

## Planning for LOTOS: A New LOwer Troposphere Observing System Terry Hock

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# What is LOTOS

**LOTOS** is proposed as a configurable and scalable integrated suite of automated and unattended ground-based in-situ and remote sensors for weather and climate research



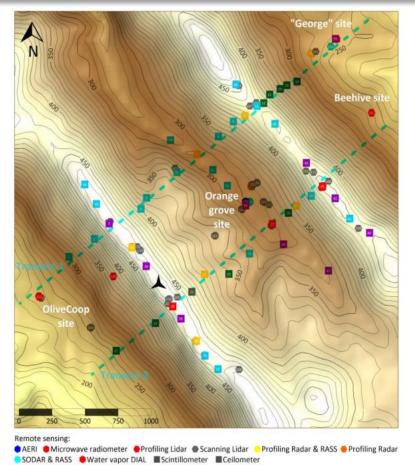
## LOTOS is designed to provide:

- Quasi-3D sensing of the lower troposphere plus mapping of spatial distribution of properties at the Earth's surface
- Full kinematic and thermodynamic profiling at five nodes
- Multiple observations of exchange processes across the land-surface interface and between BL and the free atmosphere





## **Planning for LOTOS**



Meteorological masts: masts [2 m] masts [10 m] masts [20 m] masts [30 m] masts [60 m] masts [100 m] Sounding sites: Radiosonde Tethersonde

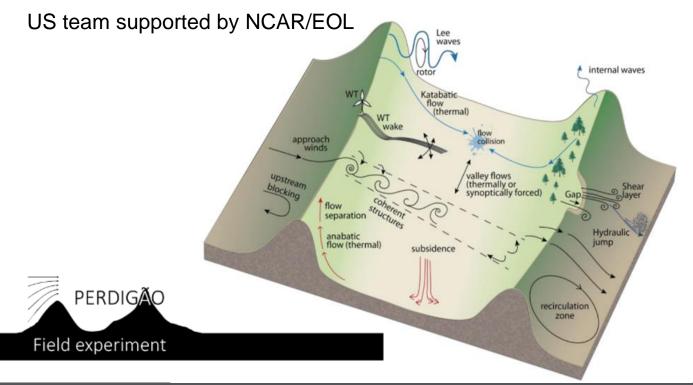
| Other                      |             |              |
|----------------------------|-------------|--------------|
| Noise Measurement terminal | Seismometer | Wind turbine |

Source: https://perdigao.fe.up.pt/

### European Geosciences Union (EGU) 2020 GI4.1 - Open session on Atmosphere, Land and Ocean Monitoring 7 May 2020 2020 EUCAR/NCAR

## Perdigão Dec 15, 2016 – June 15, 2017

EU & US collaboration, embedded in the ERANET+ project, focus on BL processes and harvesting of wind energy in complex terrain



