

Topological properties of aftershock clusters in a viscoelastic model of quasi-brittle failure

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Open chatroom with the authors on **Monday, 04 May 2020, 14:00-15:45 CET** at:

<https://meetingorganizer.copernicus.org/EGU2020/EGU2020-4948.html>

Comments are welcomed before 30 May 2020.

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Author notes:

This is the adaptation of a poster, intended to optimize the opportunities offered by the new display format: halfway between a poster and slide show. Find the original poster at the end of the document.

Officially, the chatroom will be open on **Monday, 04 May 2020, 14:00-15:45 CET** at the following link:

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The presenting author will be also available from **10:45-12:30 CET** on the same day **4 May 2020**, at chatroom:

<https://meetingorganizer.copernicus.org/EGU2020/EGU2020-6334.html>

Please, feel free to leave comments at any other time **before 30 May 2020**, at the same links.

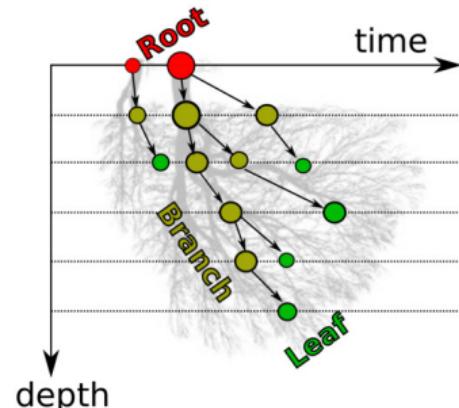
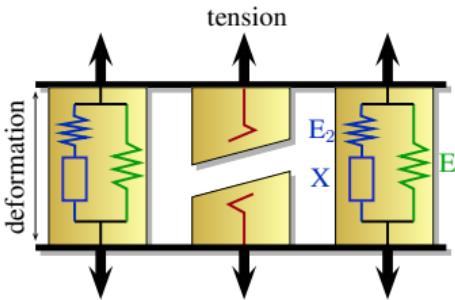
Note: **blue** texts are hyperlinks redirecting to supplementary material in this document and external links.

1. Viscoelasticity & Aftershocks

Material failure at different scales and processes can be modeled as an emergent feature of **micromechanical** systems in terms of **avalanche dynamics**. Among experimental observations, event-event triggering —**aftershocks**— is a common feature in seismological catalogs, acoustic emission experiments [1] and even other phenomena. In parallel, the statistical properties of triggering in such catalogs are often modeled as stochastic **epidemic branching** or **linear Hawkes** processes [4,5]. In the **micromechanical** approach, **viscoelastic** stress transfer and after-slip are among the proposed mechanism behind triggering and aftershocks.

Here we address a simple question:

Do aftershock sequences obtained in micromechanical models agree with the predictions and ideas behind the epidemic branching framework?



We introduce two **fibrous models** as prototypes of **viscoelastic fracture** [2] which (i) provide an analytical explanation to the acceleration of activity in absence of critical failure observed in acoustic emission experiments [3]; (ii) reproduce the typical spatio-temporal properties of triggering found in field catalogs, acoustic emission experiments; and (iii) agree with the one-to-one causality established in epidemic models, but display discrepancies with the branching topological properties predicted by stochastic models. These are probably caused by physical constraints and nonstationary parameters.

- [1] J. Baró et al., *Phys. Rev. Lett.* **110** (8), 088702 (2013);
- [2] J. Baró, J. Davidsen, *Phys. Rev. E* **97** (3), 033002 (2018);
- [3] J. Baró, et al., *Phys. Rev. Lett.* **120** (24), 245501 (2018);
- [4] J. Baró, *J. of Geophys. Res.: Solid Earth*, **125**, e2019JB018530 (2020);
- [5] S. Saichev, et al., *Pure and App. Geoph.*, **162** (6), 1113-1134 (2005).

The Epidemic Aftershock Paradigm [4]:

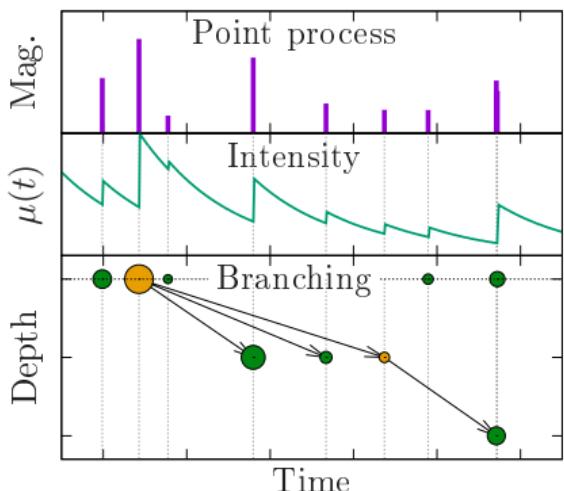
- Catalogs are modeled as a **linear Hawkes** process (ETAS):

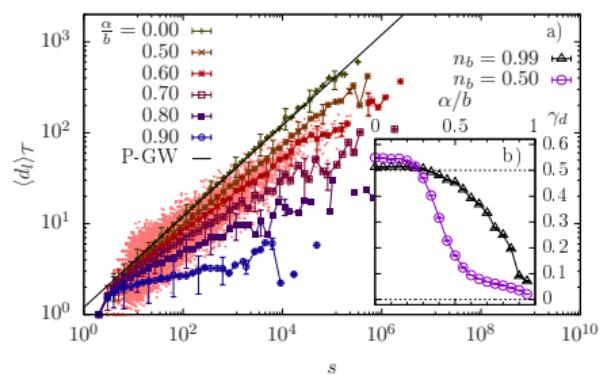
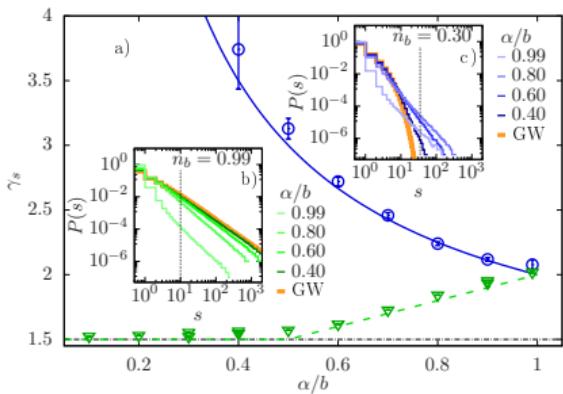
$$\mu(t, \mathbf{r}, m) = \rho(m)\mu_0(t, \mathbf{r}) + \sum_{i|t_i < t} \rho(m)n(m_i)\Psi_i(t, \mathbf{r}|t_i, \mathbf{r}_i)$$

considering:

- Gutenberg-Richter: $\rho(m) \sim 10^{-b(m-m_c)}$
- productivity law: $n(m_i) := k_c 10^{\alpha(m_i-m_c)}$

- ..or specifically as a Galton Watson **branching** process ..





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- ..or specifically as a Galton Watson **branching** process exhibiting a transition from Poisson (swarm-like) clusters to scale-free (burst-like) offspring depending on α/b . (details)

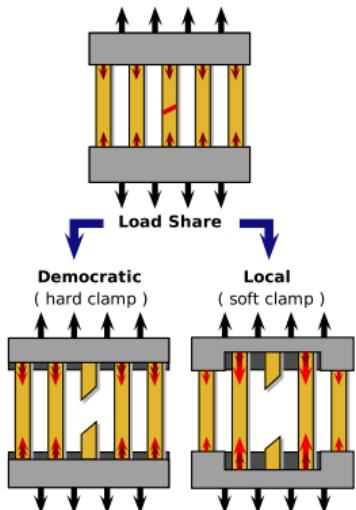
$X_i(m_i) \sim \text{Pois.}(n(m_i))$; as GW :

$$P(X_i = x) = \frac{b}{\alpha} \frac{k_c^{\frac{b}{\alpha}}}{x!} \Gamma(x - b(\alpha, k_c))$$

only depends on $0 < \alpha/b \leq 1$ and $n_b \equiv k_0 / \left(1 - \frac{\alpha}{b}\right)$.

*Notice that the branching interpretation explicitly considers **one-to-one causal links**. The Hawkes interpretation does not.

