

# New Algorithm and Processor for Obtaining Maritime Information from Sentinel-1 Radar Imagery for Near Real Time Services

Andrey **Pleskachevsky**, Sven **Jacobsen**, Björn **Tings**  
Egbert **Schwarz**, Detmar **Krause**, Holger **Daedelow**

DLR, Maritime Safety and Security Lab Bremen

DLR, National Ground Segment, Neustrelitz

- **Examples and concept**
- **Background**
- **Model Functions Tuning**
- **NRT implementation**
- **Outlook**

A large, curved satellite image of the Earth's surface occupies the right half of the slide. It shows a view of the Arctic region, with a large white ice mass in the center and surrounding green landmasses and blue oceans. The image is taken from a high angle, showing the curvature of the planet.

Knowledge for Tomorrow

## Short description

The **new empirical algorithm** allows estimation of **total integrated sea state parameters** and **also partial integrated parameters** including

- significant wave height  $H_s$ ,
- first moment wave period  $T_{m1}$ ,
- second moment period  $T_{m2}$ ,
- mean period  $T_m$
- like swell (dominant and secondary) and windsea wave heights  $S_{w1}$ ,  $S_{w2}$ ,  $S_{ww}$
- windsea period  $T_w$

The algorithm allows processing of different S1 Synthetic Aperture Radar (SAR) modes with different resolution into **sea state fields**:

- For **Sentinel-1 S1 Wave Mode (WV)**, acquires multiple vignettes with an extent of  $\sim 20\text{km} \times 20\text{km}$  and each displaced by 100 km along satellite tracks in open ocean (global) with relatively high spatial resolution of  $\sim 4\text{ m}$  wave height can be estimated with **accuracy of  $\sim 35\text{cm}$** . This is comparable with the accuracy of satellite altimetry and a new achievement for SAR based techniques.
- For **Sentinel-1 Interferometric Wide Swath Mode (IW)** covers area-strips of thousand kilometres of earth and ocean surface in coastal areas with a resolution of  $\sim 20\text{m}$  by sequences of multiple images with an approximate size of  $200\text{km} \times 250\text{km}$  the accuracy of  $\sim 70\text{cm}$
- 

The **algorithm has been integrated into** a prototype processor for Sentinel-1 SAR imagery. The DLR **Ground Station Neustrelitz** applies this prototype **as part of a near real-time demonstrator MSA service**.



# **1. Concept and Examples**

2. Background

3. Model Functions, Tuning

4. NRT implementation

5. Outlook

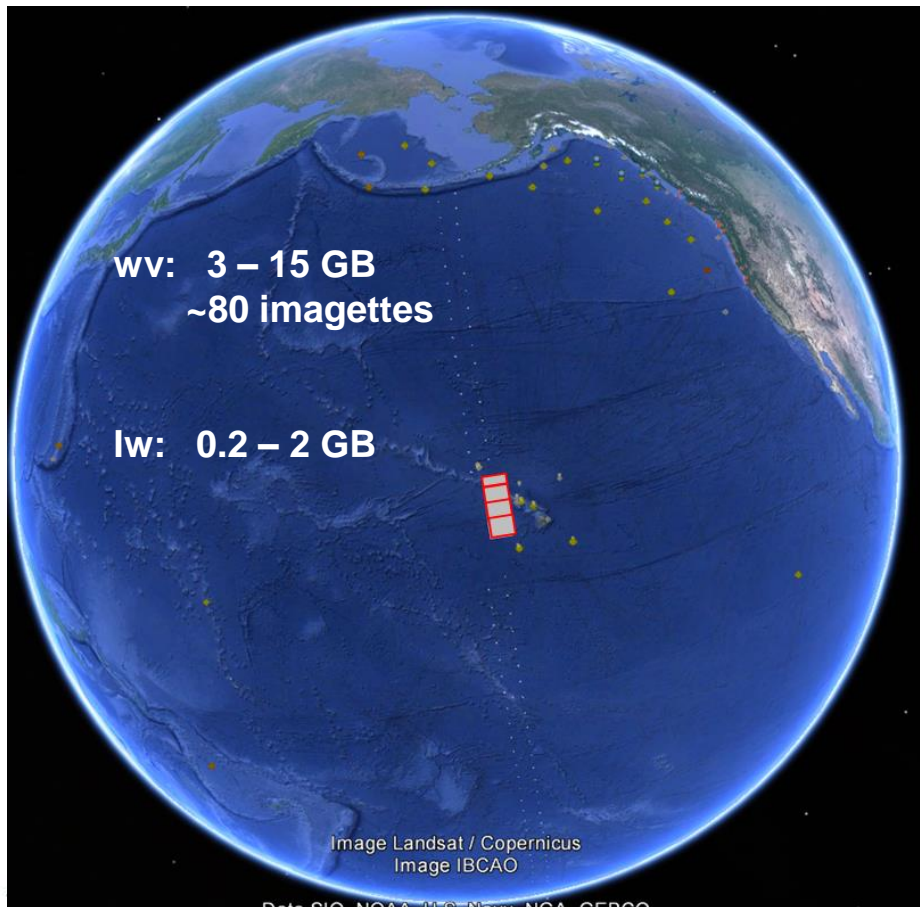




# 1.1. Sentinel 1A, 1B IW und WV Modi

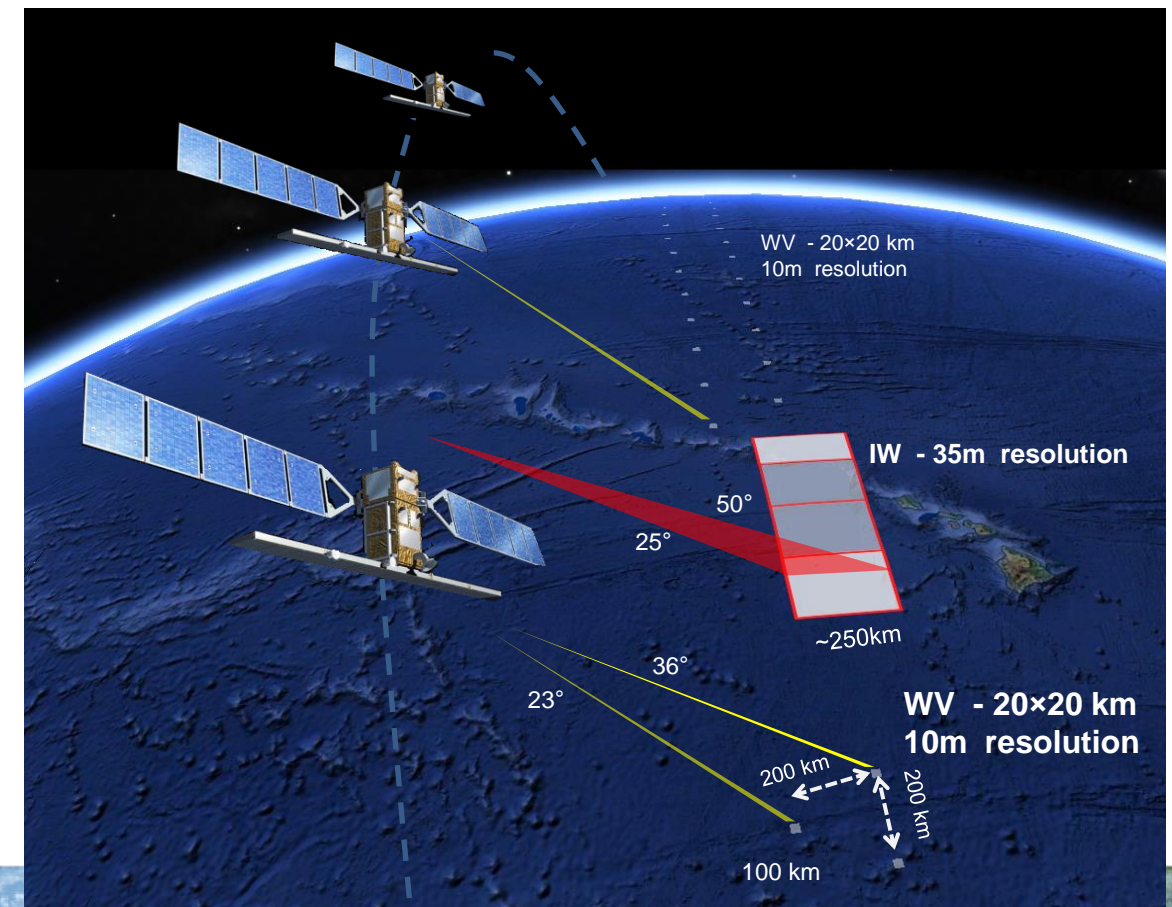
**Sentinel-1A - 2014**  
**Sentinel-1B - 2016**

- ▶ flight 704 km
- ▶ ground speed 6.8 km/s
- ▶ C-Band Radar with wavelength of 5.6 cm



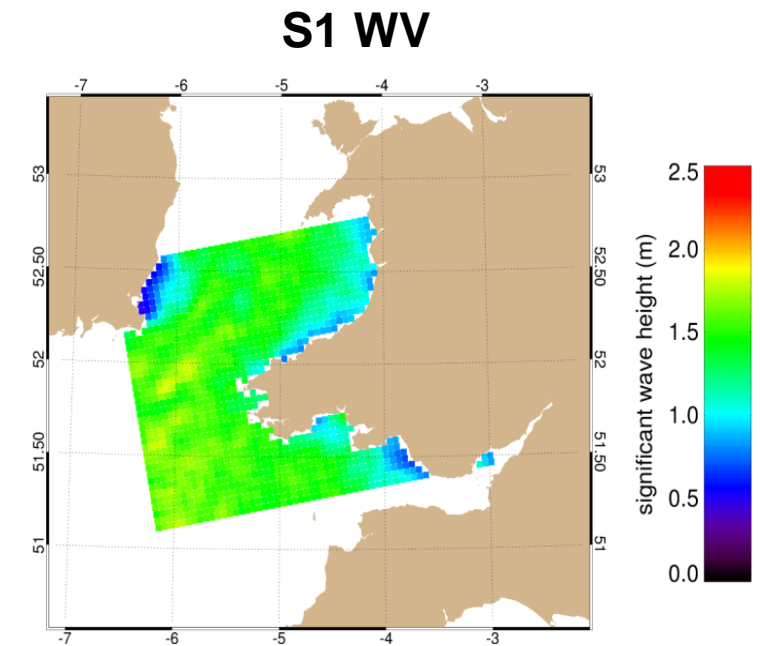
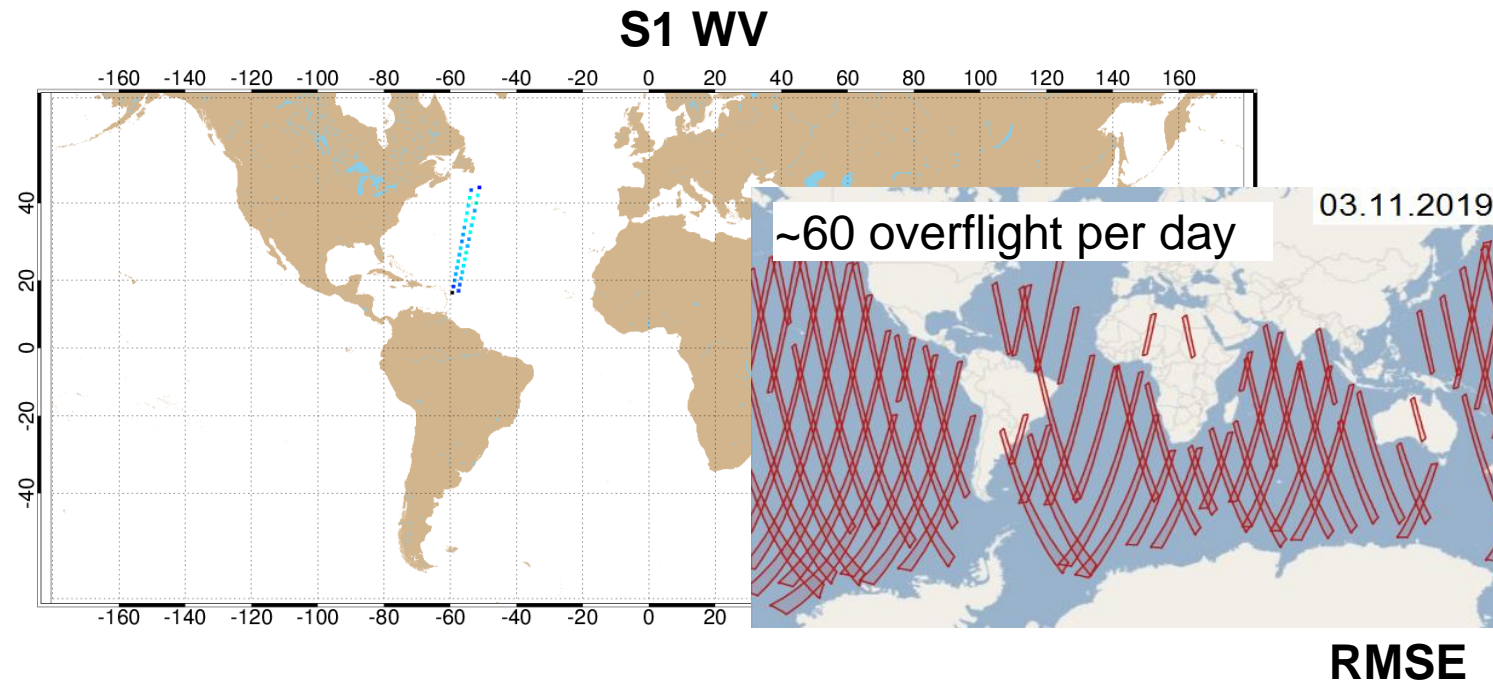
DLR