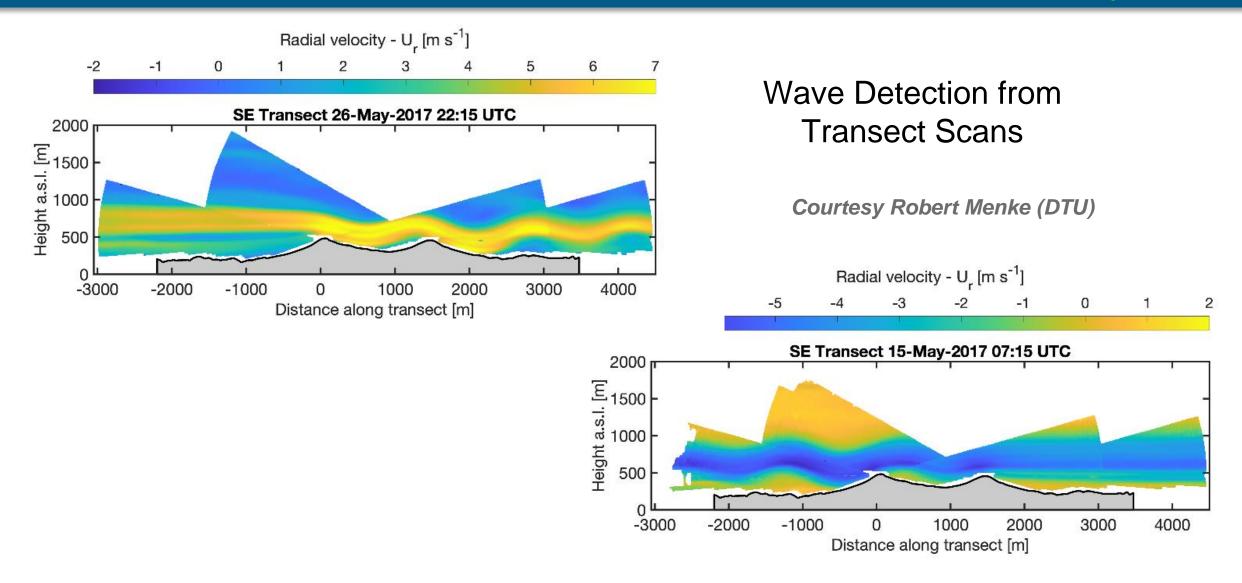




# Planning for LOTOS

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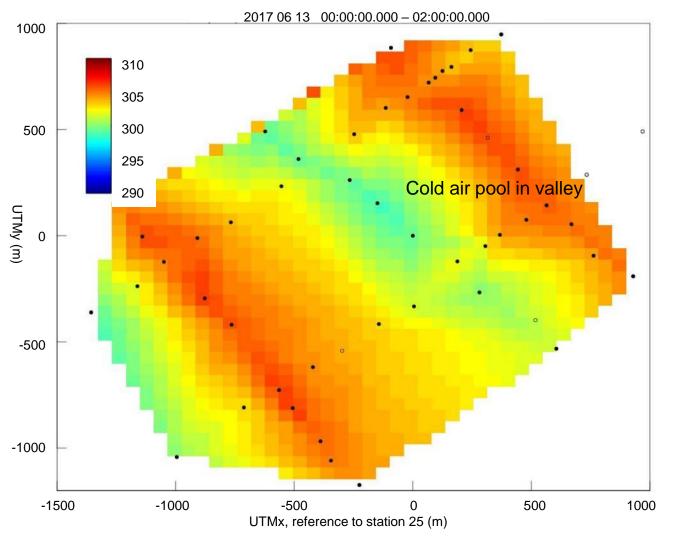
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## **LOTOS Surface Characterization**