3. Generalized Viscoelastic Fiber Bundle Models (GVE-DFBM & GVE-LFBM)



Consider a bundle of a number M of equal parallel fibers $\{l\}$: $\varepsilon_l = \int J d\sigma_l$;

each with a random strength S_l ;

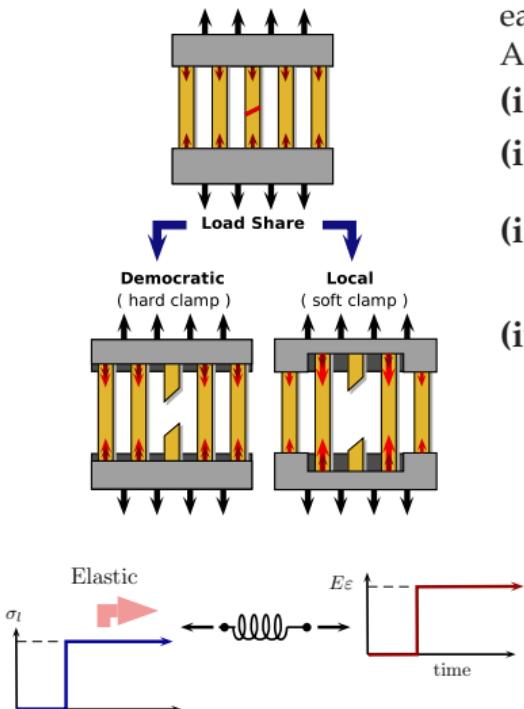
A **global load** σ is shared in individual **local loads**: $\sigma_l(t) = w_l(t)\sigma(t)$;

(i) At time t a fiber is broken if $\exists t' | S_l < \sigma_l(t' < t)$; if so: $w_l(t) \rightarrow 0$;

(ii) Conservation imposes: $\sum_l w_l = 1 \rightarrow$ load must be redistributed;

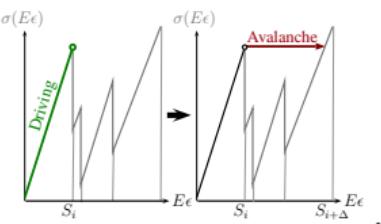
(iii) Sharing Rule: **democratic (DFBM)** (mean field)[2]: $w_l(t) = N_{S < \sigma(t)}^{-1}$
local (LFBM) ($k = 4$ n.n. in a 2d-lattice): $\delta\sigma_{j \in nn(l)} = \sigma_l/k$;

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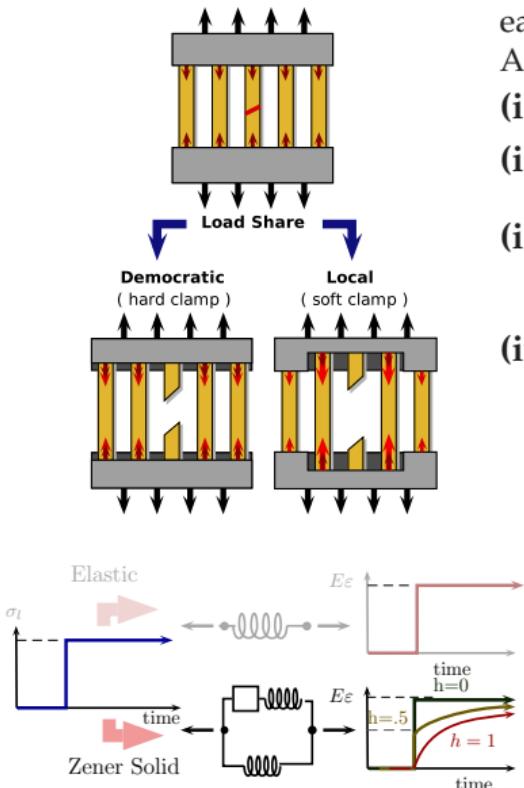
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local (LFBM) ($k = 4$ n.n. in a 2d-lattice): $\delta\sigma_{j \in nn(l)} = \sigma_l/k$;
 - (iv) Creep compliance ($\Delta\epsilon(t) = J(t)\Delta\sigma_l$): **elastic kernel** : $J_{EL}(t) = 1/E$;

ELASTIC DFBM avalanche:

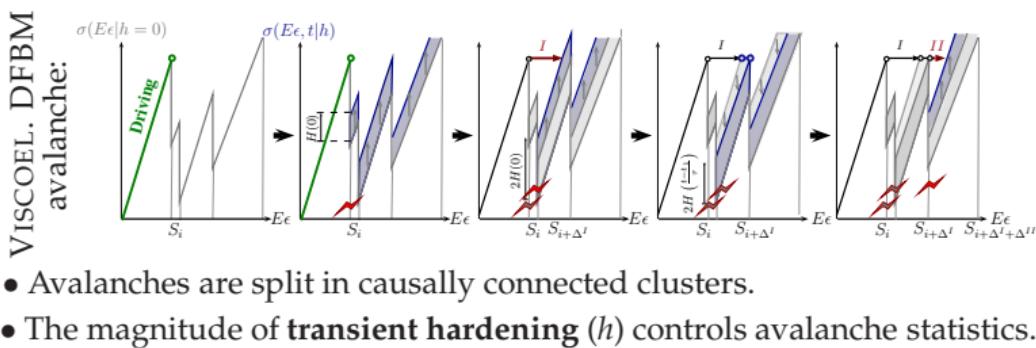


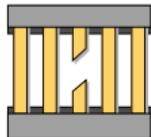
- Avalanches are caused by simultaneous failure of several fibers (with similar strength in the example of DFBM).

3. Generalized Viscoelastic Fiber Bundle Models (GVE-DFBM & GVE-LFBM)



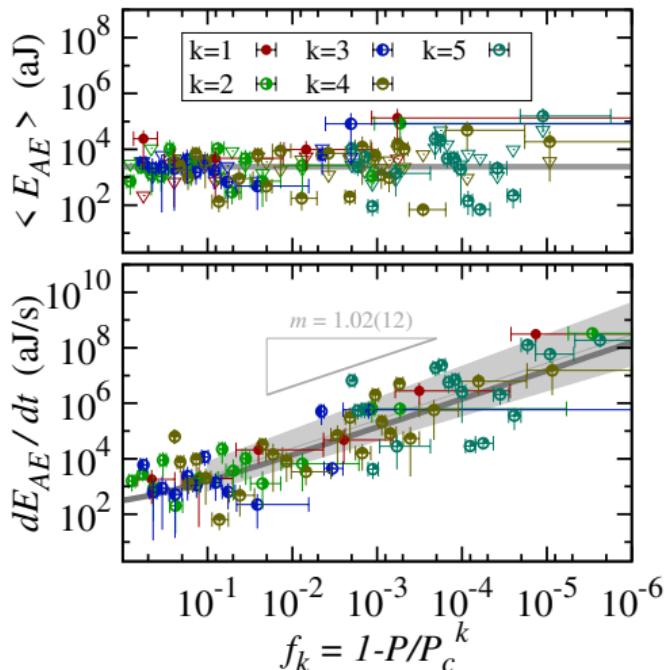
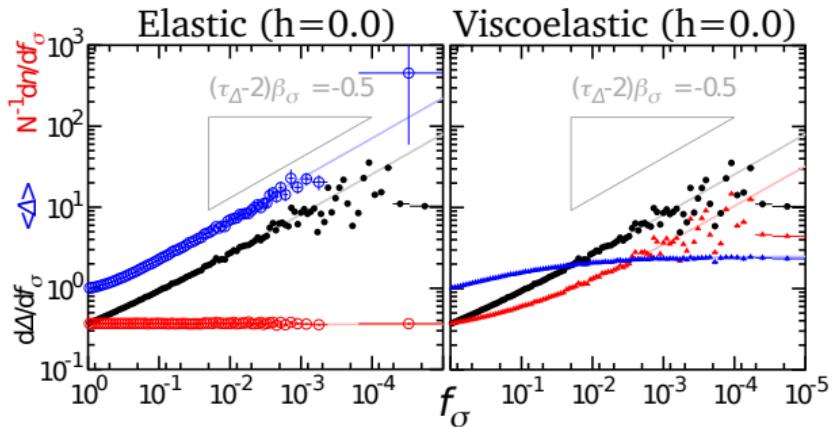
- Consider a bundle of a number M of equal parallel fibers $\{l\}$: $\varepsilon_l = \int J d\sigma_l$; each with a random strength S_l ;
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local (LFBM) ($k = 4$ n.n. in a 2d-lattice): $\delta\sigma_{j \in \text{nn}(l)} = \sigma_l/k$;
 - Creep compliance: **viscoelastic**: $J_{\text{GZ}}(t; h, \alpha) = \frac{1}{E} \left(1 - h E_\alpha \left(\frac{t}{\tau} \right) \right)$;

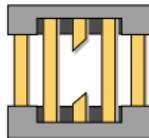




DEMOCRATIC FIBER BUNDLE MODEL

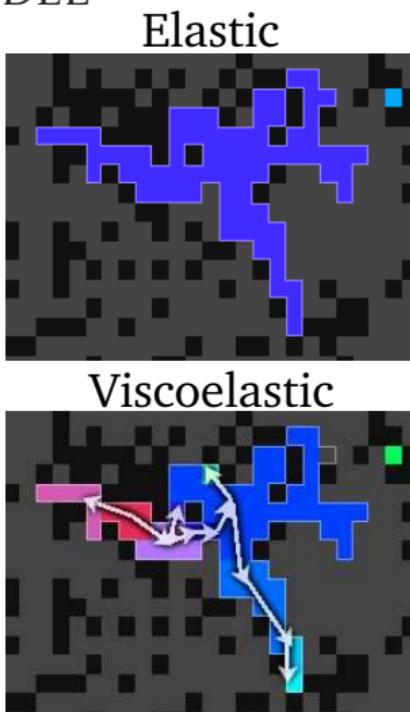
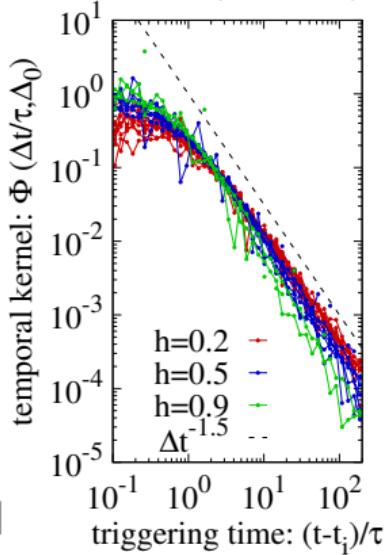
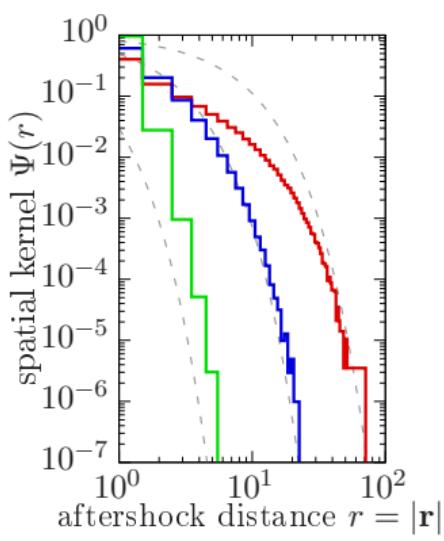
- Acceleration to failure ($d\Delta/df_\sigma(f_\sigma)$) is invariant [2], but
- viscoelasticity trades **critical avals.** for **foreshocks** [2]. ↓
- Observed in acoustic emission experiments [3]. →





