

# A NEW AND EFFICIENT PROCEDURE FOR DISPERSIVE TSUNAMI SIMULATIONS ON SPHERICAL COORDINATES BASED ON A HYPERBOLIC APPROACH

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**Goal:** Efficient model implementations for tsunami propagation and coastal-type computations.

## Requirements:

- **Simple** models as the hydrostatic Shallow water equations (SW).
- Accounting for **dispersive** effects: Stokes - Airy theory

$$Celerity_{Airy}^2 = gH \frac{\tanh(kH)}{kH}.$$

Hydrostatic Shallow Water equations:

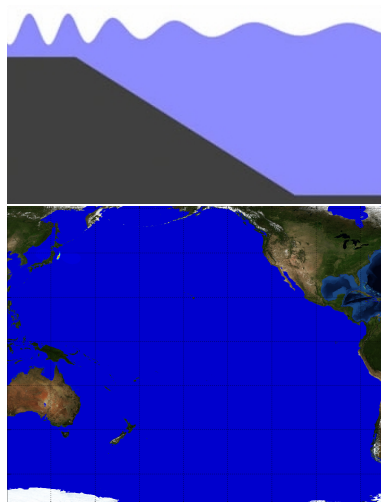
$$Celerity_{SW}^2 = gH - \text{Inaccurate.}$$

$k$  : wave-number,  $H$  : typical depth.

- *Faster Than Real Time (FTRT)*:

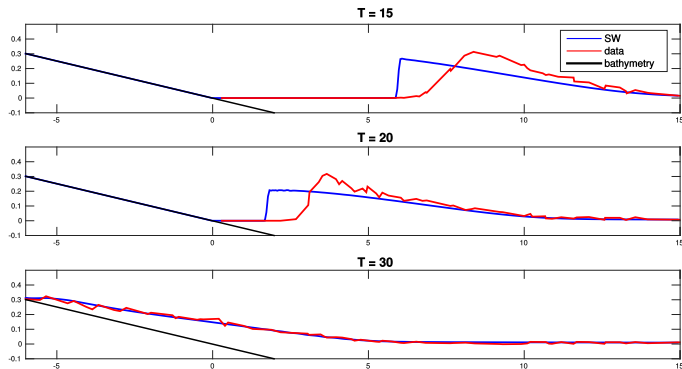
**Tsunami-HySEA:** [▶ Link](#)

- FTRT multi-GPU SW solver
- Hydrostatic - non dispersive
- Aim: include dispersive effects



# Shallow water -non dispersive- results<sup>1</sup>

Solitary wave on a beach, Synolakis, 1987.



▷ Hydrostatic models, such as SW, do not take into account dispersive effects:  
**Wrong propagation speed. Inaccurate arrival amplitude and time of the wave**

<sup>1</sup>J. Macías, M.J. Castro, S. Ortega, C. Escalante, and J.M. González-Vida. “Performance Benchmarking of Tsunami-HySEA Model for NTHMP’s Inundation Mapping Activities”. In: *Pure and Applied Geophysics* 174.8 (2017), pp. 3147–3183.

## Dispersive models

- ▷ Two prominent families of systems for the simulation of dispersive water waves:

### Boussinesq type:

- Boussinesq (1872)
- Peregrine (1967)
- Madsen (1992)
- Lynett (2002,2006,2019)
- Usually contains **high-order derivatives** in the final model
- Unaffordable complexity for 2D domains.