### ISFS Composite from Perdigão

## Potential temperature field from 47-site ISFS network in Portugal



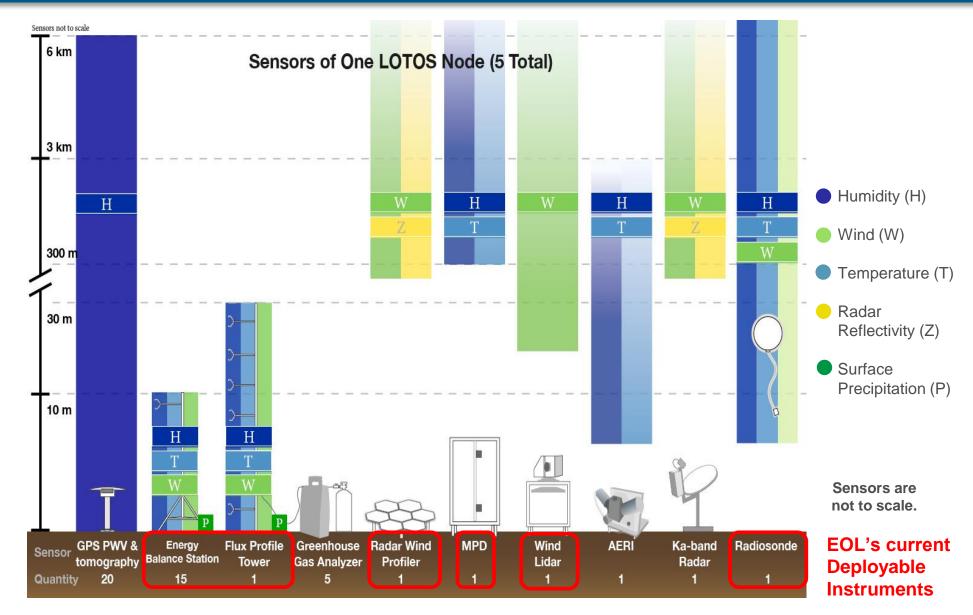


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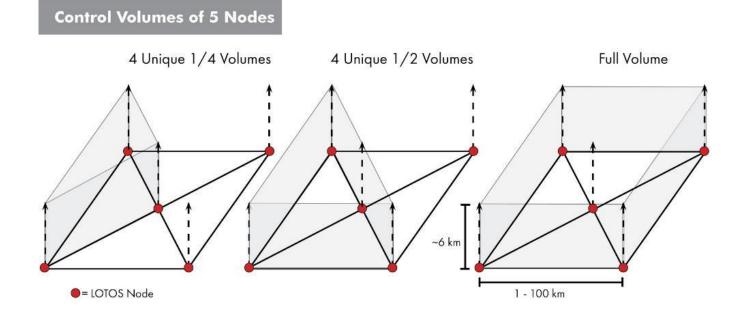
## **LOTOS Node Components**



### Vertical measurement ranges of the LOTOS sensors at each of the five nodes.

NST

## LOTOS: Why 5 Nodes?



Examples of various control volumes, as indicated by shading, that can be used with for determining mass and momentum budgets of different volumes.

**3-Nodes minimum:** A key measurement to determine entrainment velocity,  $w_e$  is the convergence or divergence of the air within the volume from the surface to the top of the PBL.

3-nodes involves determining small differences between larger wind speeds and thus has large relative uncertainties.

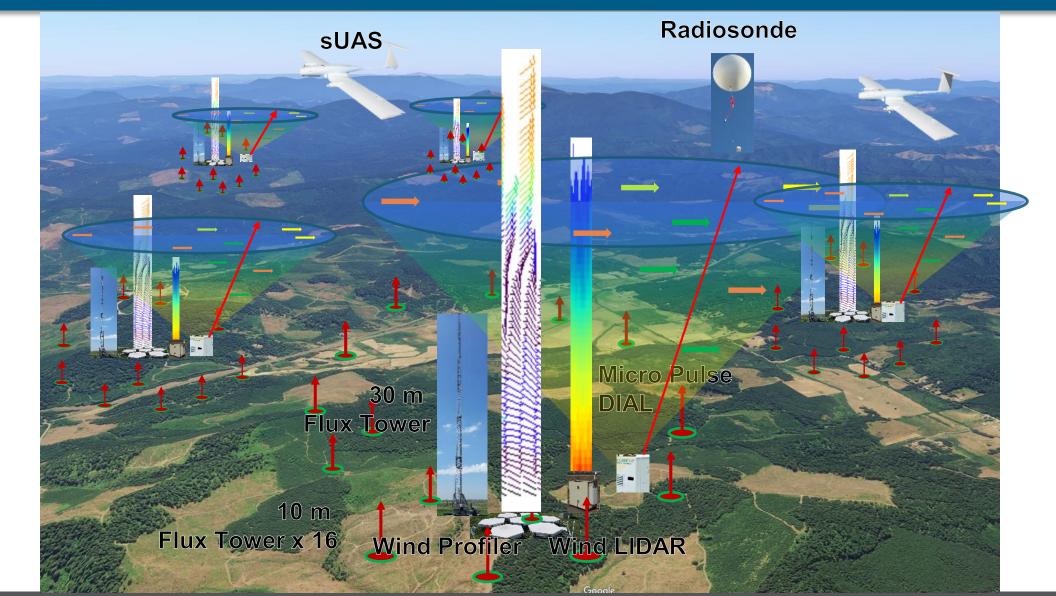
**4-Nodes:** A fourth profile enables checking the convergence calculation with four sub-volumes.

