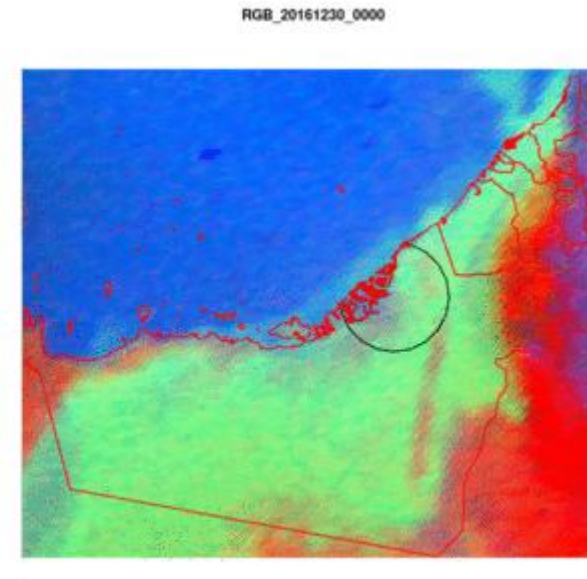


# Application of night time fog detection method using MSG810 SEVIRI in an arid environment



# Application of night time fog detection method using MSG810 SEVIRI in an arid environment

**Michael Weston and Dr. Marouane Temimi**

Department of Civil Infrastructure and Environmental Engineering, Khalifa University of Science and Technology, Abu Dhabi

michael.weston@ku.ac.ae



جامعة خليفة  
Khalifa University  
Abu Dhabi  
United Arab Emirates  
www.ku.ac.ae

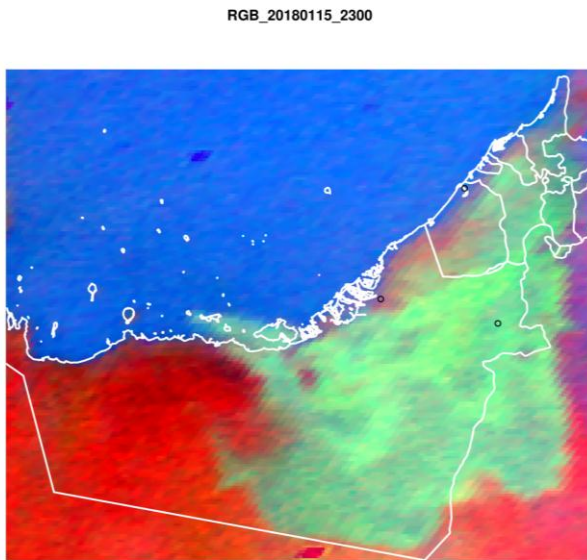


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Geosciences  
Union  
Online  
4-8 May 2020

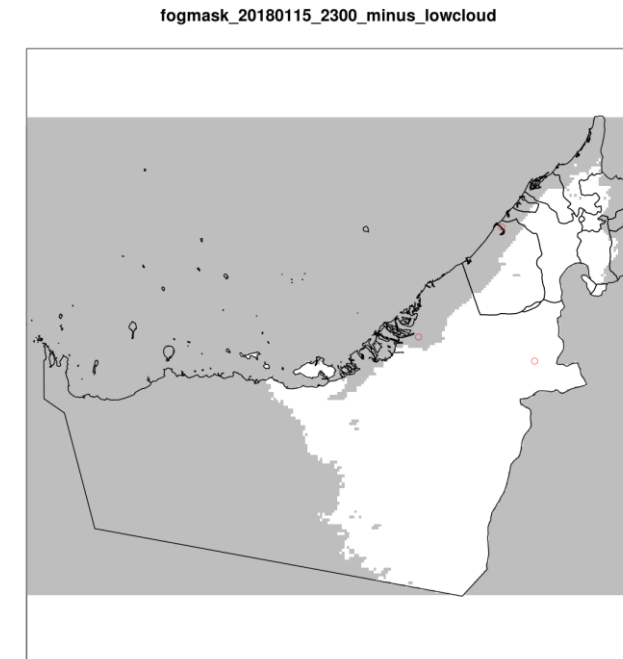
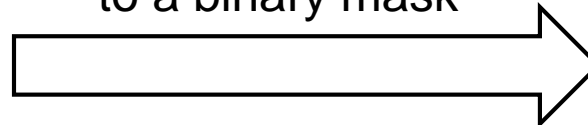
# Introduction

The detection of fog and low cloud (FLC) from satellite data remains challenging despite advances in methodologies and technology.

Here we apply the **pseudo emissivity** method (ems(3.9) after Pavolonis and Heidinger, 2005) using the **SEVIRI** instrument on **Meteosat-10** over the United Arab Emirates, and desert region.



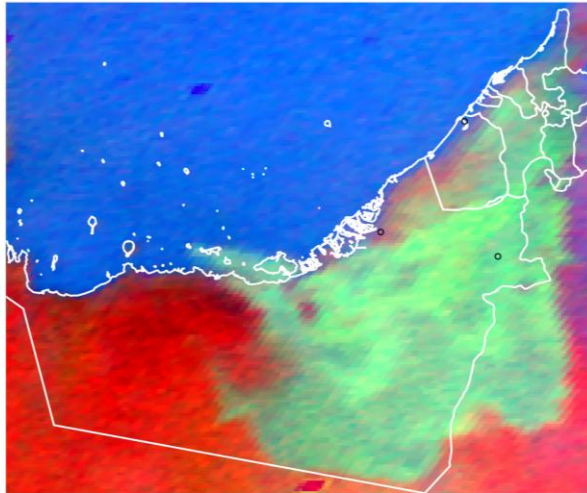
Go from raw satellite data  
to a binary mask



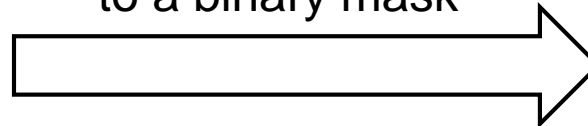
# Objectives

- Provide spatial frequency of fog days
- Identify areas of fog onset
- Understand fog dynamics

