOCE
- Acceleration approach and combination on the normal equation level using variance component estimation
- Background models
 - JPL Ephemeris DE421
 - Solid Earth tides (IERS Conventions)
 - Solid Earth pole tides (IERS Conventions)
 - Ocean tides (FES2014b)
 - Ocean pole tides (IERS Conventions)
 - Atmospheric tides (AOD1B RL06)
 - Relativistic corrections (IERS conventions)
 - AOD1B dealiasing product RL06



A new differentiator



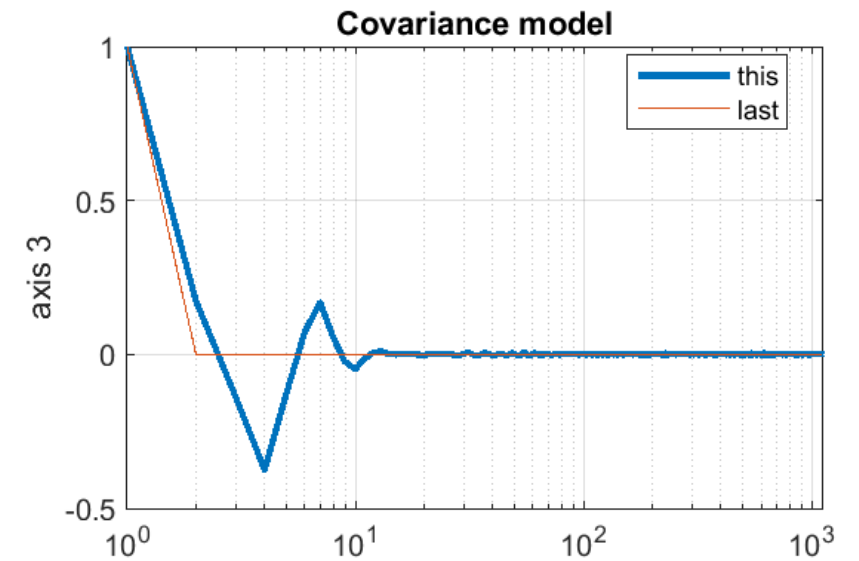
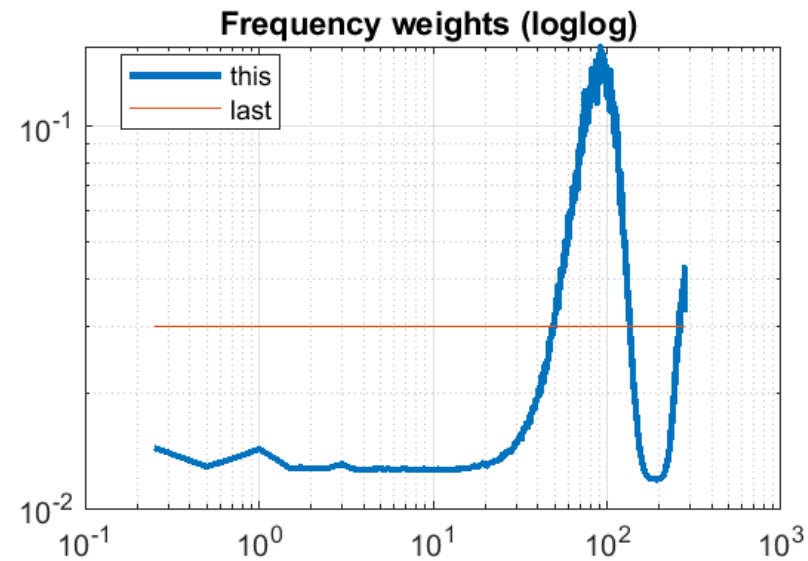
- Differentiation amplifies noise.
- Low-pass filtering properties of differentiators are used to suppress noise
- Test showed that for sampling >30s a time-shifted 30s filter is optimal.
- M. S. Hosseini and K. N. Plataniotis, "Finite differences in forward and inverse imaging problems–maxpol design," (2017).



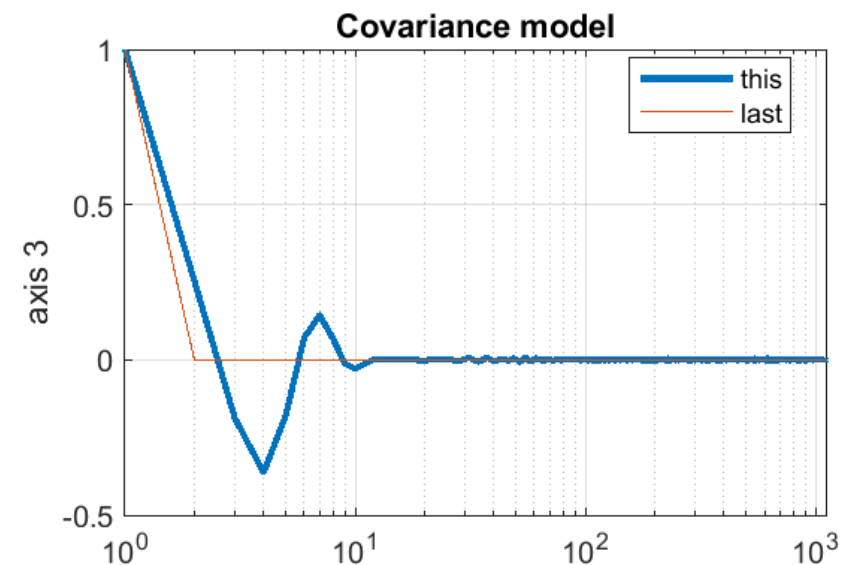
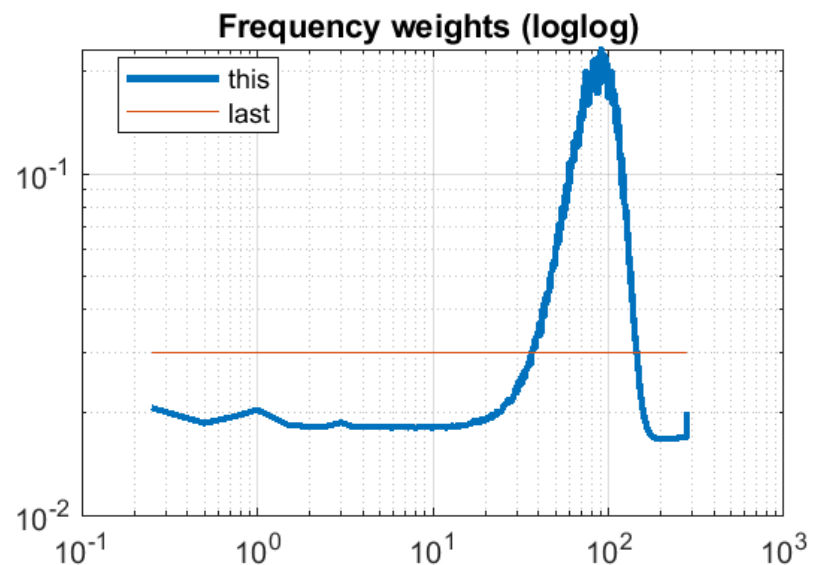