**5-Nodes:** Eight sub-volumes are possible with a total of five profiles.





## **LOTOS: Future of Complex Terrain Observations**

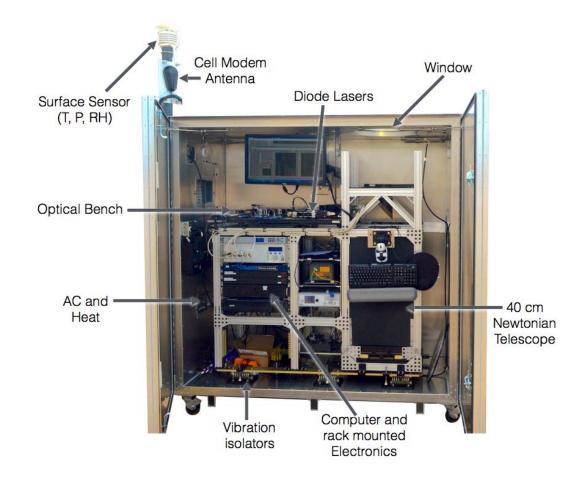






# **LOTOS Profiling: Water Vapor & Temperature**

## **MPD Development**



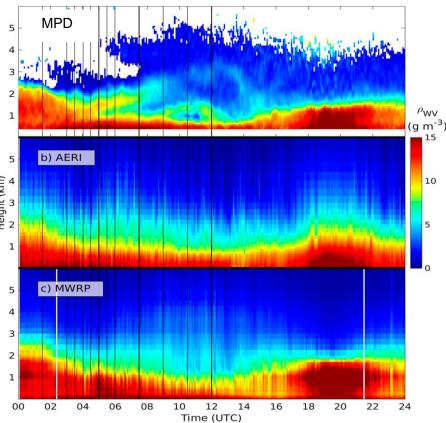
- Two tunable wavelengths (Near IR: 828 nm)
- Water Vapor Micro-Pulse DIAL (MPD) for measuring vertical profiles of water vapor up to 3-5 km AGL
- Network of five MPDs current testing in U.S. Southern Great Plains
- Calibrated aerosol addition via HSRL (780 nm)
- Efforts toward temperature MPD (770 nm)
- Low power eye safe



# LOTOS Profiling: MPD

#### Radiosonde-MPD **AERI-MPD** comparisons between 300 m and 5 km, total r = 0.78895 comparing with 90 sondes, mostly at night 30231 data points R=0.95 R=0.79 0.3-5 km 0.3-3 km 30231 pts 90 sondes total r = 0.94819 0.3-0.5km: r + 0.89800 . 295 data paint 0.5-1.0km: r = 0.82673 . 626 data point 0-1.5km r = 0.95996 . Salt data not 5-2.0km r + 0.79042 , 619 data pol 0.3-0.5km r = 0.75106 . 4123 data points 2.0.2 Service 0.77753 616 data resid 0.5-1km: r = 0.75063 , 11627 data points 2.5-3.0km; r = 0.84208 . 515 data poi 1-1.5km: r = 0.66848 . 7794 data points 3.0-3.5hm r = 0.26251, 580 data point 1.5-2km: r = 0.59408 , 3879 data points 3.5-4.0km: r = 0.72822 , 499 data point 2-2.5km: r = 0.33101 , 2808 data points 4.0-4.5km: r + 0.68400 , 299 data point 2.5-3km; r = 0.30916 . 2506 data poin 45.5 (free / a 0.23513 250 date online (m) 4 Sonde molecules/cm AERI (molecules/cm<sup>3</sup>)

Weckwerth, Weber, Turner and Spuler, 2016, *J. Atmos. Oceanic Technol.* 



- Excellent comparisons with radiosondes, MWRP, AERI and GPS receivers providing PWV
- Elevated layers of moisture observed by MPD but not by passive remote sensing systems

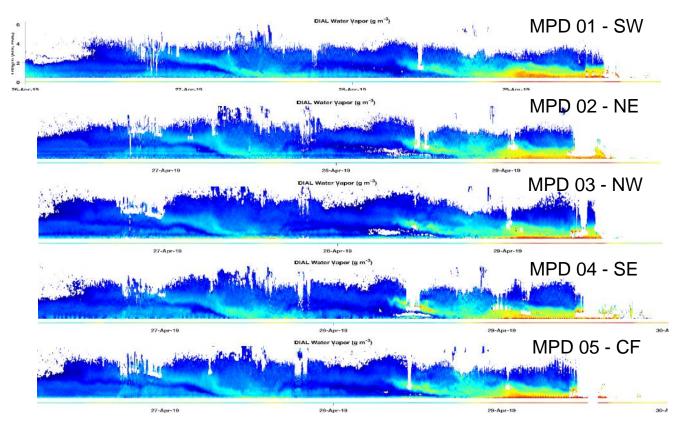
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### **MPD** Validation