RGB\_20180115\_2300



Go from raw satellite data  
to a binary mask

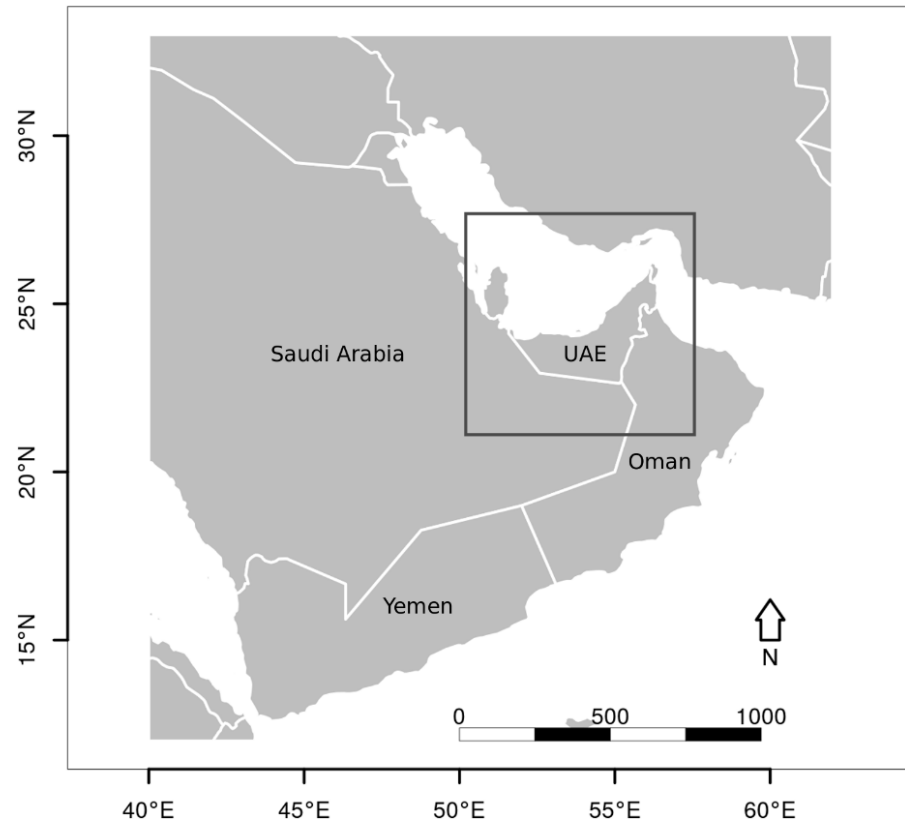


fogmask\_20180115\_2300\_minus\_lowcloud

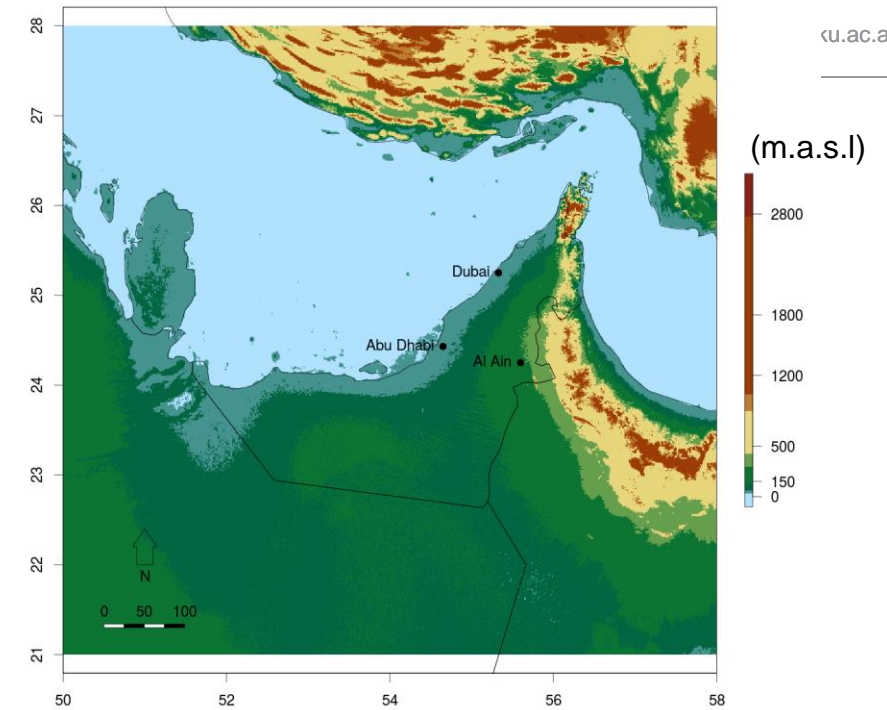


# Study Area

## United Arab Emirates

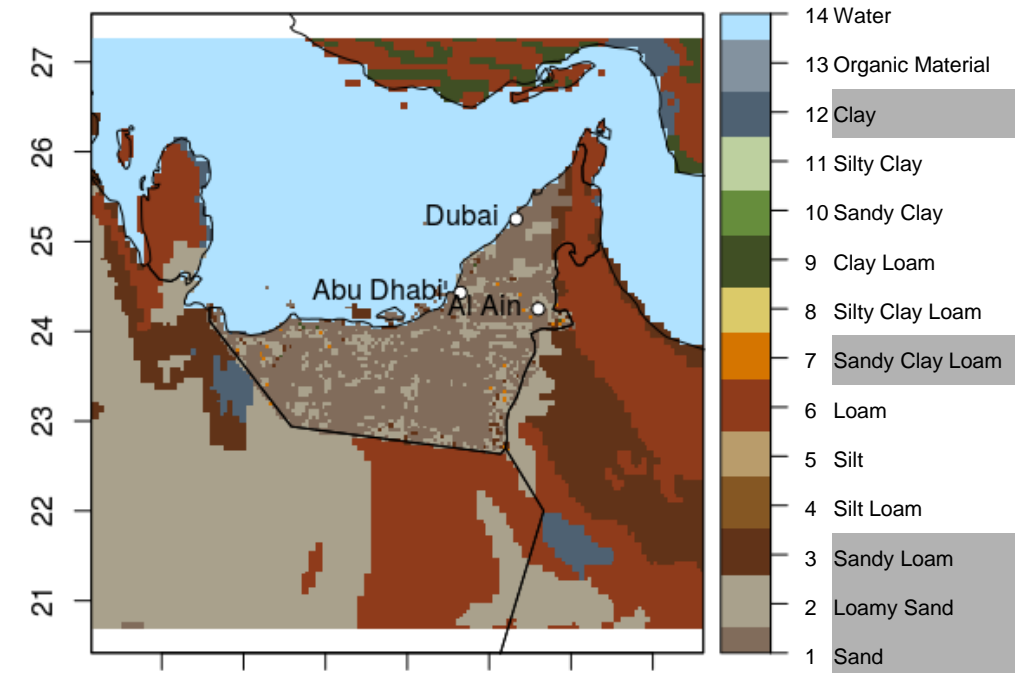


### Terrain



### Soil type

USGS  
+  
Abu Dhabi  
Survey



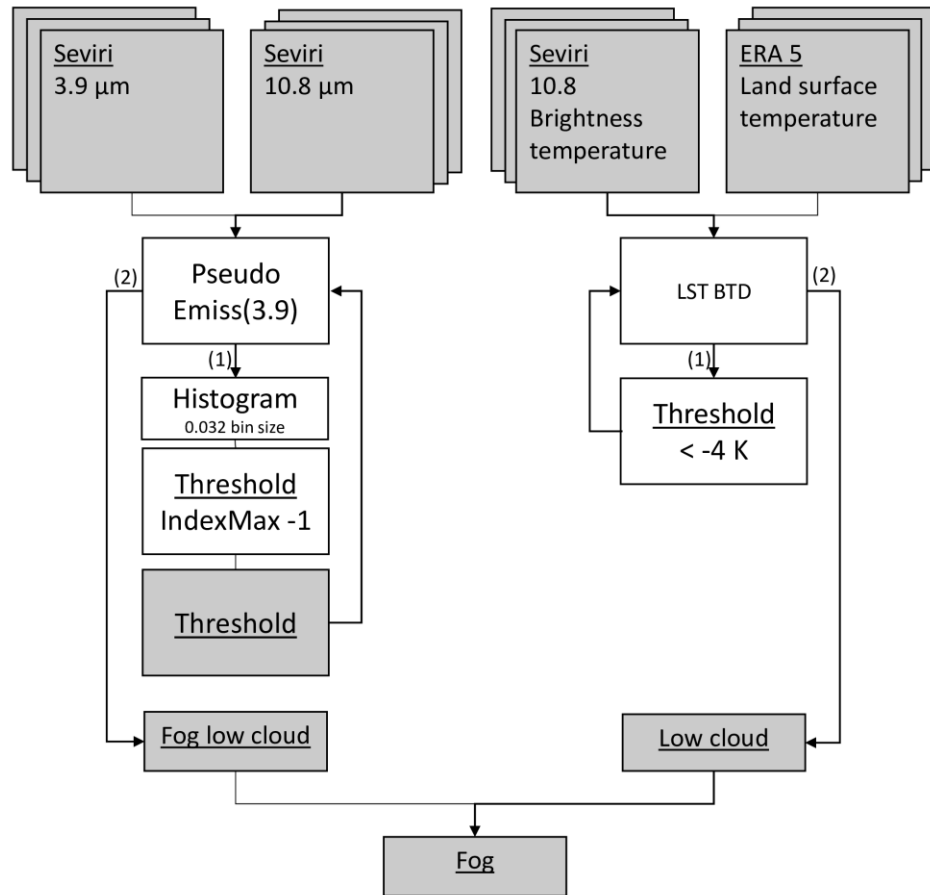
## Data sets

- **SEVIRI**
  - Meteosat-10 situated over 9.5 °E
  - Resolution ~3 km
- **ERA5**
  - Global atmospheric reanalysis product
