



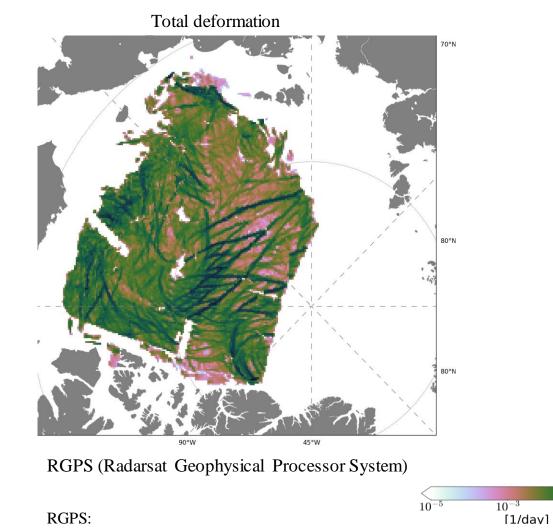
Comparing Arctic Sea Ice Model Simulations to Satellite observations by Multiscale Directional Analysis of Linear Kinematic Features

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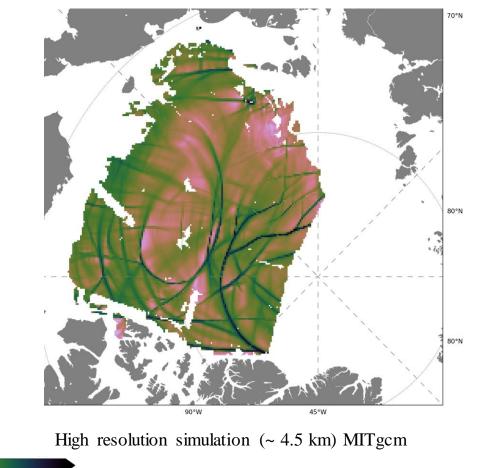
EGU 2020

Objective

Meaningful comparison of satellite observations and high-resolution model simulations



Total deformation



https://asf.alaska.edu/data-sets/derived-data-sets/seaice-measures/sea-ice-measures-data-products/

 10^{-1}

1- Linear Kinematic Features (LKF)

We define LKF as a one-dimensional curve in a two dimensional sea ice deformation field.

2- Multiscale Directional Analysis (MDA)

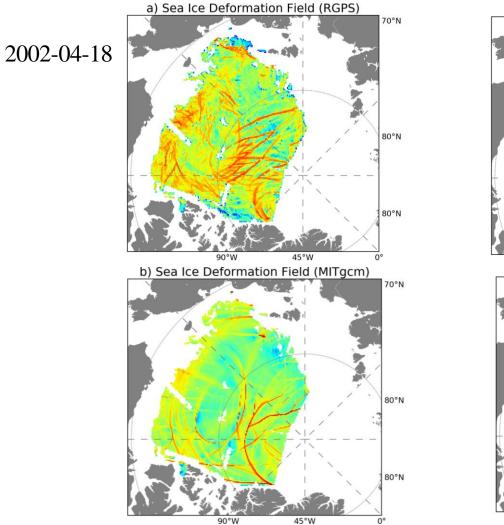
2.1. Methodology

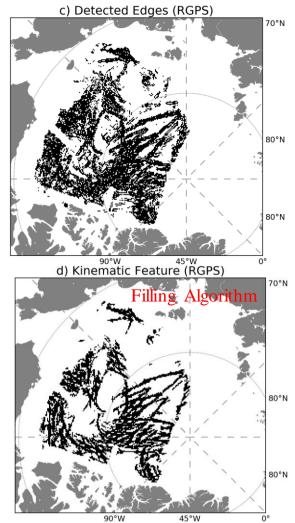
- a) Detecting LKF Edge Detecting and Image Separation (EDIS)
- b) Estimation of main orientation
- c) Feature classification
- d) Estimation of intersection angles
- e) Distance and similarity measures
- 3- Application of the MDA