Impact on the estimated noise spectrum: here for GRACE A

30 sec time-shifted



Maximum Flat





Key elements of the data processing



Combination with satellite laser ranging

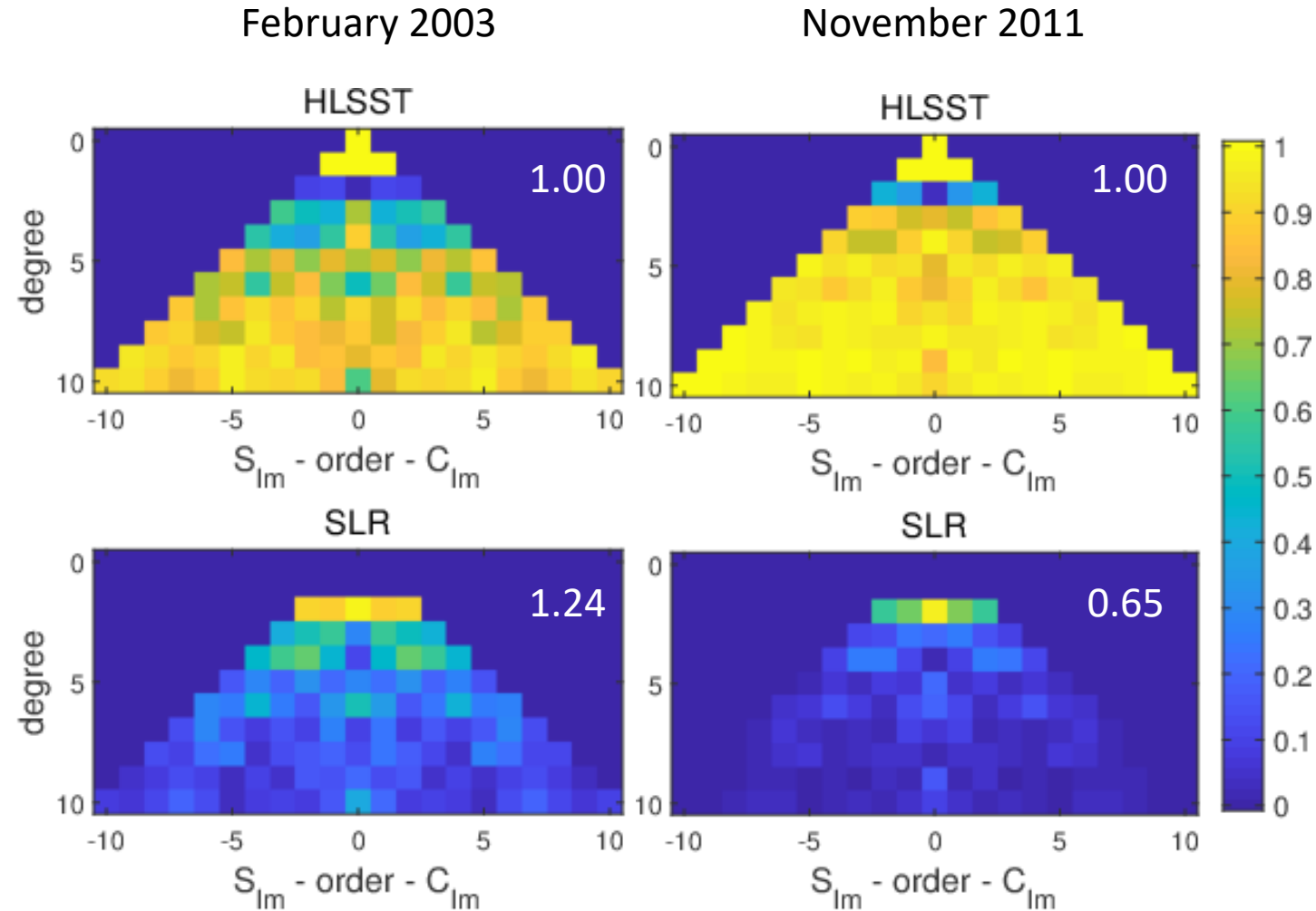
- 9 satellites

Lageos 1	Lageos 2	LARES
Starlette	Stella	Larets
AJISAI	Beacon-C	Blits

- Combined estimation:

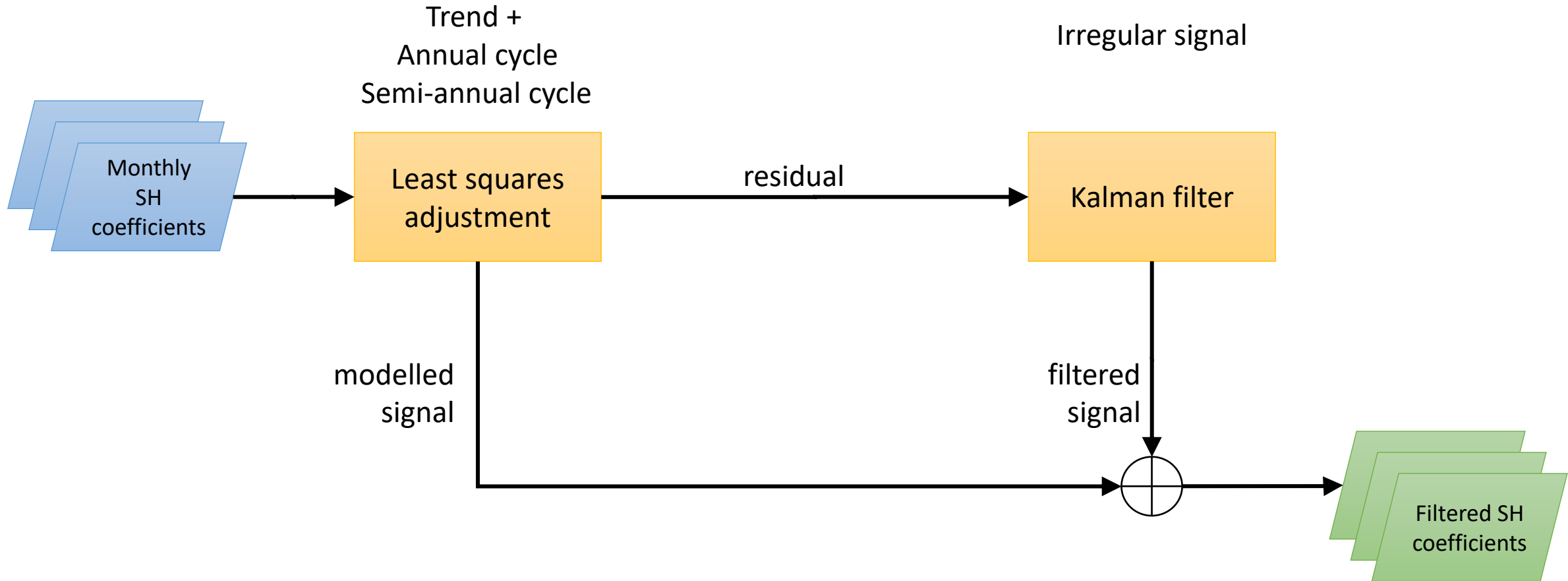
- gravity parameters till degree 10,
- station coordinates,
- Earth rotation parameter,
- geocenter,
- range biases

