# A swarm intelligence-based method for hydrological model calibration through a simulated solution space Juan F. Farfán<sup>1</sup>, Luis Cea<sup>2</sup>

2 Environmental and Water Engineering Group, Department of Civil Engineering, University of A Coruña, A Coruña, Spain (luis.cea@udc.es)

#### Problem

Hydrological models are widely used for flood forecasting, continuous streamflow simulation and water resources management. The success of a hydrological model depends on different factors such as its formulation, data availability and parameter optimization. There are many approaches to identify the optimal parameter sets, which can be categorized in 1) Local search methods and 2) Global search methods. In the group of global search methods, swarm intelligence could provide an alternative to improve the application of surrogate models and to provide robust calibration.

## ABC algorithm and adaptation

Pseudocode of Artificial Bee Colony Algorithm

Initialize the set of food sources:  $x_i$  for i = 1, 2, ...SN by  $x_i = low_d + rand[0, 1](up_d - low_d)$ Calculate goodness-of-fit for:  $fit(x_i)$ , for i = 1, 2, ...SNwhile Stop criterion is not reached do for i = 1, 2, ..., SN do  $v_i = x_{ij} + rand[-1, 1](x_{ij} - x_{kj}),$  $k \neq j$  **Pseudocode of Artificial Bee Colony Al**gorithm for simulated solution space Initialize the set of food sources  $x_i$  for (i = 1, 2, ..., SN)Use Quasi-random Sampling Calculate goodness-of-fit for each  $f(x_i), i = 1, 2, ..., SN$ Train the ANN-SM model while Stop criterion is not reached do for i = 1, 2, ..., SN do  $v_i = x_{ij} + rand[-1, 1](x_{ij} - x_{kj}),$  $k \neq j$ end for for i = 1, 2, ..., SN do Estimate  $f(v_i)$ , for (i = 1, 2, ..., SN)through ANN-SM end for for i = 1, 2, ..., SN do if  $f(v_i) >= f(x_i)$  then  $x_i = v_i$ end if end for Generate a new random food source (if required) end while Selection of possible food sources by means of a threshold criterion Evaluation through the hydrological model



### Basic idea

Quasi-random sampling of parameters with the aim of mapping the feasible solution space. Montecarlo simulation for SN parameter sets, and goodness-of-fit coefficients calculation: Nash-Sutcliffe Efficiency (NSE), adapted for peaks Nash-Sutcliffe Efficiency (ANSE), Kling Gupta Efficiency (KGE), and adapted for peaks Kling Gupta Efficiency (AKGE). Configuration of the SN parameter sets and its goodness-offit coefficients as training set of a **Surrogate** Model based on Artificial Neural Networks (ANN-SM) [3] in order to generate a simulated solution space. Adaptation of a swarm intelligence-based approach in order to search in the simulated space. For this study, Artificial Bee Colony algorithm (ABC) [2] is adapted. The applied hydrological model is

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if fit(v_i) >= fit(x_i) then

x_i = v_i

end if

end for

for i = 1, 2, ..., SN do

Select an employed bee:

p_i = \frac{fit(x_i)}{\sum_{j=1}^{SN} fit(x_j)}

Repeat evaluation

Generate a new random food

source (if required).

end for

end while
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fit() denotes goodness-of-fit, *low* is the lower limit of a parameter, up is the upper limit of a parameter, d denotes the d - th parameter of the model of D parameters.

Preliminary results

the Modelo Idrológico Lumped in Continuo (MILC) [1].

## MILC model

Model parameters: Initial water content of the soil layer  $(W_0)$ , maximum water capacity of the soil layer  $(W_{max})$ , exponent of drainage (Computed from the pore size distribution index  $(m2 = 3 + 2/\lambda)$ ) (m2), saturated hydraulic conductivity  $(k_s)$ , baseflow to drainage ratio  $(\alpha)$ , lag-area parameter  $(\nu)$ , Correction factor for evapotranspiration (b), initial abstraction coefficient  $(\lambda 1)$ , coefficient to compute soil max retention from soil water content (Sr).

#### References

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Figure 1 shows the parameter distribution sampled and the one obtained after 3 search cycles for those that provide goodness-of-fit values greater than 0.65 for NSE and ANSE and 0.70 for KGE and AKGE. The ANN-SM captures information about the sensitivity of the parameters and the ABC algorithm is able to use it in order to converge towards the position of good food sources. The computational burden is minimized, reducing search procedures that could take 3-10 days to 60-200 seconds. For this case study, the ANN-SM provided a 96-99 % success rate in identifying the position of food sources over the threshold criterion

The method has provided a large number of suitable parameter sets. The validation and prediction result is shown for one of these sets. The validation step shows NSE of 0.81, ANSE of 0.843, KGE of 0.77 and AKGE of 0.74. The parameter set overperformed local search method (in this case), especially in validation and prediction stages. Specifically, in the prediction stage, NSE of 0.77 and ANSE of 0.83 were obtained against NSE of 0.45 and ANSE of 0.57 for the local search parameter set.







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Fig 2: Validation and prediction results for a ANN-SM parameter set

**Conclusion:** The adaptation approach has been able to provide good preliminary results; however, this methodology should be evaluated in more computationally intensive models, where the advantages and limitations of combining ANN-SM and ABC algorithm (among others) can be explored.