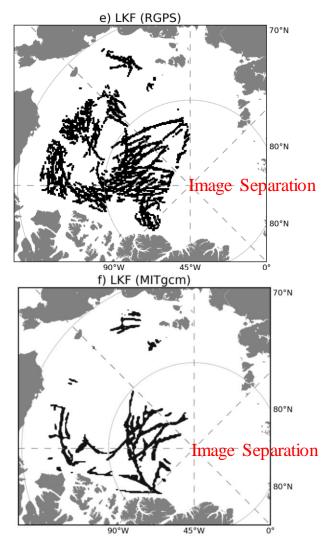
3.1. MDA of high-resolution sea ice deformation

a) EDIS

- Edge Detection using a two dimensional Marr-Hildreth Operator (MHO)
- Filling algorithm using detected edges to find kinematic features
- Image Separation curve-like features are separated from point-like features







4

km

a) Binary Feature and Centrline Spatial filter at P1₁₆₀₀ **b)** Estimation of main orientation <u>E</u> 1200 Measuring the angle of the centerlines with horizontal direction 800 1200 1600 km b) Histogran Suf=3, Suf=1, P1 S_{lf}=6, S_{wf}=1, P1 Slf=9, Swf=3, P1 Thinning or centerline tracing of LKFs • Estimating directional responses – using a set of multiscale directional filters • Histogram Determining the main orientation • Histograms of the directional response at P1 and P2 60 90 120 Orientation (Degree) 30 150 c) LKF Orientation ($S_{lf}=3, S_{wf}=1$) Main local orientation 1600 E 1200 800 800 1200 1600

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c) Feature classification

I. All points on the centerline with more than one local maximum in the directional response

Other points

II. Contiguous patches of the extended set of Intersection-points

III. Search for the points on the graph of centerline that are at most five grid points away from the centroid of each intersection-point cluster

IV. In each cluster, find the closest point to the actual centroid of the cluster

V. Repeat III & IV steps



Intersection-point clusters & an arbitrary point in each cluster as initial centroid

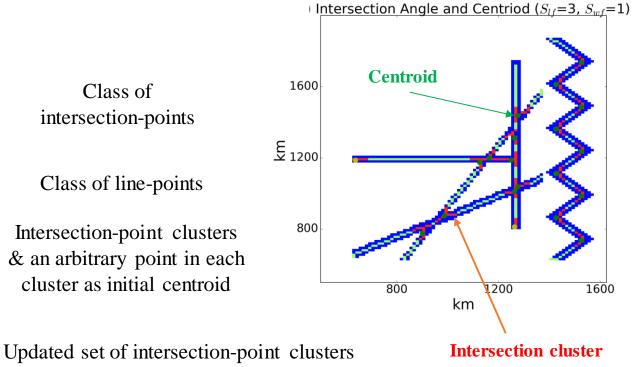
Class of

intersection-points

Class of line-points

Updated centroid

Until centroids do not change



d) Estimation of intersection angles

The difference between the main orientation of the points that are furthest away from each centroid but still within the same intersection-point cluster

e) Distance and similarity measures

Comparison of frequency distributions of orientations and intersections angles of LKFs.