- Combination at the normal equation level using variance component estimation





Temporal filtering



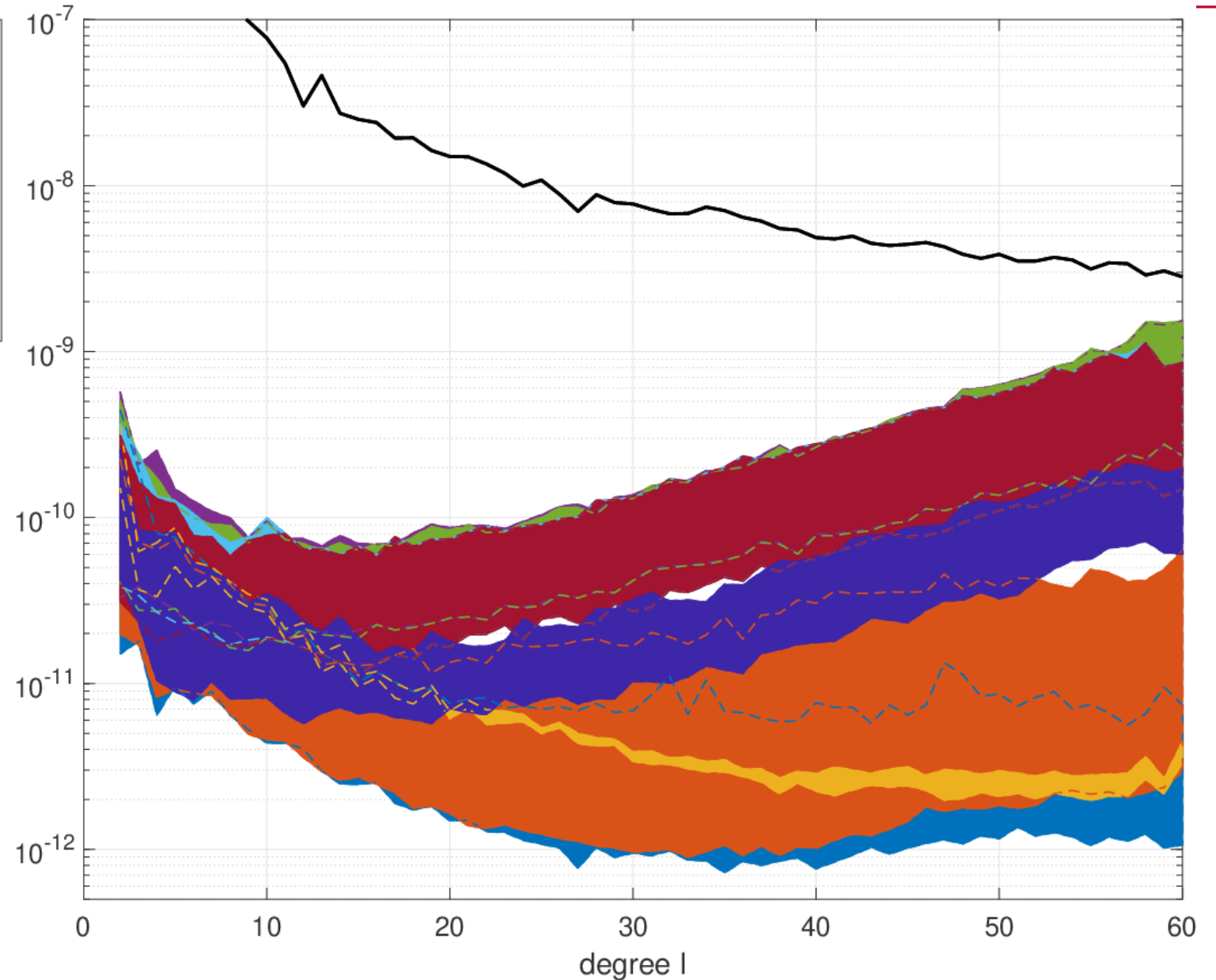
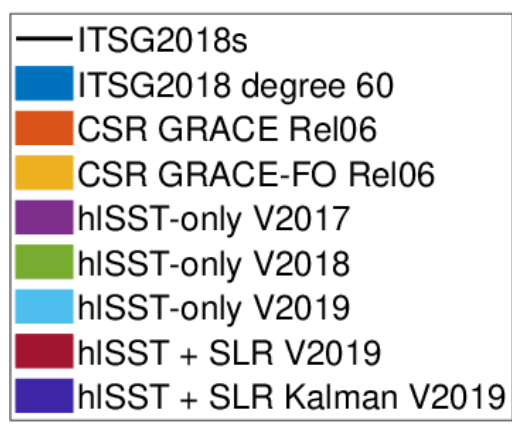
Kalman filter:

- continuous Wiener process acceleration (CWPA) model
- accelerations as white noise model



Difference degree RMS w.r.t. GOCO05s

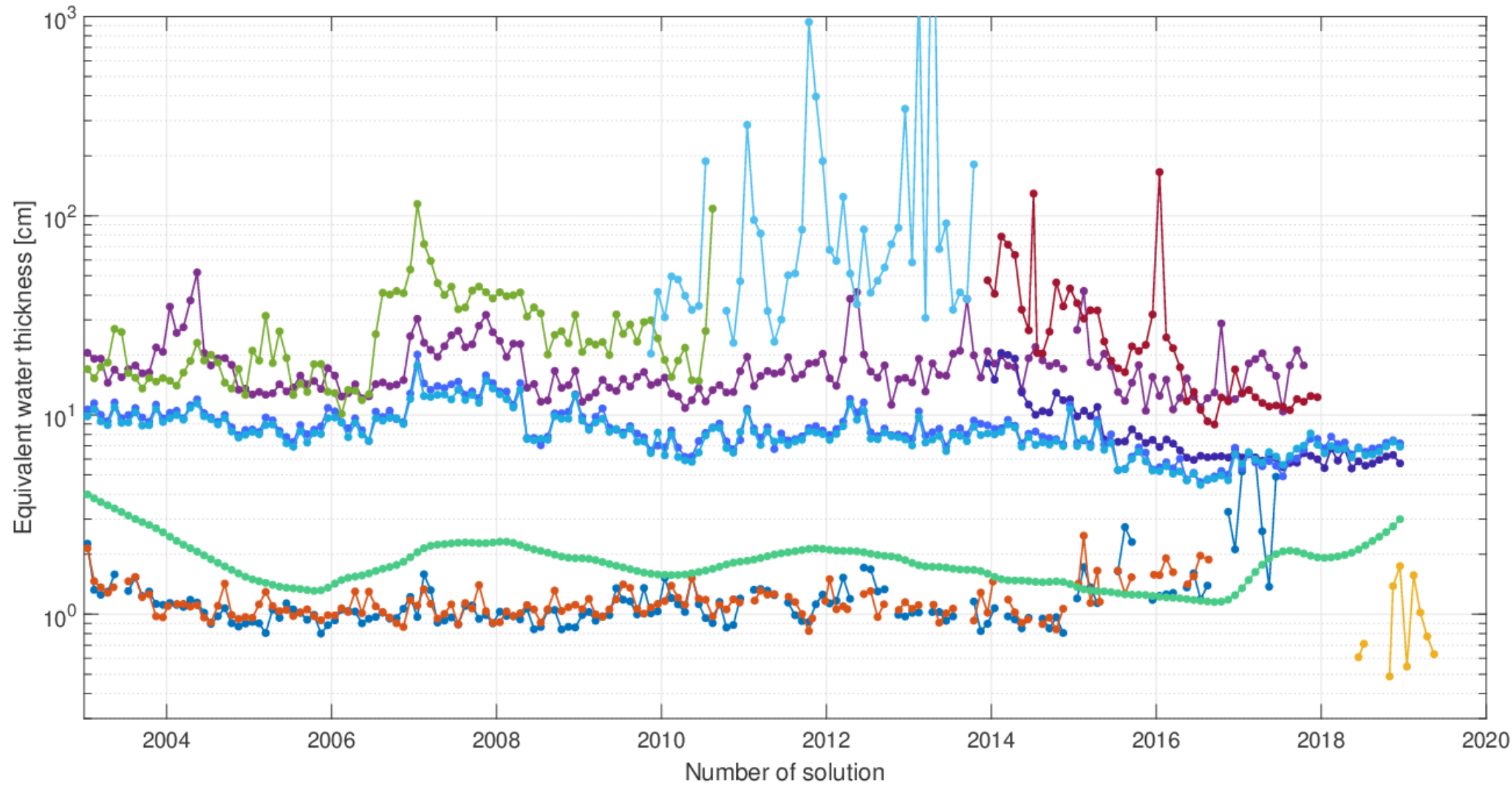
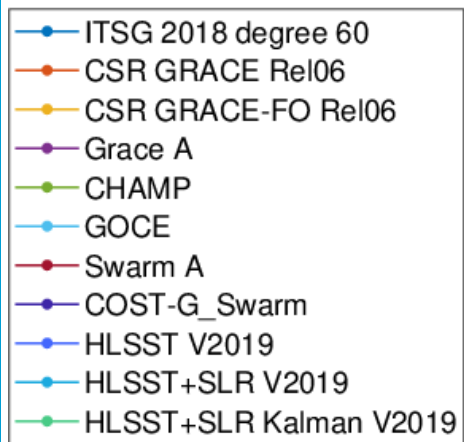
error model
VCE error model
new VCE error model
Temporal filtering