- ▶ **IW** - Interferometric Wide Swath Mode - **Coastal areas**  
~ 200 km × 250 km, ~ 35m resolution, 10m pixel  
GRDH: level-1 Ground Range Detected High-resolution products
- ▶ **WV** - Wave Mode - **Ocean**  
~ 20 km × 20 km vignette each 100 km, ~ 5m pixel  
SLC: Single Look Complex products



# 1.2. New sea state processor S1 IW and WV

New method allows estimating series of integrated sea state parameters for both S1 WV (tracks) and IW (fields)



	SWH	Tm0	Tm1	Tm2	Sw1	Sw2	Sww	Tw
S1 IW	63cm	1.15 sec	0.95 sec	0.79 sec	0.52 m	0.38 m	0.73 m	0.92 sec
S1 WV	35cm	0.64sec	0.52 sec	0.53 sec	0.42 m	0.35 m	0.41 m	0.65 sec

Total integrated

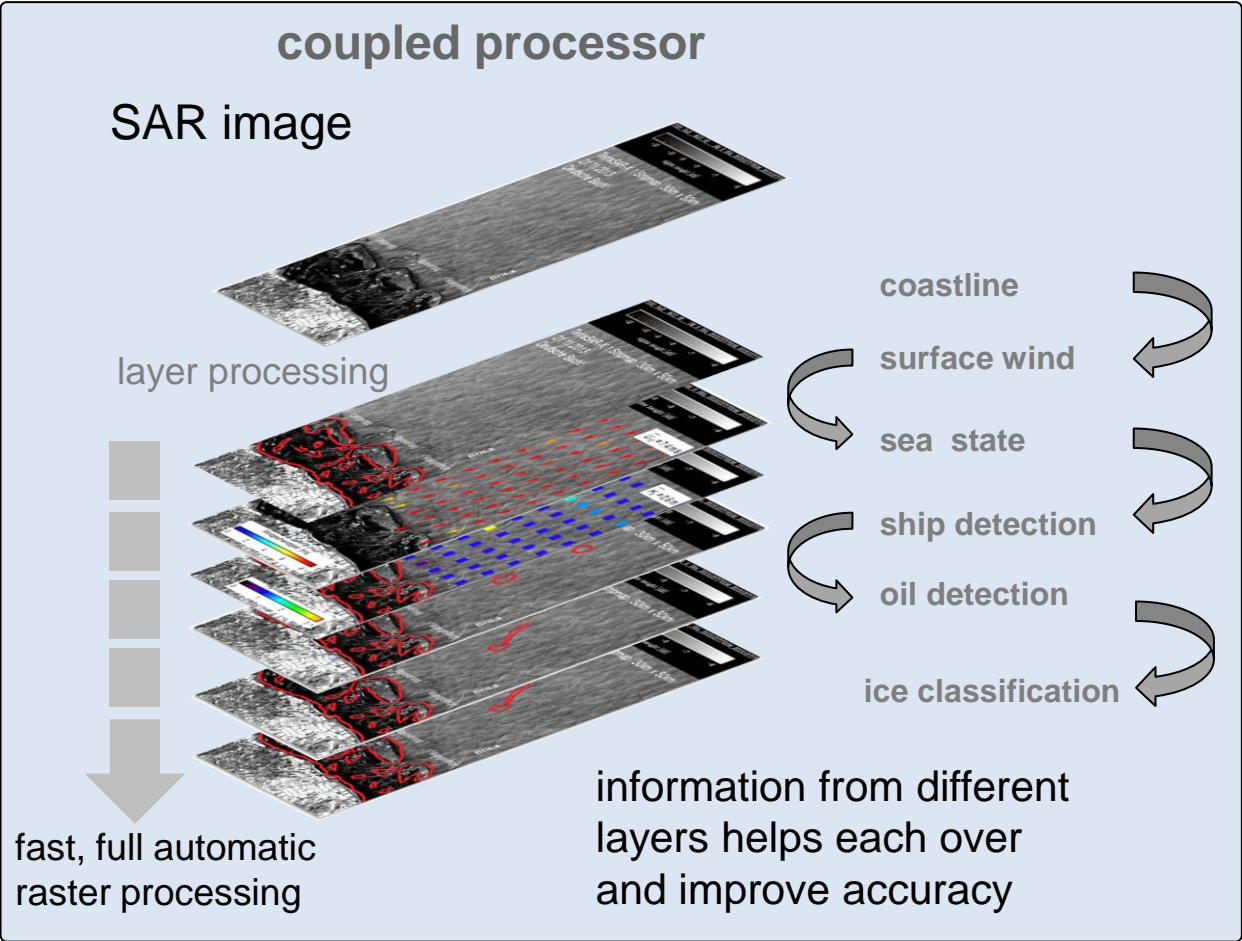
partial integrated



# 1.3. Concept: maritime situation awareness (MSA) for safe navigation

## Integrated Processor for MSA: Near Real Time services(NRT)

DLR Maritime safety and security Lab Bremen  
**algorithms** and **processor** development



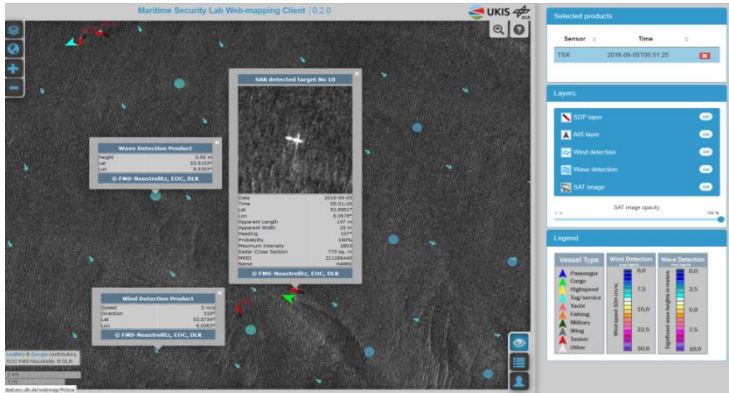
DLR Ground Station Neustrelitz (NZ)  
**NRT chain**



**operationally:**

- sea state
- wind
- ships
- icebergs

NRT products



**FUSION**  
WITH DATA  
FROM OTHER  
SOURCES

- + measurements
- + forecast
- + ship AIS

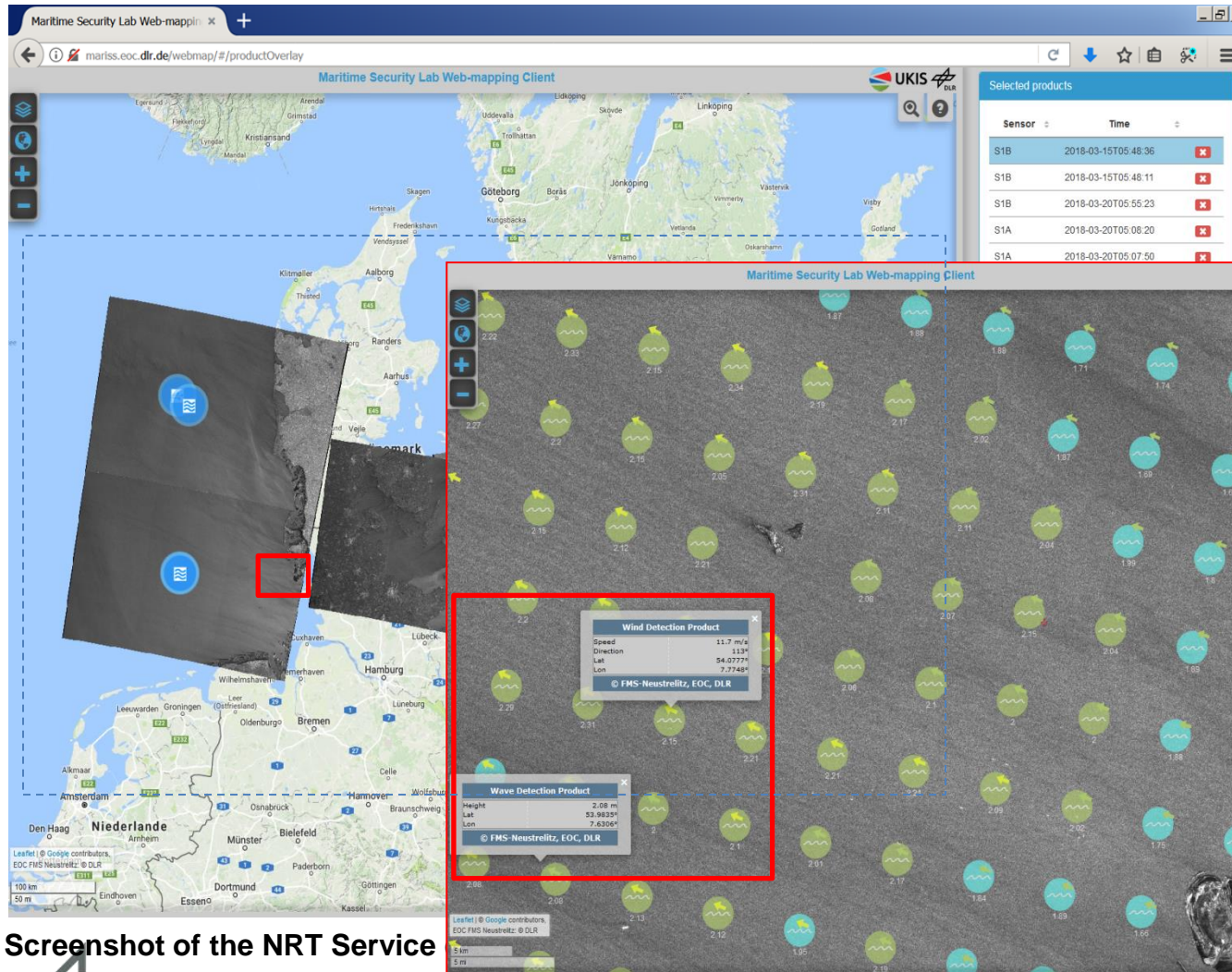
Map client, ftp, E-mail



# 1.4. Sea State Processor for Maritime Situation Awareness

**NRT services: SENTINEL-1 waves, wind, ships**

**Raster: 6 km, Subscenes: 2.5kmx2.5km**



Different product layers available on the GeoServer in NRT and displayed on the Maritime Security Web-mapping Client.



