



Ambient seismic noise suppression in COST action G2Net

Velimir Ilić - Mathematical Institute of the Serbian Academy of Sciences and Arts, Serbia

Alessandro Bertolini - National Institute for Subatomic Physics, Netherlands

Fabio Bonsignorio - Heron Robots, Italy

Dario Jozinović - Istituto Nazionale di Geofisica e Vulcanologia (INGV), Italy

Tomasz Bulik - Astronomical Observatory, University of Warsaw, Poland

Ivan Štajduhar - University of Rijeka, Faculty of Engineering, Croatia

Iulian Secrieru - Institute of Mathematics and Computer Science, Moldova

Soumen Koley - National Institute for Subatomic Physics, Netherlands



CA17137 : A network for Gravitational Waves, Geophysics and Machine Learning



- WG1 Machine Learning for Gravitational Wave astronomy
- WG 2 Machine Learning for low-frequency seismic measurement
- WG3 Machine Learning for Advanced Control techniques

<https://www.cost.eu/actions/CA17137/#tabs|Name:overview>

<https://www.g2net.eu/>



WG 2: Machine learning for low-frequency seismic measurement

Led by Velimir Ilic
and Christopher Zerafa

velimir.ilic@gmail.com
christopher.zerafa.08@um.edu.mt

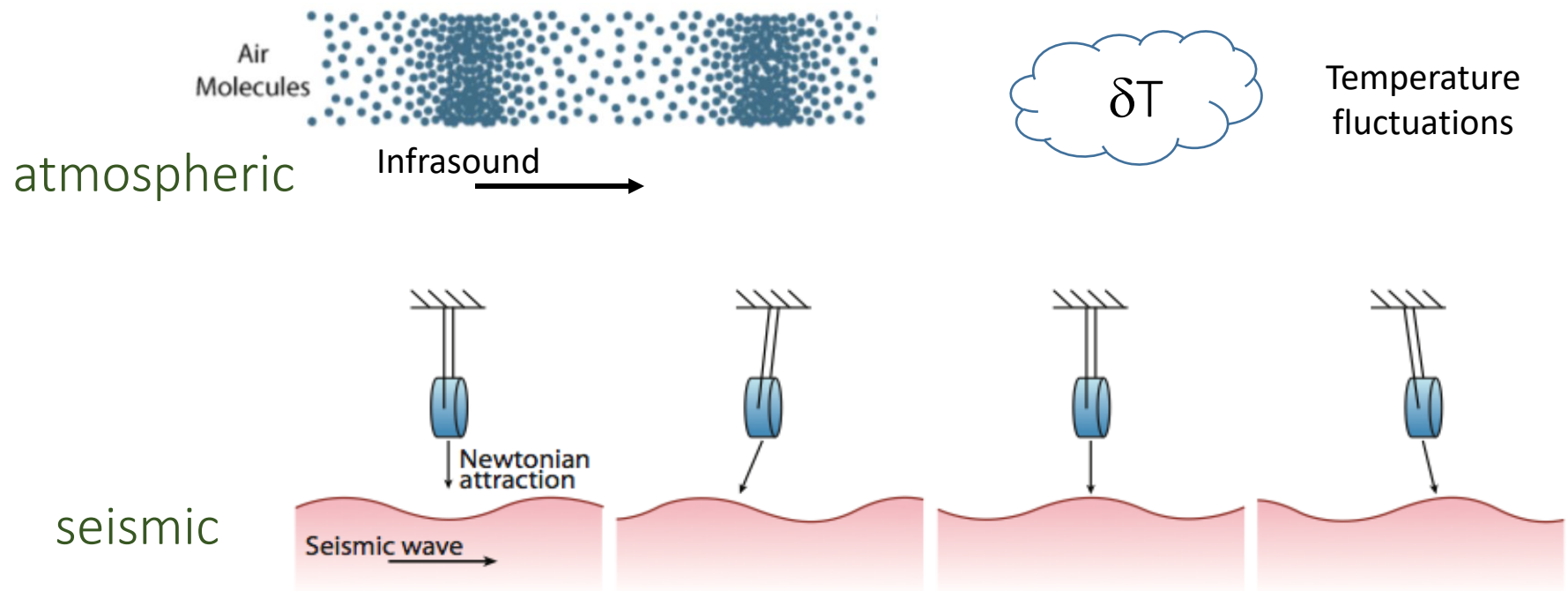
Abstract

The performance of Earth-based GW detectors is largely influenced by the ability of combating the low-frequency ambient seismic noise and other seismic influences. These tasks require multidisciplinary research in the fields of seismic sensing, signal processing, robotics, machine learning and mathematical modeling.

The working group 2, deals with acquisition, processing and interpretation of seismic data, with the goal of combating the seismic influences at GW detector site, using the multidisciplinary research, with a focus on advanced techniques available from state of the art machine learning algorithms.

WG 2 focus

Newtonian noise on GW detectors



Gravitational coupling between the mirrors and surrounding mass density fluctuations

WG 2 objectives