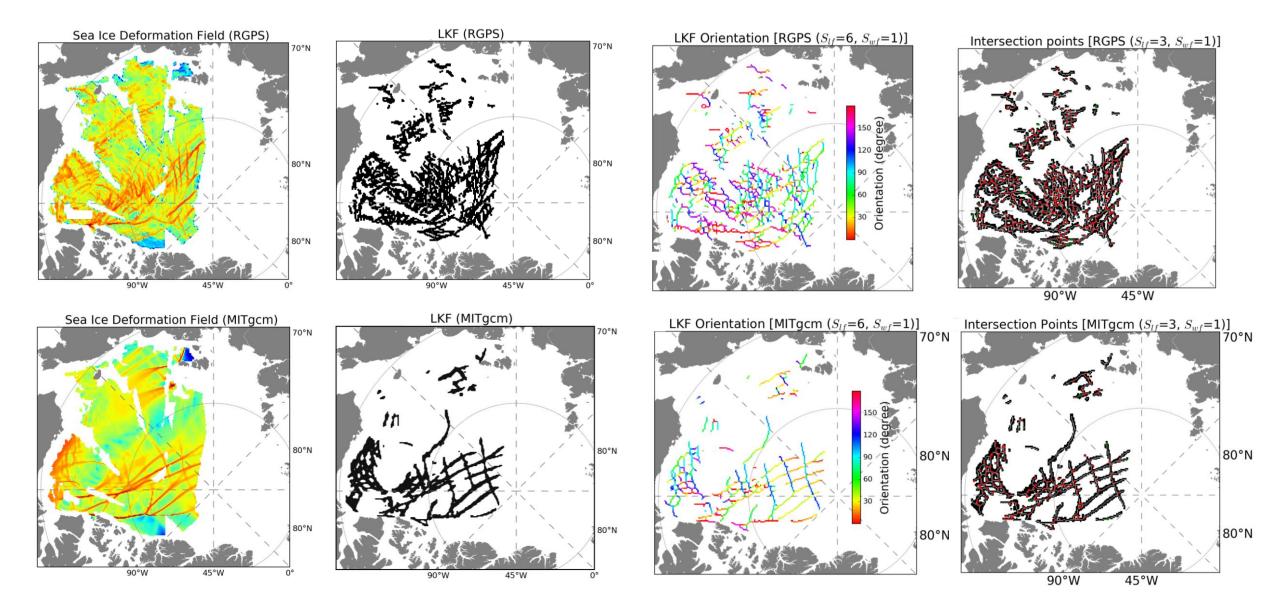
We use the Earth Mover's Distance (EMD).

Low EMD High similarities

We compare EMD to a Benchmark EMD.

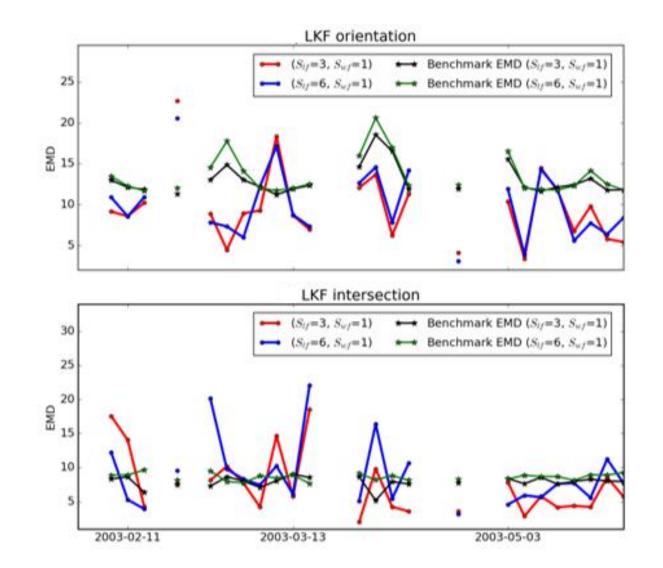
We compute EMD benchmark values for each date by averaging the EMD of the single RGPS scene relative to all individual MITgcm scenes.

MDA of high-resolution sea ice deformation



2003-03-13

MDA of high-resolution sea ice deformation



Summary and Conclusions

1 - We introduce a Multi-Directional Analysis (MDA) as a new method for evaluating the spatial patterns of linear kinematic features (LKF).

2- A MDA-based comparison will complement established sea-ice forecast verification methods by adding local and scale-dependent spatial information of geomorphological patterns of LKFs.

3- MDA quantifies properties such as orientation for each LKF-classified grid point individually instead of assigning one value for a segment of LKF.

4- The possibility to use different spatial filters enables us to assess sea-ice dynamics on different spatial scales while properly accounting for the finite width of LKFs.

5- MDA is designed to work reliably, even in places with complex patterns of LKFs, and avoids the cost of feature segmentation and semantic post-processing.

Submitted manuscript: http://mitgcm.org/~mlosch/mohammadi-etal_mda.pdf