

Distributed Fiber Sensing

Integration of Machine Learning on Distributed Acoustic Sensing surveys

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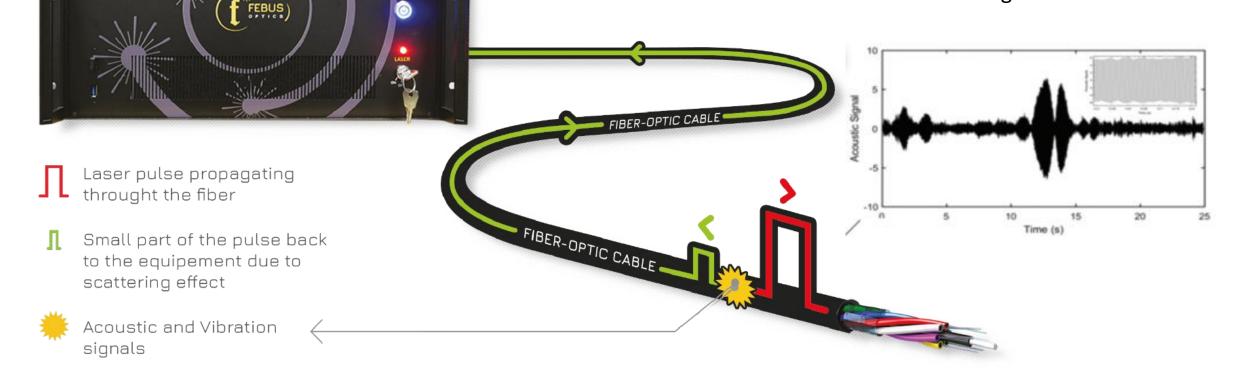
FEBUS OPTICS Distributed Fiber Sensing



Introduction

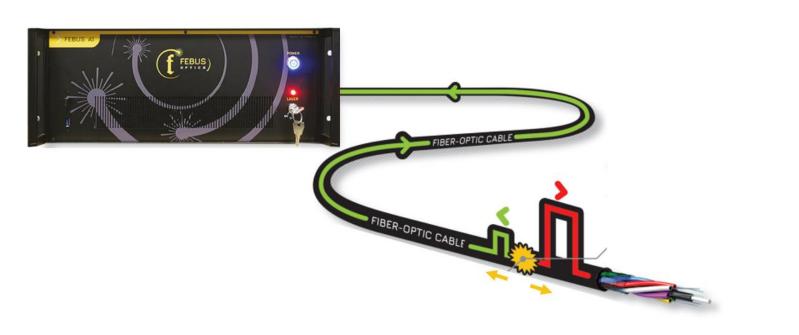
* DAS principle

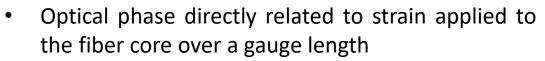
- Scattering effect occurs everywhere along the fiber
- The backscattering light contains the information of strain from where it was generated



Introduction







- Time derivative of the strain -> strain rate
- Strain-rate unit : nm/m/s

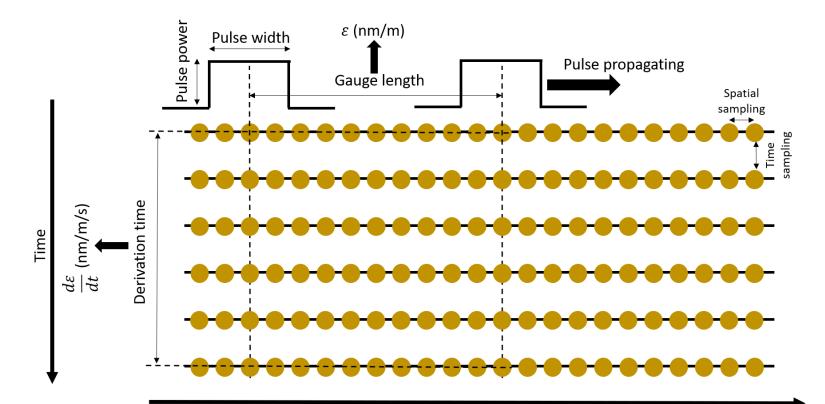
 $4\pi nG\xi$

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Introduction

* DAS principle: Acquisition parameters

- Parameters to adjust :
 - Fiber distance
 - Optical power
 - Pulse width
 - Pulse rate frequency
 - Spatial sampling resolution
 - Gauge length
 - Derivation time