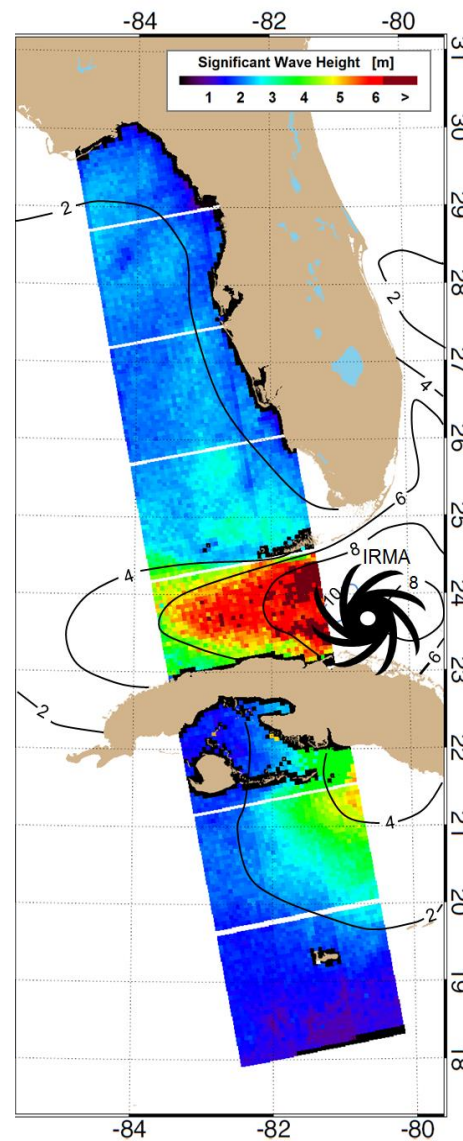
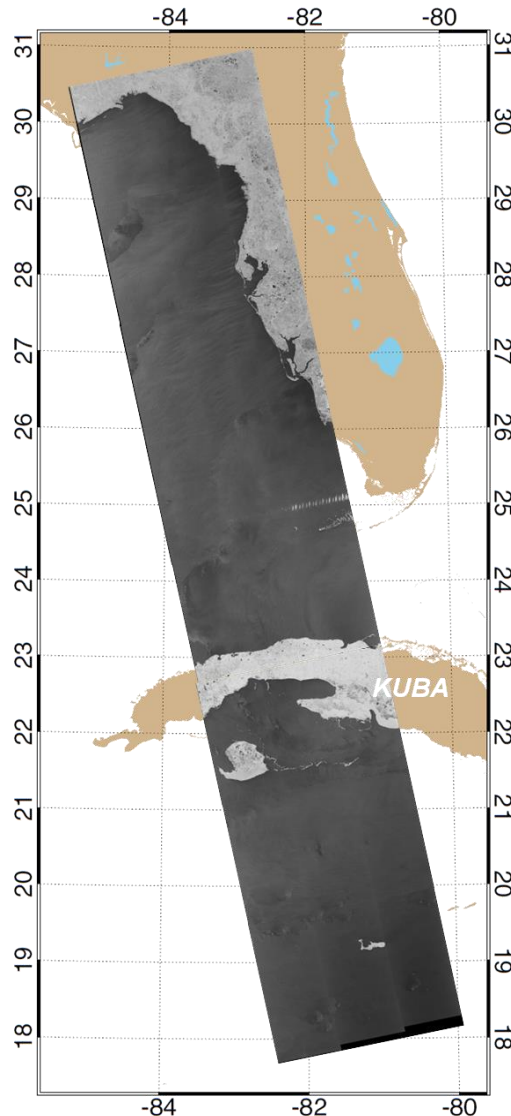
Screenshot of the NRT Service



# 1.5. Sea State Processor Example Hurricane Irma – ESA news

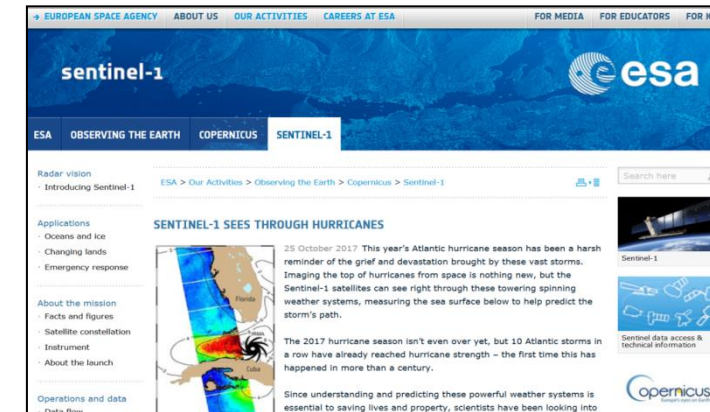
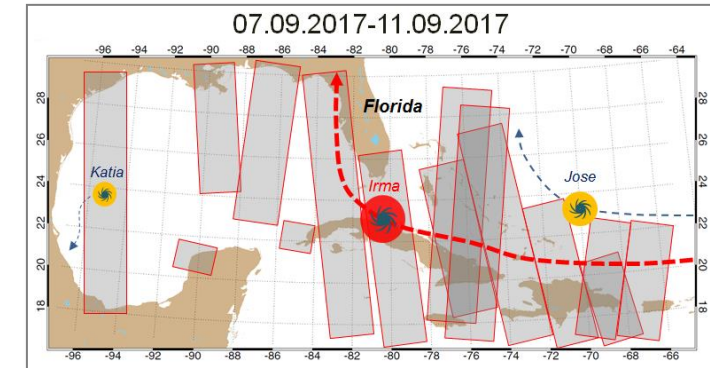
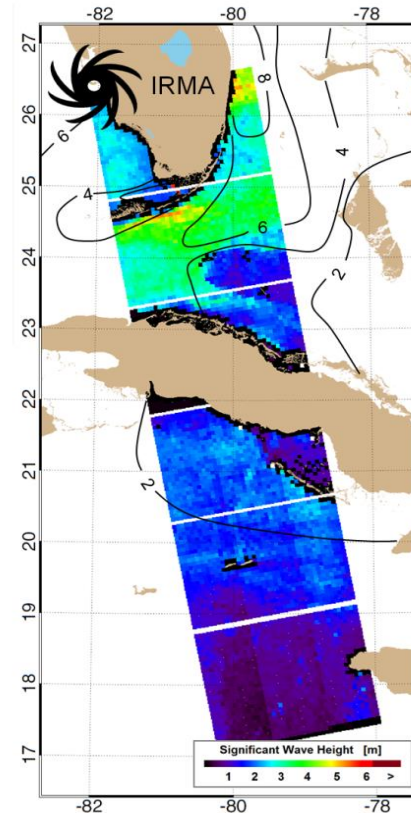
## Hurricane „Irma“ 2017 (S-1)

SENTINEL S-1 IW VV 2017-09-09 23:33 UTC TOTAL SIGNIFICANT WAVE HEIGHT



new techniques and algorithms allow observation and validation of forecast models worldwide

2017-09-10 23:25 UTC



### ESA news: Sentinel-1 sees through hurricanes

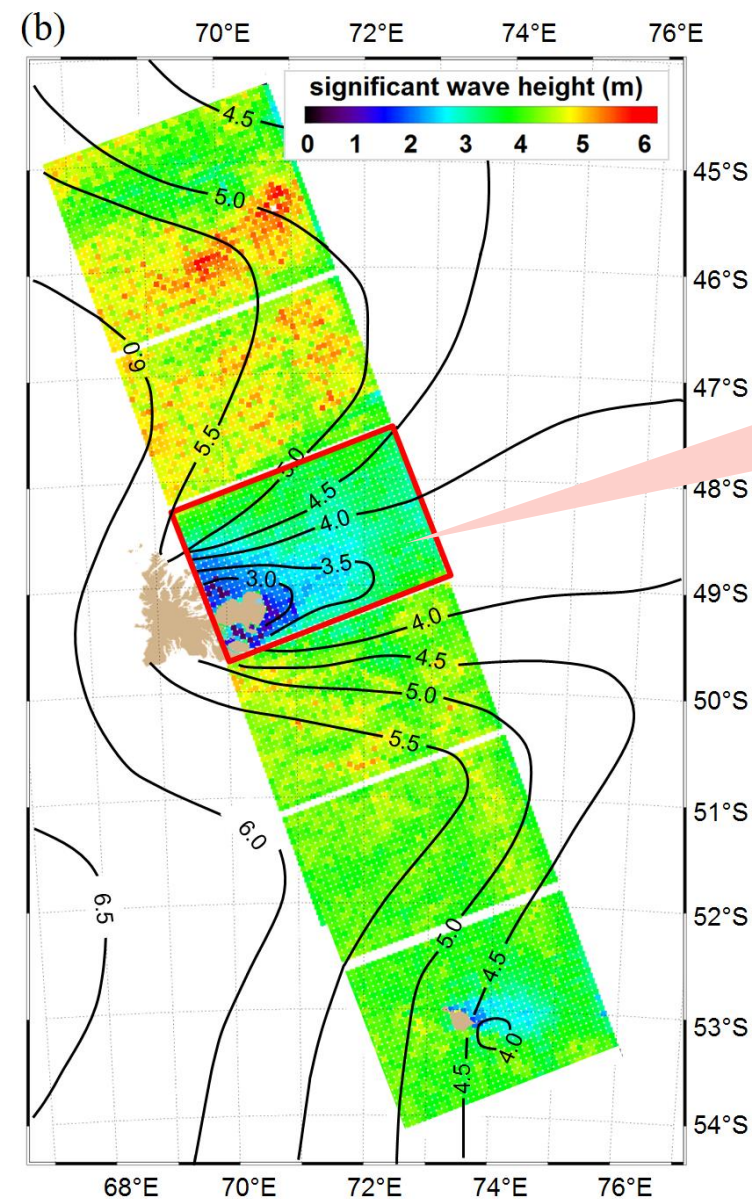
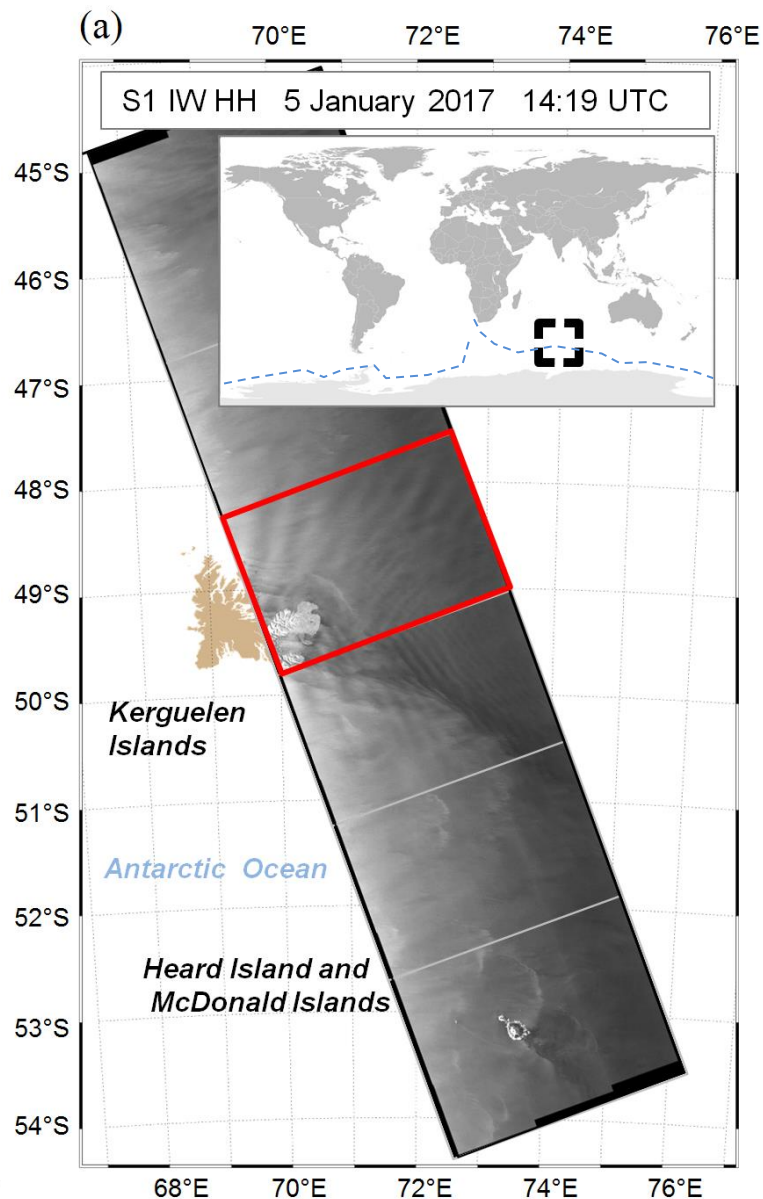
“... information about the sea state can help to assess how destructive a hurricane is and can predict its path respectively time and location on which it will make landfall ...”