### Non-hydrostatic pressure:

- Casulli *et al* (1995)
- **Bristeau** *et al* (2008)
- **Yamazaki** *et al* (2009) (NEOWAVE code)
- Fernández-Nieto *et al* (2017)
- First order systems
- Simple systems

**Non-hydrostatic** solvers are capable of solving many relevant features of coastal water waves such as:

- Dispersive water waves **propagation**
- **Shoaling**
- Non-linearities
- Refraction
- **Run-up**
- **Run-down**

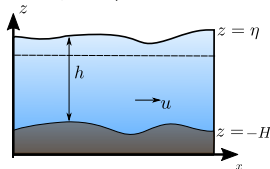


# Non-Hydrostatic pressure model

1D domain equations. Bristeau *et al*, 2008.

$$\left\{ \begin{array}{l} \partial_t h + \partial_x(hu) = 0, \\ \partial_t(hu) + \partial_x \left( hu^2 + \frac{1}{2}gh^2 + hp \right) = (gh + \gamma p) \partial_x H, \\ \partial_t(hw) + \partial_x(uhw) = \gamma p, \\ \partial_x u + \frac{w - w_b}{h/2} = 0, \quad w_b = -\partial_t H - u\partial_x H \end{array} \right.$$

- Improved **dispersion** relation valid from **intermediate** to **shallow-waters**
- For  $\gamma = 2$ , the model is similar to Yamazaki *et al* system (NEOWAVE code)
- For  $\gamma = 3/2$ , the model reduces to the Green-Naghdi system



$$C_{NH}^2 = gH \frac{1}{1 + \frac{1}{2\gamma} (kH)^2}.$$

We choose  $\gamma = 2$ .

# Non-Hydrostatic implementation. Escalante, Castro and Morales<sup>1</sup>

▷ Numerical implementation of the previous system.

## Pros:

- Efficiently solved for 2D domains on **GPU** (Escalante *et al* 2018<sup>1</sup>). Hybrid finite-volume finite-difference 2<sup>nd</sup> order scheme.
- **Computational cost:** 2 times more expensive than a **one-GPU hydrostatic Shallow Water solver**.

## Cons:

- The system is **not hyperbolic** and the numerical scheme involves the solution of **linear systems**
- The computational cost increases for **high-order** schemes
- Not amenable for simple **multi-GPU** implementations

▷ The **difficulties** arise from the imposition of the divergence condition:

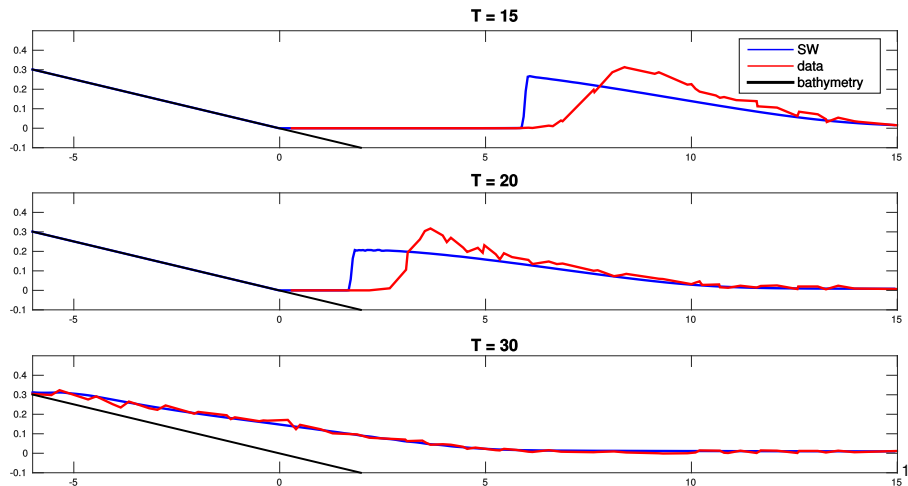
$$\partial_x u + \frac{w - w_b}{h/2} = 0, \quad w_b = -\partial_t H - u \partial_x H.$$

▷ That will lead to developing implicit numerical schemes. Otherwise, a quite restrictive time-step CFL condition must be considered. The same difficulties arise for Boussinesq-type systems.