Spatial RMS over ocean areas

Gaussian filter 750 km





Temporal signal evaluation

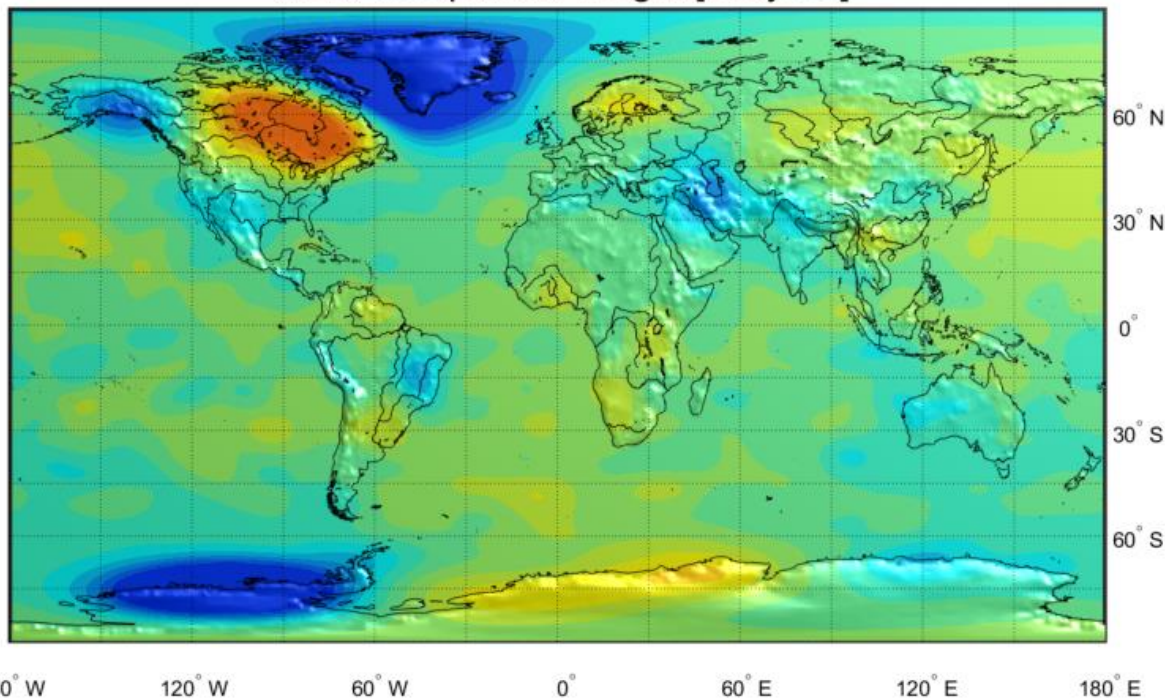


Trend

Gaussian filter 750 km

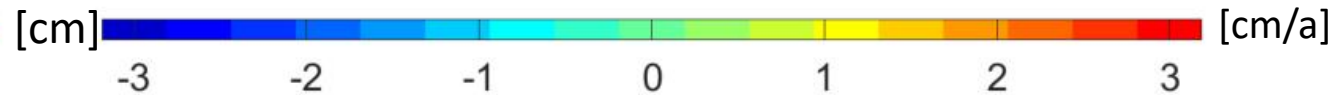
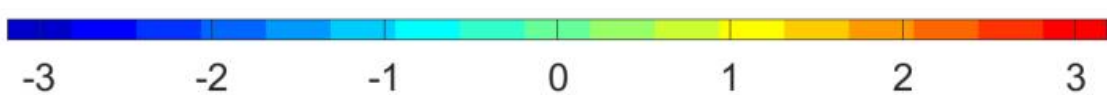
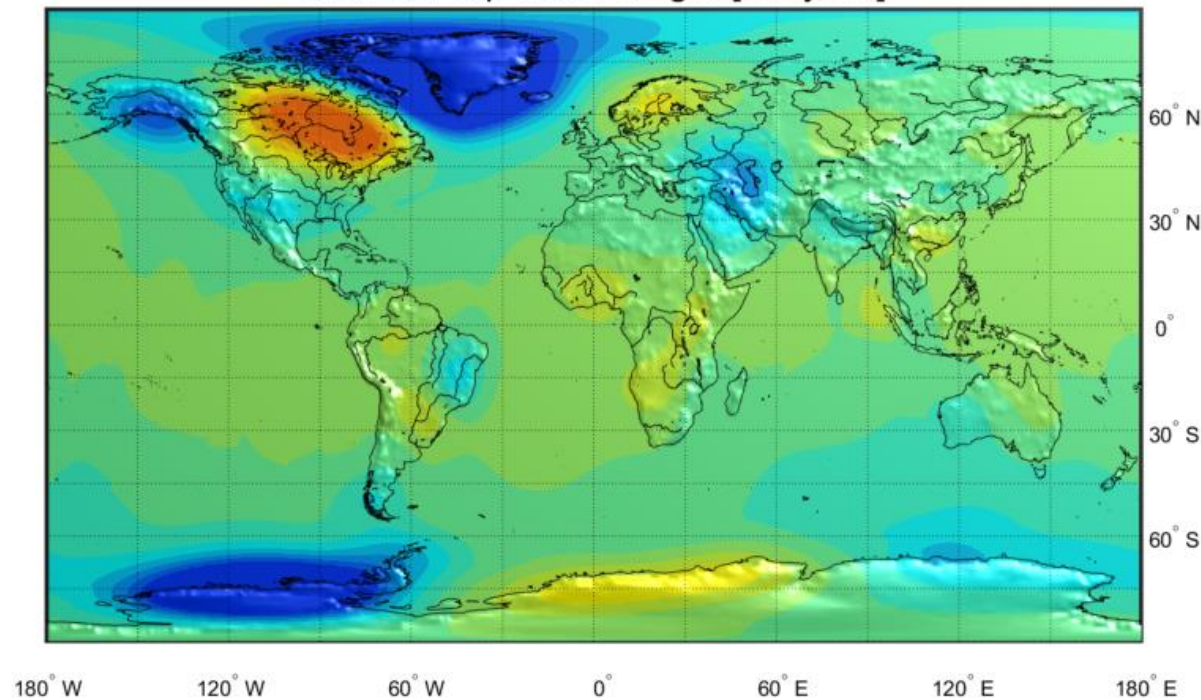
hISST+SLR Kalman 2019