Distance



Machine Learning applied to DAS surveys

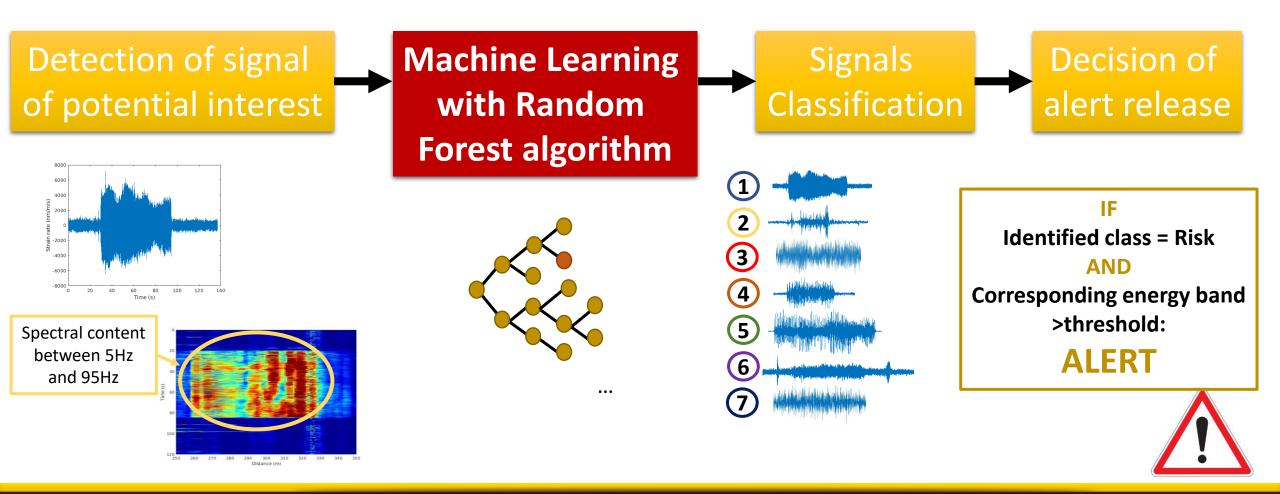
Context of the study

Pipeline monitoring for intrusion detection:

- Third party works detection and location using DAS is commonly applied in different contexts
- Challenge in identifying the origin of the signal:
 - Necessity of pattern recognition for relevant alarm.
 - Source and amplitude analysis for determining the threat at the pipeline neighbourhood.
 - The source identification must be fast, accurate and robust.
 - For its application to DAS data, the used method must be able to handle a big amount of data.

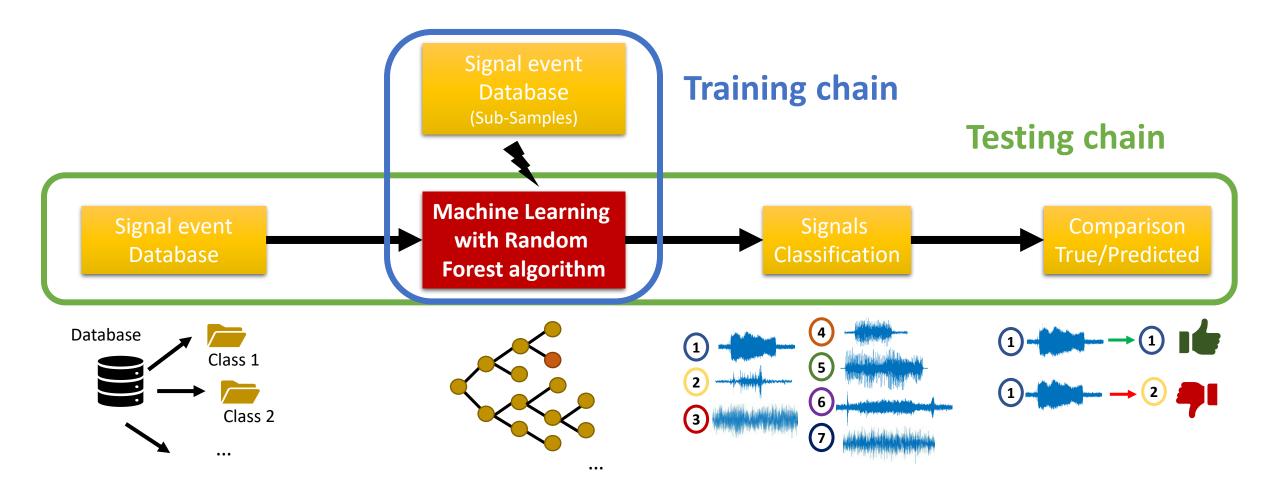
Solution: A Machine Learning algorithm enabling Classification of patterns before the alert release