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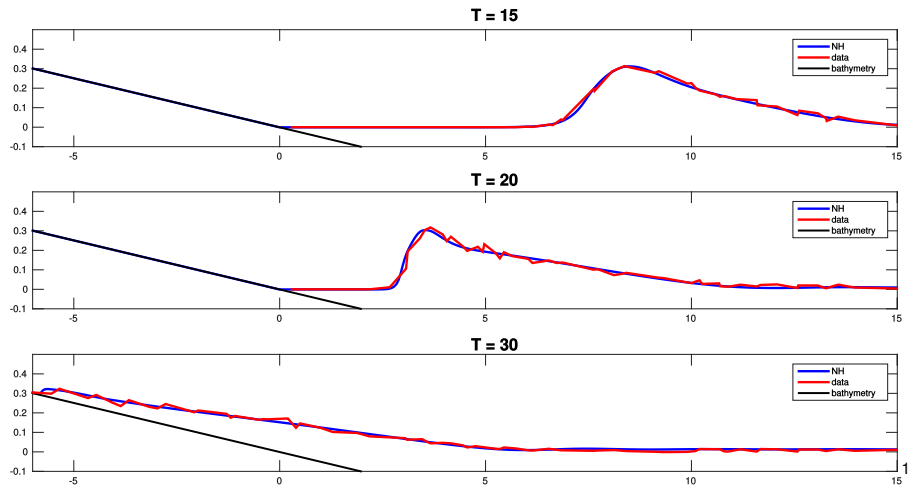
<sup>1</sup>C. Escalante, T. Morales, and M.J. Castro. “Non-Hydrostatic Pressure Shallow Flows: GPU Implementation Using Finite Volume and Finite Difference Scheme”. In: *Applied Mathematics and Computation* 338 (2018), pp. 631–659.

# Solitary wave on a plane beach. Hydrostatic approach - SW



<sup>1</sup>“Performance assessment of the Tsunami-HySEA model for NTHMP tsunami currents benchmarking. Laboratory data”. In: *Coastal Engineering* 158 (2020), p. 103667. ISSN: 0378-3839. DOI: <https://doi.org/10.1016/j.coastaleng.2020.103667>.

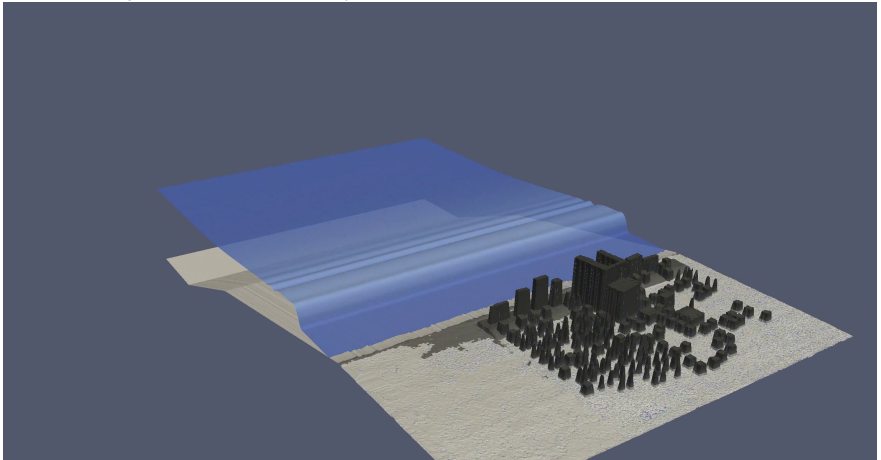
# Solitary wave on a plane beach. Non-hydrostatic approach



<sup>1</sup>C. Escalante, T. Morales, and M.J. Castro. "Non-Hydrostatic Pressure Shallow Flows: GPU Implementation Using Finite Volume and Finite Difference Scheme". In: *Applied Mathematics and Computation* 338 (2018), pp. 631–659.