2-D LOCAL FIBER BUNDLE MODEL

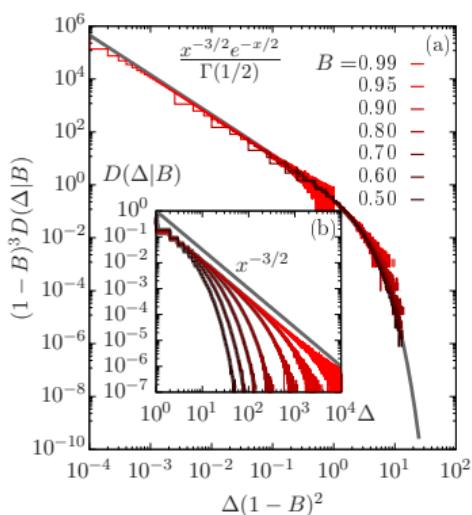
- Kernel: $\Psi_i(t, \mathbf{r}|t_i, \mathbf{r}_i) \approx \frac{d\mathbf{E}_\alpha}{dt}((t - t_i)/\tau) \exp\left(\frac{-|\mathbf{r} - \mathbf{r}_i|}{r_0(h)}\right)$.





DEMOCRATIC FIBER BUNDLE MODEL

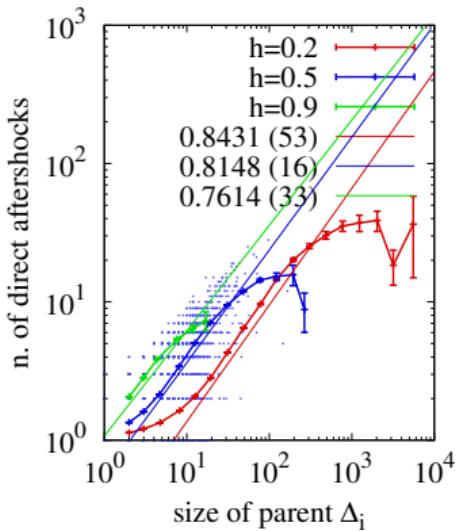
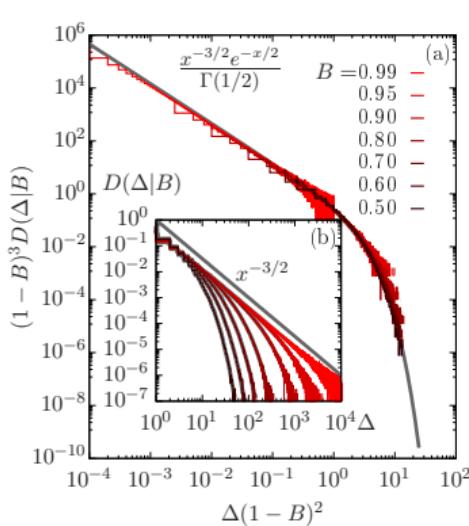
- All avalanche **sizes** are i.i.d. as **Borel** depending on f_σ : $\rho(\Delta; f_c) = (f_c \Delta)^{\Delta-1} e^{-f_c \Delta} / \Delta!$ (details).

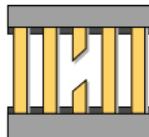




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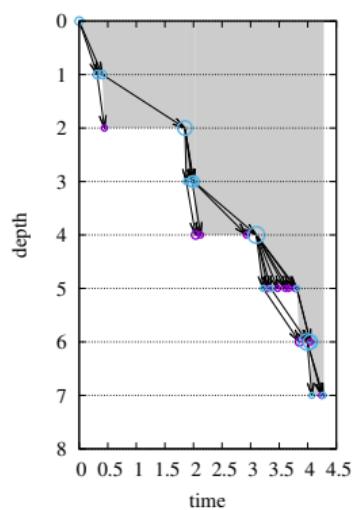
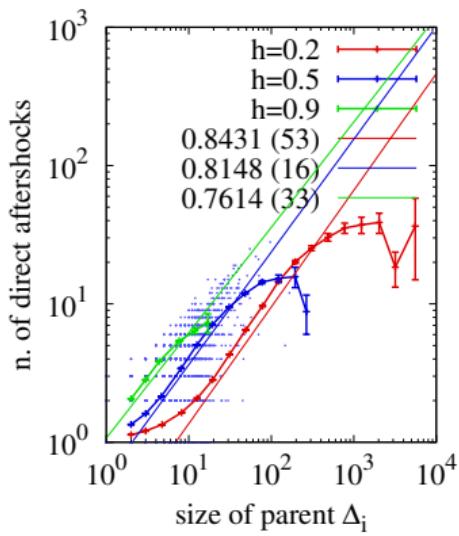
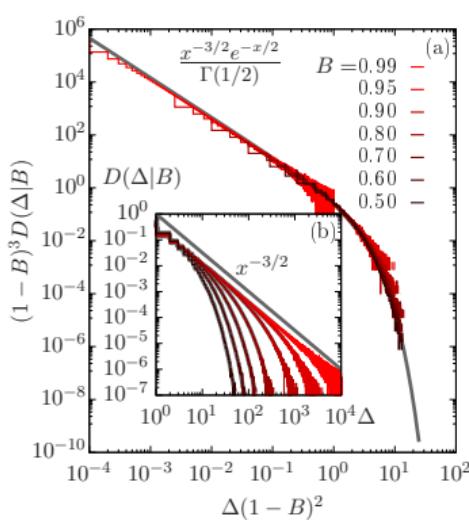
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- Considering $m = \log_{10} \Delta$ this implies b-value = 0.5; $\alpha \approx 0.8$ ($\alpha/b = 1.6 > 1$).

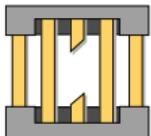




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- Considering $m = \log_{10} \Delta$ this implies b-value = 0.5; $\alpha \approx 0.8$ ($\alpha/b = 1.6 > 1$).
- Triggering is sorted by parent (see model) rendering unrealistically (non-ETAS) ‘combed’ trees;

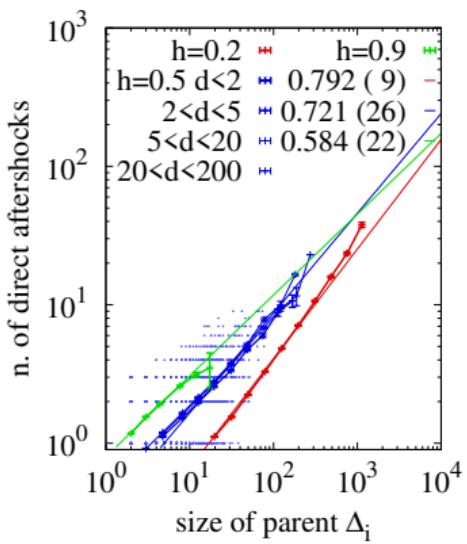
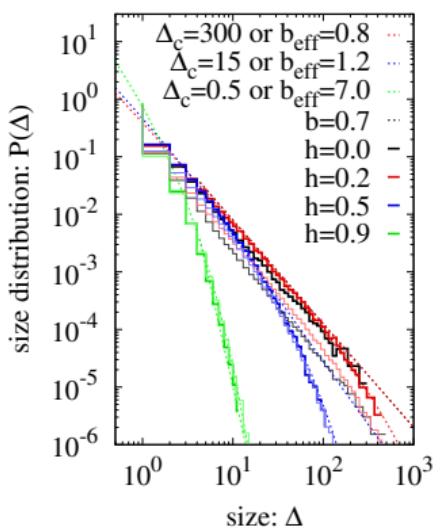
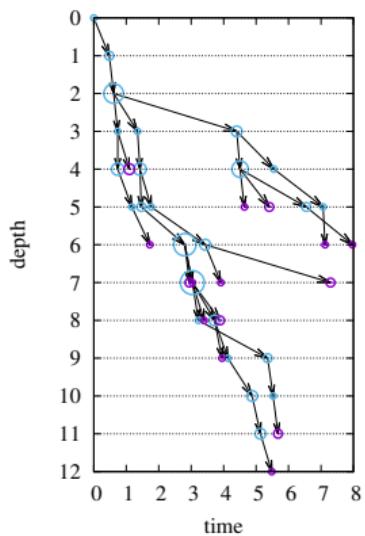