# 1.6. Support of a research cruise in Arctic Seas – navigation and routing

Arctic Sea, 05.01.2017

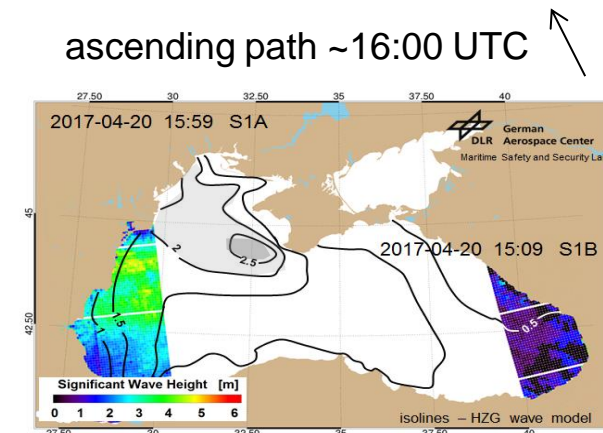
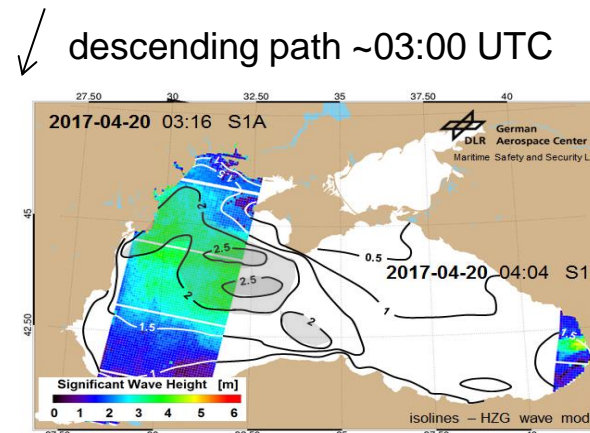
Processed in NRT  
And send to research  
vessel "Akademik  
Treshnikov" on Antarctic  
Circumnavigation



# 1.7. Following a storm in the Black Sea: 3 days (S-1)

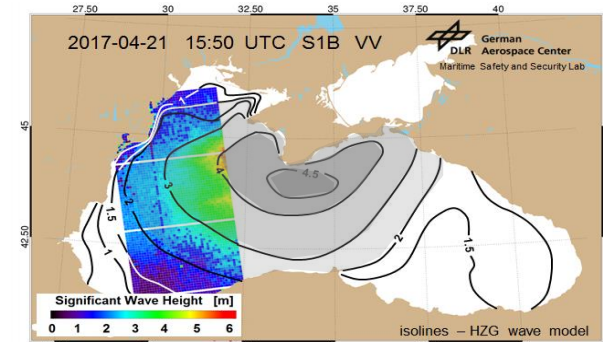
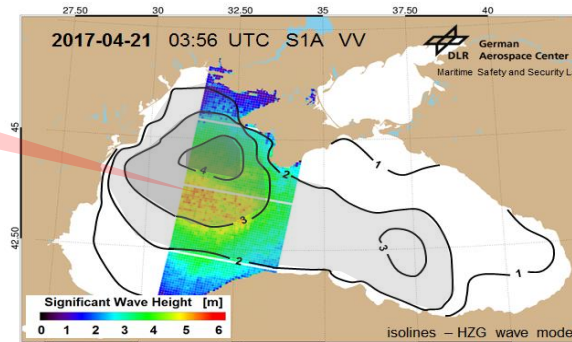
Total Significant Wave Height | Black Sea storm 20-23.04.2017 | SENTINEL -1 SAR C-band IW mode | processing mesh 6km×6km

2017-04-20



Modelled storm peak  
~90 km northerly

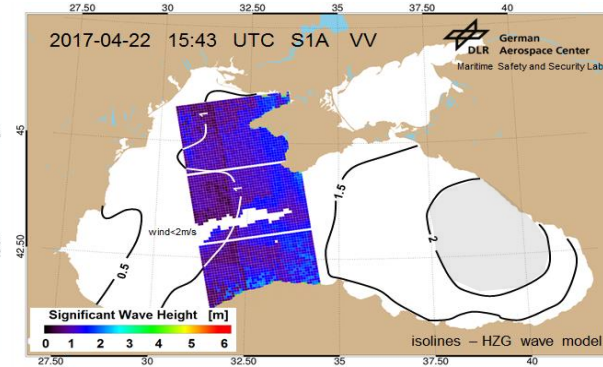
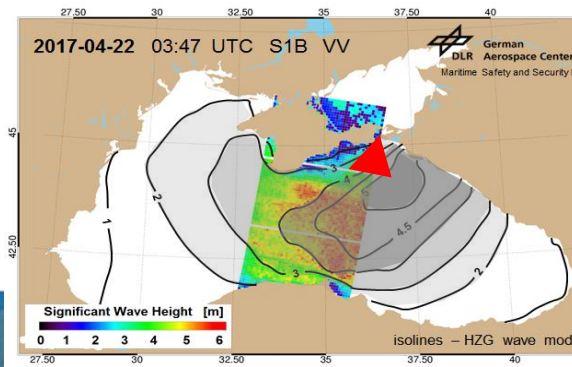
2017-04-21



114-m long cargo vessel with 12 crew sinks



2017-04-22



Raging Black Sea storm  
splits cargo ship in half





1. Concept and Examples

**2. Background**

3. Model Functions, Tuning

4. NRT implementation

5. Outlook



# 2.1. Background: Objective

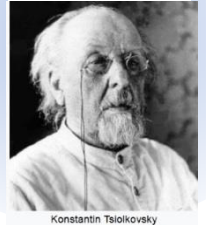
## 1. Basic Research - Functions & Algorithms

SAR Imaging Mechanism: Geophysical Model Function (GMF):  
development and adoption

- mathematic investigations
- for practical applications

Tsiolkovsky  
rocket equation 1903

$$\Delta v = v_e \ln \frac{m_0}{m_f}$$



## 2. Software Development - Prototype & NRT Processors

- implementation of GMF into Processors (SSP) prototype
- implementation of SSP into processing chain for NRT services,

first human in space



## 3. Processing and Results Analysis - What do we learn?

Forecasts improvement and geophysics

- statistics, local distributions
- extreme events
- assessments, danger localization, follow up and validation of forecast models (e.g. DWD)

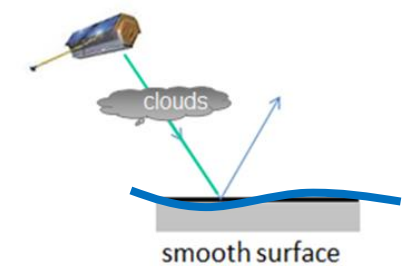
International Space Station 1998



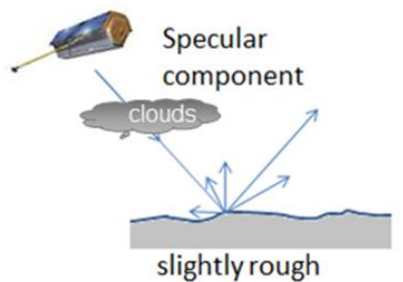


# 2.2. Satellite Radar Imagery

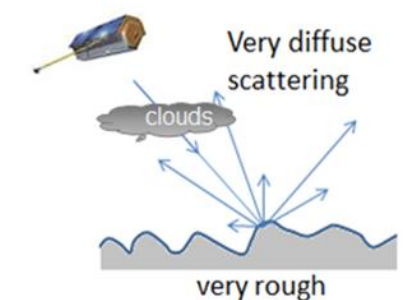
Imaging of sea surface by radar



no radar echo

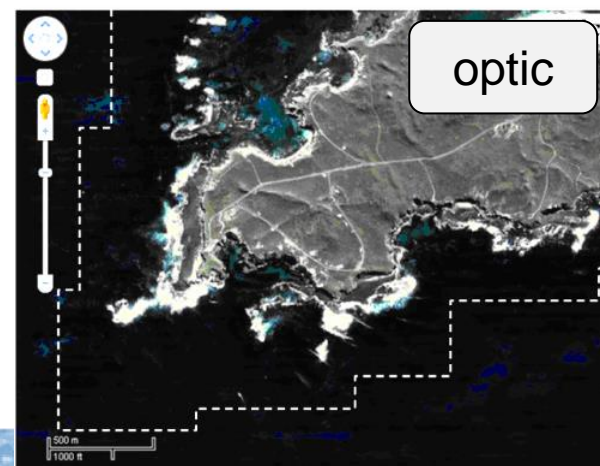
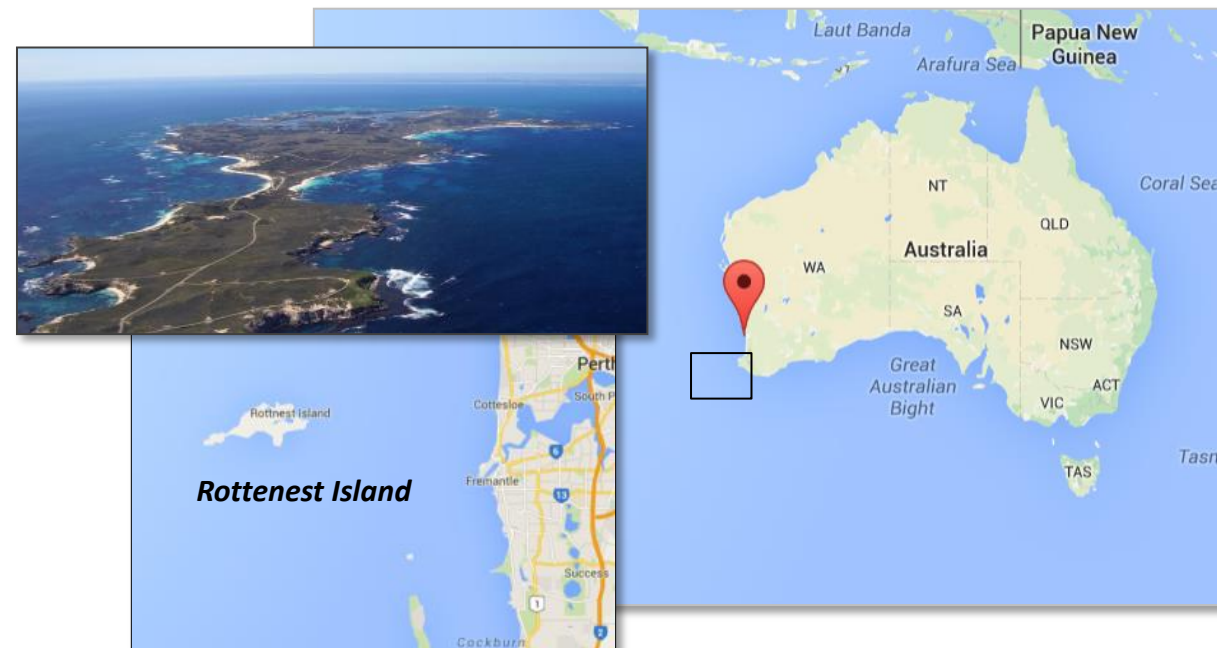
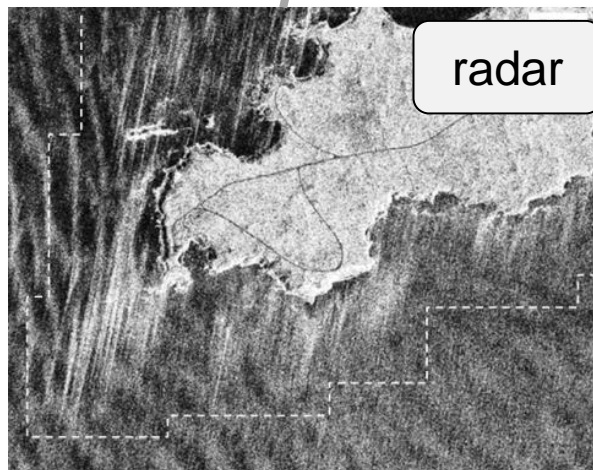
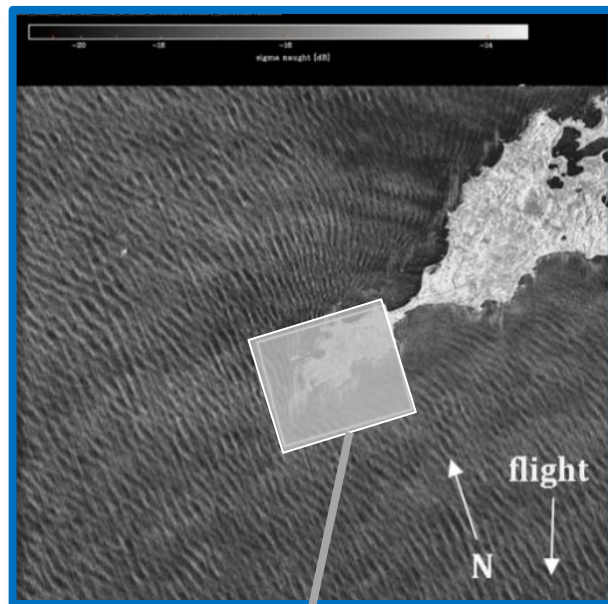