The data processing chain

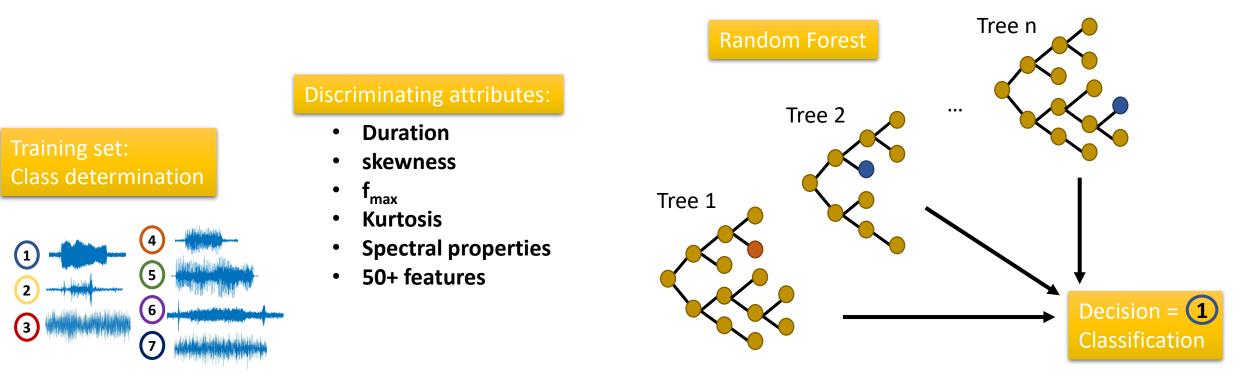


Machine Learning applied to DAS surveys

The training and testing chains



Test of the use of the supervised classifier named <u>Random Forest</u> algorithm, an ensemble learning method based on the use of decision trees



Machine Learning: Use of tens of attributes

Waveform Attributes: 23

- 1. Duration
- 2. Max/Mean ratio
- 3. Max/Median ratio
- 4. Ascending/Descending time ratio
- 5. Kurtosis of raw signal
- 6. Kurtosis of signal envelop
- 7. Skewness of raw signal
- 8. Skewness of signal envelop
- 9. Number of peaks in autocorrelation function
- 10. Energy in 1st third part of autocorrelation function
- 11. Energy in remaining part of autocorrelation function
- 12. Ratio of 11 and 10
- 13-17. Energy of the signal filtered in 5-10Hz, 10-30Hz, 30-50Hz, 50-75Hz and 75-99Hz
- 18-22. Kurtosis of the signal filtered in 5-10Hz, 10-30Hz, 30-50Hz, 50-75Hz and 75-99Hz
- 23. RMS between decreasing part of the signal and $I(t) = Y_{max} \frac{Y_{max}}{t_f t_{max}}t$

Spectral Attributes: 17

- 24. Mean of the Discrete Fourier Transform (DFT)
- 25. Max of the DFT
- 26. Frequency at the maximum DFT
- 27. Frequency at the centroid
- 28. Central frequency of the 1st quartile
- 29. Central frequency of the 3rd quartile
- 30. Median of the normalized DFT

- 31. Variance of the normalized DFT
- 32. Number of peaks in normalized DFT
- 33. Number of peaks (>0.75 DFT_{max})
- 34-37. Energy in [0, 1/4]Nyf, [1/4, 1/2]Nyf, [1/2, 3/4]Nyf, [3/4, 1]Nyf
- 38. Spectral centroid
- 39. Gyration radius
- 40. Spectral Centroid width