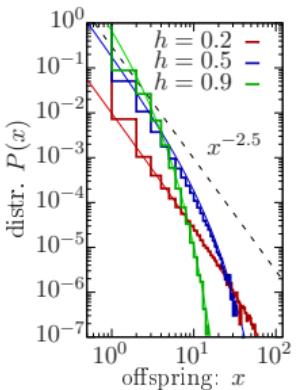
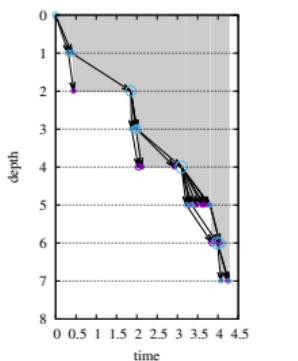
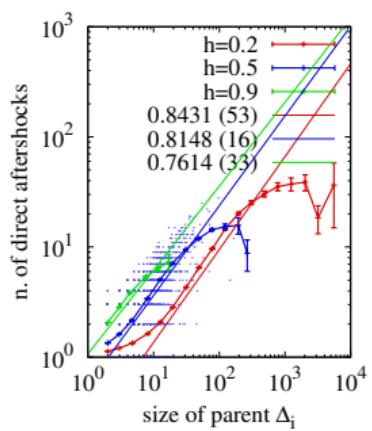
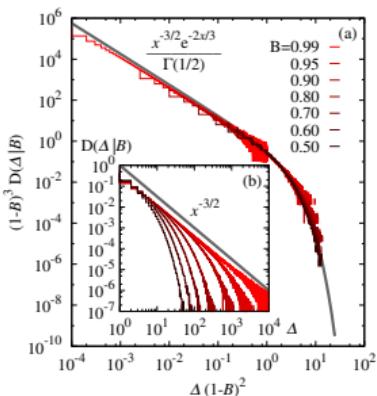
2-D LOCAL FIBER BUNDLE MODEL

- No analytic solution. Critical failure for $S_i \sim \text{Weibull}(k(h))$, being $k(0) = 1.36$.

$P(\Delta) \sim \Delta^{-1-b} \exp(-(\Delta/\Delta_c)^b)$ with $b \sim 0.7$, a cutoff $\Delta_c(h)$ & productivity exponent $\alpha(h)$.



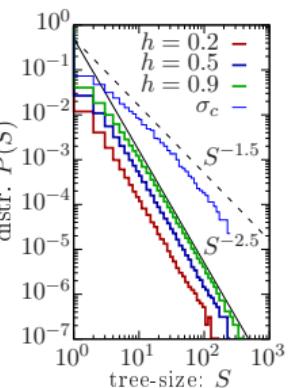
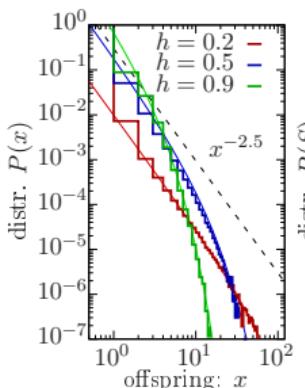
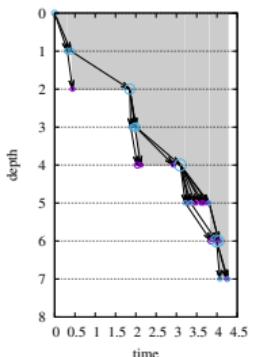
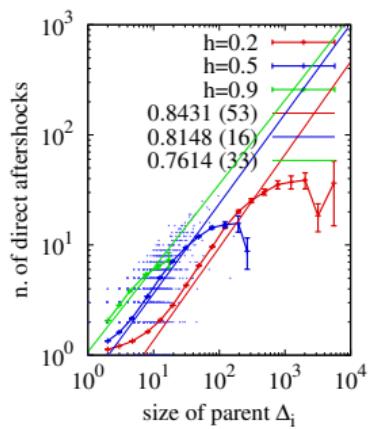
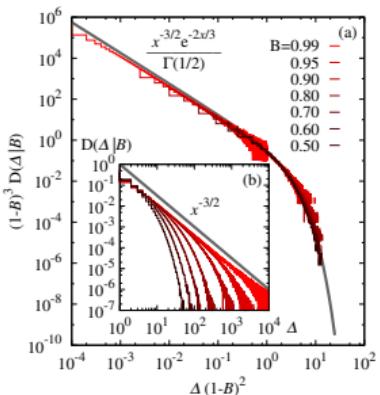
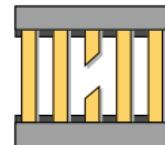
6. Triggering in the FBM with democratic load sharing (DFBM)



The exponent values in the DFBM imply: $\alpha/b = 1.6 > 1!!$ (unphysical)

BUT, failure is sub-critical
(no divergence of $\langle \text{number of offsprings}^2 \rangle$)

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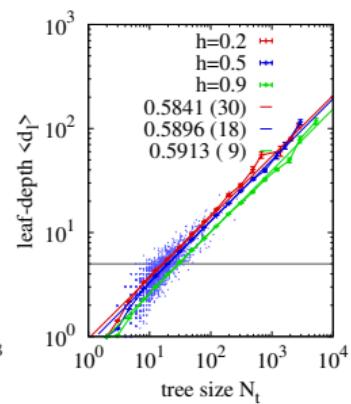


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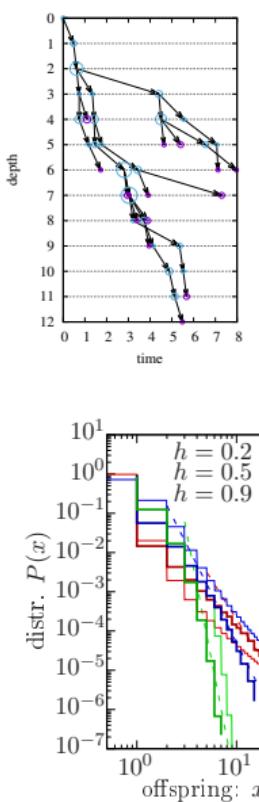
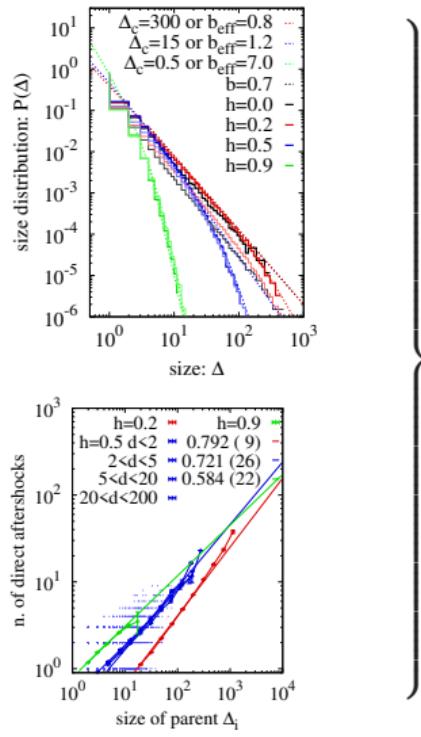
BUT, failure is sub-critical
(no divergence of $\langle \text{number of offsprings}^2 \rangle$)

Distr. of tree-size (S) \sim Distr. of avalanche sizes (Δ)
(imposed by physical constrains [2])

Only swarm-like clusters ($d_l \sim S^{0.5}$)



6. Triggering in the FBM with local load sharing (LFBM)

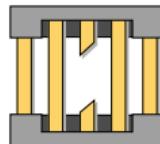


Power-law avalanches can occur with $h > 0$ (unlike the DFBM)

Transition from swarms to bursts is observed by tuning h .

Global exponents ([table here](#)) do not fully satisfy expectations from ETAS.

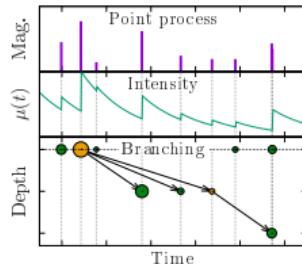
This is corrected by considering the non-stationary evolution of statistical parameters corresponding to the phase transition. (WIP not shown here)



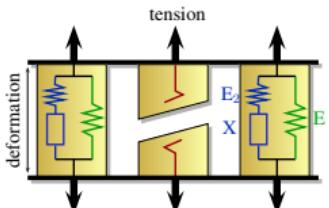
7. Conclusions:

- ▶ Epidemic models (ETAS) interpret aftershock sequences as:

- (1) linear Hawkes' processes with an intensity factorized in empirical terms accounting for: mainshock mag., and spatio-temporal and mag. distribution.
- (2) a Galton-Watson branching forests with one-to-one causal links, independent offspring production and a transition between Poisson and power-law offspring distribution.



- ▶ Avalanches in micromechanical models of viscoelastic fracture can be triggered by external driving (mainshocks in terms of seismology) or one-to-one causal triggering (aftershocks) and reproduce *qualitatively* the expectations of the ETAS model.