# Solitary wave impinging on a small-scale model of Seaside, Oregon<sup>1</sup>

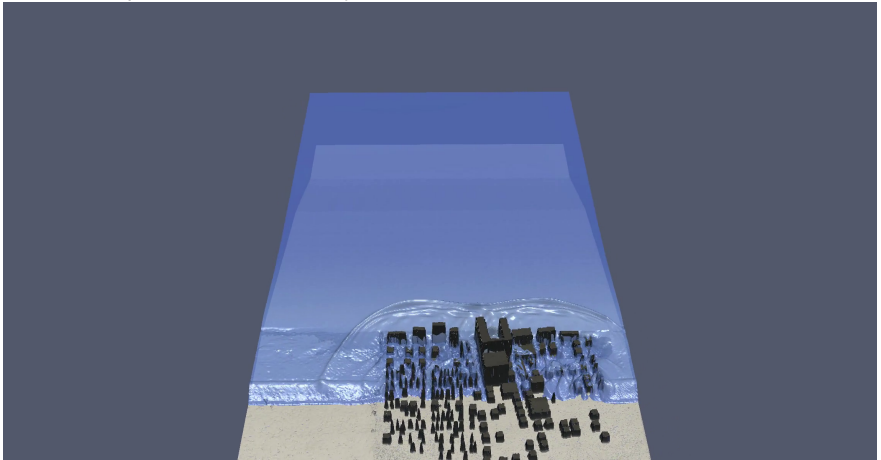
▷ Benchmark problem. 2<sup>nd</sup> order hybrid finite-volume finite-difference scheme



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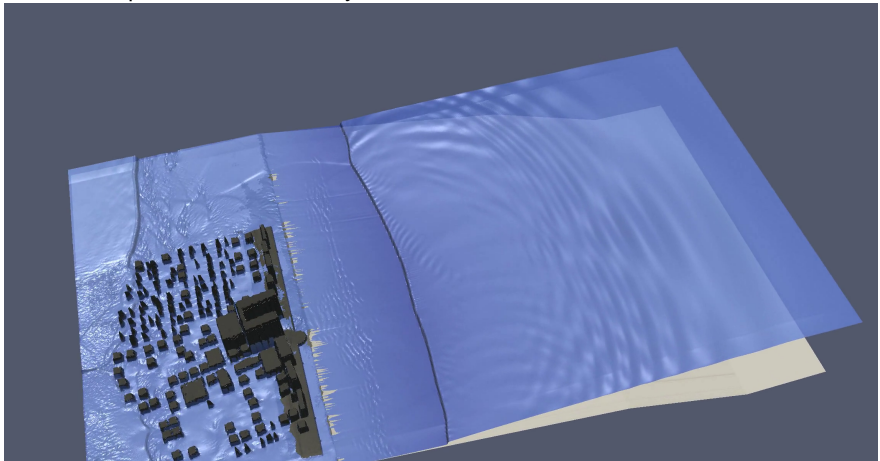
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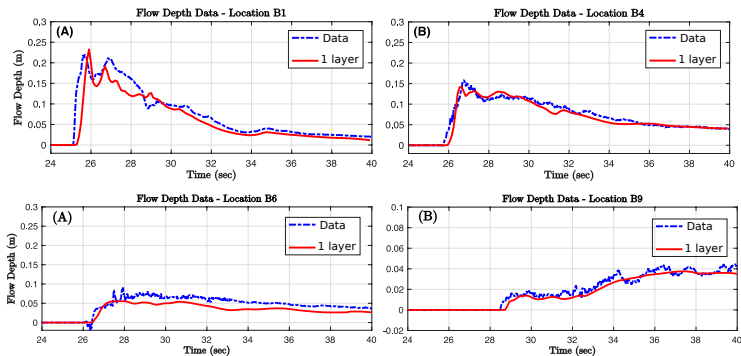
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# Solitary wave impinging on a small-scale model of Seaside, Oregon<sup>1</sup>

- ▷ Benchmark problem. 2<sup>nd</sup> order hybrid finite-volume finite-difference scheme



- ▷ **Computational time:** 2-3 times slower than a one-GPU SW simulation.