Trend in eq. water height [cm/year]



GRACE CSR Rel06

Trend in eq. water height [cm/year]



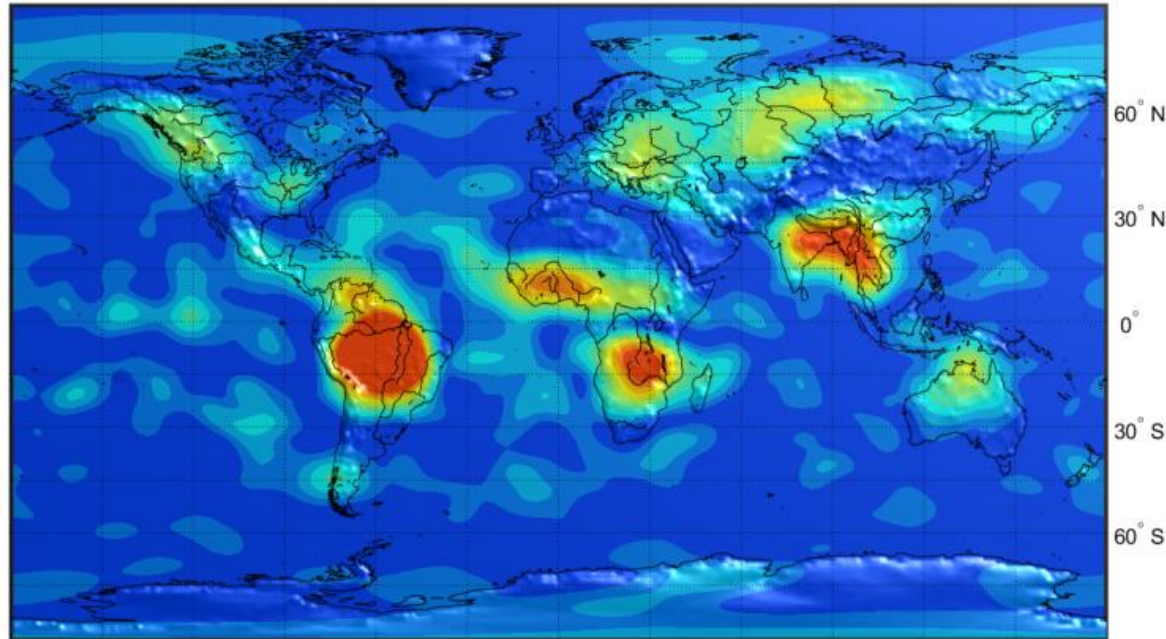


Annual signal amplitude

Gaussian filter 750 km

hISST+SLR Kalman 2019

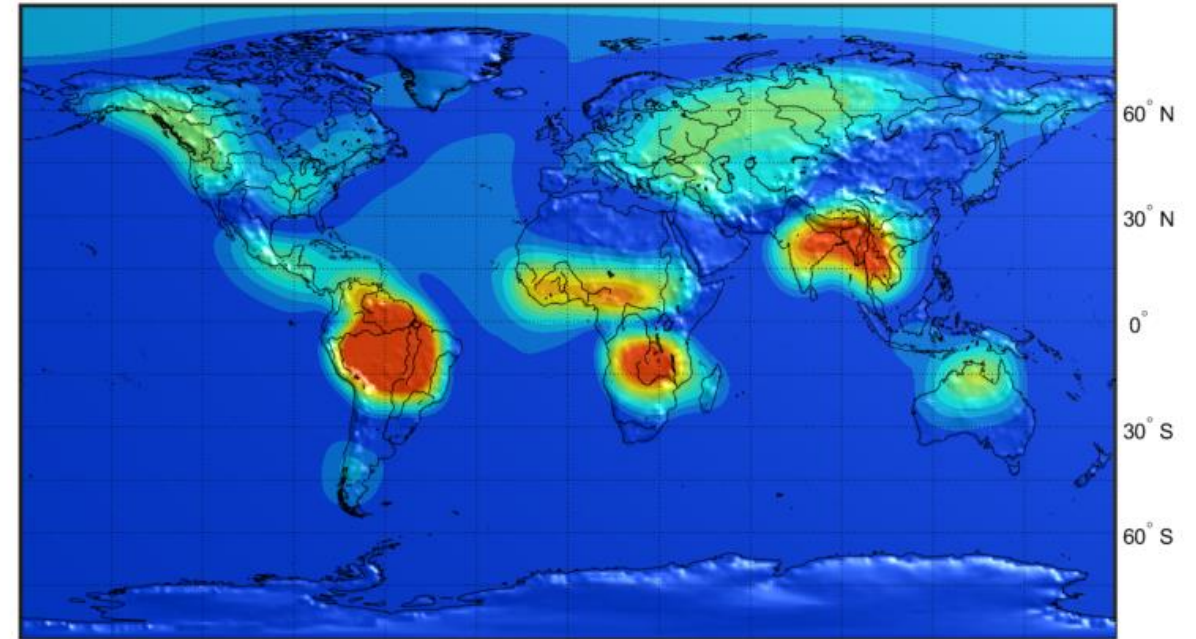
Mean annual amplitude in eq. water height [cm]



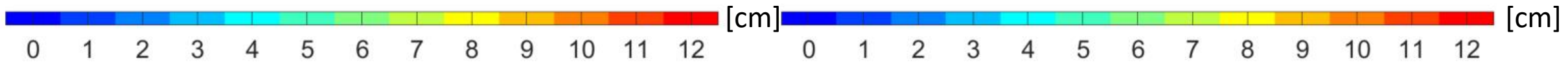
180° W 120° W 60° W 0° 60° E 120° E 180° E

GRACE CSR Rel06

Mean annual amplitude in eq. water height [cm]