slightly rough



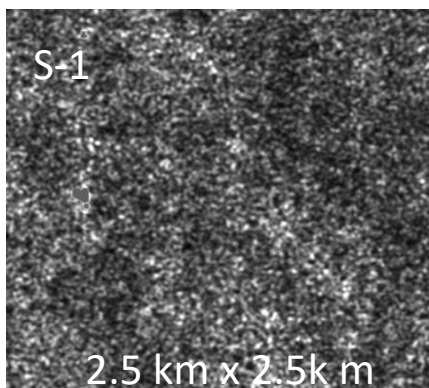
strong radar echo

active sensor

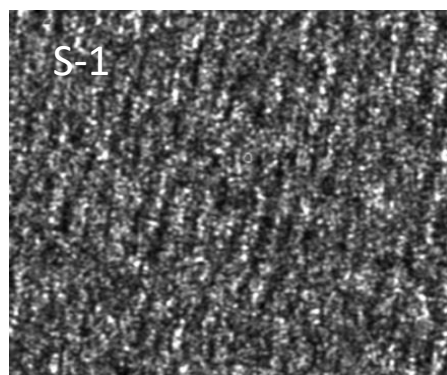


## 2.3. Sea surface by different sensors

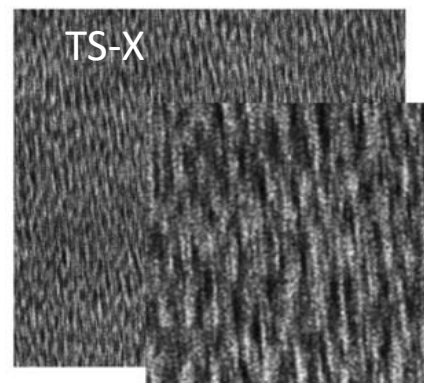
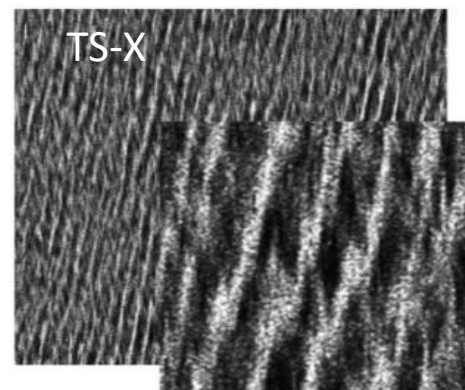
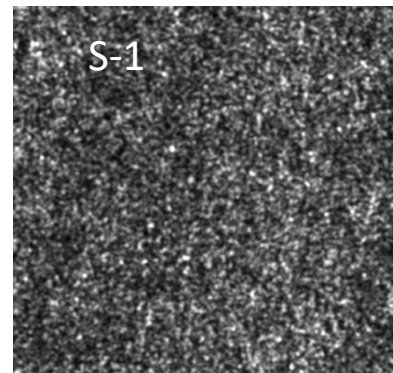
Hs ~ 0.5m



Hs ~ 4m



Hs ~ 7m



calm (swell)

moderate

strong

SENTINEL S-1 IW VV 10m Pixel, C-band  
TerraSAR-X StripMap VV 1.25m Pixel, X-band

### Principle wind and sea state estimation

averaged  
value

Local wind

SAR  
subscene

Variance,  
FFT  
GLCM

Local waves

compatibility





## 2.4. Artefacts pre-filtering

### Artefacts in SAR image impact spectra

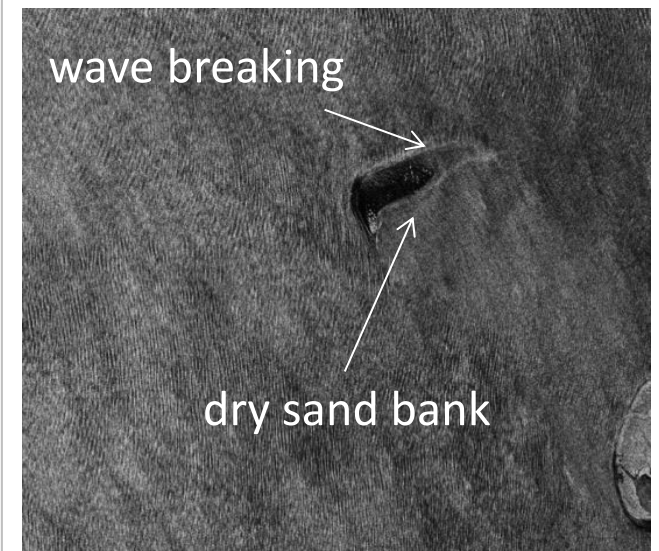
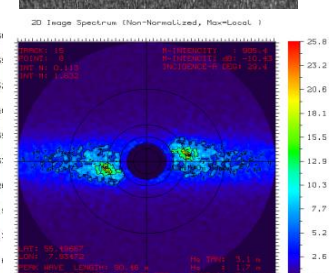
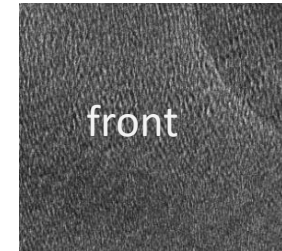
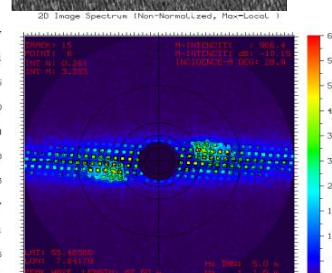
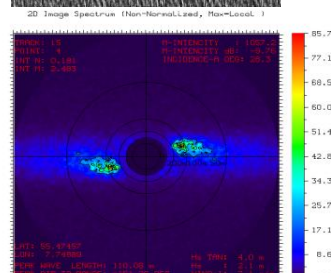
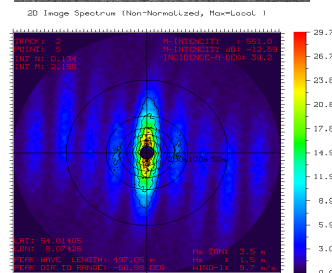
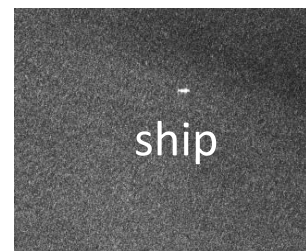
### Task №1 - removing artefacts before analysis

- Sand banks
- Wave breaking
- Ships, Buoys, Wind farms
- Current fronts, ship wakes

Without pre-filtering estimated  $H_s$   
can > 10 times overestimate real value

### 3 STEPS

- Removing before analysis
- Function correction terms
- Control results



1. Concept and Examples

2. Background

**3. Model Functions, Tuning**

4. NRT implementation

5. Outlook





# 3.1. Empirical Function and Parameter (SAR features)

**Function:** linear regression

$$P_i = \sum_{n=0}^N A_n S_n$$

**Solution:** quadratic minimization using SVD (singular value decomposition) – optimal solution for a linear system

## SAR features type

## Parameters first order

### 1. Subscene properties and statistics

NRCS, Norm.-variance, skewness, kurtosis,

+ 5 additional parameters (will be published later)

### 2. Geophysical

Wind

### 3. GLCM (grey level co-occurrence matrix)

GLCM-mean, variance, entropy, correlation, homogeneity, contrast, dissimilarity, energy

### 4. Spectral-A

using spectral bins for different wavelengths

Goda-parameter, Longuet-Higgins-parameter,  
+ 5 additional parameters (will be published later)

### 5. Spectral-B

20 parameter by using orthonormal functions,  
cutoff by ACF (autocorrelation function)



## 3.2. Model Function

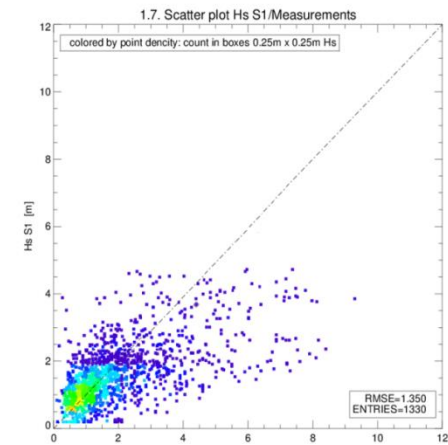
### Linear regression Empirical Model Function (EMF) bases on parameters

- Image spectral parameters (20 par.)
- Local wind information, variance
- GLCM (Grey Level Co-Currence Matrix) parameters (Entropy, Homogeneity, Contrast, Dissimilarity, etc.)

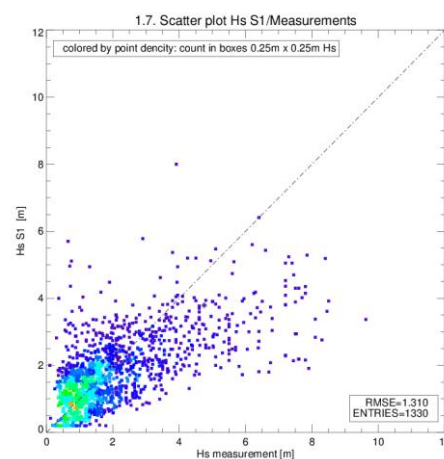
$$W = a_0 + \sum_{i=1}^{n_s} a_i s_i$$

### Model Function tuning – combination of spectral and Image feature analysis + filters

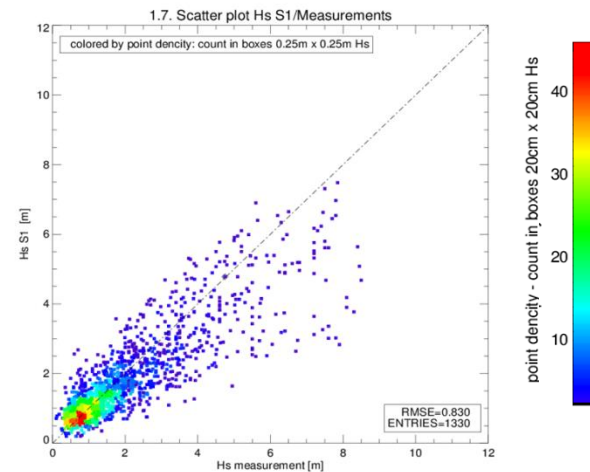
- tuning by minimizing root mean squared error RMSE
- number of used features improve results



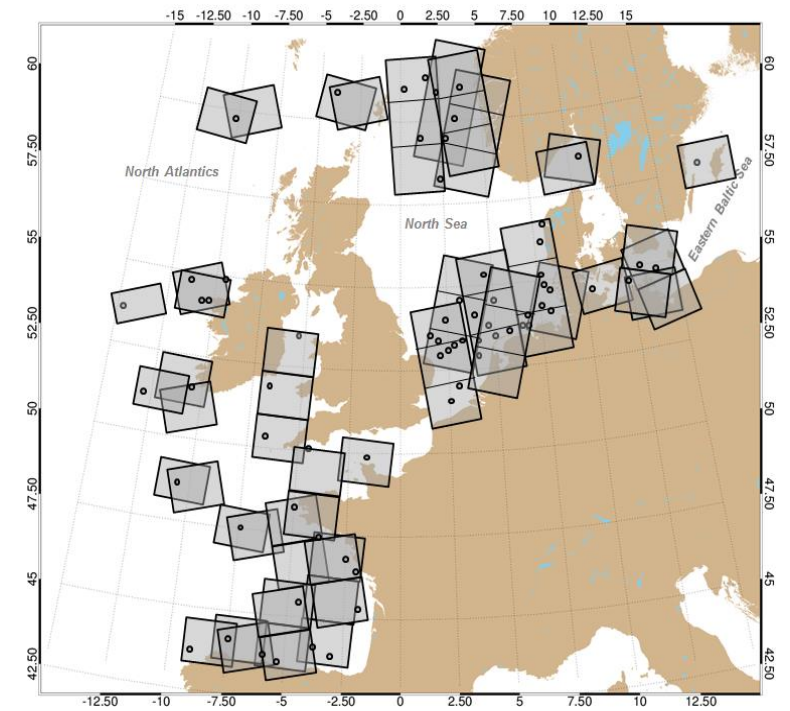
Tuning using  
local wind  $U_{10}$  only  
(optimal RMSE =1.35m)



Tuning using  
integrated spectrum energy only  
(optimal RMSE =1.31m)



Tuning using:  
- integrated image spectrum energy  
- local wind  $U_{10}$   
- spectral parameters  
- GLCM parameters (optimal RMSE =0.83m)



**Example** for collocations of individual S1 IW images with measurement stations in the **North Sea, Eastern Baltics and North Atlantics** used for algorithm tuning and validation.



