

River-landslide erosion interaction assessed through **LiDAR** and **UAV SfM** high-resolution DEMs, **SAR** and **photogrammetry**

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- In landslide research an important part is dedicated to the reconstruction of past landslide events and activity. This is an important aspect regarding the possibility to understand both landslide evolutions mechanisms and factors.
- For the last 100 years, cartographic, and for the last 50 years, remote sensing (RS) data is of crucial importance for such approaches.
- The spatial and temporal resolution of this data is increasing toward the present day.
- The information that can be used is both quantitative and qualitative.
- We present a study case of the usage of various RS data and methods to characterize river and landslide interactions in the hilly area of NE Romania.

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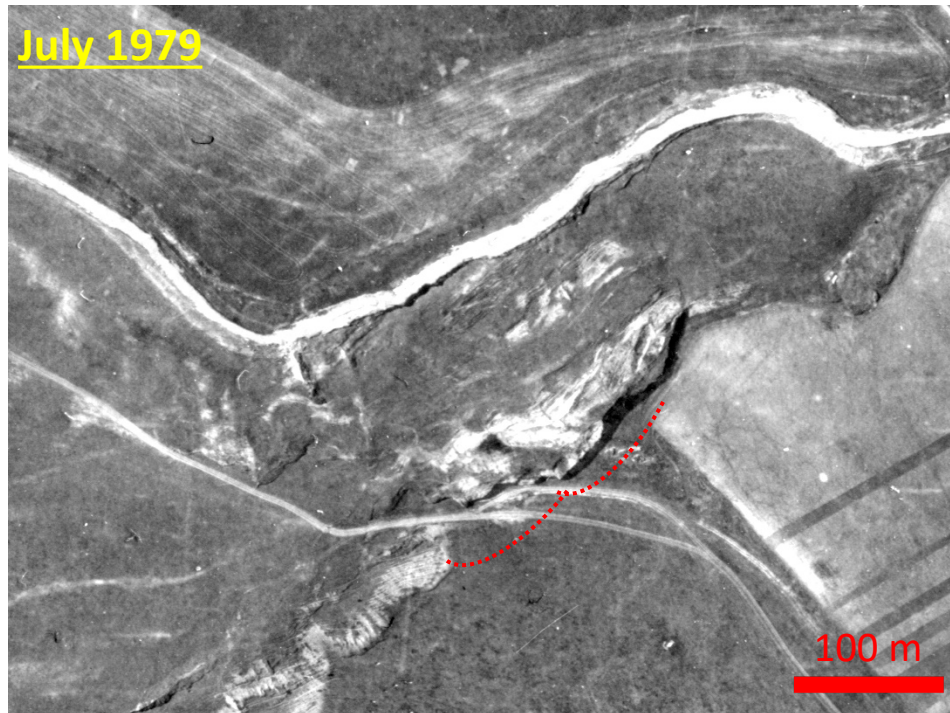
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- Topographic maps and optic imagery show that the river Miletin created the instability at least at the beginning of the XXth century, in 1980 the landslide appearing laterally to an old dormant landslide, and showing transgressive evolution trough scarp slumping.
- Between 1980 and 2005, the landslide has shown important scarp reactivation and Miletin river channel sinuosity increased .

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- After 2005, the scarp slumping continued, but in the same time the increased Miletin river channel sinuosity started to erode the basal part of the landslide. The evolving channel sinuosity and erosion has created stability of the landslide body, the previous scarp slump deposits being mobilised. The scarp has shown new signs of slumping.

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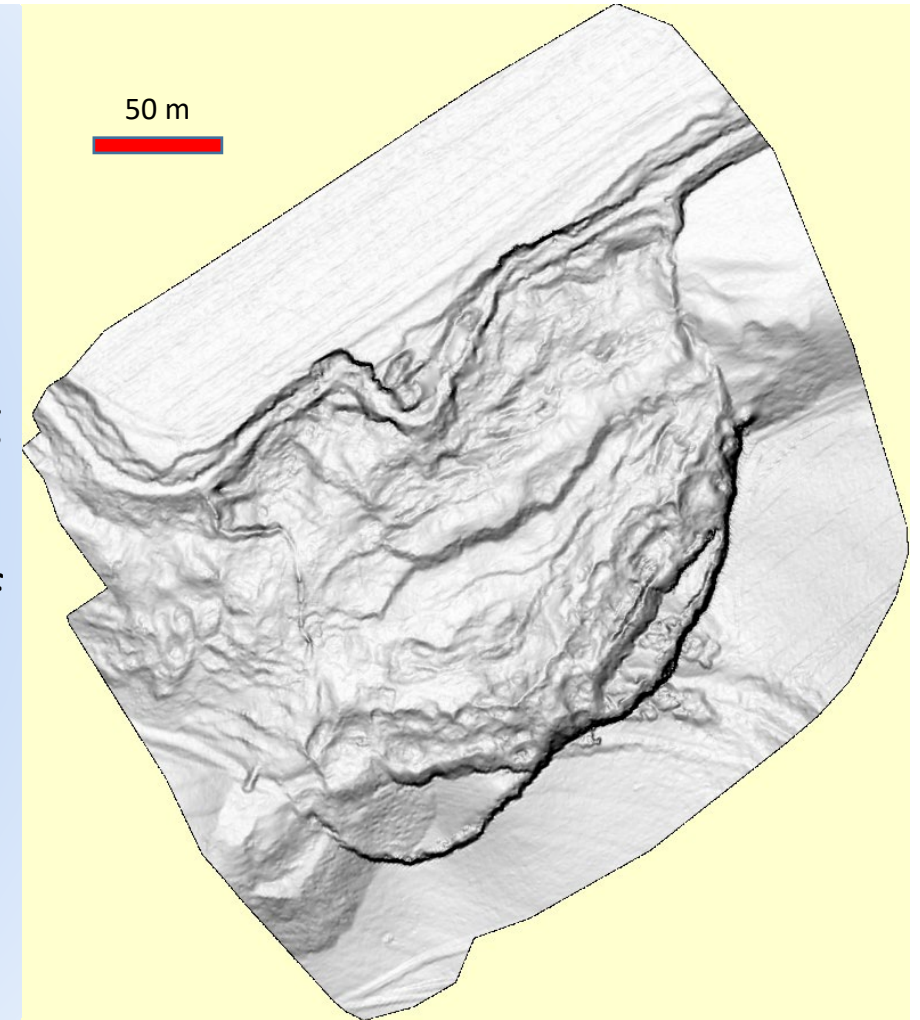
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LiDAR data

- LiDAR data acquired in February 2012 with 4-6 points per meter density and was classified in Cloud Compare with the CANUPO (Brodu and Lague, 2012) and CSF (Zhang et al., 2016) plugins.
- The DEM was obtained through interpolation in SAGA GIS using Multilevel B-spline (for a detailed description of the methodology see Niculiță et al., 2020) at a resolution of 0.25 m.
- Geomorphic Change Detection (Wheaton 1998, Wheaton et al., 2010a, 2010b) in it's simplest setup (through thresholding of ± 0.15 m) was used to asses the changes.



