The Parallel Implementation of the full resolution SBAS-DINSAR processing chain for surface deformation analysis in extended urban areas

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Outline

✓ Exploited algorithm

- Full Resolution Parallel Small BAseline Subset (FR P-SBAS) DInSAR algorithm

✓ Proposed approach

- Full exploitation of Big SAR Data archives
- Automatic FR P-SBAS chain for large SAR data stacks processing
- Deployment of FR P-SBAS solution on Cloud/HPC architectures

✓ Future perspective

- Mapping the ground displacements at national scale with COSMO-SkyMed
- Integration of FR P-SBAS results for large scale damage assessment analyses





The FR P-SBAS DInSAR algorithm

- An advanced Differential Interferometry Synthetic Aperture RADAR (DInSAR) algorithm to retrieve deformation time-series and velocity maps both in natural and anthropic hazard scenarios (i.e., seismic events, volcanic unrest, landslides, urban areas and single man-made structures).
- Small Baseline interferometric pairs are only considered in order to minimize the noise effects and maximize the number of detectable (coherent) measure points.
- Full Resolution Interferograms are exploited to retrieve temporal and spatial characteristics of detected displacements at full spatial resolution scale (about 3-10 m).





The Small BAseline Subset (SBAS) DInSAR approach



The Small BAseline Subset (SBAS) DInSAR approach



The Full Resolution SBAS technique: multi-scale approach



Lanari et al., 2004, IEEE Trans. Geosci. Rem Sens. Bonano et al., 2012, Int. Jour. Remote Sensing.





The Full Resolution SBAS technique: main applications



The Full Resolution SBAS technique: main applications



The Full Resolution P-SBAS algorithm: block diagram

- FR-SBAS deals with low and full resolution interferograms. FR-SBAS processing starts with the retrieval of the residual interferometric phase by subtracting modulo- 2π the low resolution phase from the full resolution one.
- The residual interferometric phase is then processed to estimate the linear phase components:
 - Mean deformation velocity, v(x,r)
 - Residual topography, $\Delta z(x, r)$
 - Azimuthal position, $\Delta x(x, r)$
 - Thermal dilation coefficient, K(x, r)
- Once the linear components are filtered out from residual phase, the non-linear deformation phase $\beta(x, r)$ is finally retrieved.
- Last step carries out the combination of v and β deformation components with the corresponding low resolution ones to retrieve the full resolution signals.





The Full Resolution P-SBAS algorithm: block diagram



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The Full Resolution SBAS-DInSAR analysis: a Big Data challenge



Parallel hardware architectures based on **GPU** and **multi-core** processing





The FR SBAS technique: sequential implementation



The FR SBAS technique: sequential implementation

	Area of Roma		
	Area [km ²]	40x40	
TOP DE LA LERE ALEXA DE LE	#Images	129	
A AND AND AND AND AND AND AND AND AND AN	Sensor	CSK	
	Spatial Resolution [m]	3x3	
	Time span	03/2011 – 03/2019	
	#Pixels	21000x15000 (> 300 M)	
	#Interf	392	
~ 3000 hours (120 days) for the sequential processing			

3000 hours (120 days) for the sequential processing (1 single processing node) of the full frame!!!





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Full exploitation of large SAR data archives

Computing Resources & Data Proximity:

Availability of distributed HPC

infrastructures and data proximity



Efficient Processing Tools:

Development of parallel algorithms for HPC

platforms to cut down the processing times







Implemented Computing Architecture



- ✓ All working nodes are controlled by a single Master Node
- The working nodes are connected with each other via NFS and acts as client and server at same time
- High I/O performance is obtained thanks to dedicated storage volumes shared among the nodes
- ✓ Final results are transferred to a long-term persistent storage

NFS-based distributed storage implementation designed to minimize the I/O and data transfer overhead





The Parallel Full Resolution P-SBAS algorithm: block diagram





The Full Resolution P-SBAS: parallel implementation

	Area of Roma	
	Area [km ²]	40x40
TOTAL VILLANDER STORAGE STORAGE	#Images	129
A CALLER AND AND AND A CALLER	Sensor	CSK
	Spatial Resolution [m]	3x3
	Time span	03/2011 – 03/2019
	#Pixels	21000x15000 (> 300 M)
	#Interf	392

~ 12 hours for a parallel processing solution (4 GPU and 25 CPU cores) of the full frame!!!





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Sequential vs. Parallel FR SBAS processing chain: computing time for linear phase components estimation (step B)





processing time [hours]





Ascending orbits Time span: 03/2011 - 03/2019 129 acquisitions Descending orbits Time span: 07/2011 - 03/2019 107 acquisitions





The A90-A91 Roma-Fiumicino Highway





The A90-A91 Roma-Fiumicino Highway







The A90-A91 Roma-Fiumicino Highway



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Displacement [cm] 0 - 2 - 4 - 9 - 10 - 12 - 14

-16 -18



The Fiera di Roma area





The Fiera di Roma area





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The Fiera di Roma area



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Gasometer, Ostiense railstation and Via Giustiniano Imperatore



The Gasometer







<-1

>1



Ostiense railstation







Ostiense railstation



[cm/year]



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<-1

>1



Via Giustiniano Imperatore





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The FR P-SBAS results: the case study of Rome (Italy) Descending orbits: Fiumicino airport







Descending orbits: Fiumicino airport



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Future perspective

- ✓ Mapping the whole Italian territory by exploiting the full CSK data archive
- ✓ Integration of the FR P-SBAS measurements with structural models (FEM, semi-empirical, etc) for large scale damage assessment analyses
- ✓ Exploration of Big Data and AI approaches for advanced remote sensing and data interpretation methods





Thank you!