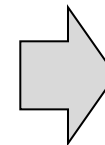
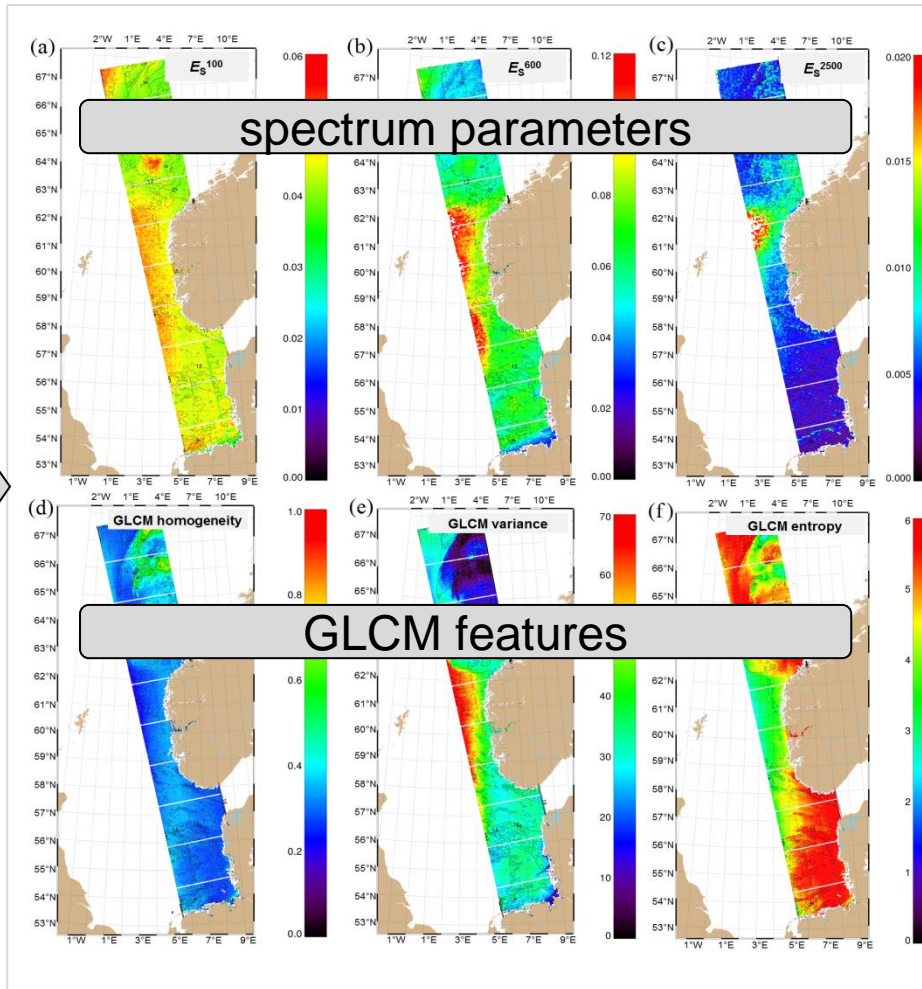
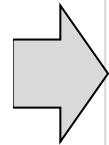
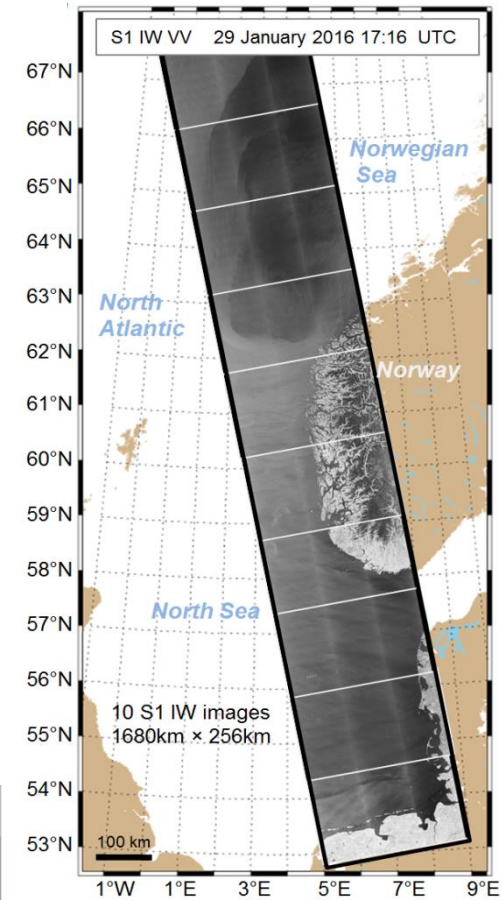
# 3.3. Model Function – example features estimation

## Linear regression Empirical Model Function (EMF) bases on parameters

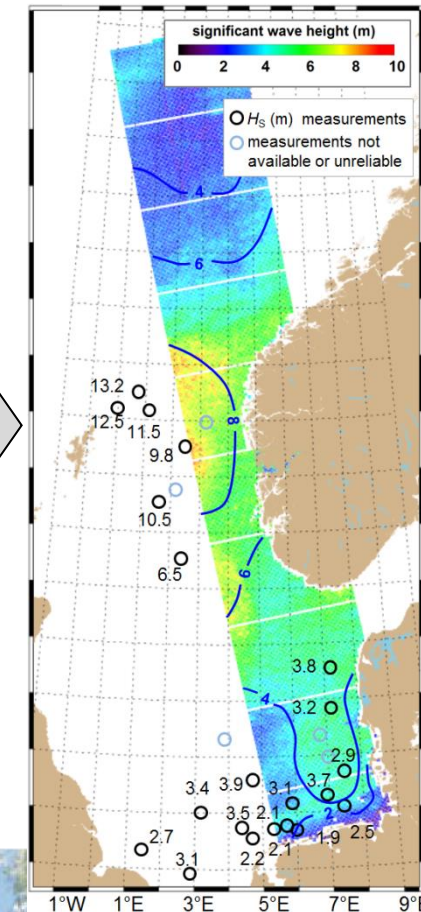
- Image spectral parameters (20 par.)
- Local wind information, variance
- GLCM (Grey Level Co-Ccurrence Matrix) parameters (Entropy, Homogeneity, Contrast, Dissimilarity, etc.)

$$W = a_0 + \sum_{i=1}^{n_s} a_i s_i$$

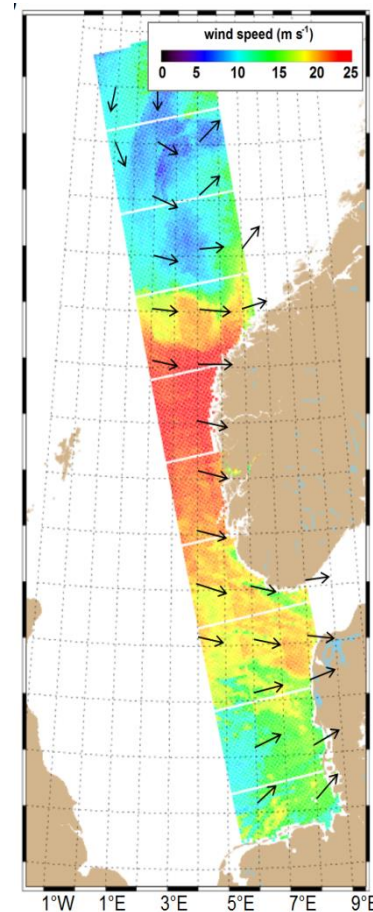
S1 IW scene



Wind



Waves



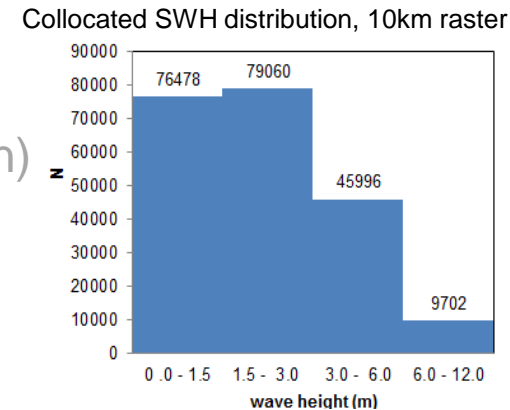


# 3.4. New sea state processor 2020: SWH improvement IW

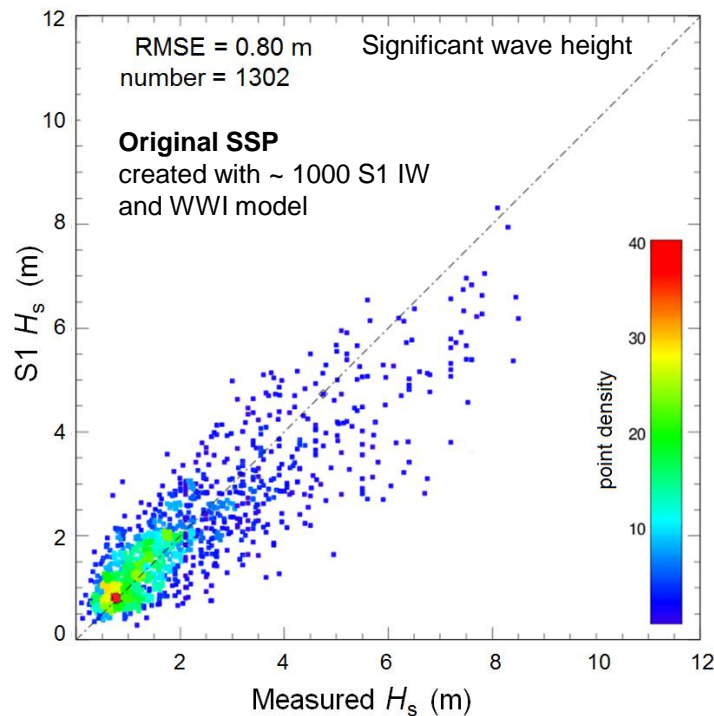
## New processor 2020

- New function with new parameters
- New S1 IW acquisition (~ 2000) + new validation data -  
CMEMS model results with ~5km resolution worldwide (WW3 ~30km resolution)
- New software
- Higher accuracy for SWH + additional parameters

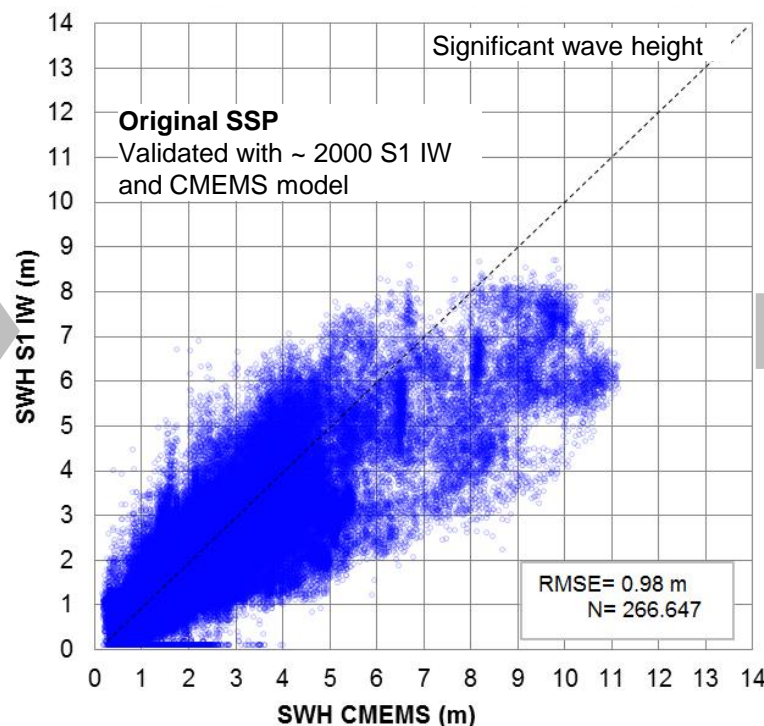
## SAINT Sea State Processor SSP for sea state fields estimation