180° W 120° W 60° W 0° 60° E 120° E 180° E



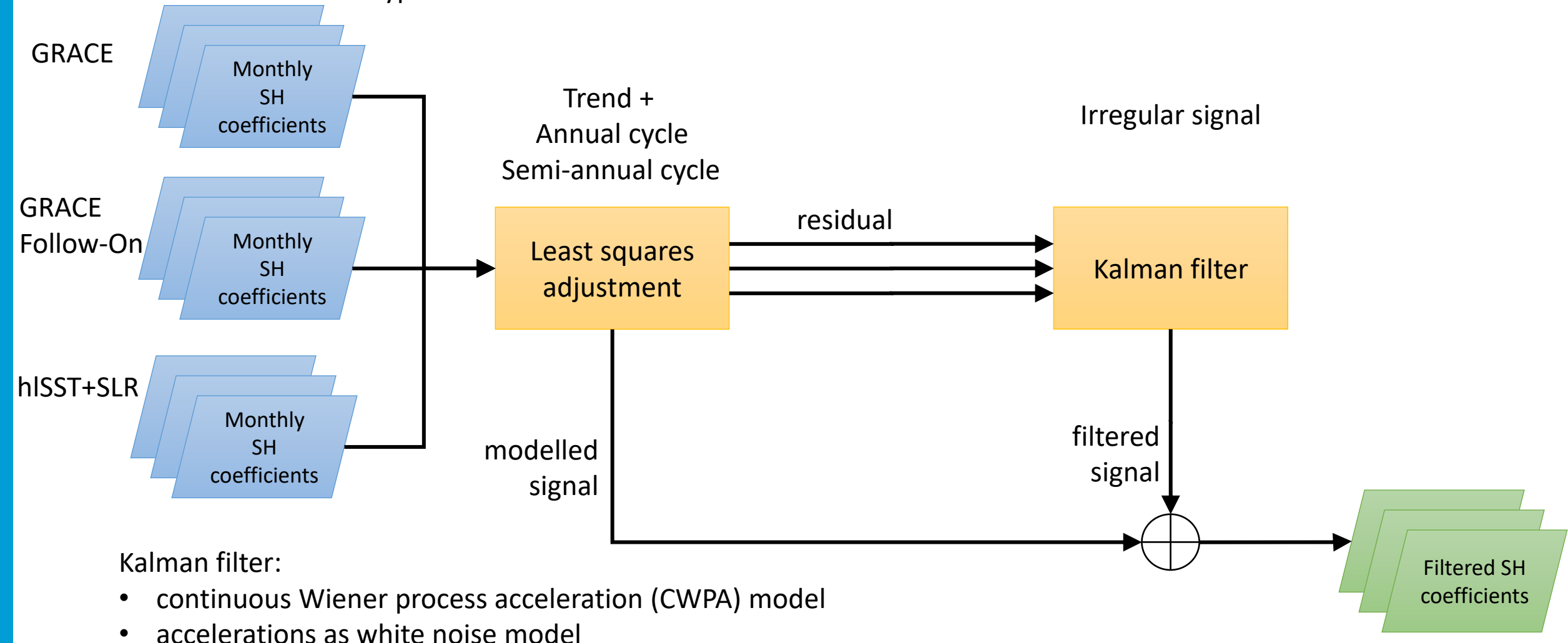


Bridging the gap



Filtering + Combination

Hypothesis: combine various data sets within the same Kalman filter environment

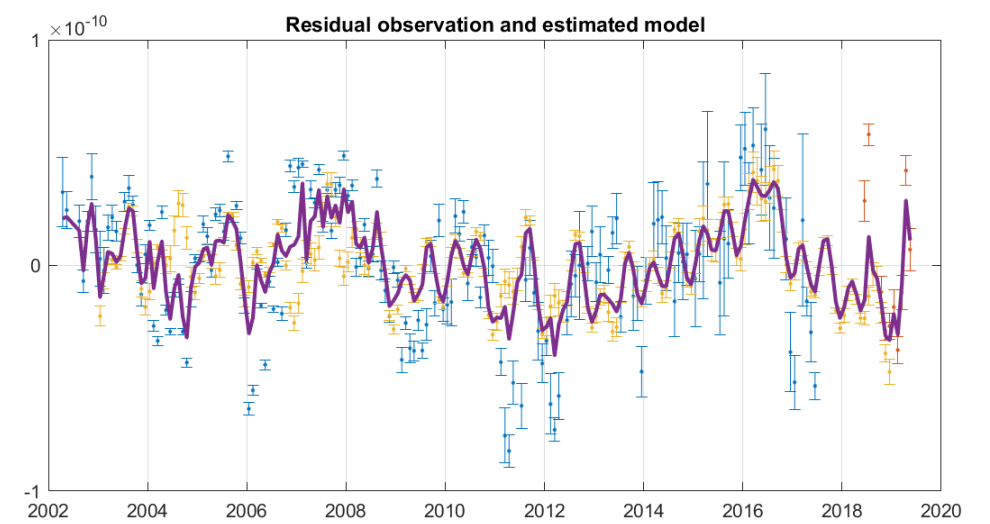
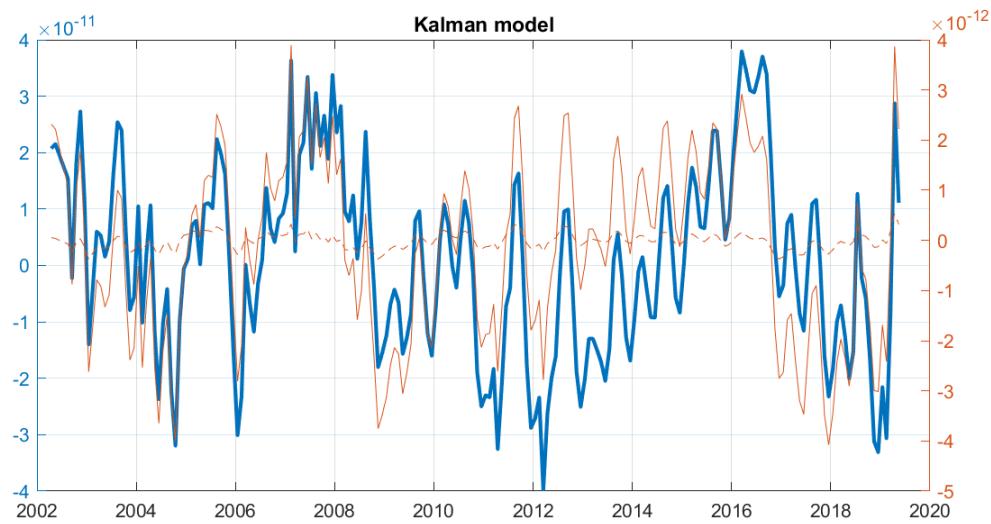
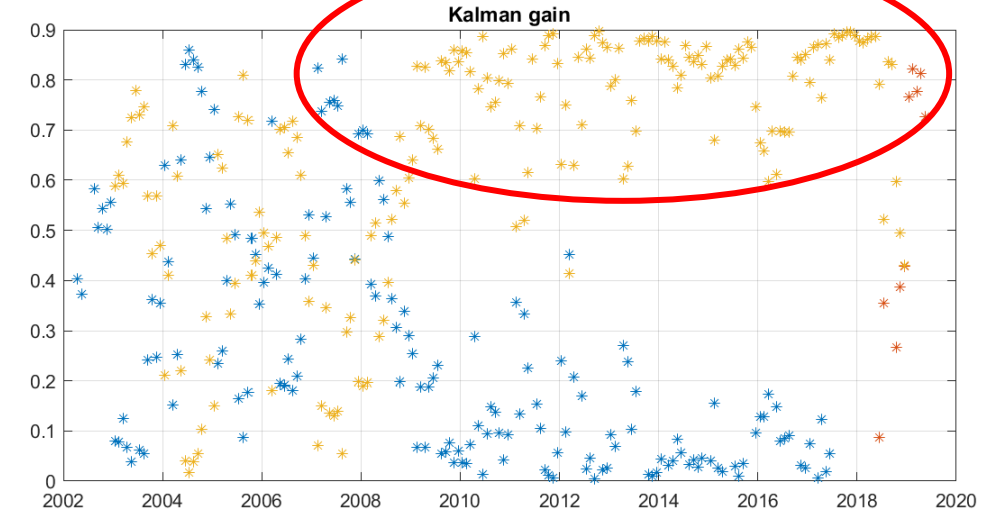
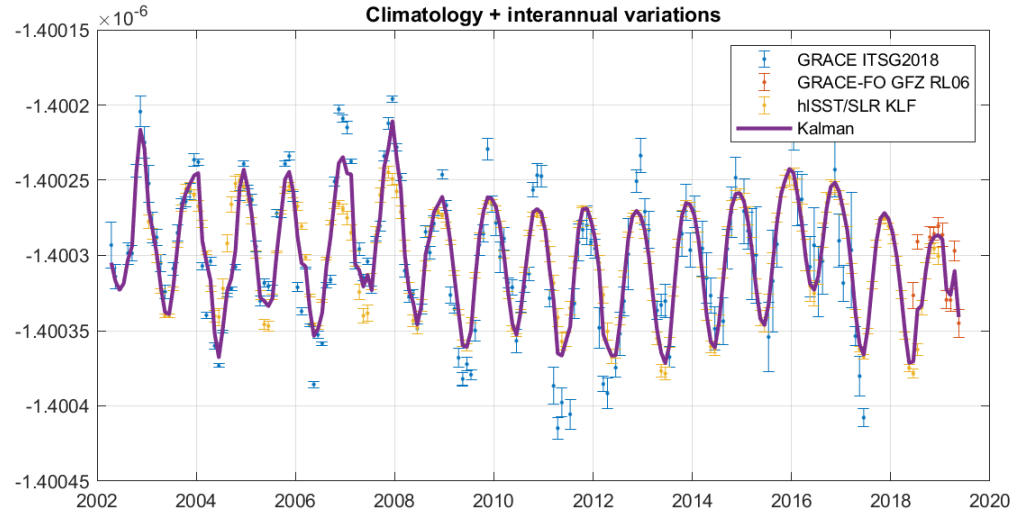