  - Resolution around 30 km
- **METAR (Meteorological aerodrome reports)**
  - NOAA National Climatic Data Center (NCDC) database
  - Data from three stations:
    - Abu Dhabi (OMAA, 54.65N, 24.43E),
    - Dubai (OMDB, 55.33N, 25.25E)
    - Al Ain (OMAL, 55.60N, 24.25E).

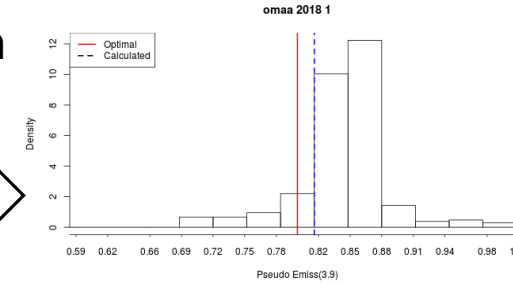
## Study period

- **Winter months over two seasons**
  - Dec 2016 to Mar 2017
  - Oct 2017 to Mar 2018

# Methodology overview

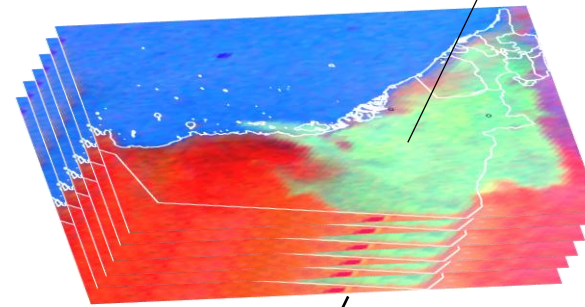
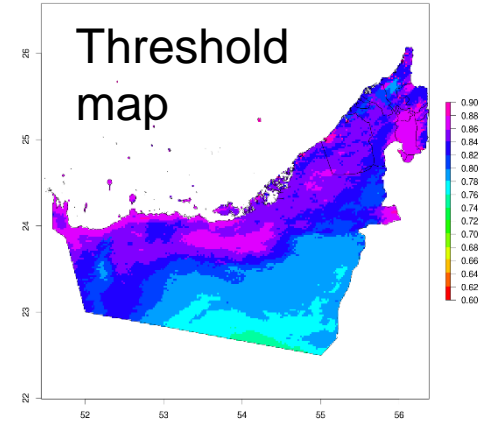