# LOTOS Profiling: MPD

- Network of Five MPDs at DOE/ARM/SGP
- Water vapor concentration at 150 m vertical and 5 min temporal resolution
- From 300 m to 3-5 km (or cloud base) in day, night and cloudy conditions



- MPD Network Demonstration at DOE/ARM/SGP sites
- 22 April 19 July 2019

### Courtesy Scott Spuler (EOL)

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- 26-30 April 2019
- Consistent WV pattern

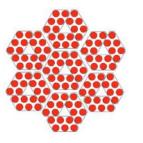
- Descending moist layer
- Development of CBL

# **LOTOS Vertical Profiling: Wind**

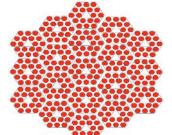
- NCAR/EOL developed radar wind profiler
- Operates at 449 MHz (other frequency options are also proposed)
- Spaced antenna for rapid wind measurement
- Modular design enables scalability and flexibility



Boundary Layer Configuration 3 antenna modules Range: 150 m – 4 km Resolution: 30 - 100 m



Mid Troposphere Configuration 7 antenna modules Range: 200 m – 7 km Resolution: 50 - 200 m



Full Troposphere Configuration 19 antenna modules

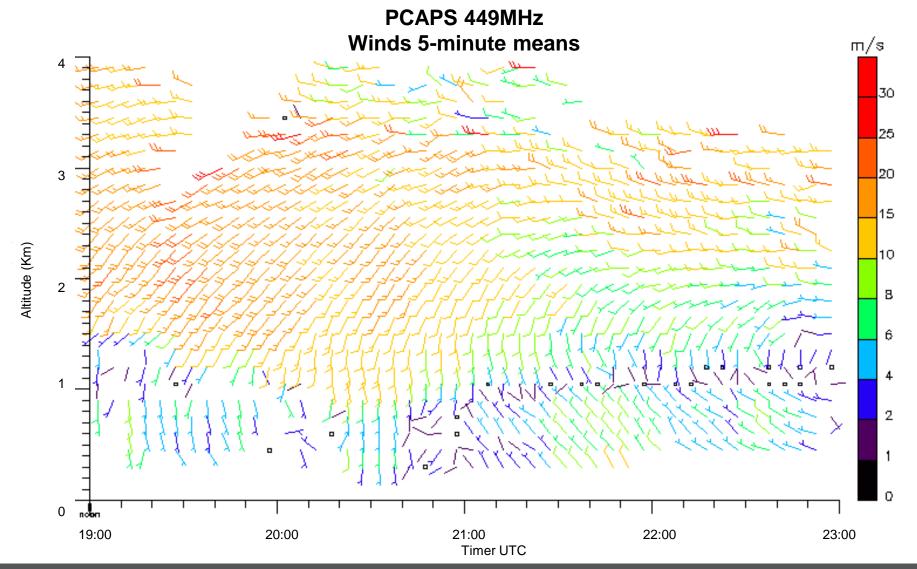








## **LOTOS Vertical Profiling: Wind**





## NCAR EOL LOTOS Team

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### Co - Science PIs:

Dr. Steve Oncley – Leads the Integrated Surface Flux System Dr. Tammy Weckwerth – Leads the MPD Science, GPS WP, AERI-I

#### Science/Technical Team:

Dr. Britt Stephens – Surface Chemistry Dr. Bill Brown – Wind Profiling/Ceilometer/Sounding Systems Dr. Scott Spuler – MicroPulse DIAL Dr. Mike Dixon – Software Engineer Gary Granger – Software Engineer

Management

Dr. Vanda Grubišić – NCAR Associate Director & Director of EOL Dr. Wen-Chau Lee – RSF Manager