Pseudo-Spectrogram Attributes: 17

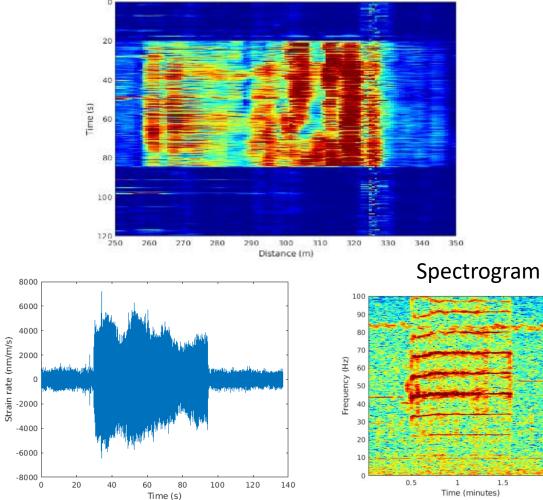
- 41. Kurtosis of max of all DFTs as a function of time
- 42. Kurtosis of median of all DFTs as function of time
- 43. Mean ratio between max and mean of all DFTs
- 44. Mean ratio between max and median of all DFTs
- 45. Number of peaks in the curve of temporal evolution of DFTs max frequency
- 46. Number of peaks in the curve of temporal evolution of DFTs mean frequency
- 47. Number of peaks in the curve of temporal evolution of DFTs median frequency
- 48. Ratio between 45 and 46
- 49. Ratio between 45 and 47
- 50. Mean distance between max and mean of all DFTs as function of time
- 51. Mean distance between max and median of all DFTs as function of time
- 52. Number of peaks in the curve of centroid frequency spectrum DFT
- 53. Number of peaks in the curve of max frequency spectrum DFT
- 54. Ratio between max frequency and centroid frequency DFTs
- 55. Mean distance between 1st quartile and median of all DFTs as function of time
- 56. Mean distance between 3rd quartile and median of all DFTs as function of time
- 57. Mean distance between 3rd and 1st quartiles of all DFTs as function of time



Manual Compactor



Energy band [5 - 95]Hz



1.5

2

0.8

0.6 0.4

0.2 Strain Rate 0 -0.5

-0.4

-0.6 -0.8

Time (s)

Excavation



Energy band [5 - 95]Hz Time (s) ® 10 12 14 270 280 290 300 310 320 33(Distance (m) Spectrogram $\times 10^4$ 100 90 (Hz) ency eq -1 b 0 0.5 1 5 10 15 Time (minutes)

15 6

10

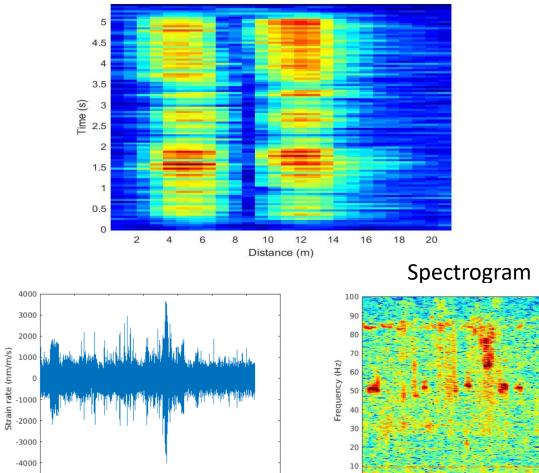
2

1.5

* Drilling



Energy band [5 - 95]Hz



-5000

0

20

40

60

80

Time (s)

100

120

140

0.5

45

40

35 ₽

15 &

2

1.5

1

Time (minutes)