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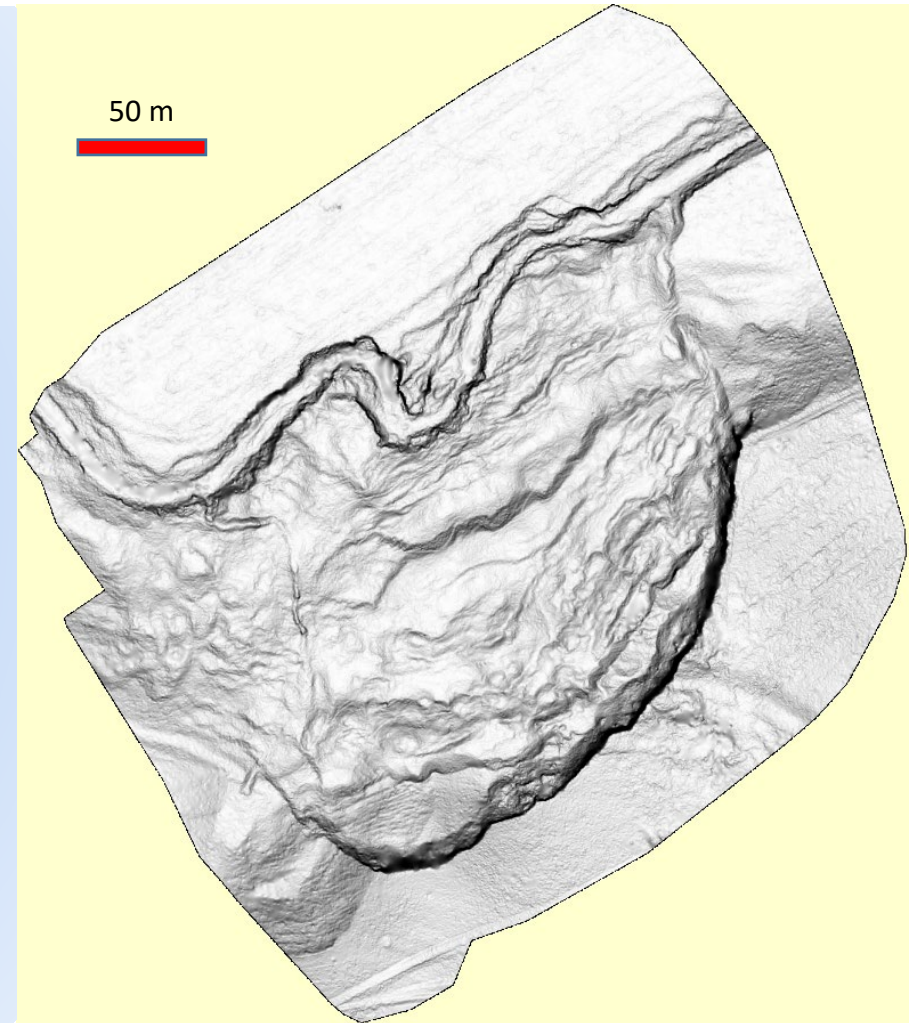
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Structure from Motion from UAV images

- The Phantom 4 Pro quadcopter was used to capture the images in stereo pairs (models) as a string & block photogrammetric flight path with 80% side and forward (end) overlap. The altitude of the flight was 50 m relative to the terrain surface, the flight plan being computed and executed by UgGS software. The camera acquired images at 20 MP resolution, in 3:2 Aspect Ratio with a size of 5472x3648 pixels per image and RAW format. The nominal pixel size was ~ 0.012 m.
- SfM was performed in Visual SFM, the point cloud being georeferenced using 14 GCPs measured in the field with a Trimble GeoExplorer 6000 GPS and the ROMPOS differential correction service.



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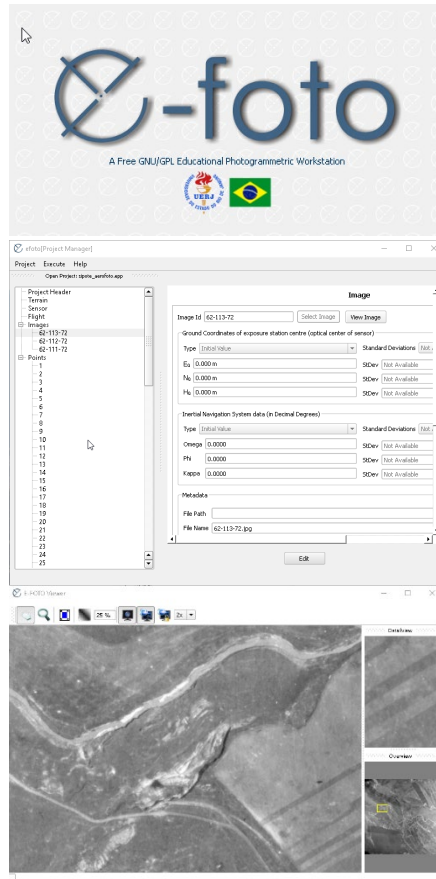
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Digital Photogrammetry



- E-Foto photogrammetry software (<http://www.efoto.eng.uerj.br/en> - Ribeiro et al., 2018) was used to perform a digital photogrammetry workflow .
- Two photogrammetric images acquired in July 1979, in stereo pair with 60% overlap; interior orientation > photo-triangulation > exterior orientation by spatial resection > vector points generated through stereo plotter.
- Unfortunately since the point cloud was sparse a DEM could not be obtained, and five topographic profiles were extracted by stereoscopic measurements.