Bringing the NN challenge to a new level by involving expertise outside GW physics

ML techniques for seismic field modeling
and NN field reconstruction:
-wave propagation characteristics
-noise stationarity and time evolution
-design of optimized sensor arrays

Robotics for adaptive arrays of environmental sensors

Complementary to WG3



WG 2 objectives

Interdisciplinary research topics
(check out CA17137 Memorandum of Understanding):

Seismology:

- earthquake waveforms, seismic array interferometry, Newtonian noise analysis

Signal processing:

- match-filtering, Wiener filtering, deconvolution

Mathematical modeling:

- Bayesian analysis, Markov chains, Fokker-Planck and Langevine equations

Machine learning for robotics:

- deep learning, reinforcement learning, Belief space planning

Gravitational waves detection:

- instrumentation, hardware and data processing



WG 2 Tasks

WG 2 is structured in several tasks

1. Applied mathematics for seismology
2. Optimized sensor arrays
3. Mobile networks of environmental sensors
4. Machine learning for seismology

More info: <https://www.g2net.eu/wgs/WG 2-machine-learning-for-low-frequency-seismic-measurement>

Equipment



Quantum by INNOSEIS (a spin-out from the National Institute for Subatomic Physics in the Netherlands) is an ultra-light weight ($< 1\text{kg}$) wireless seismic sensor network that dramatically reduces deployment costs, while scaling up to 1 million nodes for onshore exploration. It has been designed for static Wireless, sensor networks. However, a daisy-chain small network is operating in Cascina already and no major issues prevent to mount them on mobile platforms.

Info:

Alessandro BERTOLINI

NIKHEF, Netherlands, Amsterdam

alberto@nikhef.nl

Info:

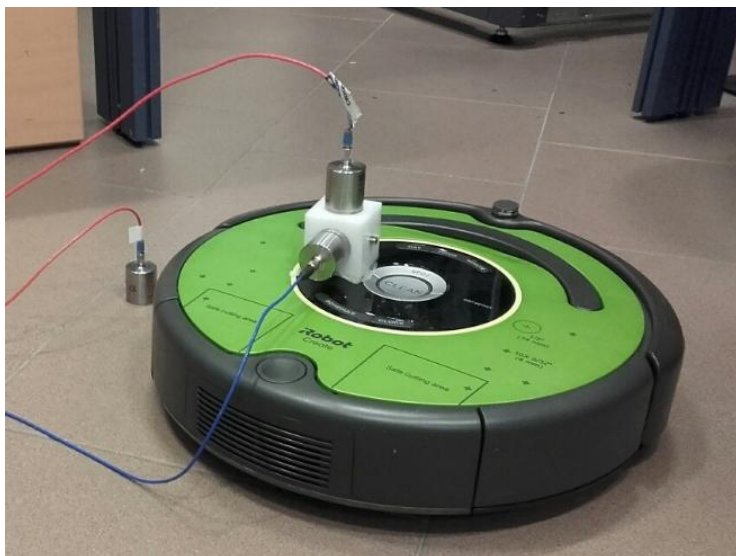
Soumen KOLEY

NIKHEF, Netherlands, Amsterdam

skoley@nikhef.nl

Equipment

Testing Platform:
A Multisensory Multiagent platform
for GW detection and Geophysics applications