Histogram per pixel

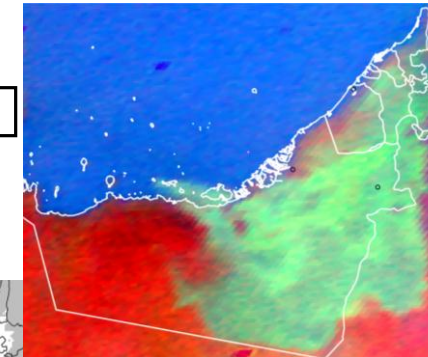


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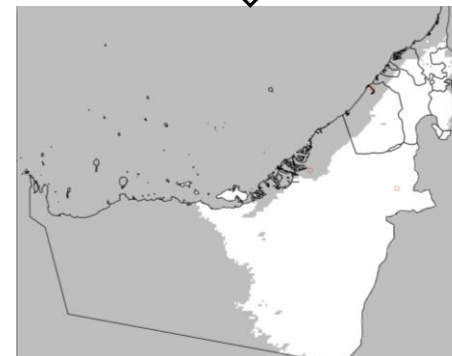
Threshold 201703  
Pseudo Emiss(3.9)  
Elf Rad wavenumber



Remove low cloud (ERA5)



Apply to scene



# Fog/low cloud detection

Pseudo emissivity was calculated using equation (1) (Calvert and Pavolonis, 2010).

$$ems(3.9) = \frac{R_{Obs}(3.9)}{B(3.9, BT(10.8))}, \quad (1)$$

$R_{Obs}$  = radiance at 3.9 $\mu$ m observed

BT = brightness temperature at 10.8 $\mu$ m

B = Planck function

Planck function defined in equation (2) (Cao and Shao, 2019).

$$B(\nu, t) = \frac{C_1 \nu^3}{e^{C_2/\nu} - 1}, \quad (2)$$

$B(\nu, t)$  = blackbody radiance (mW/m<sup>2</sup> -sr-cm<sup>-1</sup>),

$C_1 = 1.19104 \times 10^{-5}$  (mW/m<sup>2</sup> -sr-cm<sup>-4</sup>),

$C_2 = 1.43877 \times 10$  (K cm),

$\nu$  = wavenumber (cm<sup>-1</sup>),

$\lambda$  = wavelength ( $\mu$ m) and

$t$  = blackbody temperature (K).

# Verification

## Contingency table

	METAR fog yes	METAR fog no
SEVIRI fog yes	Hits	False Alarms
SEVIRI fog no	Misses	Correct Negative

$$POD = \frac{\text{Total hits}}{\text{Total hits} + \text{total misses}},$$

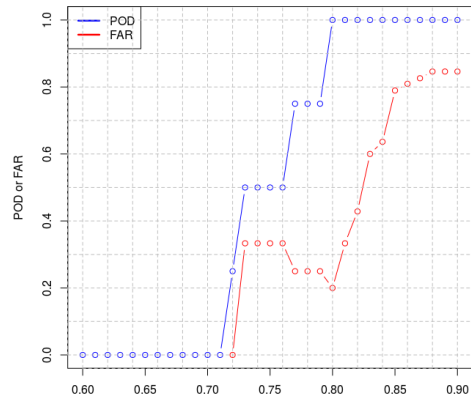
$$FAR = \frac{\text{Total false alarms}}{\text{Total hits} + \text{total false alarms}},$$

- Verification is performed over a **6 hour window from 00h00 to 06h00** local time
- Time when **fog is most frequent**
- The aim is to **assess daily fog** frequency

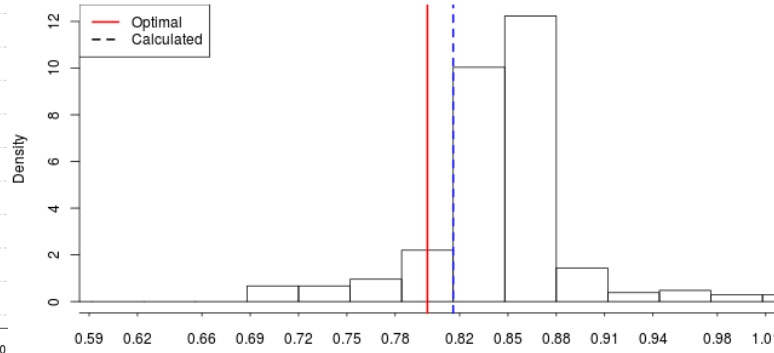
# Histograms

(after Cermak and Bendix, 2008)