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The screenshot displays the SBA website interface. On the left, a sidebar shows navigation options like 'Home', 'About', 'Contact', 'FAQ', 'Privacy Policy', and 'Terms of Service'. The main content area features a map of the San Francisco Bay Area. A red polygon is drawn on the map, indicating a specific geographic area. To the right of the map is a sidebar with a 'Profile' section for 'Run 65'. This section includes fields for 'Assigned Date', 'Status', 'Start Date', 'End Date', 'Base Value', 'Days', 'Light Level', 'Low Density', 'Parameters', 'Low Level', 'Category', 'Min. Temp', and 'Max. Temp'. Below the map is a table with columns: Options, Allocation, Start Time, Drop Time, Satellite ID, First Name, First Name, Base Value, Days, Light Level, Low Density, Parameters, Low, Check Date, and Date. The table contains 10 rows of data for 'Run 65'.

Options	Allocation	Start Time	Drop Time	Satellite ID	First Name	First Name	Base Value	Days	Light Level	Low Density	Parameters	Low	Check Date	Date
Run 65	3076	20 50:00:00.000000000	20 50:00:00.000000000	30	3076	3076	80	NA	GPS/IRIDIUM	C	VMM	0.0	NA	00/00/00
Run 65	3076	20 50:00:00.000000000	20 50:00:00.000000000	30	3076	3076	80	NA	GPS/IRIDIUM	C	VMM	0.0	NA	00/00/00
Run 65	3076	20 50:00:00.000000000	20 50:00:00.000000000	30	3076	3076	80	NA	GPS/IRIDIUM	C	VMM	0.0	NA	00/00/00
Run 65	1491	20 50:00:00.000000000	20 50:00:00.000000000	30	3076	3076	80	NA	GPS/IRIDIUM	C	VMM	0.0	NA	00/00/00
Run 65	1491	20 50:00:00.000000000	20 50:00:00.000000000	30	3076	3076	80	NA	GPS/IRIDIUM	C	VMM	0.0	NA	00/00/00
Run 65	1491	20 50:00:00.000000000	20 50:00:00.000000000	30	3076	3076	80	NA	GPS/IRIDIUM	C	VMM	0.0	NA	00/00/00
Run 65	1491	20 50:00:00.000000000	20 50:00:00.000000000	30	3076	3076	80	NA	GPS/IRIDIUM	C	VMM	0.0	NA	00/00/00
Run 65	1491	20 50:00:00.000000000	20 50:00:00.000000000	30	3076	3076	80	NA	GPS/IRIDIUM	C	VMM	0.0	NA	00/00/00
Run 65	1491	20 50:00:00.000000000	20 50:00:00.000000000	30	3076	3076	80	NA	GPS/IRIDIUM	C	VMM	0.0	NA	00/00/00
Run 65	1491	20 50:00:00.000000000	20 50:00:00.000000000	30	3076	3076	80	NA	GPS/IRIDIUM	C	VMM	0.0	NA	00/00/00

- Graph Builder
- File Graphs
-
- ```
graph LR; Read --> TOPSAR-Split; Read2[Read(2)] --> TOPSAR-Split; Read3[Read(3)] --> EAP-Phase-Correction; EAP-Phase-Correction --> TOPSAR-Split; TOPSAR-Split --> Apply-Orbit-File; Apply-Orbit-File --> Interferogram; Interferogram --> TOPSAR-Deburst; TOPSAR-Deburst --> Subset; Subset --> Multilook; Multilook --> GoldsteinPhaseFiltering; GoldsteinPhaseFiltering --> SnaphuExport; SnaphuExport --> Snaphu-unwrapping; Snaphu-unwrapping --> SnaphuImport; SnaphuImport --> PhaseToDisplacement; PhaseToDisplacement --> Terrain-Correction; Terrain-Correction --> Write;
```

- SNAP Phase processing and SNAPHU unwrapping to estimate displacement from Phase.
- Future approach will try a SBAS DInSAR since PS is not suitable, and displacement from Phase results are promising.