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# A novel hyperbolic relaxation non-hydrostatic pressure system<sup>1</sup>

- A more efficient approach is developed in Escalante, Castro and Dumbser, 2019<sup>1</sup>. The **key idea** is to replace the divergence condition:

$$\partial_x u + \frac{w - w_b}{h/2} = 0, \quad w_b = -\partial_t H - u \partial_x H.$$

by the relaxed equation:

$$\partial_t(hp) + \partial_x(uhp) + hc^2 \left( \partial_x u + \frac{w - w_b}{h/2} \right) = 0, \quad w_b = -\partial_t H - u \partial_x H.$$

- Here, divergence errors are transported with a wave speed  $c = \alpha \sqrt{gH_0}$ ,  $H_0$  being the typical depth.
- The resulting system is **hyperbolic** and the time-step CFL condition is similar to the SW system:

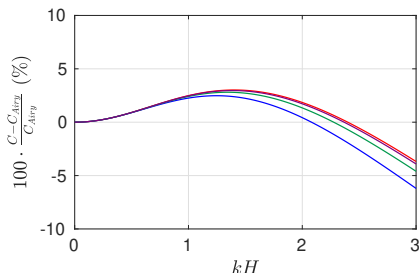
$$\Delta t \leq \frac{\Delta x}{\lambda_{\max}}, \quad \lambda_{\max} = |u| + \sqrt{gh + p + c^2}.$$

<sup>1</sup>C. Escalante, M. Dumbser, and M.J. Castro. “An efficient hyperbolic relaxation system for dispersive non-hydrostatic water waves and its solution with high order discontinuous Galerkin schemes”. In: *Journal of Computational Physics* 394 (2019), pp. 385–416. ISSN: 0021-9991.

# A novel hyperbolic relaxation non-hydrostatic pressure system<sup>1</sup>

## Pros:

- The system is **hyperbolic**:  
No need of solving linear systems
- Can be discretized by any efficient **high-order** and **explicit** numerical scheme.
- Simple and straightforward **multi-GPU** implementations
- Preserves the **dispersion relation** from the original non-hyperbolic system
- The same model recovers hydrostatic results (**classical SW equations**) by setting  $\alpha = 0$ .



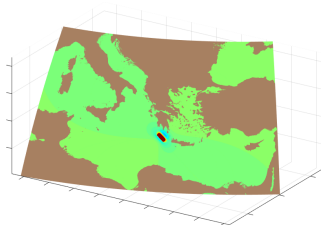
Relative error of the phase velocity with respect to the Airy theory for different values of the relaxation parameter:  $\alpha = 3, 5, 10$  given in blue, green and magenta respectively. **In practice we choose  $\alpha = 3$ .**

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# Real-world Tsunami simulations

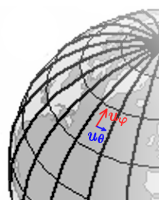
- The 2D implementation of the non-hyperbolic non-hydrostatic pressure system,
- and the 2D implementation of the hyperbolic non-hydrostatic pressure system,

may suffer the lack of **Earth-curvature** effects for simulations on bigger scenarios.



To account for curvature effects:

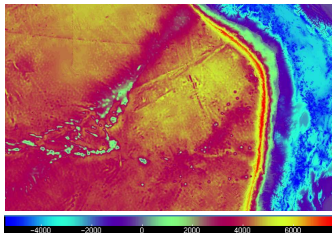
- We consider the non-hydrostatic pressure formulation for spherical coordinates,
- similar to the one given for the NEOWAVE code (Yamazaki *et al*, 2010).
- Then, we propose a similar hyperbolic approach technique to relax the divergence constraint, and obtaining a **hyperbolic model**.



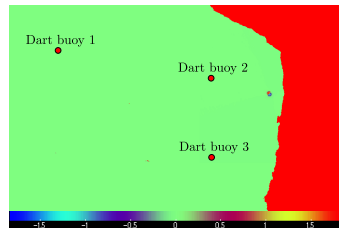
# The 2014 Iquique earthquake. Comparison with NEOWAVE

The real test case to solve using a one-GPU implementation

- The domain: west coast of northern Chile. Grid resolution: 1 arc-min.
- Size:  $2880 \times 1800 = 5184000$  cells.
- Wall clock to be simulated: 10000 seconds  $\approx$  2 hours 45 minutes.
- We are interested in compare the Green's functions obtained in a subfault of  $20 \times 20$  km size (corresponding to the 2014 Iquique earthquake) time series provided by **Dart buoys** in 3 locations against the computed numerical simulations from the new hyperbolic **non-hydrostatic model**.