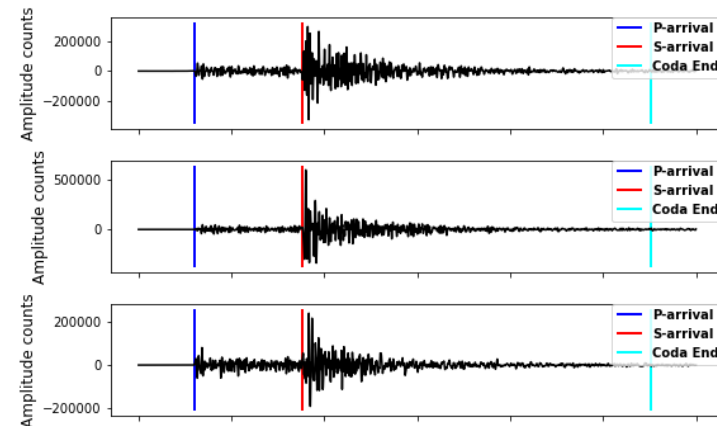
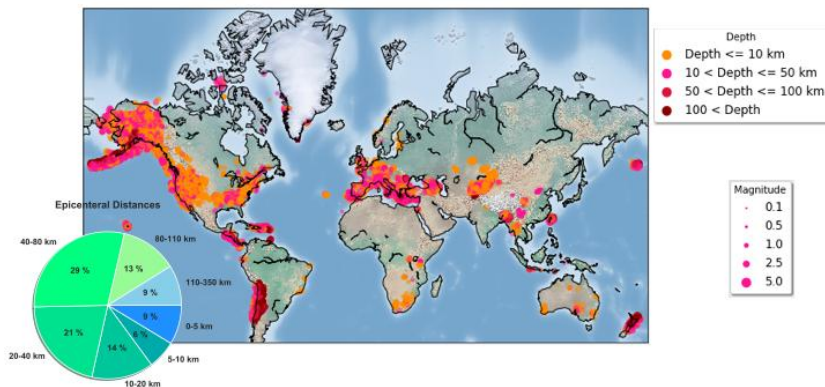
Info:
Fabio BONSIGNORIO
Heron Robots srl, Italy, Genova
fabio.bonsignorio@santannapisa.it

Configuration number	Description	Sketch drawing
1	One Vertical accelerometer on Roomba, one Vertical accelerometer on ground	
2	One Horizontal accelerometer on Roomba, one Vertical accelerometer on ground	
3	As n.1 but added extra weight (1kg) on the Roomba	
4	As n.2 but added extra weight (1kg) on the Roomba	
5	One Vertical accelerometer on Roomba left side, one Vertical accelerometer on Roomba right side.	
6	As n.1 but placing the Roomba onto 3 rigid tips	
7	As n.5 but placing the Roomba onto 3 rigid tips	

STSM outcomes

STanford Earthquake Dataset (STEAD): A Global Data Set of Seismic Signals for AI

1.2 M Labeled Waveform. **450 k** Earthquakes. **19,000** Hours of Data.



Contact:

Christopher ZERAFA

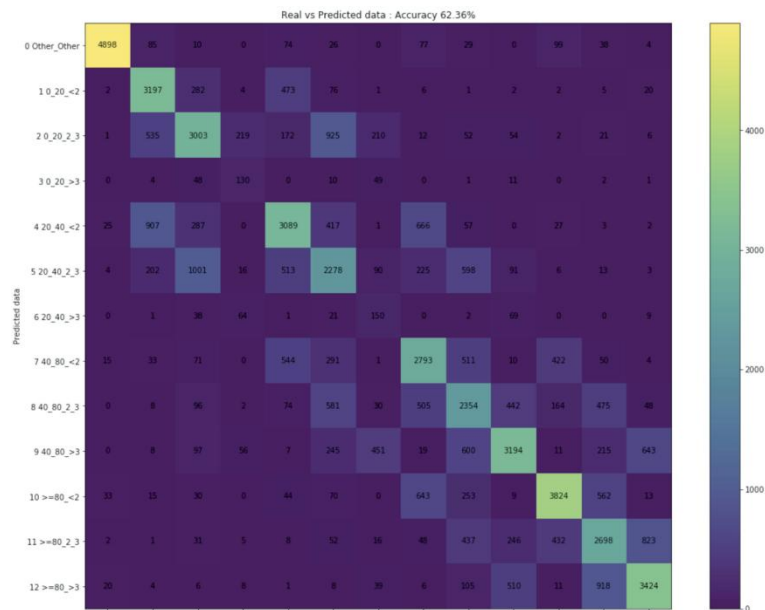
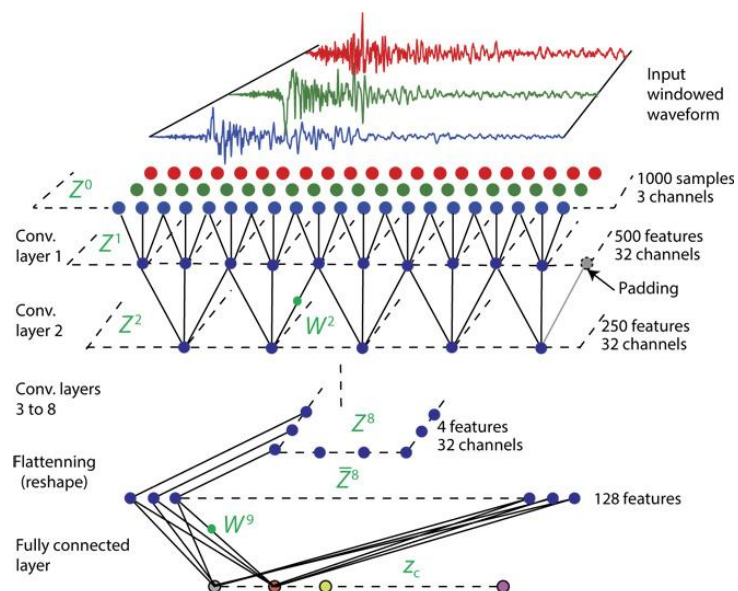
University of Malta

christopher.zerafa.08@um.edu.mt

13 classes:

Noise, Distance and Magnitude
combination

STSM outcomes



Contact:
Christopher ZERAFA
University of Malta
christopher.zerafa.08@um.edu.mt

- Initial results
- Noise nearly 100% correct
- Sample of data
- Large magnitude (>3) more inaccuracies due to low accuracies
- 62% accuracy



STSM outcomes

- Investigating the utility of different time-frequency representations for characterization of earthquakes.
- Detection and characterization of seismic waveforms using machine learning
- Exploration of different machine learning techniques and data transformations which help in achieving the goal above
- Rapid ground motion prediction at a site from multi-station waveforms using machine learning

Contact:

Ivan ŠTAJDUHAR

University of Rijeka, Croatia

istajduh@riteh.hr

Contact:

Dario JOZINOVIC

INGV, Italy

djozinovi@gmail.com



Thank you for your attention! Contact us!

WG 2 is still growing!

Feel free to contact us via the links and addresses below.

Website:

<https://www.g2net.eu/wgs/WG-2-machine-learning-for-low-frequency-seismic-measurement>

Mailing list: wg2-g2net@ego-gw.it

WG 2 leader:

Velimir ILIĆ

Mathematical Institute SASA, Serbia

velimir.ilic@gmail.com

WG 2 co-leader:

Christopher ZERAFA

University of Malta, Malta

christopher.zerafa.08@um.edu.mt