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Outline

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 - Linear Potential theory
 - The underwater disturbance
 - Analytical solution
- 3 Results
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Summary

There are only a few analytical 2+1 D models for tsunami propagation, in which most of them treat tsunami generation from static deformation field isolated from the kinematics of the rupture. This work examines the behavior of the tsunami propagation in a simple set-up including a source time function which accounts for a time description of the rupture process on the tsunami source. An analytical solution is derived in the wavenumber domain, which is quickly inverted to space with the Fast Fourier Transform. The solution is obtained in closed form in the 1+1D case. The inclusion of temporal parameters of the source such as rise time and rupture velocity reveals a specific domain of very slow earthquakes that enhance tsunami amplitudes and produce non-negligible shifts on the arrival times. The obtained results confirm that amplification occurs when the rupture velocity matches the long-wave tsunami speed and the static approximation corresponds to a limit case for (relatively) fast ruptures.

Mathematical model

Linear Potential theory



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Governing Equations

In this study, Tsunamis are governed by the Linear potential theory. In a constant depth ocean, the system of equations takes the form:

$$egin{array}{lll} \Delta arphi = 0 \ arphi_z = \zeta_t, & ext{at } z = -h \ arphi_z = \eta_t, & ext{at } z = 0 \ arphi_t = -g\eta, & ext{at } z = 0. \end{array}$$

where g is the gravity acceleration and $(u, v, w) = \nabla \varphi(x, y, z, t)$

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Governing Equations

In terms of the Laplace-Fourier Transform, the well-known solution is:

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Governing Equations

In terms of the Laplace-Fourier Transform, the well-known solution is:

$$\overline{\widehat{\eta}}(k_x,k_y,s) = \frac{s}{s^2 + \omega^2} \left\{ \frac{s\overline{\widehat{\zeta}}(k_x,k_y,s) - \widehat{\zeta}(k_x,k_y,0^-)}{\cosh(kh)} + \widehat{\eta_0}(k_x,k_y) \right\}$$

where $\omega^2 = (ck)^2 \frac{\tanh(kh)}{kh}$, $k^2 = k_x^2 + k_y^2$, $c = \sqrt{gh}$, and $\eta_0(x, y)$ is the initial condition. In this work, $\eta_0(x, y)$ is set to zero.

— Mathematical model

└─ The underwater disturbance



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Mathematical model

└─ The underwater disturbance

Definition of the Forcing term

The underwater disturbance evolution defines the forcing term that makes the tsunami evolve from its source.

If this source term is defined by an earthquake, the kinematics of the rupture is included:

$$\zeta(x, y, t) = \zeta_0(x, y)T(y, t)$$

The final shape of the bottom disturbance is $\zeta_0(x, y)$ and starts to evolve when the rupture front reaches the point (x, y). Thus, it varies linearly from zero to its final value in a fixed rise-time, as shown in the next slide.

Mathematical model

└─ The underwater disturbance



$$T(y,t) = S\Big(\frac{t - t_V(y)}{t_R}\Big)$$

 $S(x) = x\mathcal{H}(x) - (x-1)\mathcal{H}(x-1)$

 $\mathcal{H}(x)$ is the Heaviside step function.

The spatial source is modeled by uncoupling variables

 $\zeta_0(x,y) = \zeta_0^x(x)\zeta_0^y(y)$

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Analytical solution

To derive an analytical solution in the wavenumber domain, the source is constant along y: $\zeta_0^y(y) = \mathcal{H}(L_2 - y)\mathcal{H}(L_1 + y)$ The next auxiliary functions are defined: $q(a,b,t) =: \frac{\mathcal{H}(t)}{a^2 - b^2} \left(\frac{\sin(bt)}{b} - \frac{\sin(at)}{a} \right)$, with $a = \omega$ and $b = V_r k_y$. $p(a, b, t, t_0) =: \mathcal{L}^{-1} \{ se^{-st_0} \overline{a}(a, b, s) \} (t) = \partial_t q(a, b, t - t_0).$ Note there are removable singularities in functions p and q when $\omega = V_r k_u$.