Bathymetry

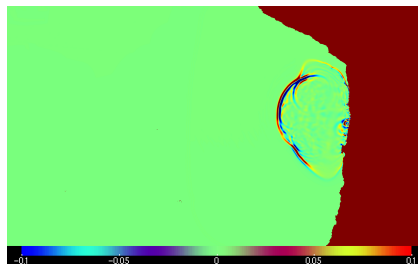


Free-surface initial cond. Dart buoys loc.

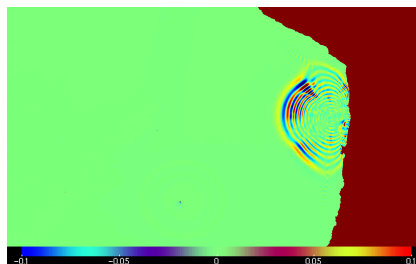
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- Hydrostatic SW simulation:  $\alpha = 0$
- Non-hydrostatic simulation:  $\alpha = 3$
- Numerical scheme: Finite-Volume  
 $3^{rd}$  order TVD Runge-Kutta in time and  $3^{rd}$  order CWENO in space.



Free-surface at time 1500 s.  
 Hydrostatic **SW** simulation ( $\alpha = 0$ .)

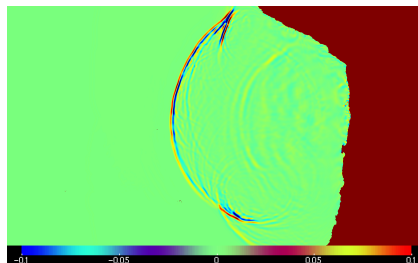


Free-surface at time 1500 s.  
**Non-Hydrostatic hyperbolic** simulation  
 ( $\alpha = 3$ .)

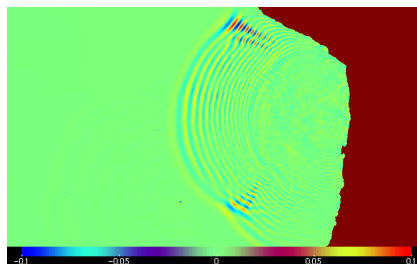
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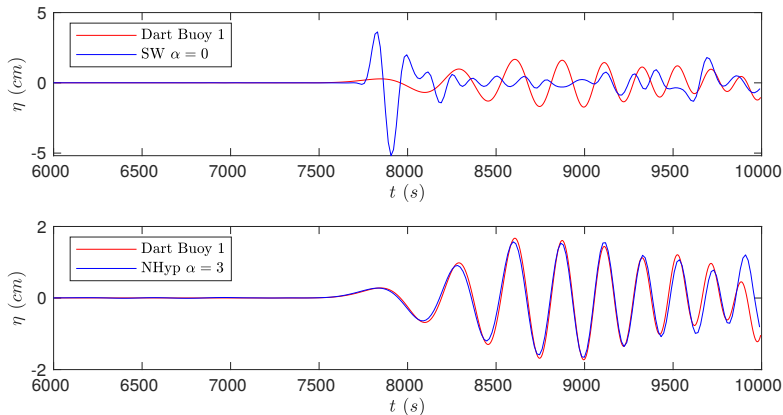


Free-surface at time 4500 s.  
 Hydrostatic **SW** simulation ( $\alpha = 0$ .)