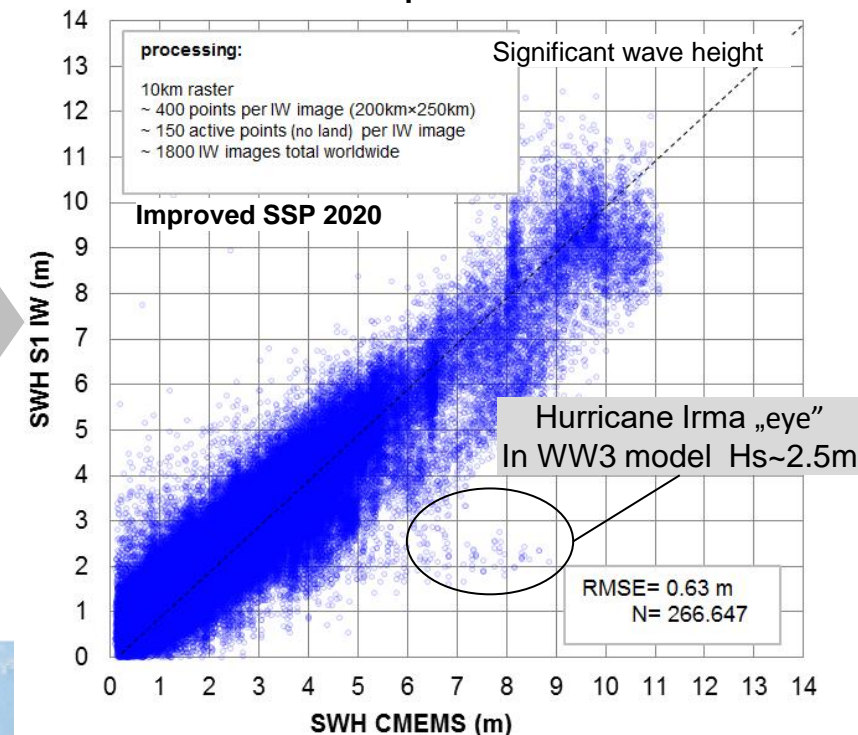
### SSP V1-2017 ~ 1000 S1-IW



### SSP V1-2017 ~ 1000 S1-IW

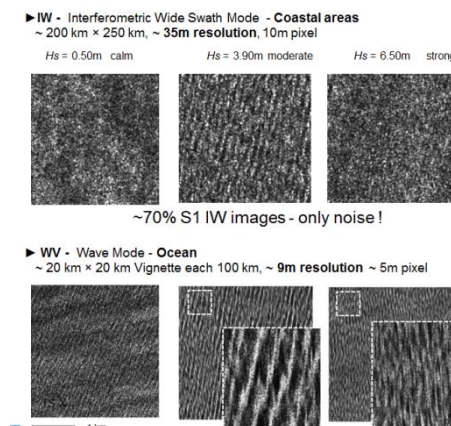
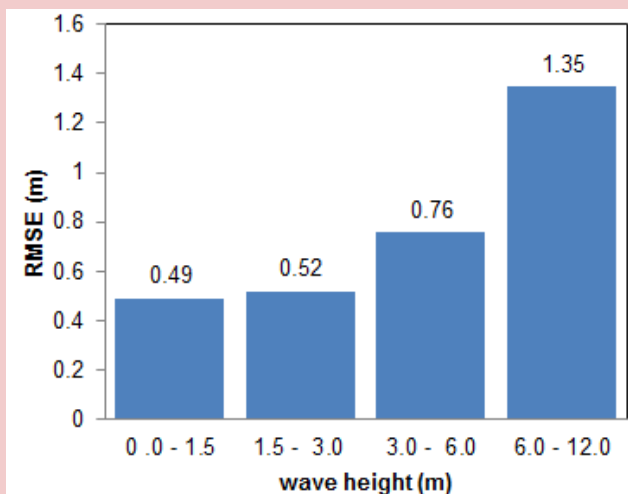


### SSP improved 2020

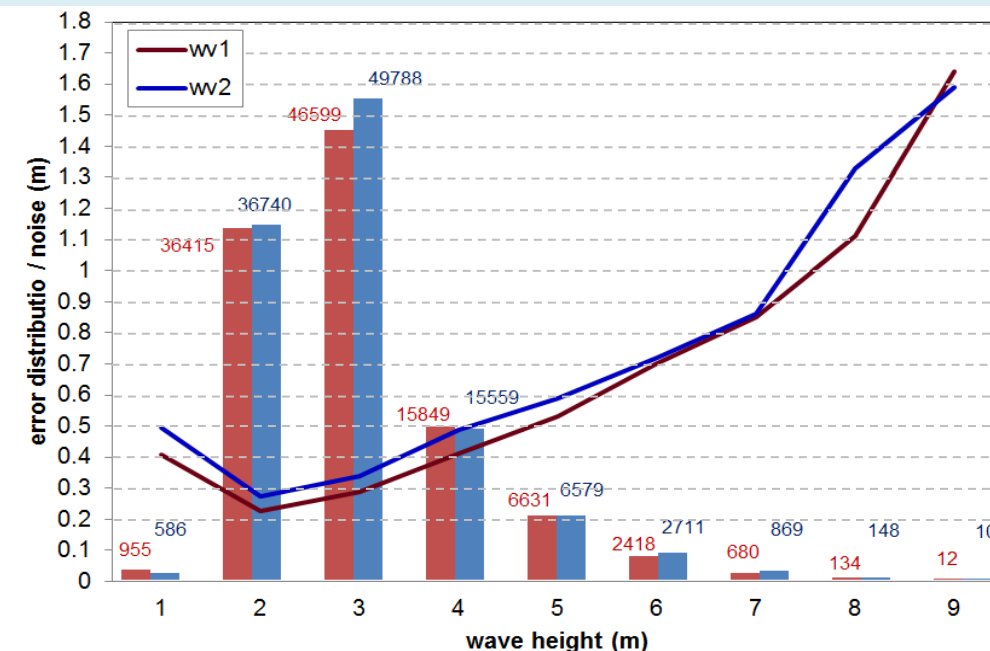


# 3.5. Accuracy: new sea state processor S1 IW and WV

Error distribution SWH S1 IW



Error distribution SWH S1 WV



RMSE

	SWH	Tm0	Tm1	Tm2	Sw1	Sw2	Sww	Tw
S1 IW	63cm	1.15 sec	0.95 sec	0.79 sec	0.52 m	0.38 m	0.73 m	0.92 sec
S1 WV	35cm	0.64sec	0.52 sec	0.53 sec	0.42 m	0.35 m	0.41 m	0.65 sec



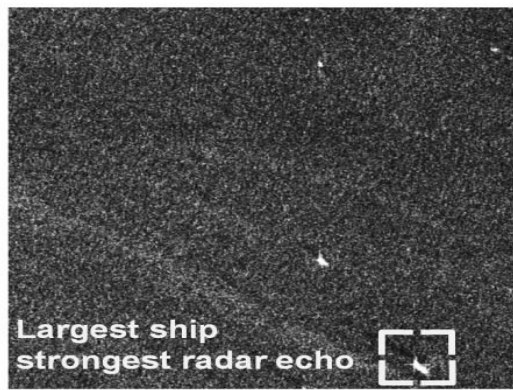


1. Concept and Examples
2. Background
3. Model Functions, Tuning
- 4. NRT implementation**
5. Outlook



# 4.1. Sea State Processor for SENTINEL-1 and TerraSAR-X at Ground Station NZ

artefact pre-filtering

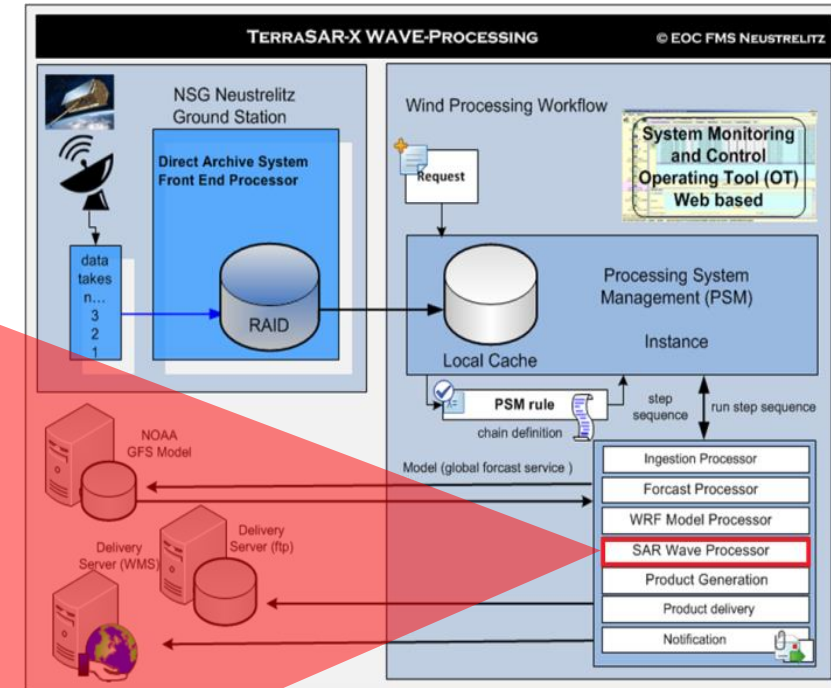
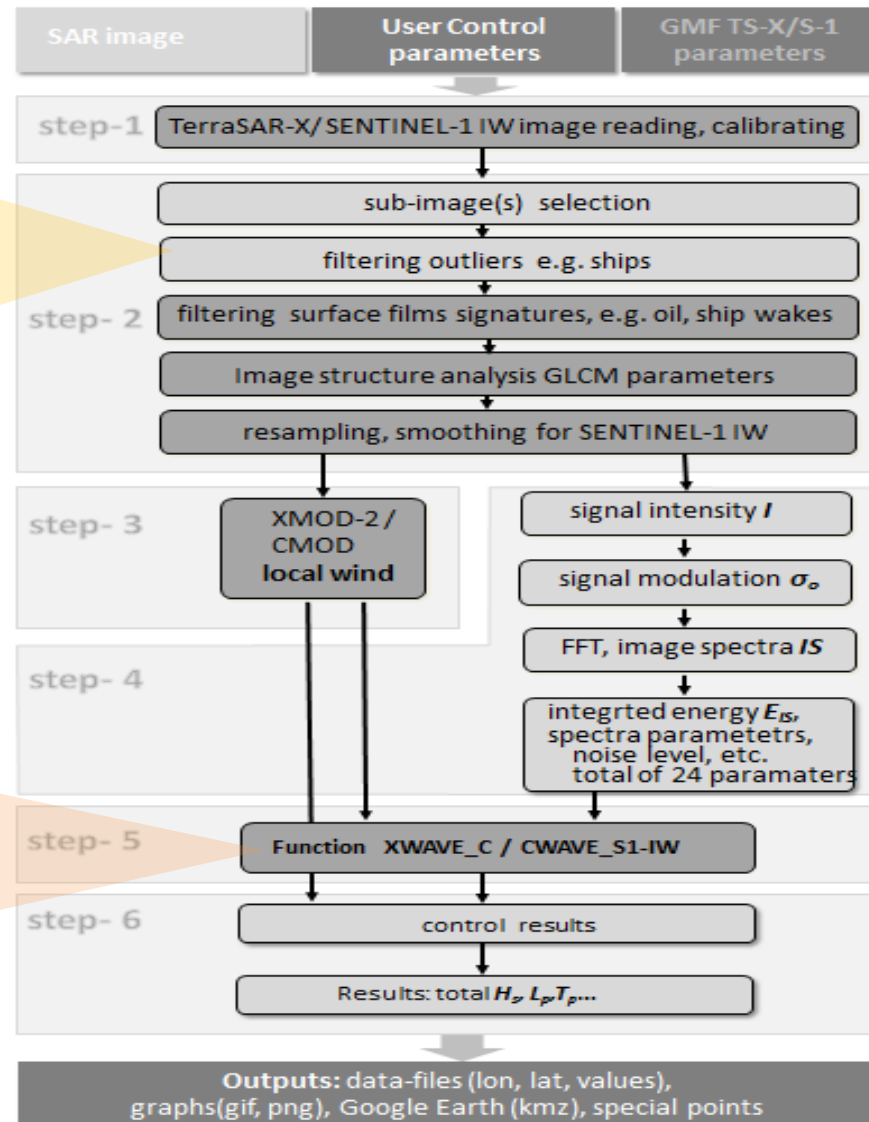