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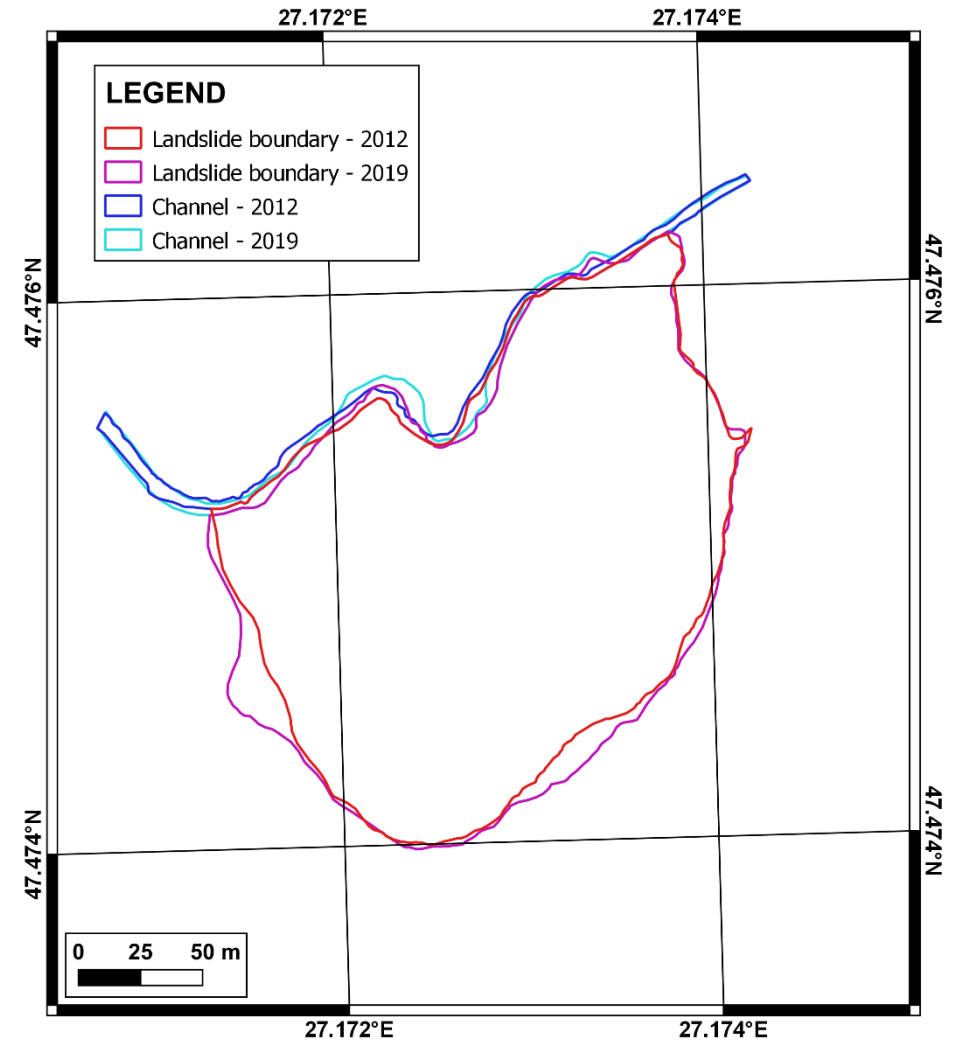
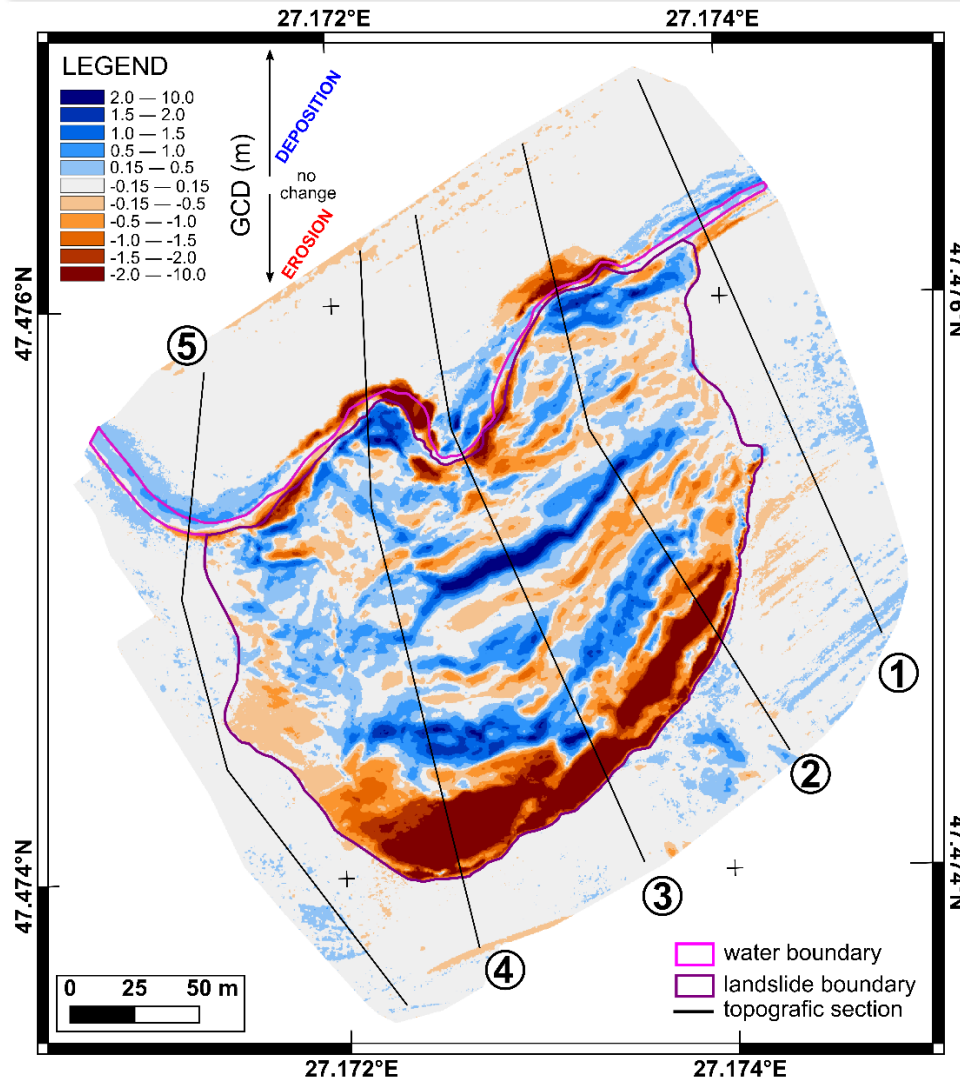