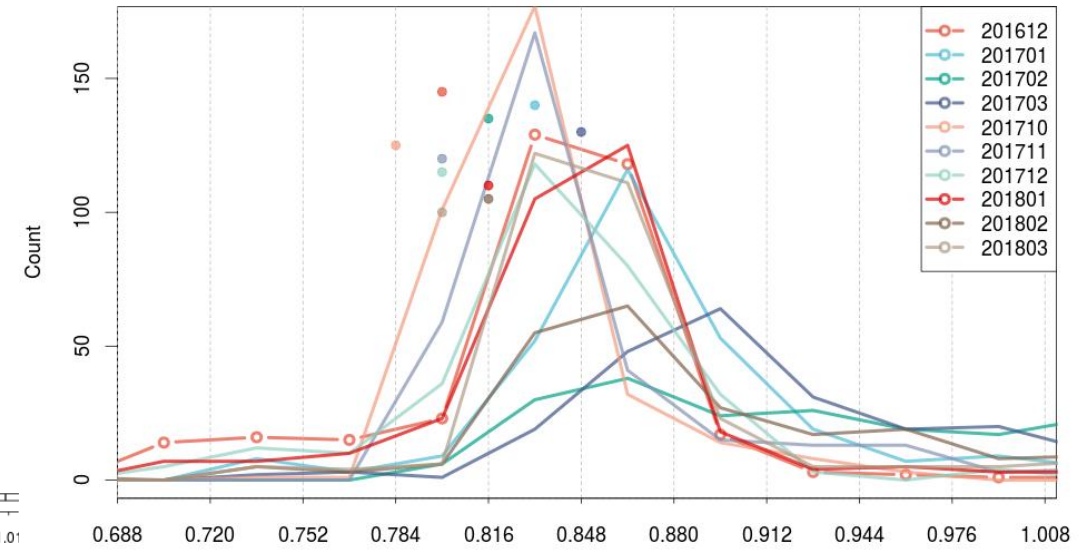
OMAA 2018 1



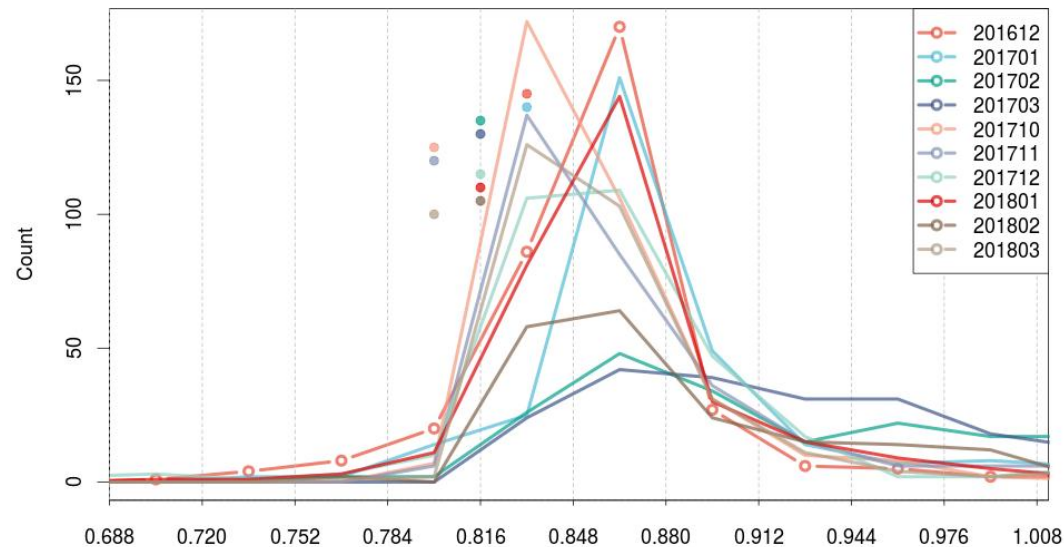
omaa 2018 1



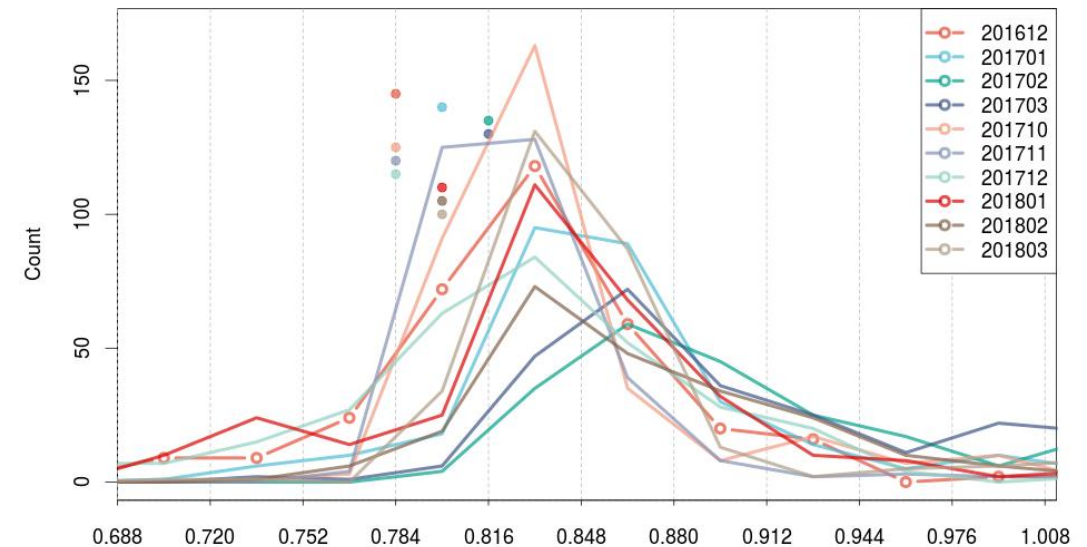
OMAA



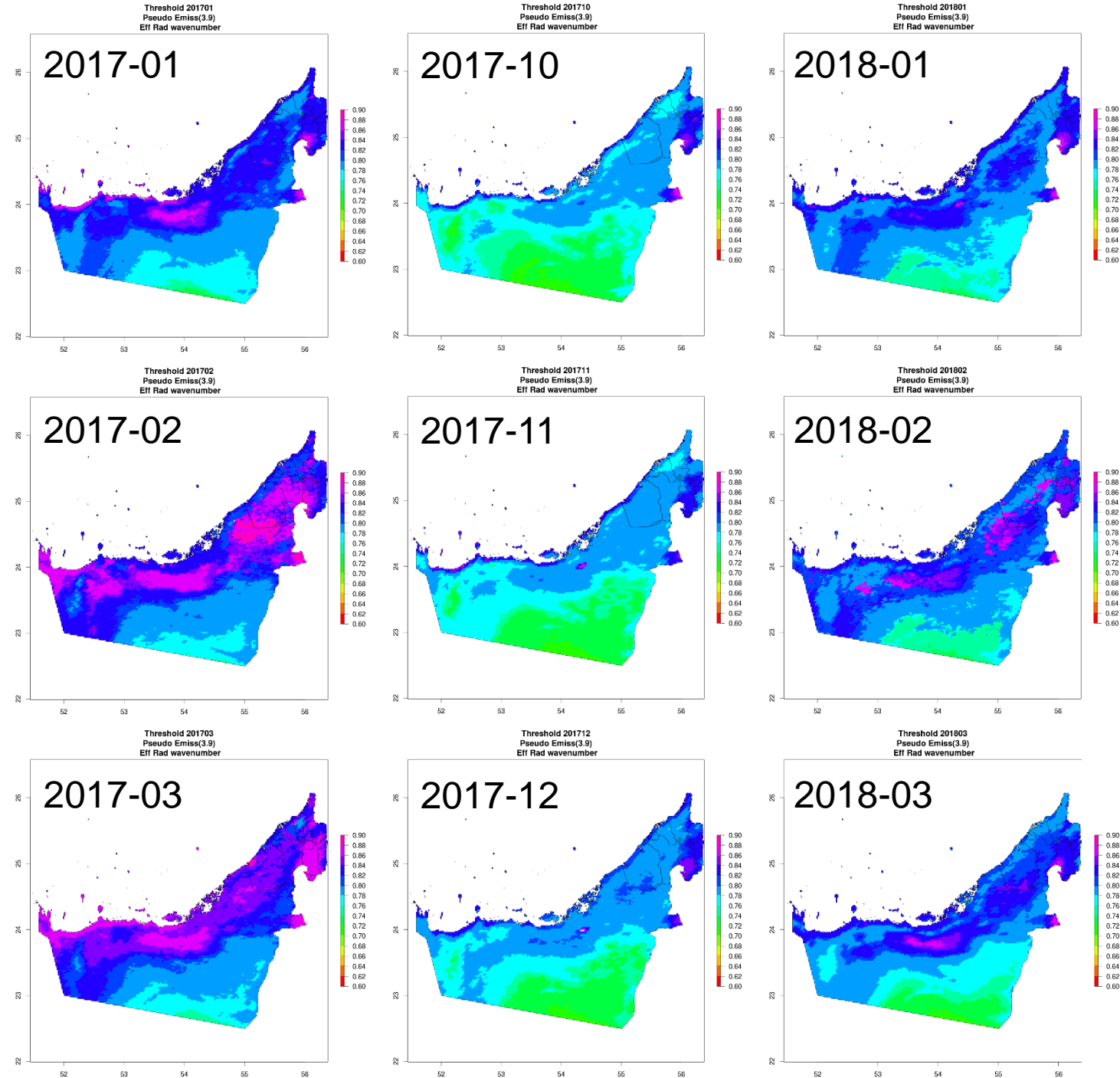
OMDB



OMAL

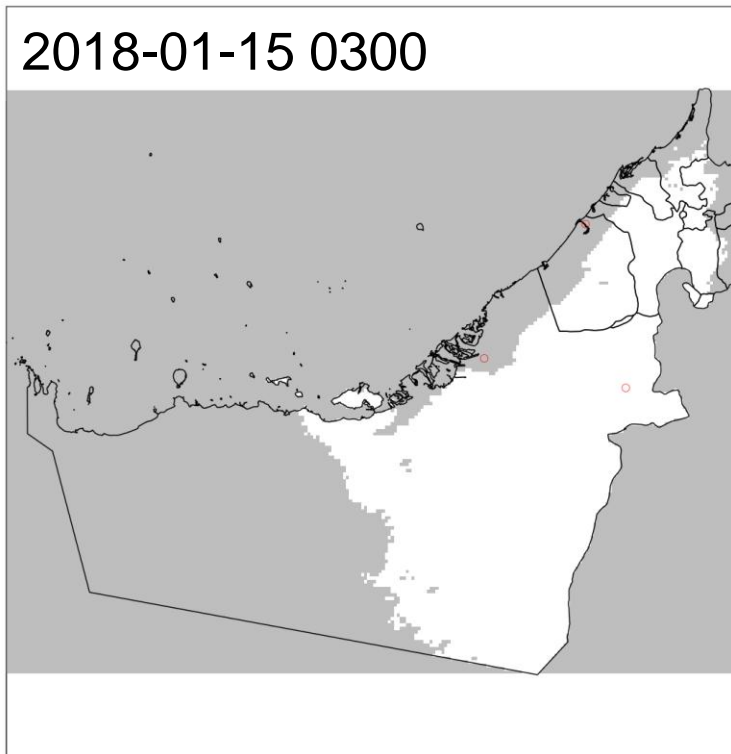


# Threshold maps

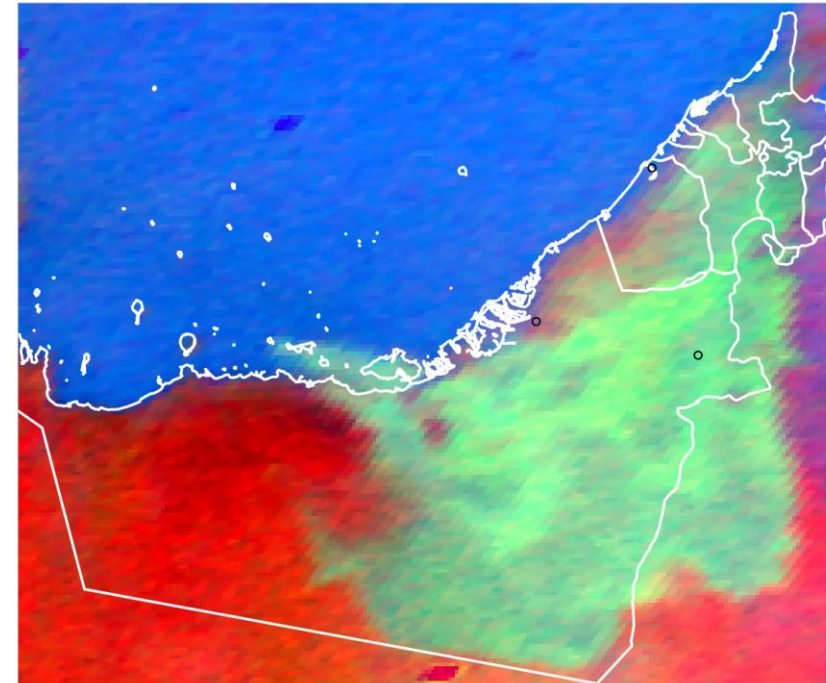


# Example

fogmask\_20180115\_2300\_minus\_lowcloud



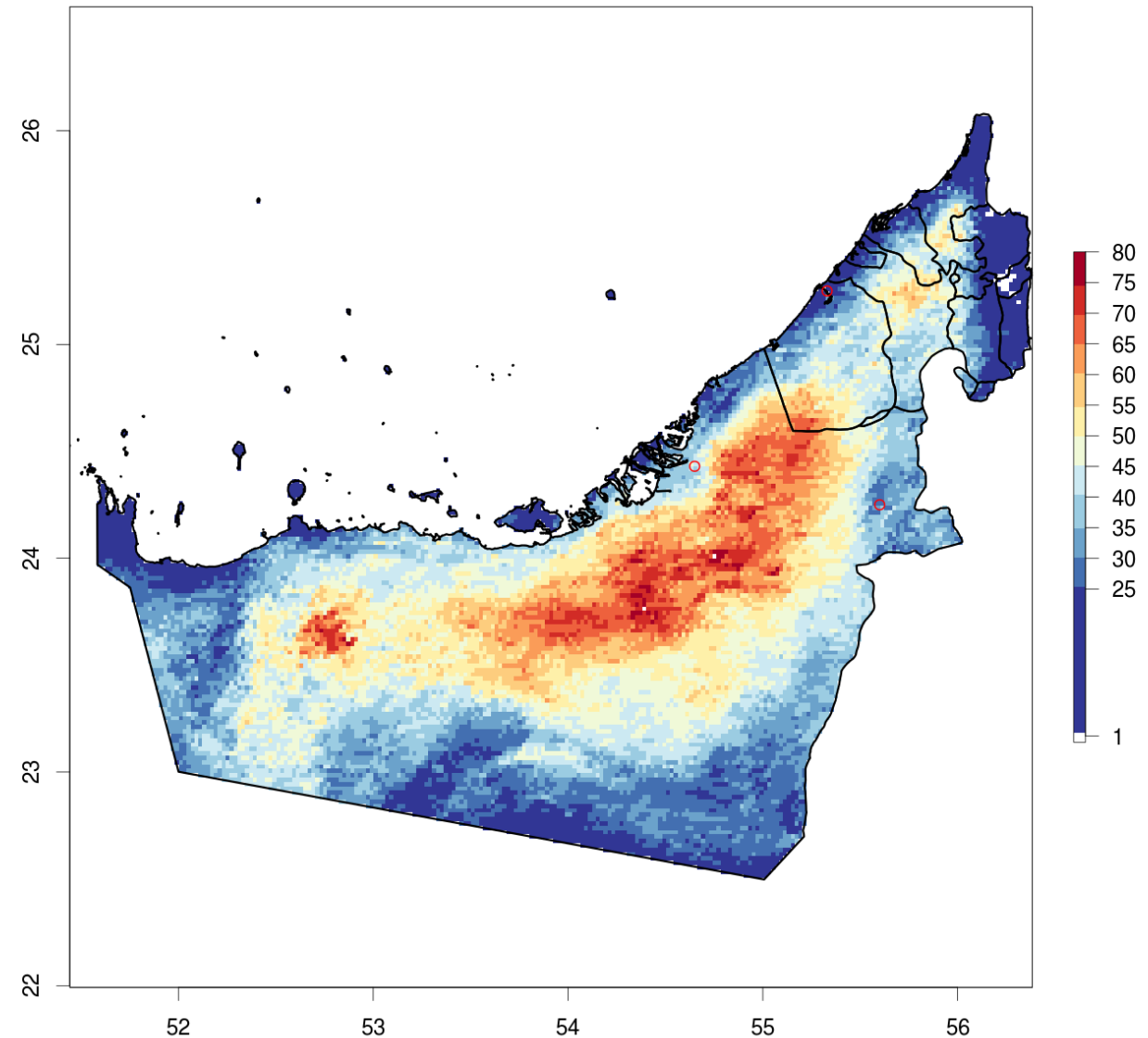
RGB\_20180115\_2300



# Verification

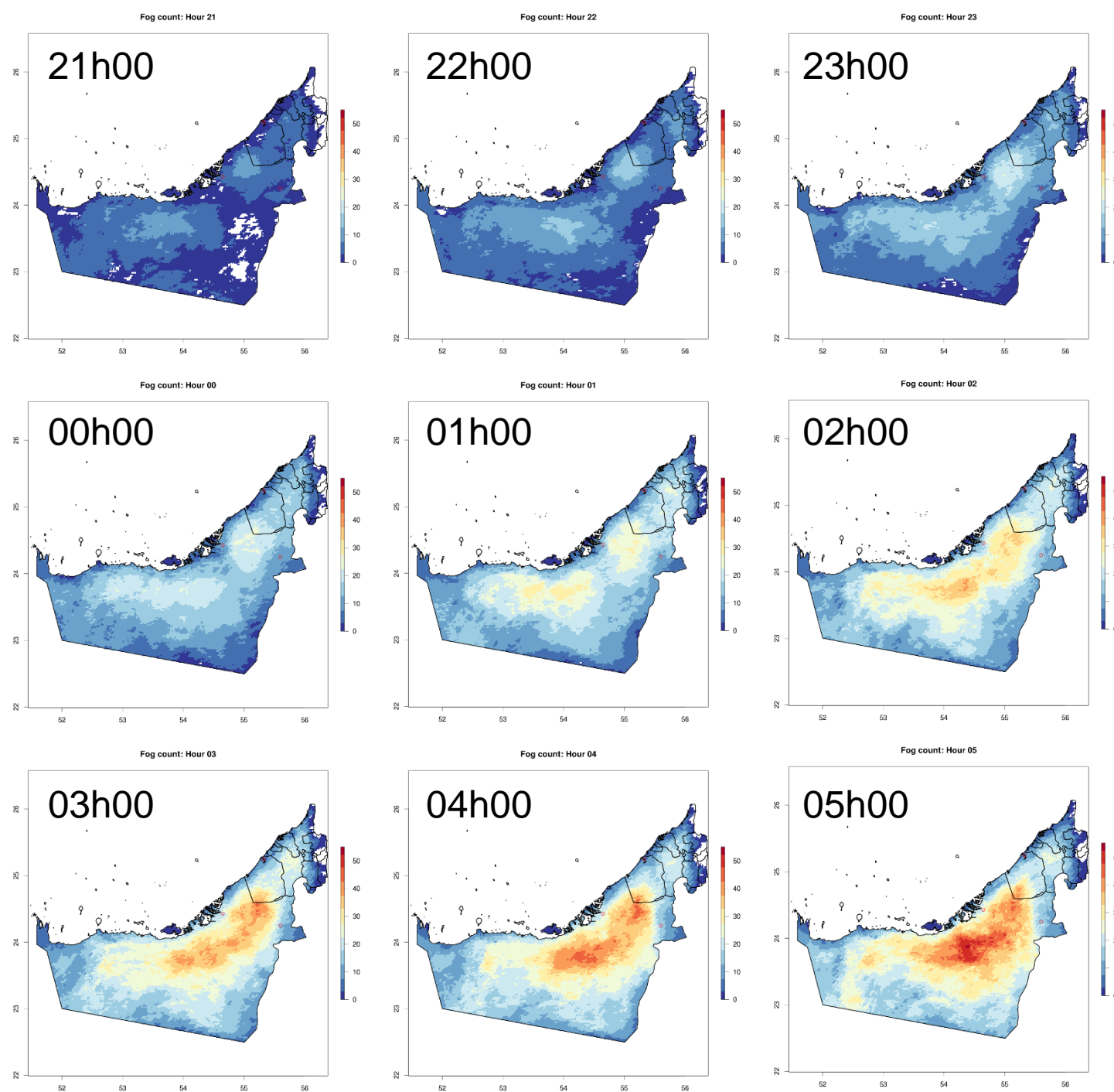
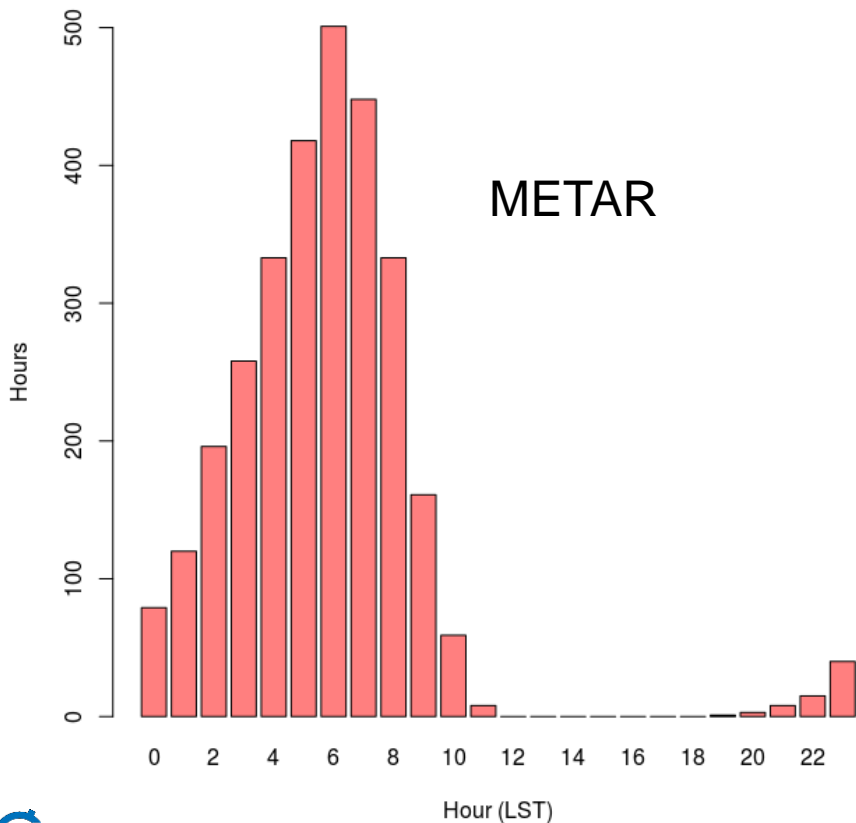