- (1) Aftershocks are defined by one-to-one causal links, leading to branching.
- (2) Explain the origin of acceleration in absence of critical avals. at failure
- (3) Reproduce the expected cluster classification depending on physical parameters. We find bursts for high viscosity (h) and swarms for low.
- (4) To reproduce *quantitatively* all topological features we must consider physical constrains and non-stationary parameters in the ETAS model (WIP).

Thanks:



AXA
Research Fund
Through Research, Protection

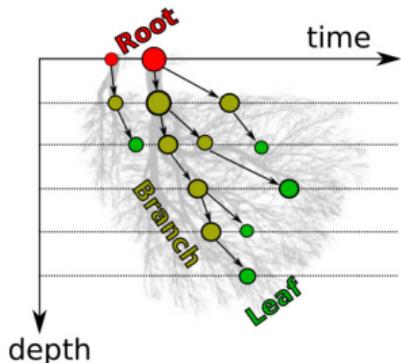


Supplementary Information

Epidemic Type Aftershock Sequence Model (ETAS) [Y. Ogata, JASA (1988)] :

$$\Psi(\Delta, t, \mathbf{r} | m_i, t_i, \mathbf{r}_i) = \rho(\Delta) n_b(\Delta_0) \Psi_t(t - t_0) \Psi_r(||\mathbf{r} - \mathbf{r}_0||)$$

$$\left. \begin{array}{l} \rho(\Delta) \sim \Delta^{-1-b} \\ n_b(\Delta_0) \sim \Delta_0^\alpha \end{array} \right\} \begin{array}{l} \text{Results depend only on } \langle n_b \rangle \text{ and } \alpha/b. \\ 0 \leq \alpha/b < 0.5 \text{ typical Galton-Watson} \\ 0.5 \leq \alpha/b < 1 \text{ special case} \\ [\text{A. Saichev, et al. (2015)}] \end{array}$$



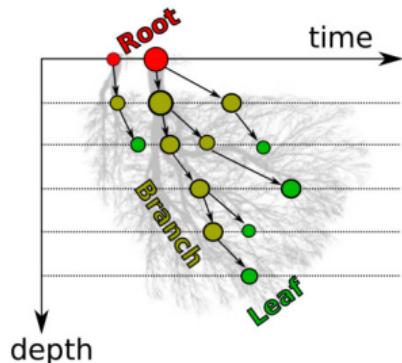
Triggering in the ETAS model

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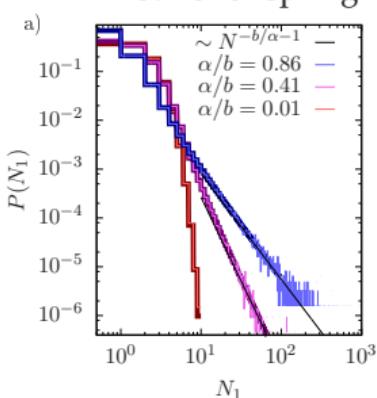
$$\Psi(\Delta, t, \mathbf{r} | m_i, t_i, \mathbf{r}_i) = \rho(\Delta) n_b(\Delta_0) \Psi_t(t - t_0) \Psi_r(||\mathbf{r} - \mathbf{r}_0||)$$

$$\left. \begin{array}{l} \rho(\Delta) \sim \Delta^{-1-b} \\ n_b(\Delta_0) \sim \Delta_0^\alpha \end{array} \right\}$$

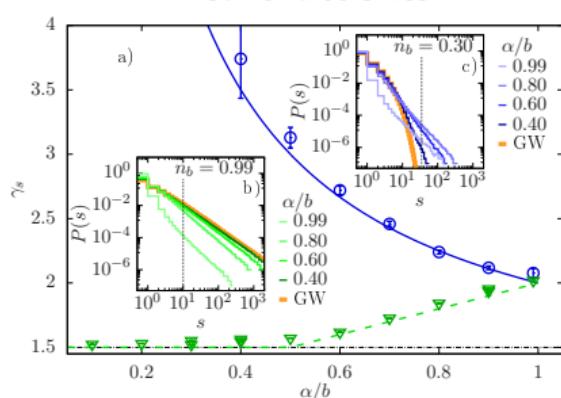
Results depend only on $\langle n_b \rangle$ and α/b .
 $0 \leq \alpha/b < 0.5$ typical Galton-Watson
 $0.5 \leq \alpha/b < 1$ special case
[[A. Saichev, et al. \(2015\)](#)]



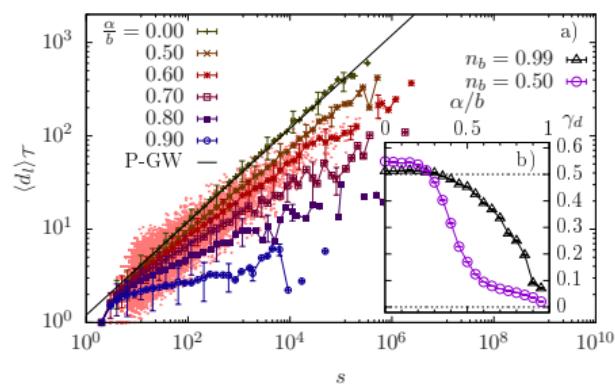
Distr. of offspring



Distr. of tree-sizes

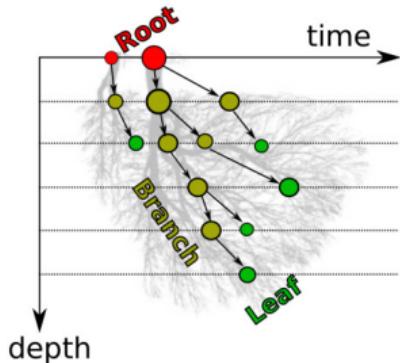
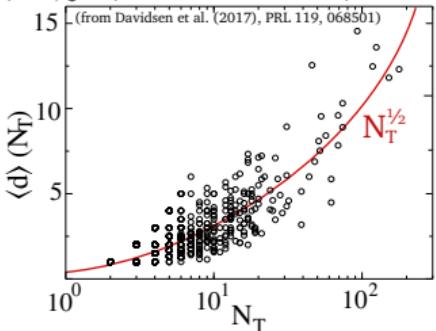
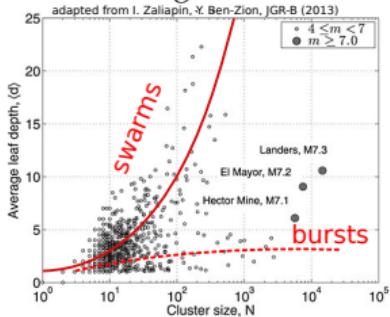


Relation: sizes vs. leaf-depths

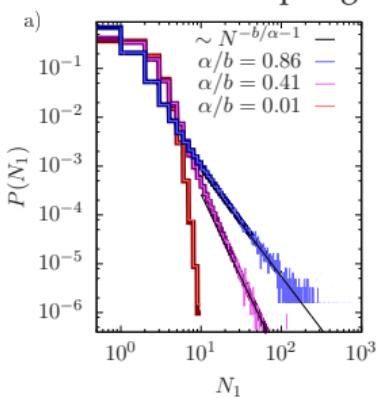


Triggering in the ETAS model

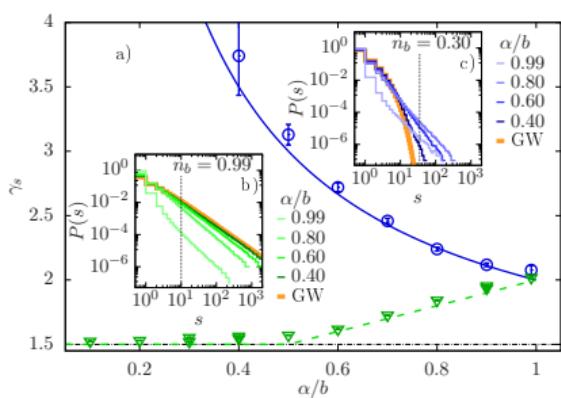
Field catalog class.: **BURSTS** ($d_l \lesssim 5$) and **SWARMS** ($d_l \sim S^{\gamma_d}$)