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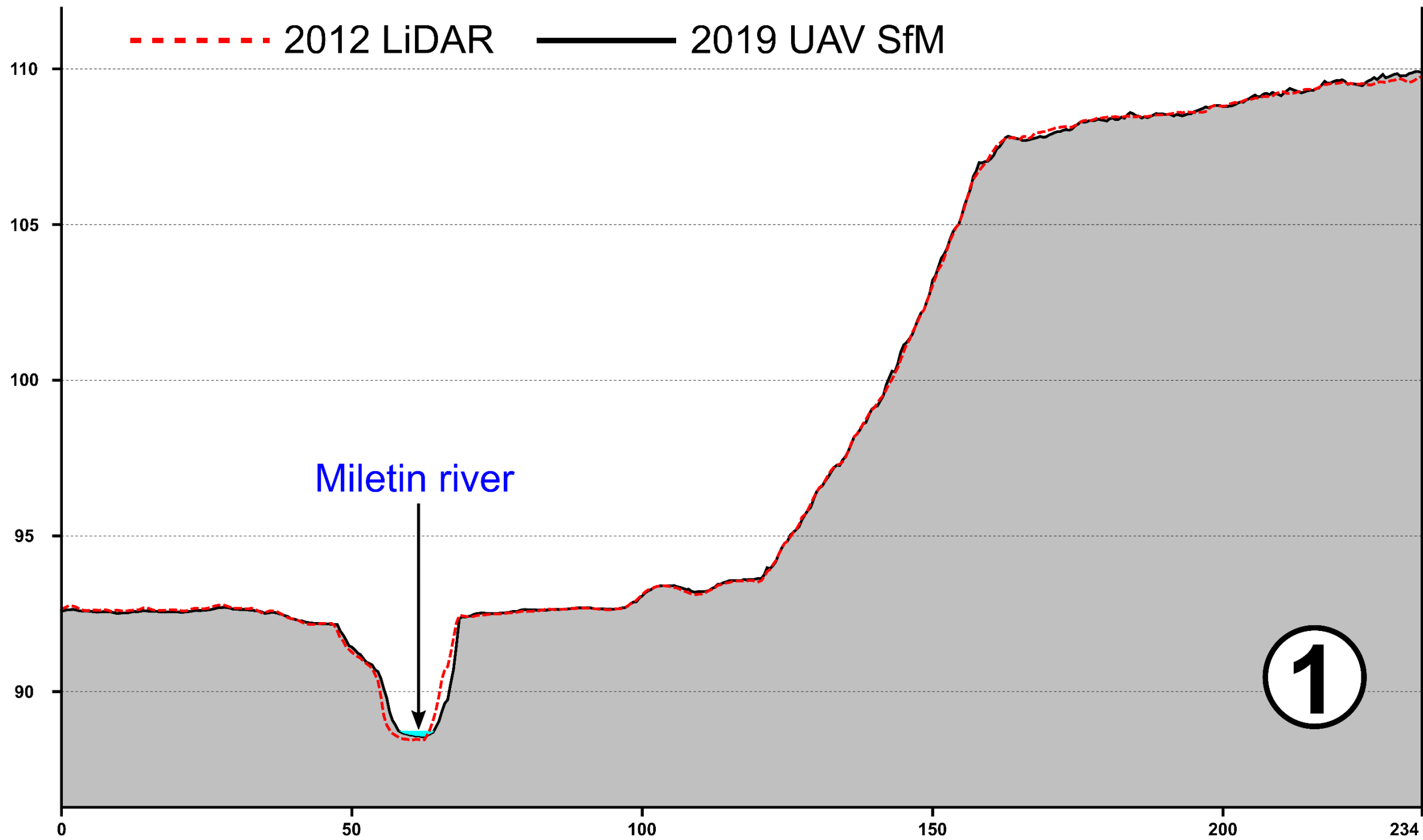
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# RESULTS – GCD 2012-2019