Coefficient-wise combination S_{22}

Coefficient $S_{2,2}$

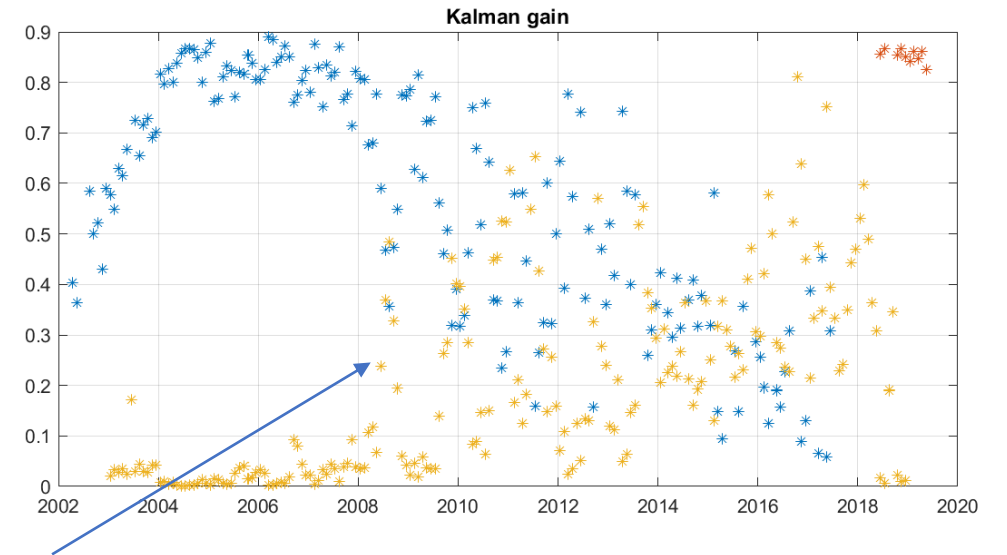
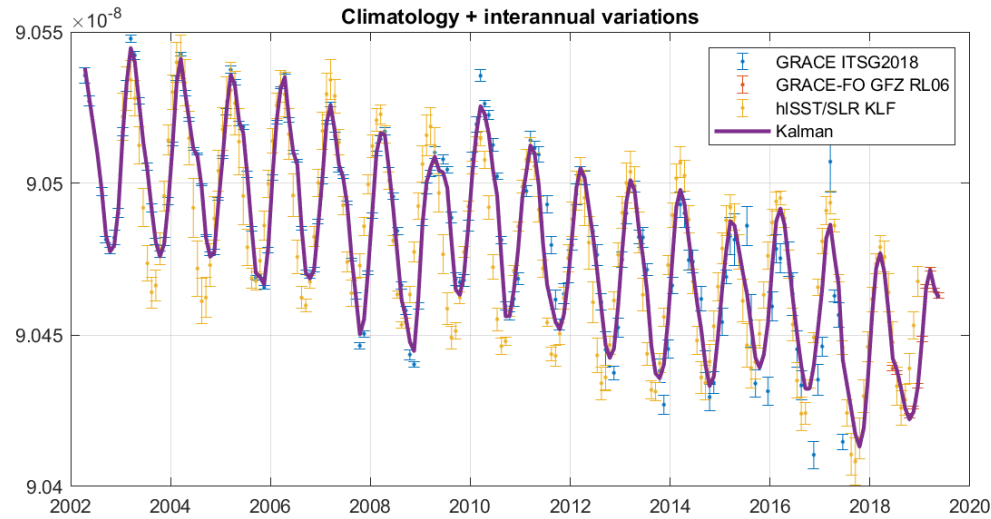
Strong weight on hISST+SLR solution due to low variability



