Are the flow dynamics of Jakobshavn Isbræ driven by calving?

Calving rate observations and modelling, 2009 to 2017



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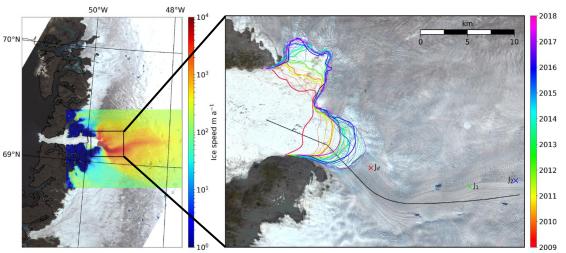




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1. Background

- Jakobshavn Isbrae has rapidly accelerated and retreated since the late 1990s, entering a phase of stability from ~2004 onwards.
- Further retreat from 2009, with maximum speeds attained in 2012 and 2013.
- Modest deceleration, readvance and thickening since 2016.



Velocity structure and smoothed quarterly calving fronts for Jakobshavn Isbræ. Background images from Landsat 8, August 9th 2016. Velocity from [1] (version 4). Calving fronts from [2], [3]. Thicker calving front denotes winter position.

Ice velocity of Jakobshavn Isbræ, Petermann Glacier, Nioghalvfjerdsfjorden, and Zachariæ Isstrøm, 2015–2017, from Sentinel 1-a/b SAR imagery

Adriano Lemos¹, Andrew Shepherd¹, Malcolm McMillan¹, Anna E. Hogg¹, Emma Hatton¹, and Ian Joughin²

Interruption of two decades of Jakobshavn Isbrae acceleration and thinning as regional ocean cools

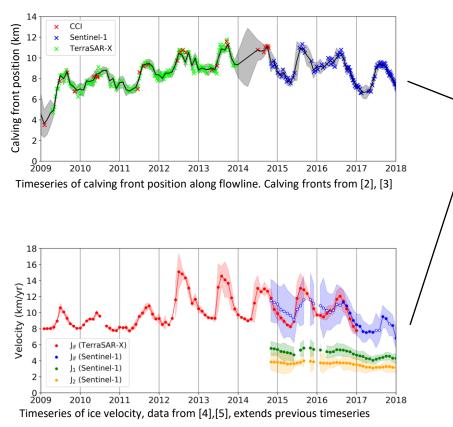
Ala Khazendar ©^{1*}, Ian G. Fenty ®¹, Dustin Carroll¹, Alex Gardner ^{®1}, Craig M. Lee², Ichiro Fukumori¹, Ou Wang¹, Hong Zhang¹, Hélène Seroussi ^{®1}, Delwyn Moller³, Brice P. Y. Noël⁴, Michiel R. van den Broeke ^{®4}, Steven Dinardo¹ and Josh Willis¹

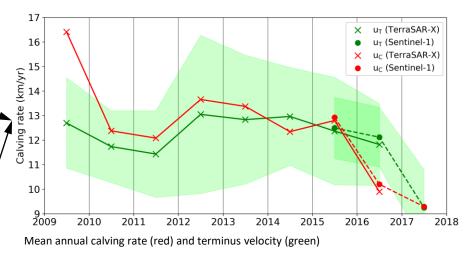




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2. Calving rate, 2009 to 2017





$$u_C = u_T - \partial L / \partial t$$

- Error bars on calculated mean annual calving rate are very wide! (not shown)
- Correlation between u_c and u_T for most years. Delayed deceleration from 2016 to 2017 following reduction in calving rate. Suggests influence of rate of calving on flow dynamics.
- Can we drive ice flow evolution by an applied calving rate?