8000

6000 4000

0000⁻ Strain Rate

-4000

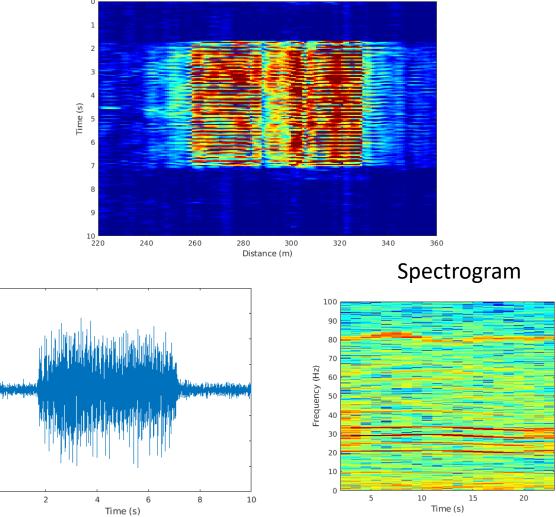
-6000

0

Sack hammer



Energy band [5 - 95]Hz



 $\times 10^4$

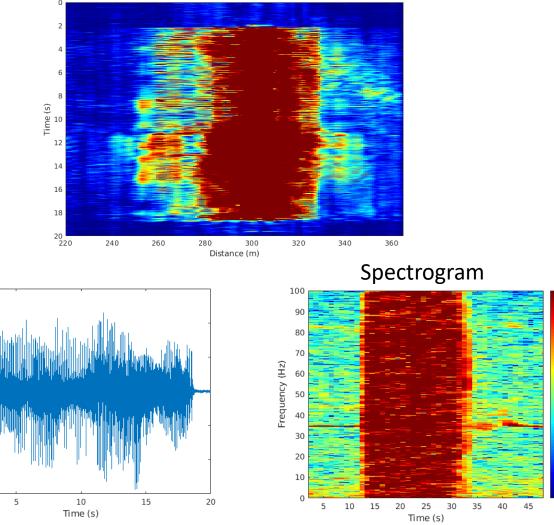
Strain Rate

-6 L 0

Sheet pile



Energy band [5 - 95]Hz



50 45

40 35 위

30 B

25

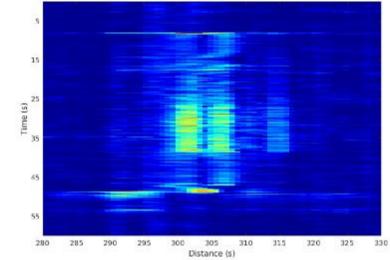
20 20 15

10

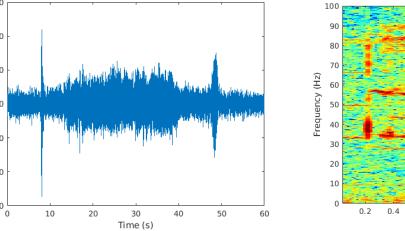
Circular saw



Energy band [5 - 95]Hz



Spectrogram



6000

4000

2000

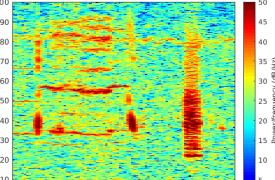
-2000

-4000

-6000

0

Strain Rate



1

Time (minutes)

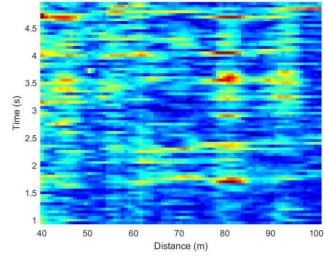
1.2 1.4 1.6

0.6 0.8

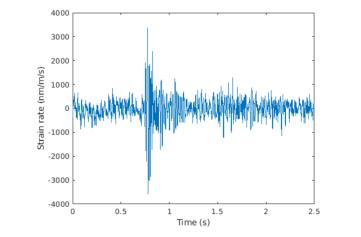
Transportations

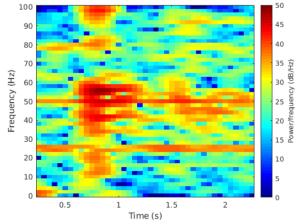


Energy band [5 - 95]Hz



Spectrogram





Then:

- In this study, we work on <u>7 classes</u> of event, numbered from 1 to 7.
- Because DAS acquisition can generate traces every few meters along fibres of tens of kilometres, <u>two methods are used for classification</u> using Random Forest algorithm:
 - 1. The first one is <u>signal</u> based: The algorithm is using each single trace/station for the signal classification.
 - 2. The second one is <u>event</u> based: A cluster of stations, identified as recording the same event, is used by the algorithm for the source signal classification. The majority of votes will release the final ID of the event.
- Three parameters are used to check the efficiency of the pattern ID using Machine Learning: <u>Precision</u>, <u>Recall</u> and <u>Accuracy</u>