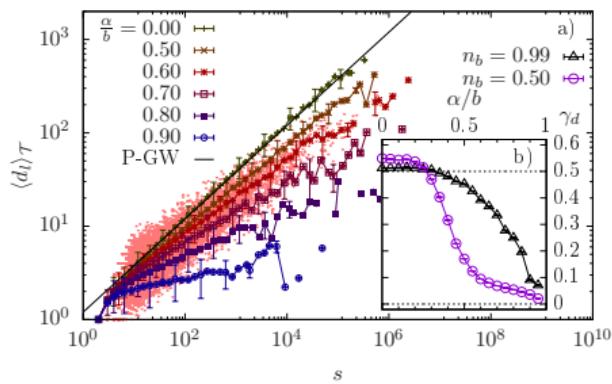
Distr. of offspring



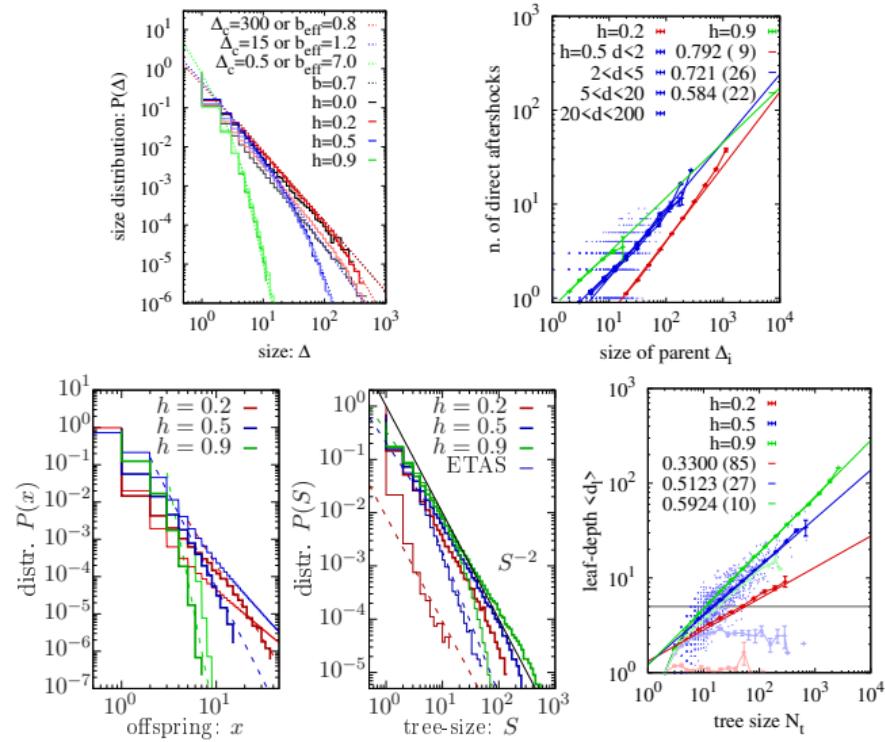
Distr. of tree-sizes



Relation: sizes vs. leaf-depths



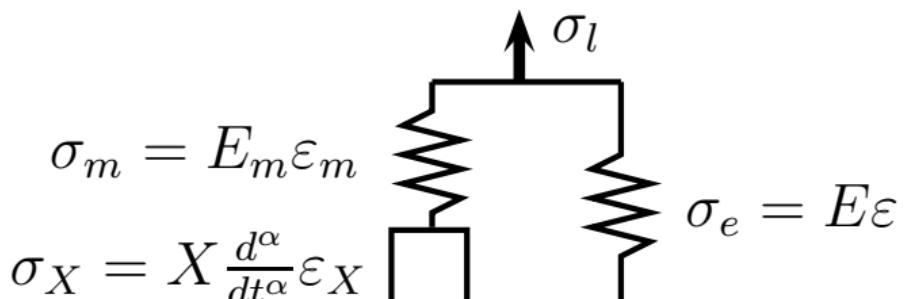
Exponent table for LFBM and ETAS expectations



h	0.2	0.5	0.9
b_{eff}	0.8	1.2	7.0
α	0.78	0.72	0.58
$\frac{\alpha}{b_{\text{eff}}}$	0.975	0.600	0.082
n_b	0.171	0.413	0.675
$\gamma_x^{\text{mod}} = 1 + b/\alpha$	2.03	2.67	13.1
$\hat{\gamma}_x$	4	5	13
$\gamma_s^{\text{mod},h} = 1 + b/\alpha$	2.03	2.67	13.1
$\gamma_s^{\text{mod},l} = 1 + \alpha/b$	1.96	1.60	1.08
$s_c^{\text{mod}} = (1 - n_b)^{1/(\alpha/b-1)}$	1775	3.78	3.40
$\hat{\gamma}_s$	2.1	1.9	1.8
γ_d^{sim}	0	0	0.5
$\hat{\gamma}_d$	0.33	0.51	0.59

Adds **dissipation**, **temporal scales** and **power-law memory**.

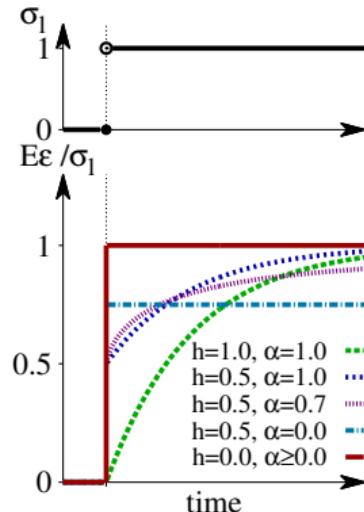
Reproduces the response of certain bulk amorphous materials



Constitutive equation for the generalized Zener Element:

$$\left[1 + \frac{X}{E_m} \frac{d^\alpha}{dt^\alpha} \right] \sigma_l = \left[1 + \frac{X(E_m + E)}{E_m E} \frac{d^\alpha}{dt^\alpha} \right] E \varepsilon.$$

$$\mathbf{H}_\alpha(t/\tau) := \frac{E_m}{E_m + E} \mathbf{E}_\alpha \left(- \left(\frac{t}{\tau} \right)^\alpha \right) \begin{cases} \mathbf{H}_\alpha(0) &= \frac{E_m}{E_m + E} := h \\ \mathbf{H}_\alpha(t \gg \tau) &\rightarrow 0 \end{cases}$$



Creep compliance:

$$J_{GZ}(t) = \frac{1}{E} \left(1 - \mathbf{H}_\alpha \left(\frac{t}{\tau} \right) \right)$$

Fiber Bundle Models (FBM):

Brittle fibers of stochastic strengths S_i :

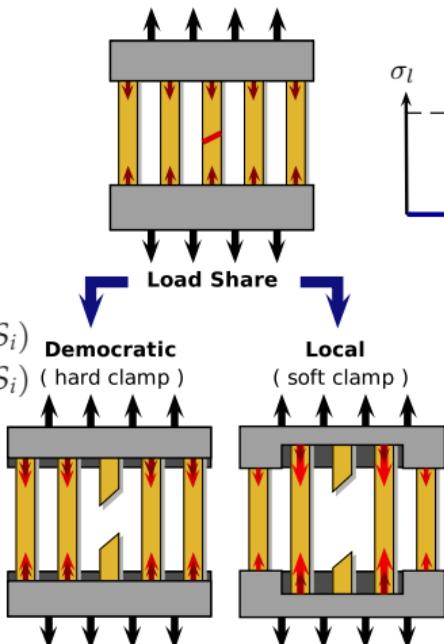
Local load at each fiber:

$$\sigma_l = \begin{cases} w_l(t)\sigma & (E\varepsilon < S_i) \\ 0 & (E\varepsilon \geq S_i) \end{cases}$$

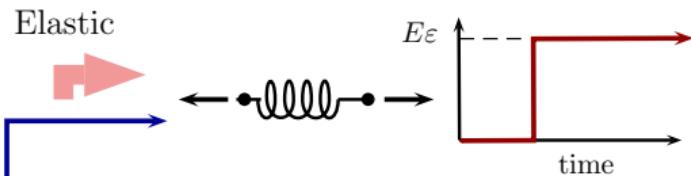
(hard clamp)

AVALANCHE:
collective failure
of Δ fibers

Interaction (*sharing rule*):



Fiber Deformation (*overdamped*):



Elastic



$E\varepsilon$

time

Fiber Bundle Models (FBM):

Brittle fibers of stochastic strengths S_i :

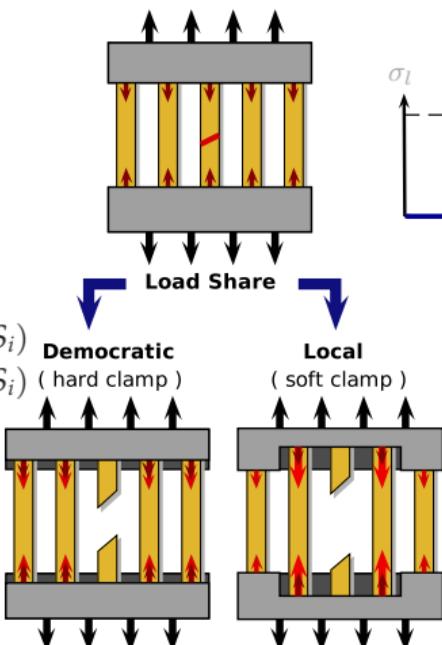
Local load at each fiber:

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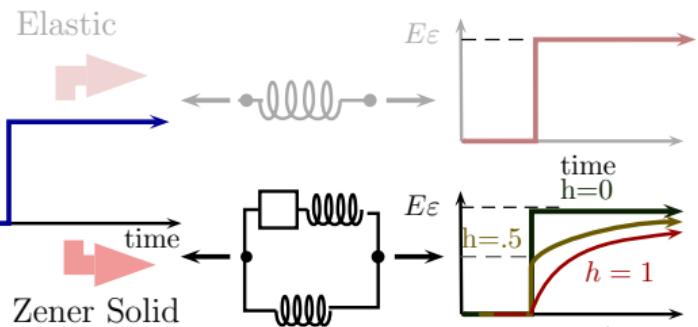
(hard clamp)