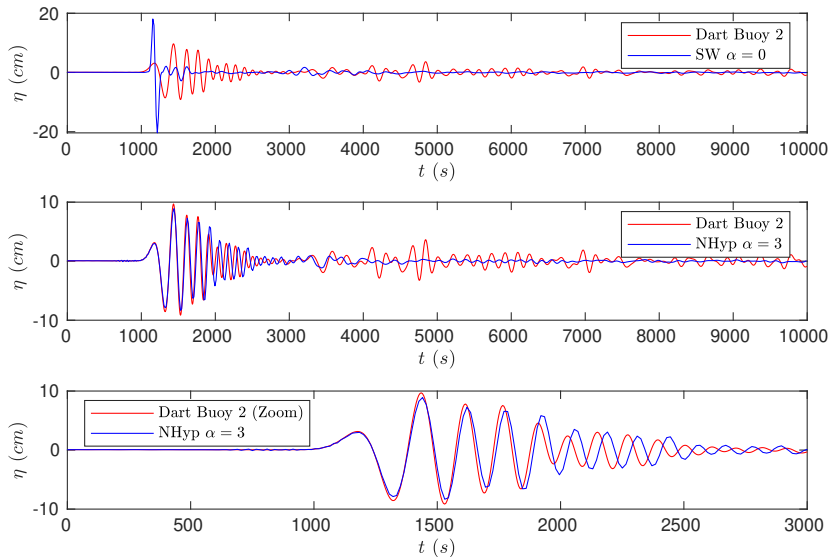


Free-surface at time 4500 s.  
**Non-Hydrostatic hyperbolic** simulation  
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# The 2014 Iquique earthquake Time series. Comparison with NEOWAVE

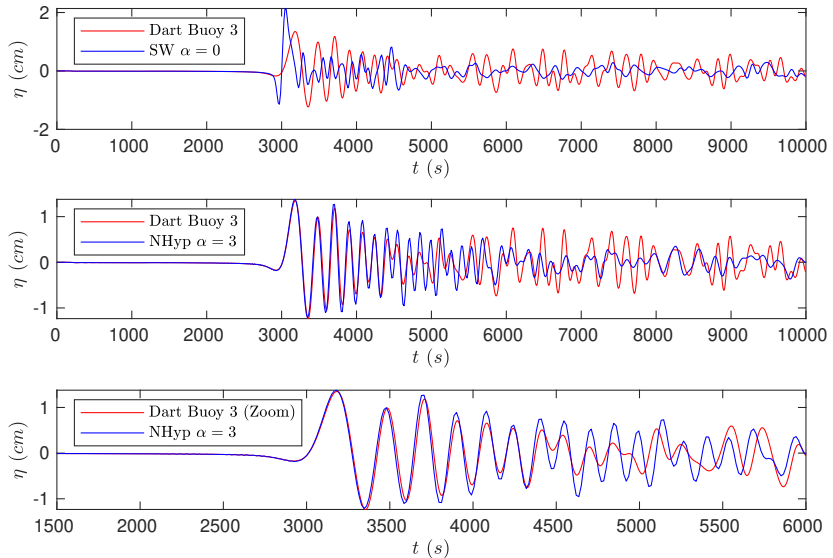


# The 2014 Iquique earthquake Time series. Comparison with NEOWAVE





# The 2014 Iquique earthquake Time series. Comparison with NEOWAVE



# The 2014 Iquique earthquake. Computational effort

Simulated time: 10000 s. Third order scheme

Model	Comput. time	# times FTRT
Hydrostatic SW ( $\alpha = 0$ )	659.29	15.17
Non-hydrostatic ( $\alpha = 3$ )	1271.92	7.86

- ▷ Ratio computational times Non-Hydrostatic/SW: 1.93.
- ▷ Computations performed with nVIDIA TESLA V100.

# Final comments

## Conclusions and perspectives

- Towards an operational **FTRT** dispersive approach.
- Model includes **dispersive** effects and **curvature** effects,
- and efficient numerical implementations can be proposed due to its **hyperbolic** nature.
- Dispersive effects without solving linear systems.
- Validation: simple geometries (lab) and complex real cases.
- Computational times: around **two times** slower than a **SW** model. Single-GPU.
- Nested meshes and multi-**GPU** implementations can be straightforwardly implemented (Future work).
- Coupling with **landslides** models (Ongoing work).