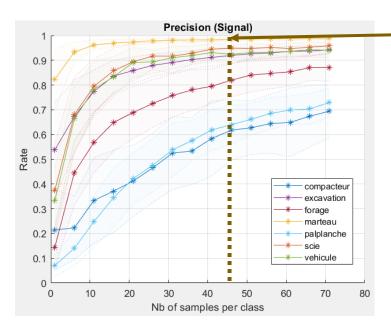
Quality Control parameters

Predicted

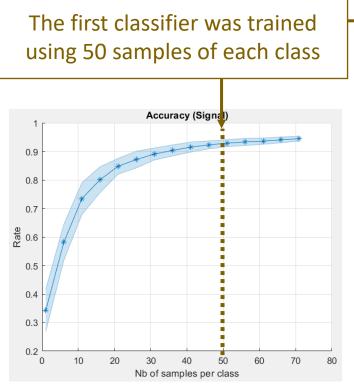
		Negative	Positive	
Actual	Negative	True negative	False positive	
	Positive	False negative	True positive	



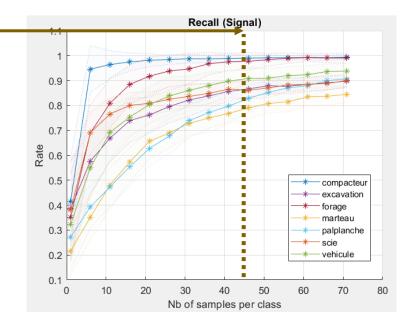
First approach: use of the same number of samples for each class



1 - False alarm rate for each class



Global good classification rate



1 – Lack of detection rate for each class

First approach: use of the same number of samples for each class

	Accuracy: 91.28%								
1	100.0%	0.0%	0.0%	1.2%	0.0%	5.3%	0.0%		
	75	0	0	20	0	17	0		
2	0.0%	91.7%	0.0%	1.1%	19.0%	0.3%	6.5%		
	0	505	0	19	20	1	35		
3	0.0%	3.4%	100.0%	1.4%	0.0%	3.4%	0.6%		
S	0	19	125	24	0	11	3		
Output Class	0.0%	0.7%	0.0%	92.8%	0.0%	1.9%	1.9%		
	0	4	0	1601	0	6	10		
б	0.0%	0.4%	0.0%	2.6%	75.2%	2.8%	1.1%		
5	0	2	0	45	79	9	6		
6	0.0%	0.0%	0.0%	0.1%	0.0%	85.7%	0.6%		
	0	0	0	2	0	275	3		
7	0.0%	3.8%	0.0%	0.9%	5.7%	0.6%	89.4%		
	0	21	0	15	6	2	481		
	1	2	3	4	5	6	7		
	Target Class								

Confusion matrix for signal

		Accuracy: 88.46%								
	1	100.0% 2	0.0% 0	0.0% 0	0.0% 0	0.0% 0	18.2% 2	0.0% 0		
	2	0.0% 0	100.0% 11	0.0% 0	0.0% 0	33.3% 1	0.0% 0	0.0% 0		
SS	3	0.0% 0	0.0% 0	100.0% 5	0.0% 0	0.0% 0	9.1% 1	0.0% 0		
Output Class	4	0.0% 0	0.0% 0	0.0% 0	91.7% 11	0.0% 0	0.0% 0	0.0% 0		
õ	5	0.0% 0	0.0% 0	0.0% 0	8.3% 1	66.7% 2	9.1% 1	0.0% 0		
	6	0.0% 0	0.0% 0	0.0% 0	0.0% 0	0.0% 0	63.6% 7	0.0% 0		
	7	0.0% 0	0.0% 0	0.0% 0	0.0% 0	0.0% 0	0.0% 0	100.0% 8		
		1	2	3 Ta	4 Irget Cla	5	6	7		