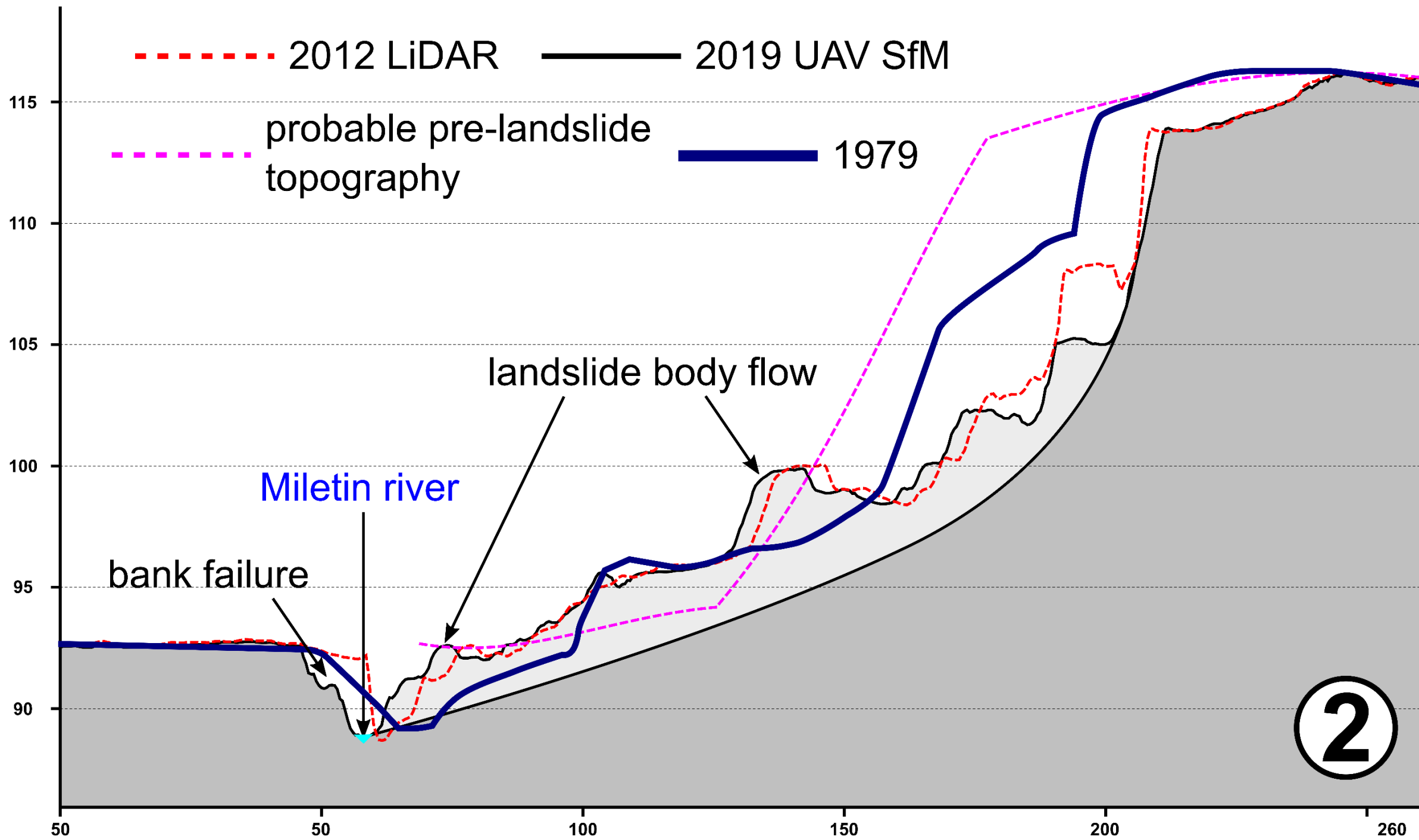


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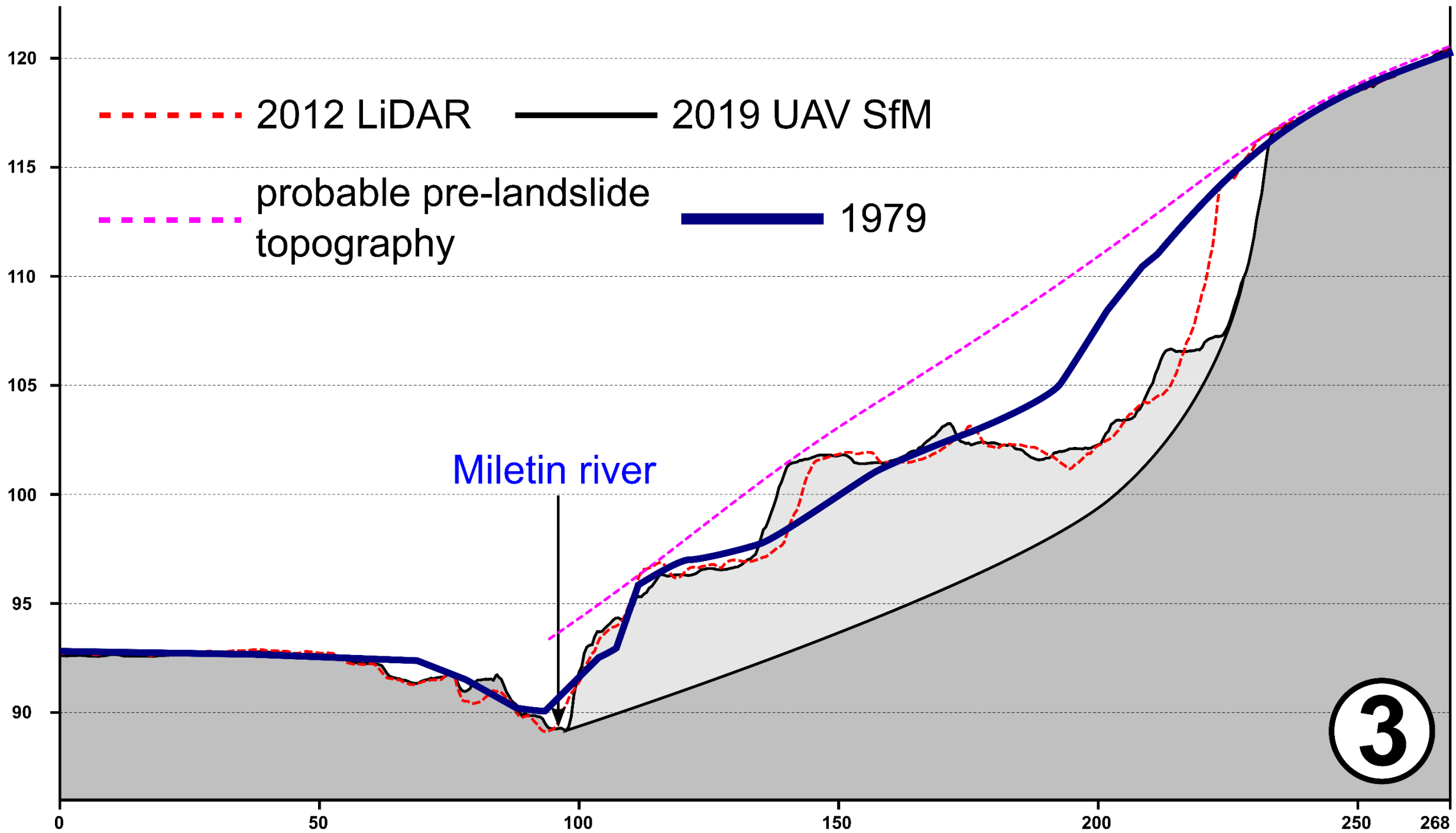