Sea State Functions  
TerraSAR-X  
Sentinel-1

- Spectral parameters
- Local wind
- GLCM parameters



## Sea State Processor

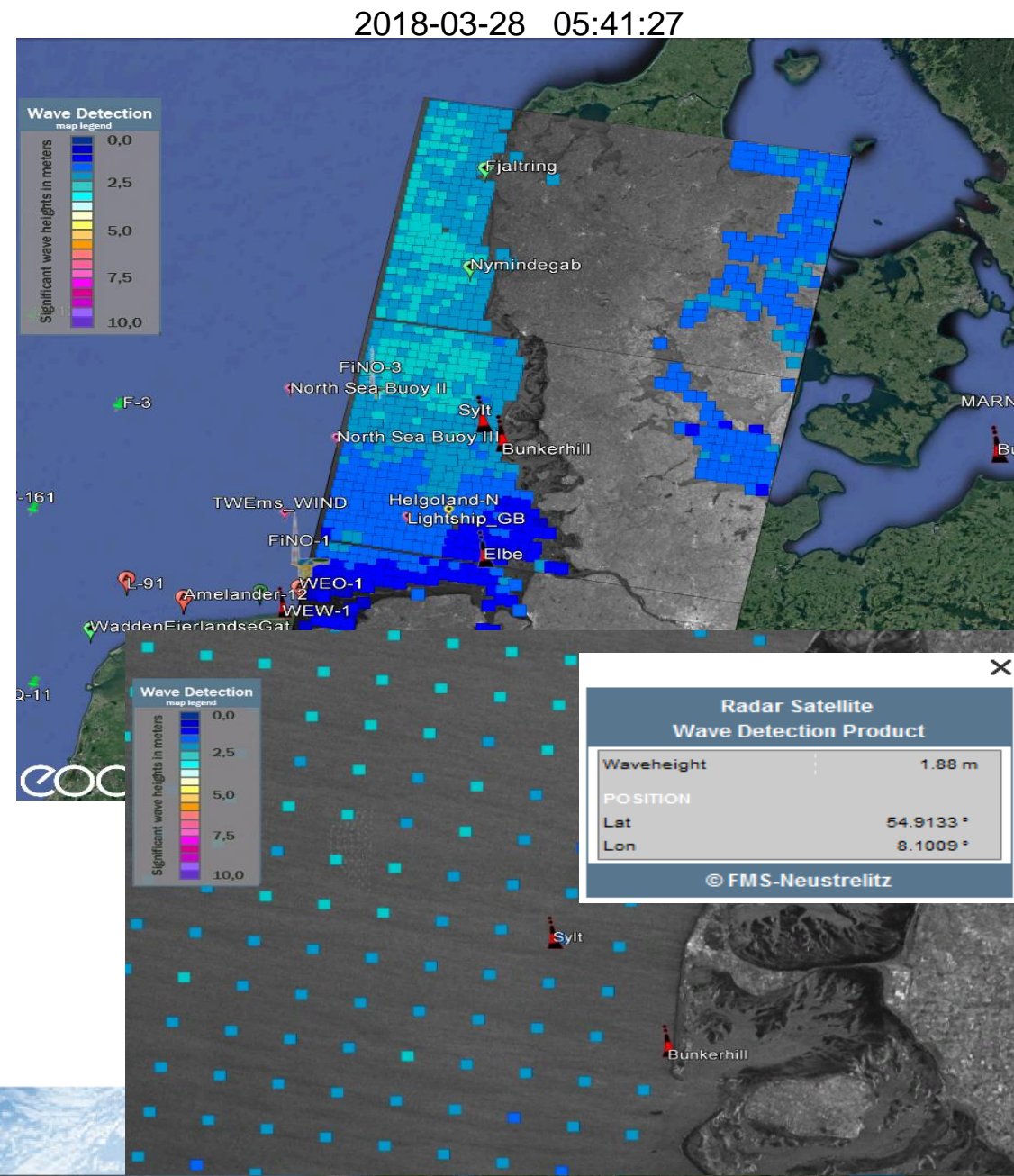
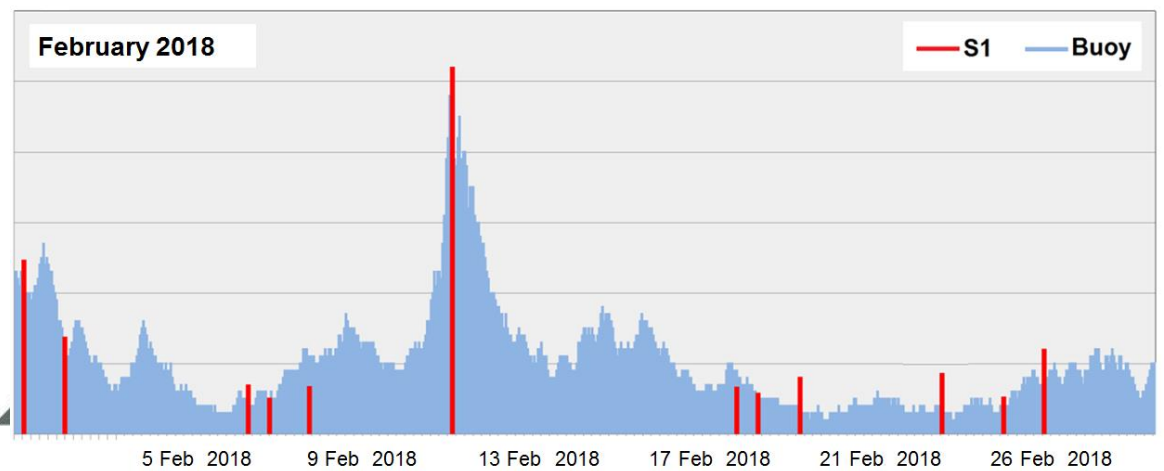
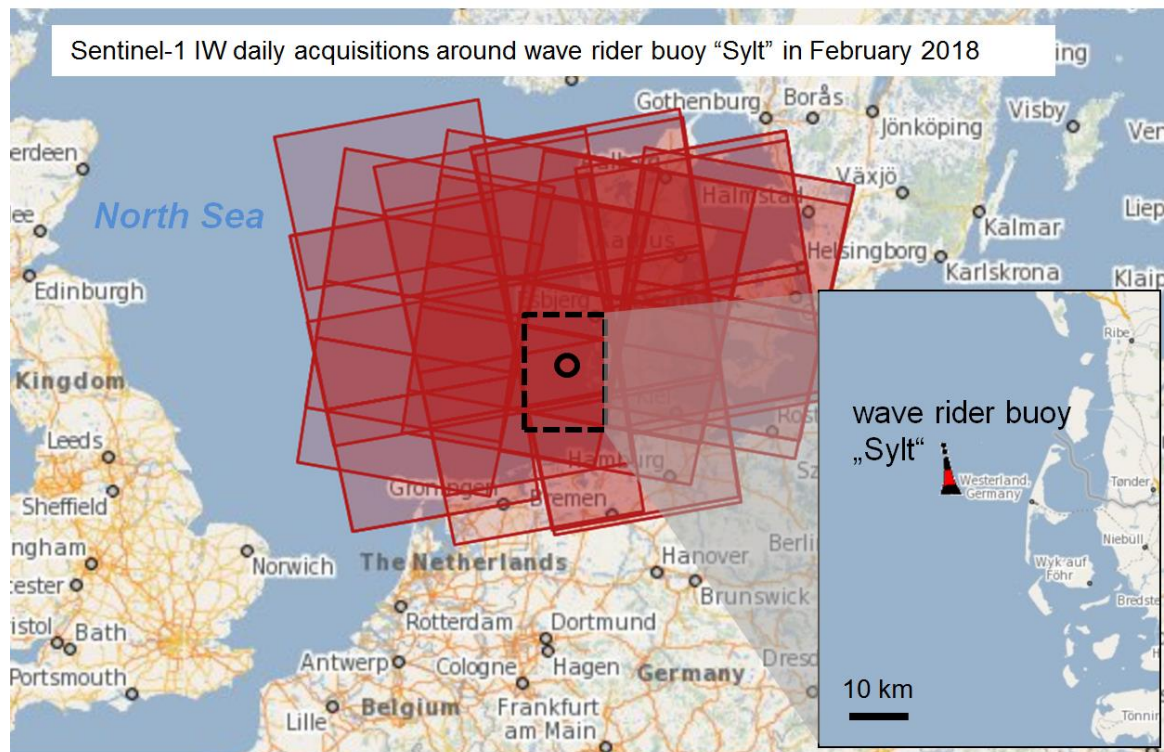


NRT chain in Neustrelitz  
NZ

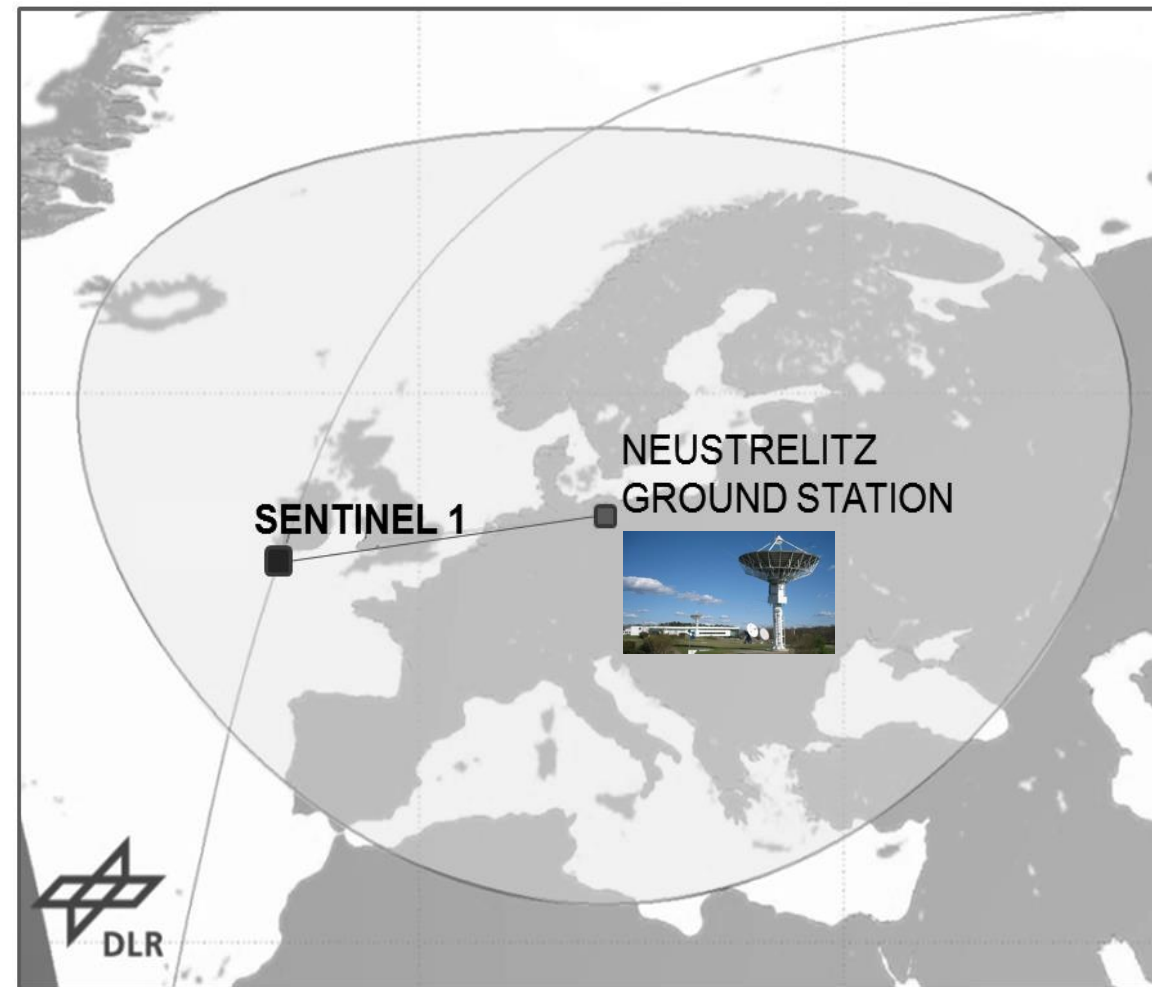




## 4.2. Acquisitions for a location S1 IW



## 4.3. Copernicus Local Ground Station Neustrelitz



Ground Station Neustrelitz, acquisition circle for Sentinel-1, 5 degree elevation. Inside of this area the data can be transferred from satellites to ground station directly after acquisition, without delay, for NRT processing.



1. Concept and Examples
2. Background
3. Model Functions, Tuning
- 4 NRT implementation
- 5. Outlook**



# Example S1 IW (2): Atlantic - Storm

Sequences of 12 S1-IW images , North Atlantic with  $H_s$  of  $\sim 9$  m  
coverage $\sim 250$  km  $\times$  2200 km, Raster 3 km (60  $\times$  80 = 4800 subscenes/image).