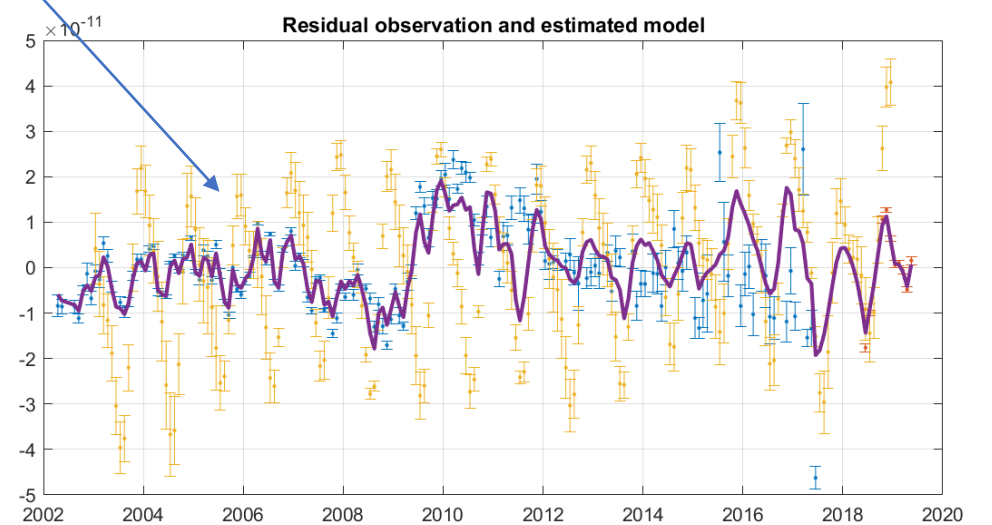
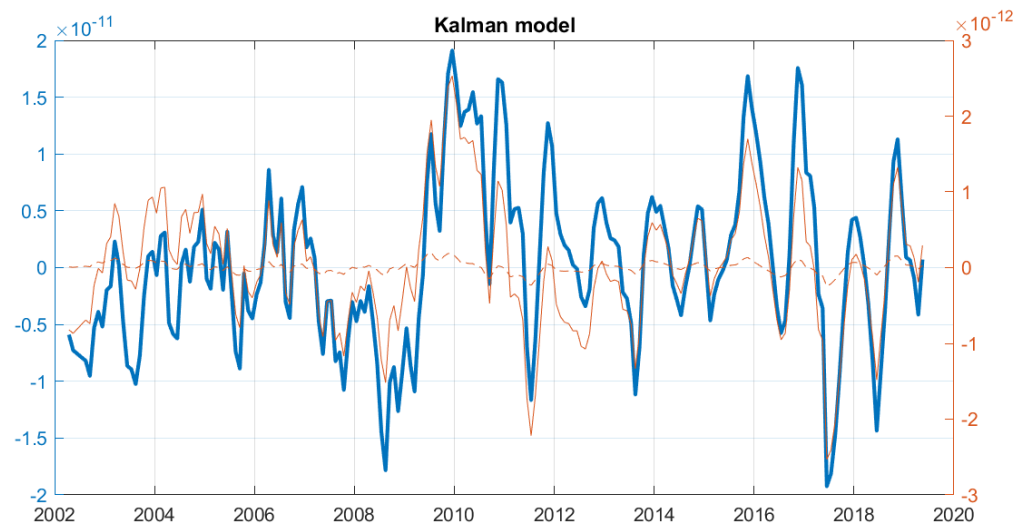


Coefficient-wise combination C_{70}

Coefficient $C_{7,0}$



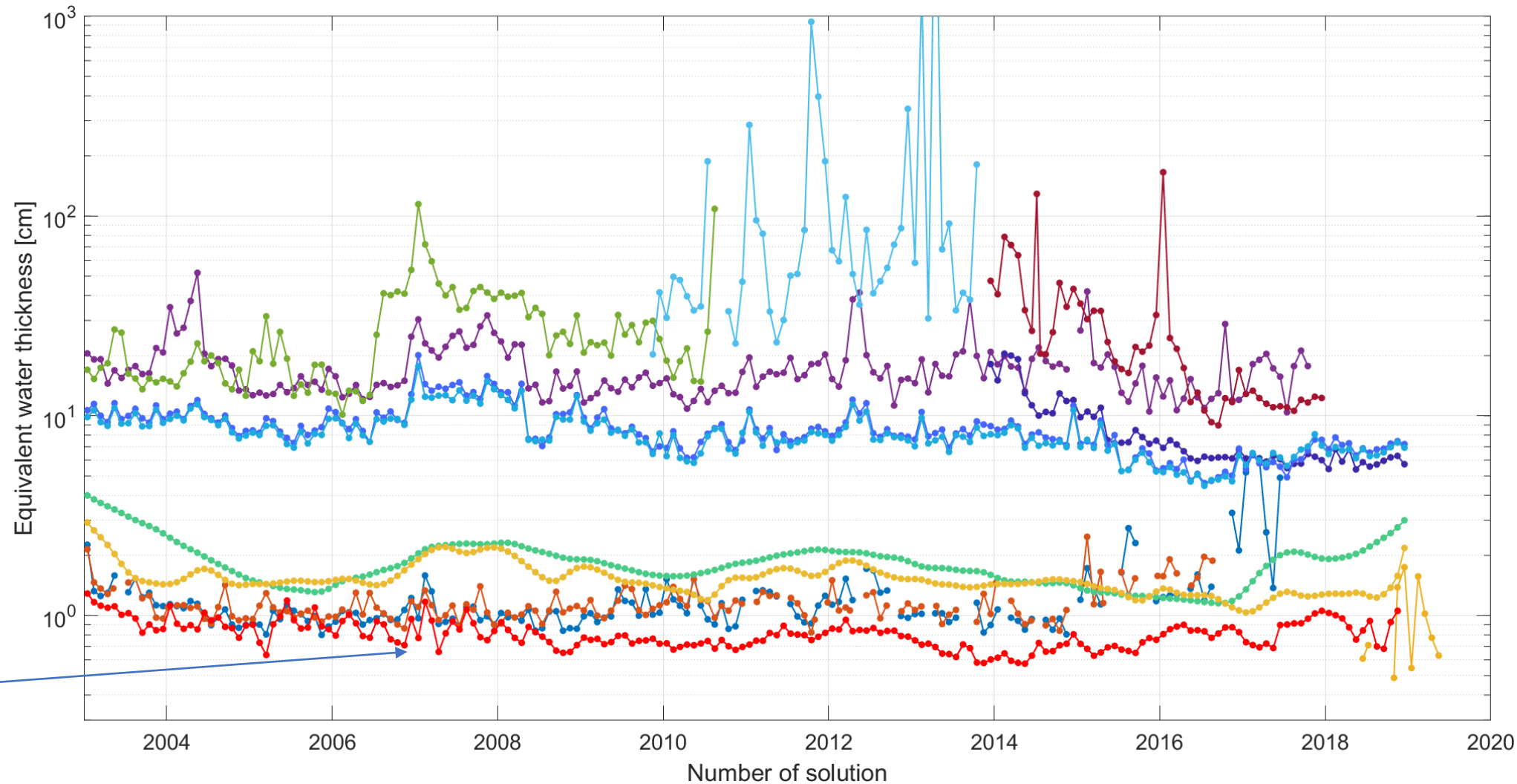
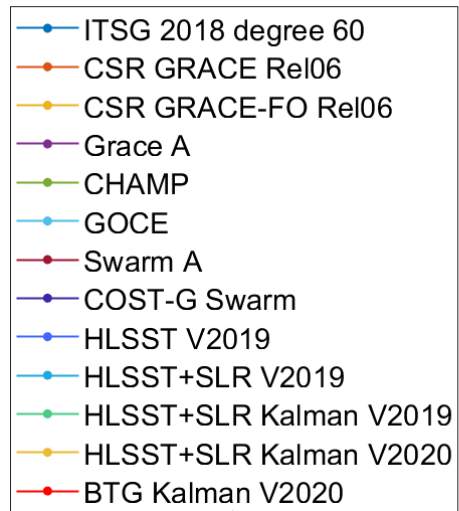
Introduction of systematic errors in the hISST+SLR solution





Spatial RMS over ocean areas

Gaussian filter 750 km



Combined solution is oversmoothed (loss of signal) due to Kalman filter properties (=low-pass filter)



Conclusion



Conclusions

- Mutual benefit by combining HLSST and SLR:
 - SLR improves (dominates) the degree-2 coefficients
 - HLSST provides the higher spatial resolution.
- HLSST + SLR solutions may be best suited for detecting inter-annual and annual variations.
- Short-term variations are not observable due to the limited spatial resolution and the higher noise level of the solutions.
- Combination of GRACE, GRACE Follow-On and hLSST+SLR in the Kalman-filter environment is inferior in periods where GRACE and GRACE Follow-On data is available caused by an oversmoothing due to the Kalman-Filter properties.



Logo 1