AVALANCHE:
collective failure
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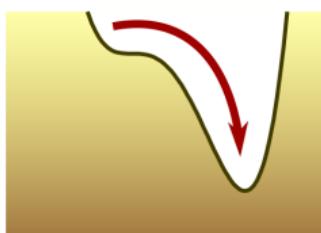
Interaction (*sharing rule*):



Fiber Deformation (*overdamped*):



Elastic



Viscoelastic

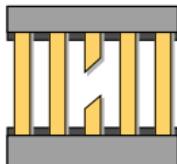
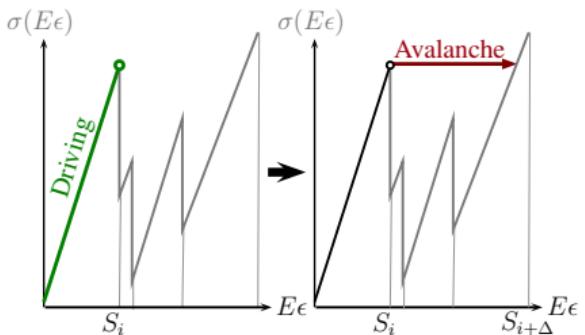
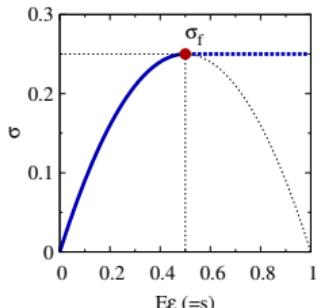


Triggering in the FBM with **democratic** load sharing (DFBM)

ELASTIC ($E\varepsilon = \sigma_l$)

Constitutive equation:

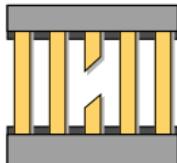
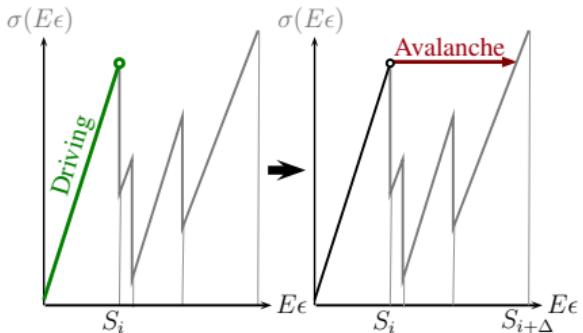
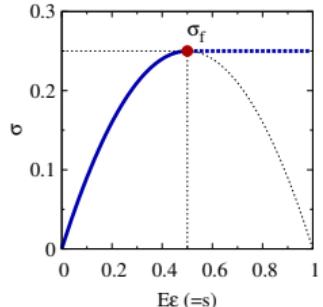
$$\sigma(E\varepsilon) = \left(\frac{N_0}{N(S_i > E\varepsilon)} \right)^{-1} E\varepsilon$$



ELASTIC ($E\epsilon = \sigma_l$)

Constitutive equation:

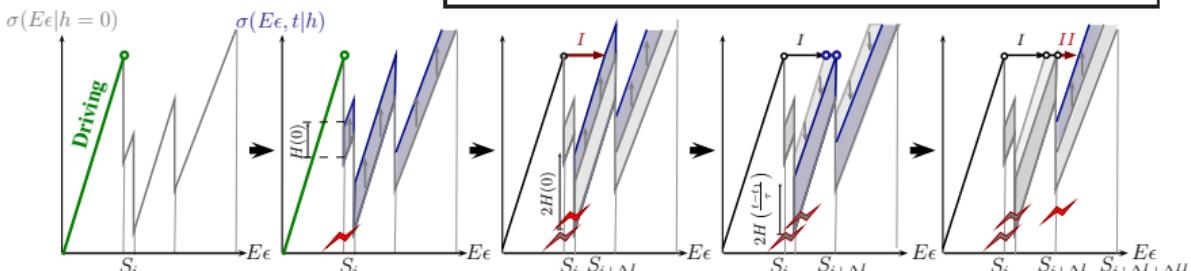
$$\sigma(E\epsilon) = \left(\frac{N_0}{N(S_i > E\epsilon)} \right)^{-1} E\epsilon$$



VISCOELASTIC ($E\epsilon = (1 - f(t))\sigma_l$)

Constitutive equation:

$$\sigma(E\epsilon, t) = \left(\frac{N_0}{N(S_i > E\epsilon)} - \sum_{S_j < E\epsilon} \phi_j (t - t_j) \right)^{-1} E\epsilon$$

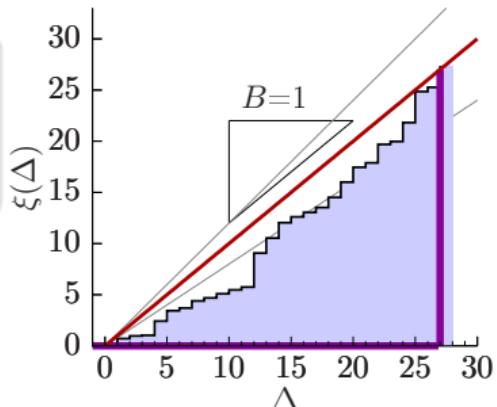


From constitutive equation: An avalanche start at S_i , stops when: $\sigma(\varepsilon) \geq \sigma(S_i)$

Universal Avalanche Definition:

$$\xi(\Delta_i) > B(S_i|h)\Delta_i$$

(hitting times)



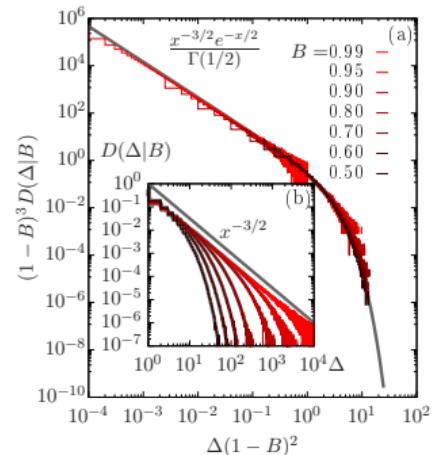
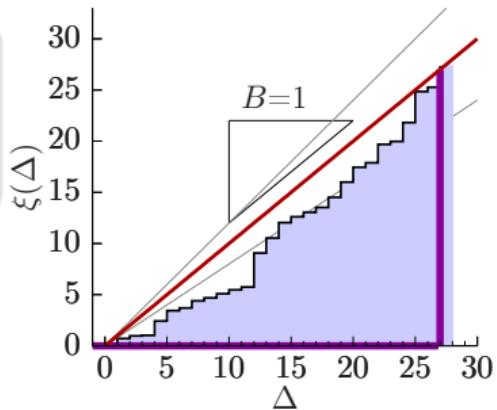
$\xi(\Delta)$: Poisson counting process of Δ steps.

From constitutive equation: An avalanche starts at S_i , stops when: $\sigma(\varepsilon) \geq \sigma(S_i)$

Universal Avalanche Definition:

$$\xi(\Delta_i) > B(S_i|h)\Delta_i$$

(hitting times)



$\xi(\Delta)$: Poisson counting process of Δ steps.

$B > 1$: Prob. $\Delta \rightarrow \infty$.

$B < 1$: Borel distribution!

$$D(\Delta; B) = \frac{(|1 - B|\Delta)^{\Delta-1} \exp(-|1 - B|\Delta)}{\Delta!} \sim \Delta^{-3/2} \mathcal{D}(\Delta|1 - B|)$$

$$B = 1: \text{Critical } D(\Delta; B) \sim \Delta^{-1.5}.$$

[Baró & Davidsen, PRE (2018)]

From constitutive equation: An avalanche starts at S_i , stops when: $\sigma(\varepsilon) \geq \sigma(S_i)$

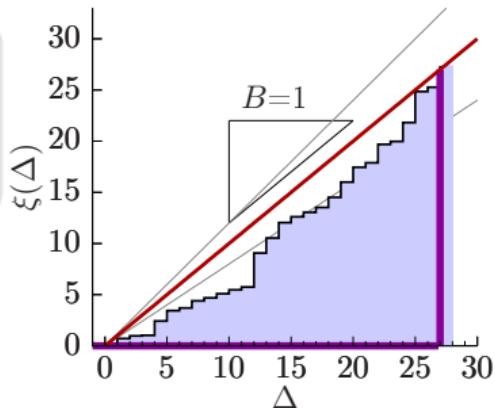
Universal Avalanche Definition:

$$\xi(\Delta_i) > B(S_i|h)\Delta_i$$

(hitting times)

Slope B is function of state:

$$B(S_i|h) = \frac{S_i \text{ pdf}(S_i)}{1 - F(S_i)} (1 - h)$$



$\xi(\Delta)$: Poisson counting process of Δ steps.