By using the properties of the Laplace transform:

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Analytical solution

$$\begin{split} \widehat{\eta}(k_x, k_y, t) &= \frac{\widehat{\zeta_0^x}(k_x)}{\cosh(kh)} \frac{V_r^2}{t_R} \left[\phi(t) - \phi(t - t_R) \right] \\ \text{where} \\ \phi(t) &= \frac{2}{V_r} p(t, 0) - \frac{1}{V_r} \cos(L_2 k_y) p(t, t_2) + k_y \sin(L_2 k_y) q(t - t_2) - \frac{1}{V_r} \cos(L_1 k_y) p(t, t_1) \\ &+ k_y \sin(L_1 k_y) q(t - t_1) + i \left\{ -\frac{1}{V_r} \sin(L_2 k_y) p(t, t_2) - k_y \cos(L_2 k_y) q(t - t_2) \\ &+ \frac{1}{V_r} \sin(L_1 k_y) p(t, t_1) + k_y \cos(L_1 k_y) q(t - t_1) \right\} \\ \text{and} \ t_i &= \frac{L_i}{V_r}, \ i \in \{1, 2\}. \end{split}$$

Finally, $\eta(x,y,t)$ is numerically retrieved with the FFT.

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Analytical solution



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Propagation when $\nu = 1$

Mathematical model

Analytical solution



1+1 D Non-dispersive case

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$$\zeta_0^x(x) = H$$
 • $t_R = 0$ • $\omega \approx ck$

In this specific case, a closed form is obtained:

$$\begin{split} \eta(y,t) &= \frac{\nu^2 H}{\pi (1-\nu^2)} \left[\psi \left(y - V_r t, 0 \right) + \psi (ct-y,0) + \left(\frac{1}{\nu} - 1 \right) \psi (ct,y) \right. \\ &+ \mathcal{H}(t') \left\{ \psi \left(L + V_r t' - y, 0 \right) - \frac{1}{2} \left(\frac{1}{\nu} - 1 \right) \psi \left(y - L + ct', 0 \right) + \frac{1}{2} \left(\frac{1}{\nu} + 1 \right) \psi \left(y - L - ct', 0 \right) \right\} \right] \end{split}$$

where ν is the ratio between velocities, $\frac{V_r}{c}$, $t' = t - \frac{L}{V_r}$, and, $\psi(x, y) = \arctan\left(\frac{\sinh\left(\frac{\pi x}{2h}\right)}{\cosh\left(\frac{\pi y}{2h}\right)}\right)$.

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x 4

Radial case
•
$$\zeta_0(x, y) = \zeta_0(r)$$

 $\eta(r, t) = \frac{\mathcal{M}(r, t) - \mathcal{M}(r, t - t_R)}{t_R}$
with
 $\mathcal{M}(r, t) = \int_0^\infty \frac{J_0(kr)k}{\omega(k)\cosh(kh)} \int_0^{\max(V_r t, 0)} J_0(k\xi)\xi\zeta_0(\xi)\sin[\omega(k)(t - \xi/V_r)]d\xi dk$
 \mathcal{M} can be efficiently computed with numerical algorithms.

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Asymmetric rupture propagation



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Symmetric rupture propagation



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A simple permanent deformation is taken:

$$\zeta_0(r) = H\mathcal{H}(R_0 - r)$$

$$R_0 = \frac{W}{2} = 40 \, km$$

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Conclusions

- Tsunami amplification is stronger when ν approaches to 1.
- The kinematics on the tsunamigenic source process can strongly influence the waveforms, especially in the near field, close to the source area.
- Wave amplitude is optimal for unilateral ruptures since there is a longer distance where the constructive interference process is taking place and grows proportionally to the fault length.
- Amplification becomes important for lower values of ν : 2.0 and 2.7 for the dispersive and non-dispersive cases, respectively. For $\nu < 0.1$, there is no amplification because in this region tsunami waves are not excited.

Analytical Model for Tsunami Propagation including Source Kinematics $\hfill \mathsf{L}$ Main references

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References

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Thanks for reading!

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