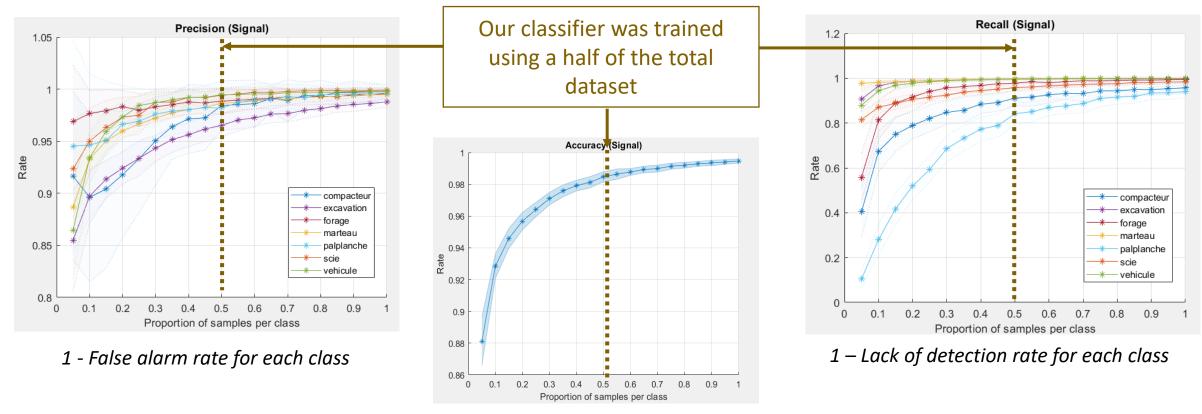
Confusion matrix for event

Classes:

- 1. Manual compactor (75)
- 2. Excavation (551)
- 3. Drilling (125)
- 4. Jack hammer (1726)
- 5. Palplanche (105)
- 6. Circular saw (321)
- 7. Transportation (538)

<u>For all studied events:</u> Classification with this algorithm is **88.46% correct** with an accuracy of 91.28%

Second approach: Training samples are taken proportional to their natural distribution occurrences



Global good classification rate

Second approach: Training samples are taken proportional to their natural distribution occurrences

	Accuracy: 98.69%								
1	93.3%	0.0%	0.0%	0.0%	0.0%	0.0%	0.0%		
	70	0	0	0	0	0	0		
2	0.0%	100.0%	0.0%	0.4%	8.6%	0.3%	0.0%		
	0	551	0	7	9	1	0		
3	0.0%	0.0%	100.0%	0.1%	0.0%	0.0%	0.0%		
S	0	0	125	1	0	0	0		
Output Class	6.7%	0.0%	0.0%	99.5%	5.7%	4.4%	0.0%		
A	5	0	0	1718	6	14	0		
Ō	0.0%	0.0%	0.0%	0.0%	84.8%	0.0%	0.0%		
5	0	0	0	0	89	0	0		
6	0.0%	0.0%	0.0%	0.0%	1.0%	95.0%	0.0%		
	0	0	0	0	1	305	0		
7	0.0%	0.0%	0.0%	0.0%	0.0%	0.3%	100.0%		
	0	0	0	0	0	1	538		
l	1	2	3	4	5	6	7		
	Target Class								

Confusion matrix for signal

Accuracy: 100.00%									
	1	100.0% 2	0.0% 0	0.0% 0	0.0% 0	0.0% 0	0.0% 0	0.0% 0	
:	2	0.0% 0	100.0% 11	0.0% 0	0.0% 0	0.0% 0	0.0% 0	0.0% 0	
	3	0.0% 0	0.0% 0	100.0% 5	0.0% 0	0.0% 0	0.0% 0	0.0% 0	
Output Class	4	0.0% 0	0.0% 0	0.0% 0	100.0% 12	0.0% 0	0.0% 0	0.0% 0	
	5	0.0% 0	0.0% 0	0.0% 0	0.0% 0	100.0% 3	0.0% 0	0.0% 0	
(6	0.0% 0	0.0% 0	0.0% 0	0.0% 0	0.0% 0	100.0% 11	0.0% 0	
-	7	0.0% 0	0.0% 0	0.0% 0	0.0% 0	0.0% 0	0.0% 0	100.0% 8	
		1	2	3 Ta	4 Irget Cla	5 ss	6	7	
	Confusion matrix for event								

Classes:

- 1. Manual compactor (75)
- 2. Excavation (551)
- 3. Drilling (125)
- 4. Jack hammer (1726)
- 5. Palplanche (105)
- 6. Circular saw (321)
- 7. Transportation (538)

For all studied events: Classification with our algorithm is **100% correct** with an accuracy of 98.69%

Conclusions

- Random Forest algorithm appears to be relevant (fast and robust) for the classification of acoustic events recorded with DAS.
- Tests on other field sites are under process to demonstrate the efficiency of our Machine Learning method on different contexts.
- Different fields of application of this algorithm are possible: intrusion detection along pipelines, in perimeters, seismic event detection and classification (volcanoes, glaciers, etc.).
- Tests on data processing in flux for real-time event detection and classification are under process.



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