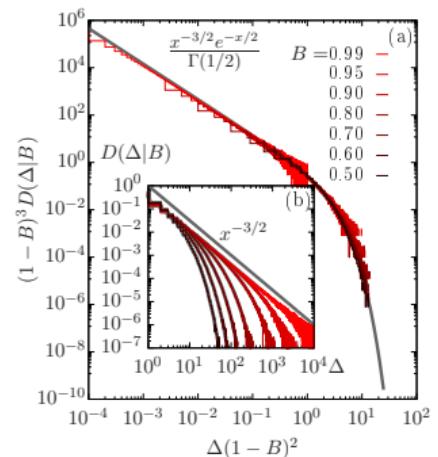
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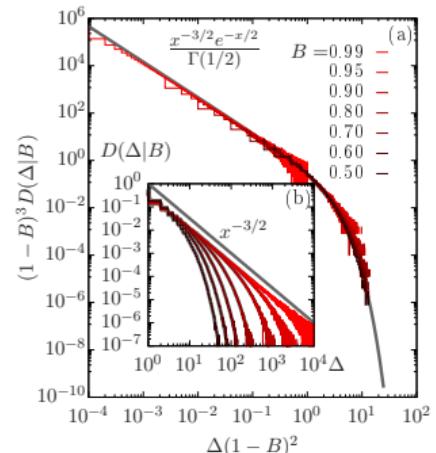
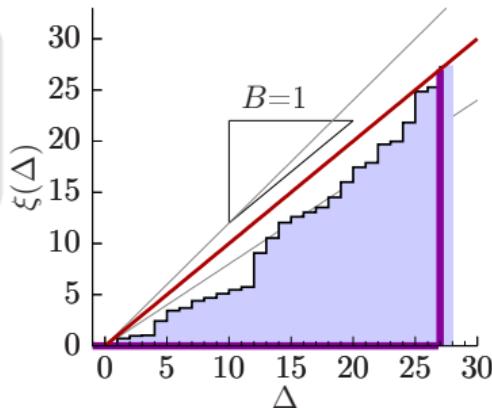
(hitting times)

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$$B(S_i|h) = \frac{S_i \text{ pdf}(S_i)}{1 - F(S_i)} (1 - h)$$

At failure ($d\sigma/d\varepsilon|_{\sigma_f} = 0$):

$$B(E\varepsilon_f|h) = (1 - h)$$



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(hitting times)

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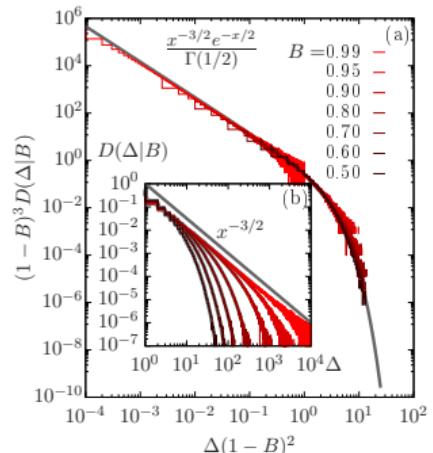
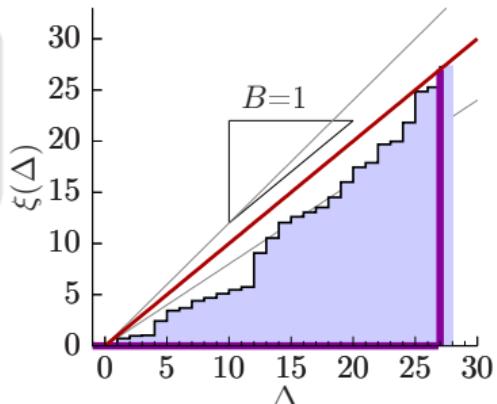
At failure ($d\sigma/d\varepsilon|_{\sigma_f} = 0$):

$$B(E\varepsilon_f|h) = (1 - h)$$

Critical failure for $h = 0$.

Subcrit. failure for $h > 0$.

[Baró & Davidsen, PRE (2018)]



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Topological properties of aftershock clusters in a viscoelastic model of quasi-brittle failure

Jordi Baró ^{a,b}, Jörn Davidsen ^a, Alvaro Corral ^b

^a Complexity Science Group, Dept. of Physics and Astronomy, Univ. of Calgary, Calgary, AB, T2N 1N4, Canada.

^b Centre for Mathematical Research (CRM), Barcelona, 08193, Spain.

1) VISCOELASTICITY & AFTERSHOCKS

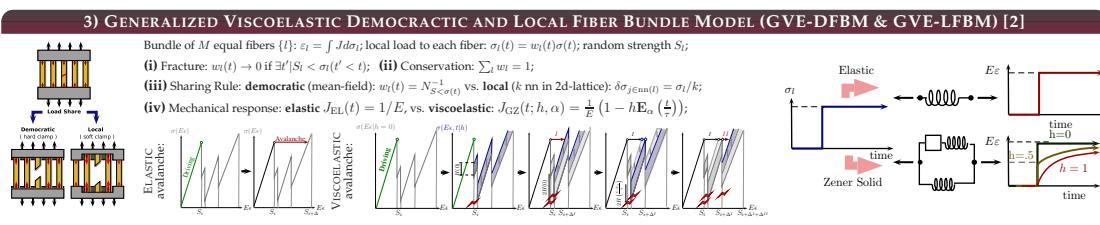
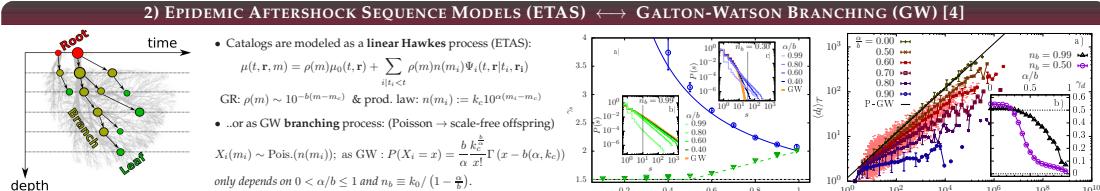
Material failure at different scales and processes can be modeled as an emergent feature in terms of **avalanche dynamics in micromechanical systems**. Event-event triggering—aftershocks—is common in seismological catalogs and acoustic emission experiments [1] among other phenomena. Stochastic branching and linear Hawkes processes are used to model the statistical properties of catalogs. In the micromechanical approach, viscoelastic stress transfer and after-slip are among the proposed mechanism of aftershocks.

Here we ask this simple question:

Do aftershock sequences in micromechanical models agree with such epidemic branching paradigm?

We introduce two **fibrous models** as prototypes of viscoelastic fracture [2] which (i) provides an analytical explanation to the acceleration of activity in absence of critical failure observed in acoustic emission experiments [3]; (ii) reproduce the typical spatio-temporal properties of triggering found in field catalogs, acoustic emission experiments; but (iii) display discrepancies with the branching topological properties predicted by stochastic models, probably due to physical constrains.

- [1] J. Baró et al., *Phys. Rev. Lett.* **10** (8), 088702 (2013).
- [2] J. Baró, J. Davidsen, *Phys. Rev. E* **97** (3), 033002 (2018).
- [3] J. Baró et al., *Phys. Rev. Lett.* **120** (24), 245010 (2018).
- [4] J. Baró, *J. of Geophys. Res.: Solid Earth*, **125**, e2019JB018530 (2020); S. Saichev, et al., *Pure and App. Geophys.*, **162** (6), 1113–1134 (2005).

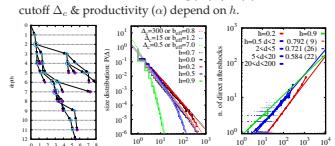


4) ACTIVITY AND AFTERSHOCKS

- Viscoelasticity trades critical avals. for foreshocks [2], as observed in acoustic emission experiments [3].
- Aftershock kernel: $\Psi_i(t, \mathbf{r}) \approx \frac{d}{dt} \frac{d}{dr} \sigma_i(\frac{r}{\Delta}) \exp(-\frac{|r|}{\sigma_i(h)})$.

5) BRANCHING PARAMETERS (α/b , n_b)

- ‘combed’ trees; Borel distr: $P(D; f_c) = (f_c/\Delta)^{\Delta-1} e^{-f_c/\Delta}/\Delta!$, considering $m = \log_{10} D \rightarrow b = 0.5$; $\alpha \approx 0.8$ ($\alpha/b = 1.6 \geq 1$).
- Size distribution: $\Delta \sim \Delta^{-1-b} \exp(-(\Delta/\Delta_c)^b)$ w. $b \sim 0.7$; cutoff Δ_c & productivity (α) depend on h .



DEMOCRATIC

2D-LOCAL

6) TOPOLOGICAL PROPERTIES OF TRIGGERING TREES

Comparison of trees in DFBM with ETAS model:

- Offspring (X) and tree-size (S) distributions: power law w. $\gamma_x = 2.5$ ($\alpha/b = 2/3$ in ETAS). From aval. size (Δ): $\int P(D; f_c) dD \rightarrow S \sim \Delta(h=0)$. ($\gamma = 1.5$ at crit. point)
- Leaf-depth (d) scale like $S^{0.5}$ like **swarms** (α/b). Not as **bursts** (indep. of S) expected for high α/b .
- ETAS needs to account for cutoff (correcting $\alpha/b > 1$) and temporal variations of parameters.

h	0.2	0.5	0.9
b_{eff}	0.8	1.2	1.7
α	0.78	0.72	0.58
$\frac{\alpha}{b_{\text{eff}}}$	0.975	0.600	0.082
$\frac{\alpha}{b_{\text{eff}}}$	0.171	0.413	0.675
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γ_{size}	0	0	0.5
γ_{off}	0.33	0.51	0.59