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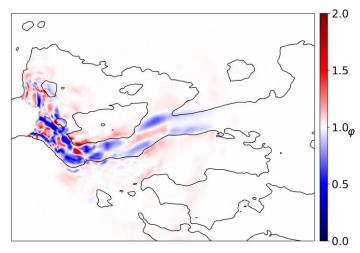


3. Transient ice sheet model initialisation in BISICLES^[6]

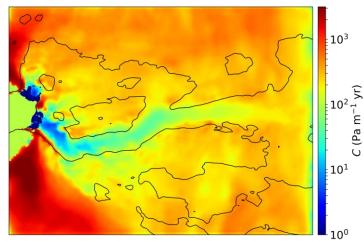
• Optimise fields for basal traction coefficient (C) and stiffening factor (φ) for by minimising an objective function^[7]:

$$J = \int_{\Omega} \alpha_u^2(x, y) (|\boldsymbol{u}| - |\boldsymbol{u}_o|)^2 \, \mathrm{d}\Omega + \alpha_C \int_{\Omega} |\nabla C|^2 \, \mathrm{d}\Omega + \alpha_{\varphi} \int_{\Omega} |\nabla \varphi|^2 \, \mathrm{d}\Omega$$

- C and φ input fields produced for individual quarterly periods from 2009 to 2017, by applying additional transient regularisation to suppress high frequency temporal variation.
- The resulting fields will be used as inputs for the forward modelling run.



Inverted ice stiffening factor, Q1 2009. Vertically-integrated effective viscosity: $\varphi h\bar{\mu}$



Inverted basal friction coefficient, Q1 2009. Sliding law: $au_b = -Coldsymbol{u}$

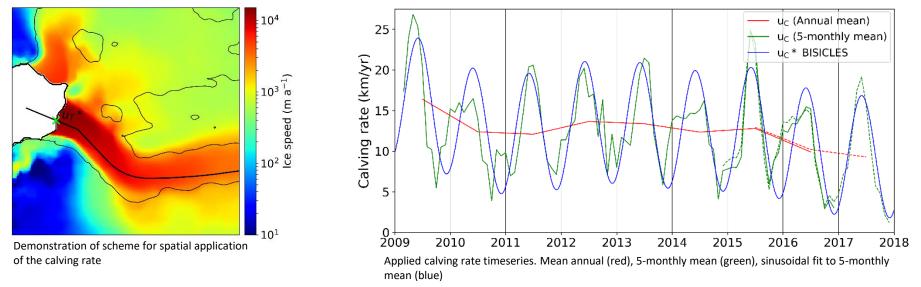


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4. Calving rate application in BISICLES



• Spatial application of calving rate scaled according to the terminus velocity to avoid destroying regions of slower-flowing ice (* = measured on flowline):

$$\boldsymbol{u}_{C}(x,y) = \boldsymbol{u}_{C}^{*} \cdot \frac{\boldsymbol{u}_{T}(x,y)}{\boldsymbol{u}_{T}^{*}}$$

• Calving rate applied either annually or as a seasonal sin-wave oscillating about the annual mean



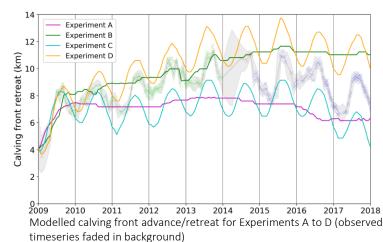
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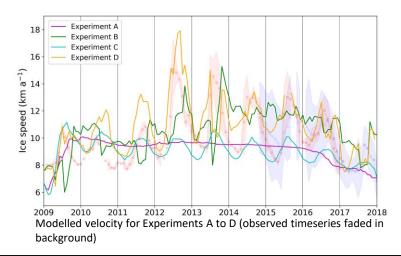


5. Decadal forward model runs

- 9 year forward model runs carried out 2009 2017.
- Experiments run for combinations of annual mean or sin-wave calving rate, and static or timeseries basal friction and ice rheology.
- Results compared to observations.
- BedMachine v3^[9] bathymetry and initial ice topography.
- Thinning rates from [10].
- Surface mass balance from RACMO ^[11].

Experiment	$oldsymbol{arphi}$ and $oldsymbol{\mathcal{C}}$ inputs	Calving rate
А	Long-term mean	Annual mean
В	Quarterly timeseries	Annual mean
С	Long-term mean	Sin wave
D	Quarterly timeseries	Sin wave







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6. Conclusions

- By applying a prescribed calving rate, we are giving the model half the picture.
- Model evolution broadly follows the observed decadal pattern when applying the annual mean calving rate model flow adjusts well to the calving.
- Applying a quarterly timeseries of basal friction and ice rheology inputs improves the fit.
- Applying a seasonal oscillation in calving reproduces the annual advance-retreat cycle well.
- Our experiments neatly bracket the observed calving front position.

References

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