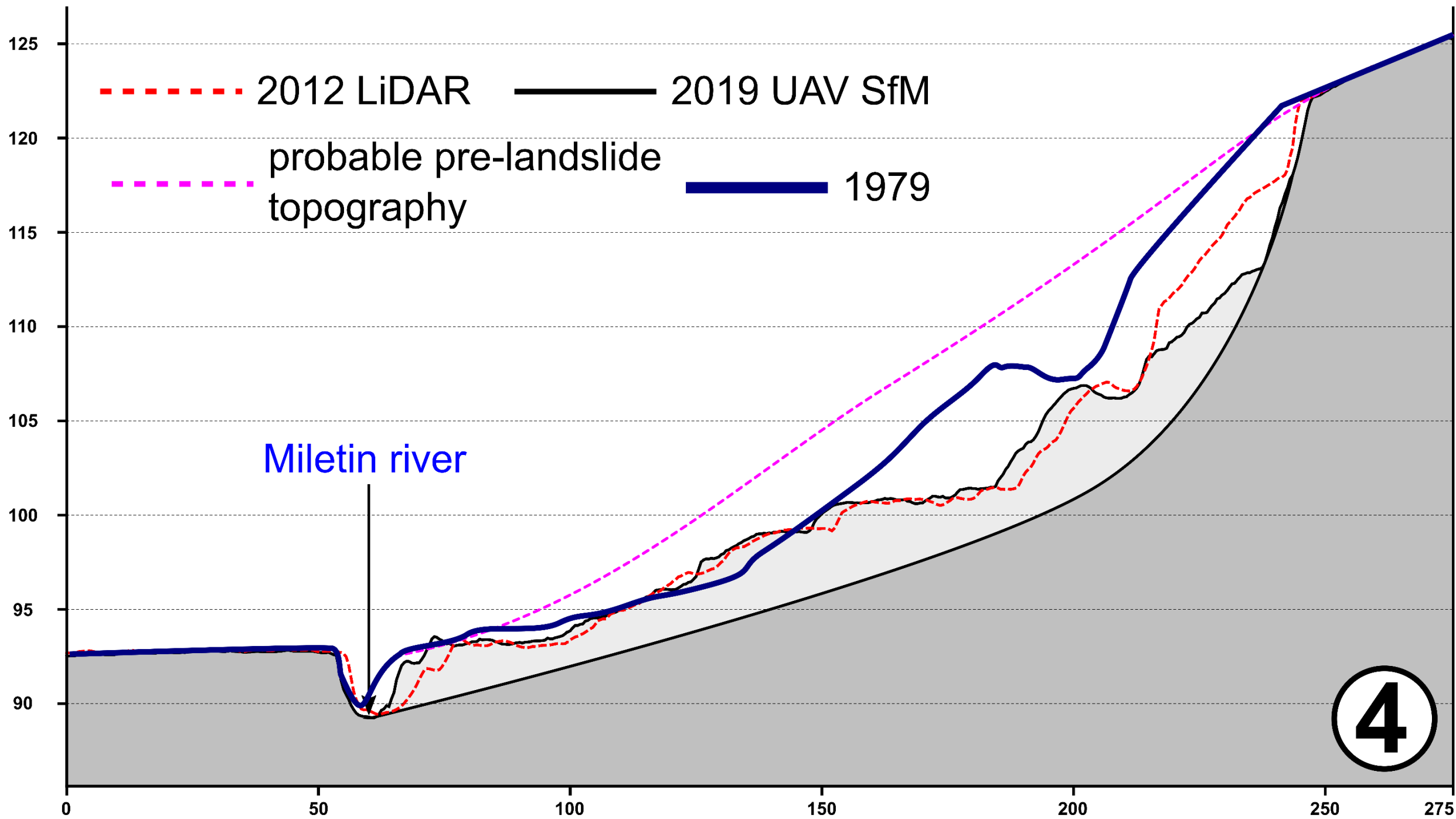


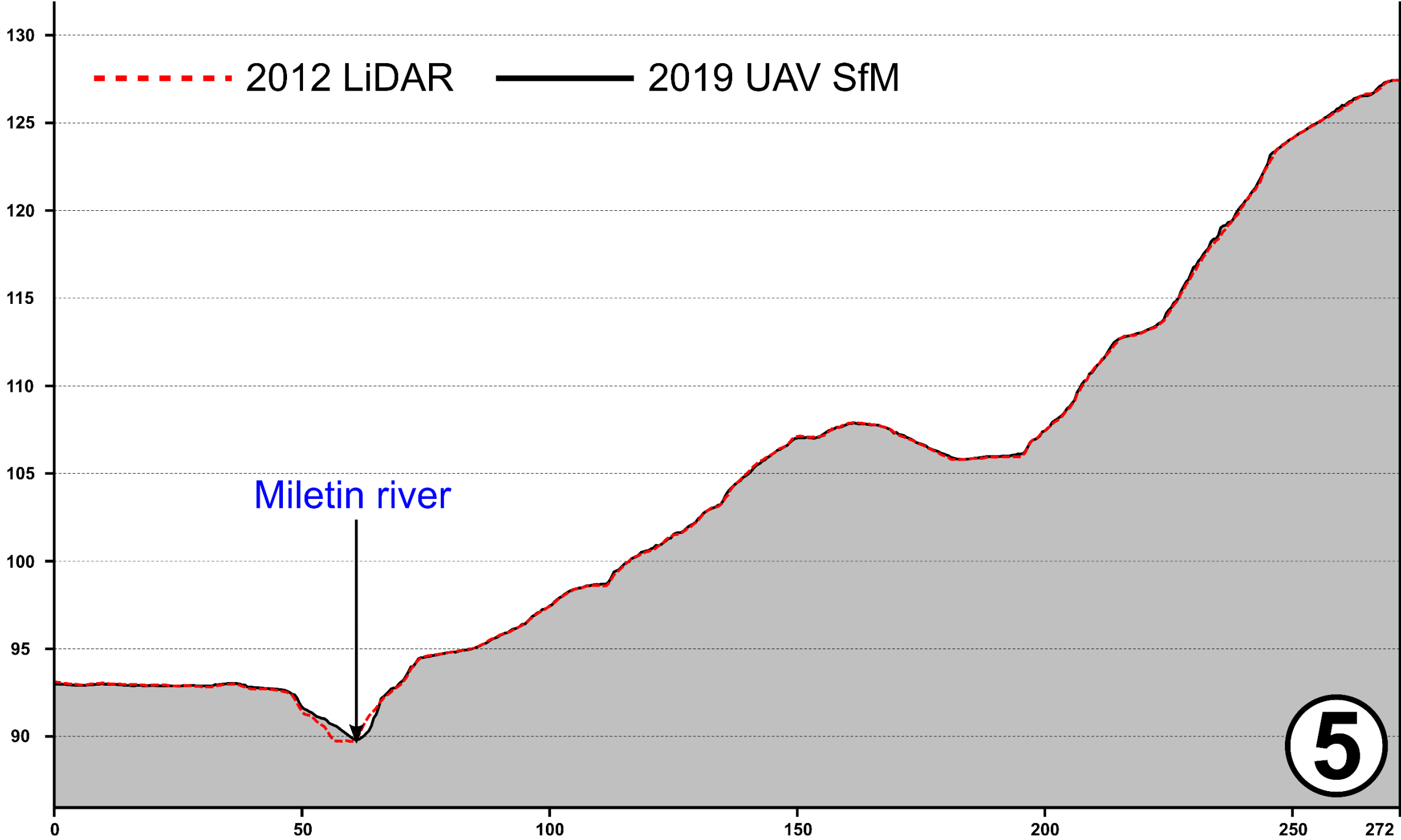




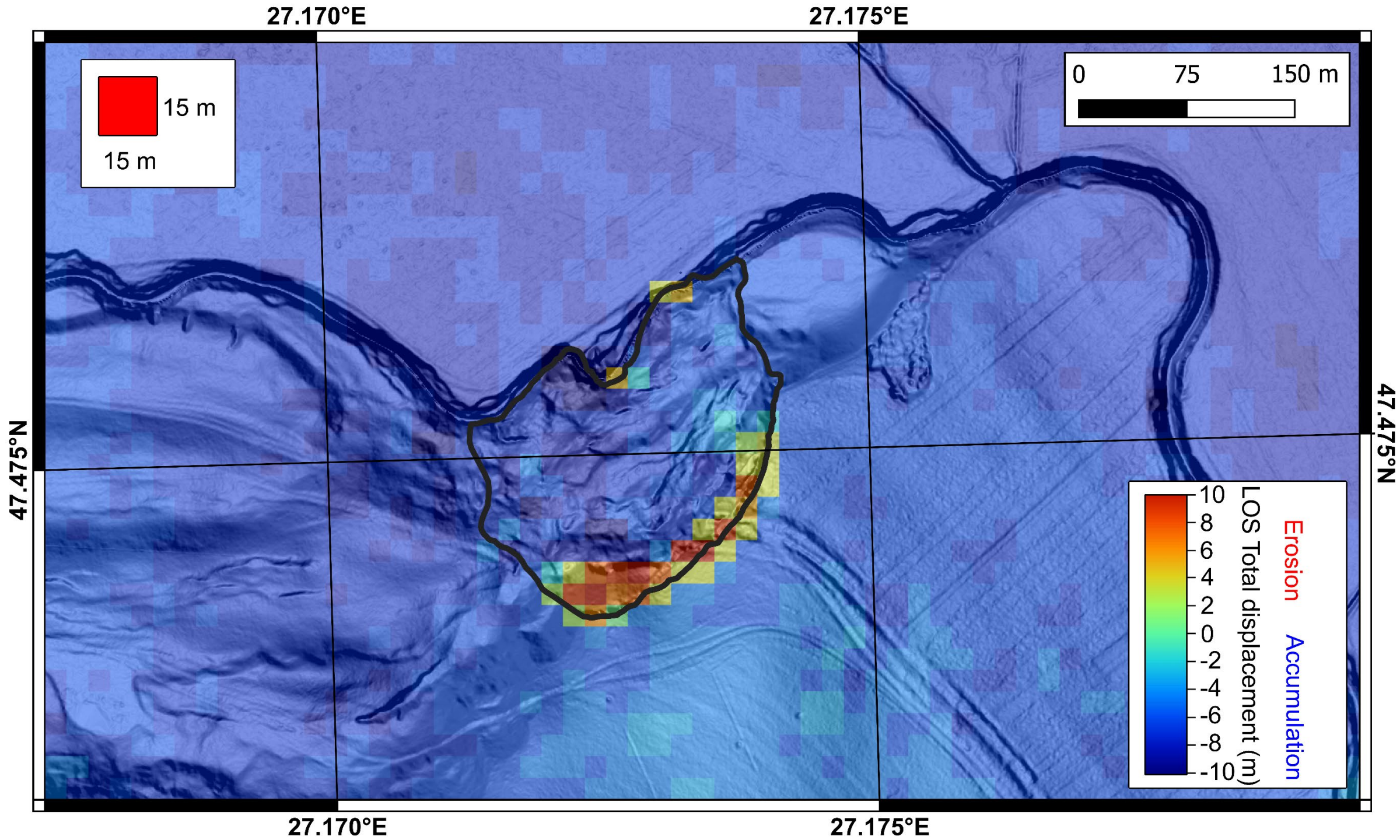












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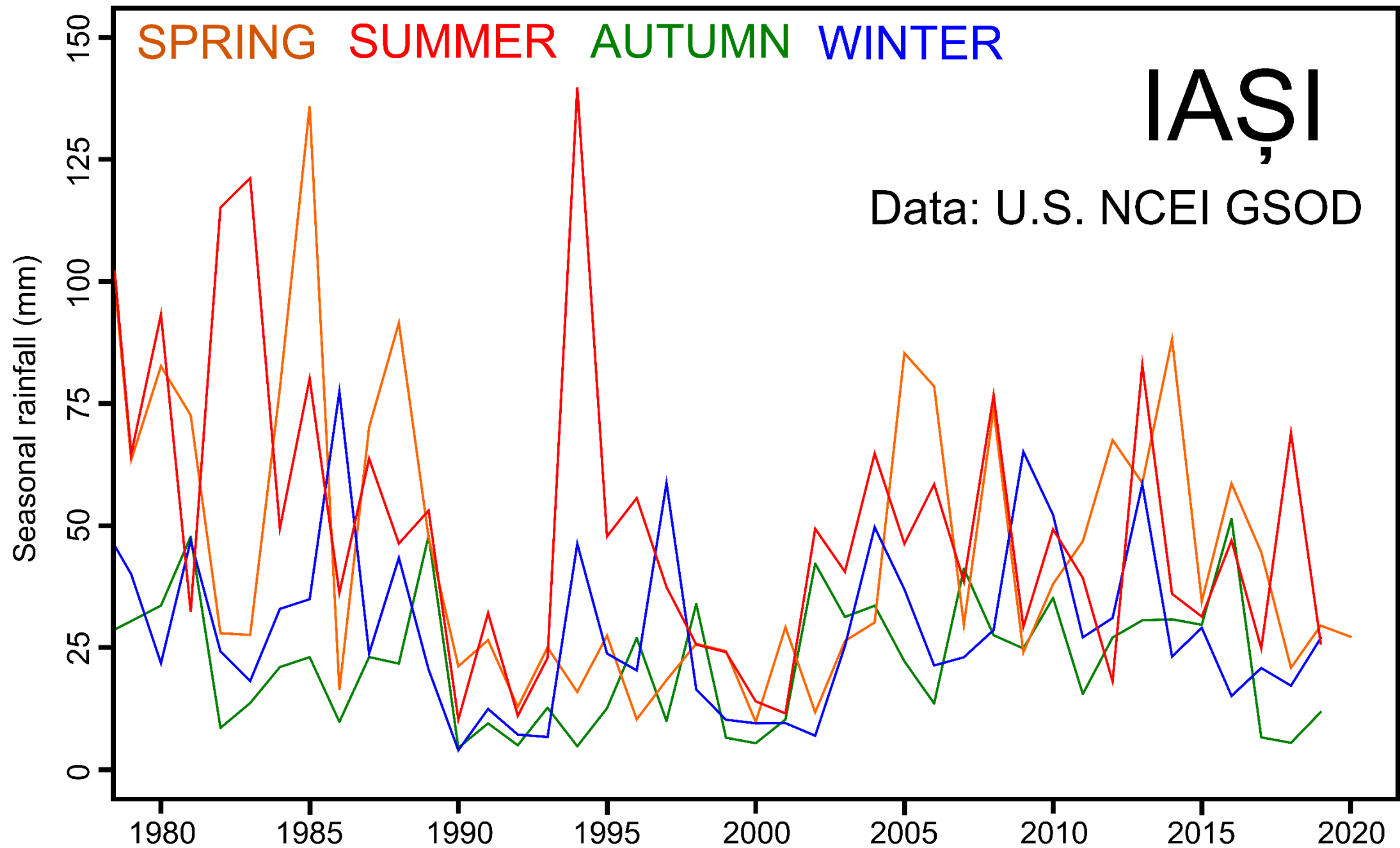
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# DISCUSSIONS

- The RS data and methods are able to show the following aspects regarding the Șipote-Chișcăreni landslide:
  - The landslide triggered before 1920, evolved through retrogression scarp slumping as the river incised and migrated toward the base of the hillslope.
  - The incision of the river and its ability to evacuate the basal part of the landslide body maintained the instability, the flow of the body material and the scarp slumping.
  - The intensification of fluxes of landslided material generate the increasing of channel sinuosity;
  - Erosion and accumulation, both for river channel, banks and landslide elements are spatially assessed;
  - SAR displacement estimates are in good agreement with the GCD rates, and an SBAS temporal assessment of the rates could provide a temporal characterization of landslide activity;
  - The landslide scarp reactivated after the 2005, 2008 and 2010 wetter years and its retreat has stopped in the last five years which are dry during the winter.

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- The availability of historic and active RS data and of RS techniques is proving beneficial to natural hazard studies.
- By merging the qualitative and quantitative information gathered about geomorphological processes and changing topography the near future evolution can be estimated.
- We have shown that in the case of Șipote-Chișcăreni landslide, channel incision and fluvial erosion are linked with landslide triggering and dynamics. In its present state the landslide is inactive during dry seasons, but it is re-activated during wet seasons.

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An aerial photograph of a river canyon. The river flows from the top left towards the bottom center. The canyon walls are steep and show signs of erosion, with some areas of exposed rock and others covered in sparse vegetation. A dirt road runs along the right side of the canyon. A small white car is parked on the grassy bank near the bottom right. The surrounding landscape is green and hilly.

Thank  
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attention 😊



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