Statistic	OMAA ems(3.9) - Low cloud	OMDB ems(3.9) - Low cloud	OMAL ems(3.9) - Low cloud
Total Hits	26	10	20
Total Miss	6	2	4
Total False Alarms	17	10	10
POD	0.81	0.83	0.83
FAR	0.40	0.50	0.33
Bias score	1.34	1.66	1.25

Fog Frequency Days



# Diurnal Cycle

Fog frequency by hour 1983-2018



# Conclusions

- **What is novel about this study**

- Pixel based threshold = spatially varying threshold
- Dynamic method for selecting threshold from histogram
- Application of Pseudo Emissivity in Meteosat. Previously only used in GOES-R
- First spatial statistics of fog over the UAE, revealing fog dynamics over the region.

- **Results**

- The method verified well, with POD (FAR) ranging from 0.81 to 0.83 (0.33 to 0.5)
- The classification had a **positive bias**, ranging from **25 to 66 %**, mostly due to the inclusion of **haze and mist** in the classification
- The **hourly frequency** is presented and is **in line with *in situ* measurements**, indicating peak fog frequency at 05h00 local time
- This method can for the basis for further refinement and investigation

# References

- Cermak, J.; Bendix, J. A novel approach to fog/low stratus detection using Meteosat 8 data. *Atmospheric Research* 2008, 87, 279--292, doi:10.1016/j.atmosres.2007.11.009.
- Pavolonis, M.J.; Heidinger, A.K. Advancements in identifying cirrus and multilayered cloud systems from operational satellite imagers at night. *Applications with Weather Satellites II* 2005, 5658, 225, doi:10.1117/12.577640.
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- Cao, C.; Shao, X. Planck Function. Available online: <https://ncc.nesdis.noaa.gov/data/planck.html> (accessed on 26 September 2019).