

Preliminary GRACE-FO gravity field solutions

Qiujie Chen^{1,2}, Yunzhong Shen¹, Jürgen Kusche²

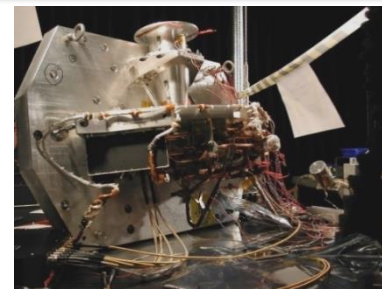
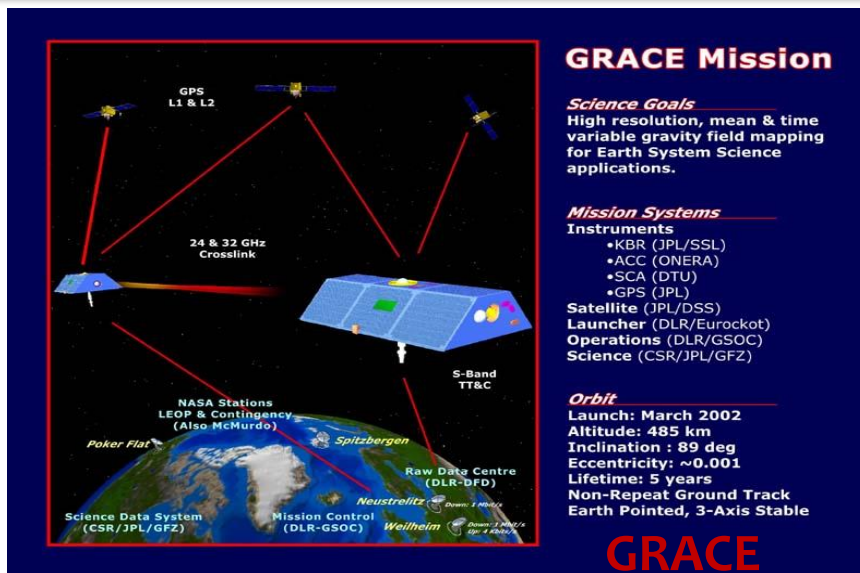
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May 8, 2020

Outline

1. Introduction of GRACE/GRACE-FO mission
2. Gravity Field Estimation Methods
3. GRACE static/monthly solutions
4. Preliminary GRACE-FO monthly models
5. Concluding Remarks

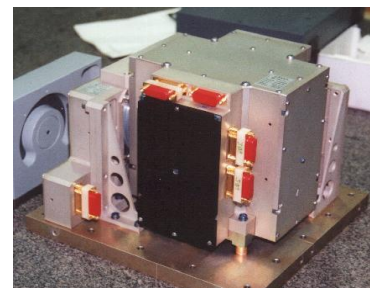
Introduction — GRACE & GRACE-FO



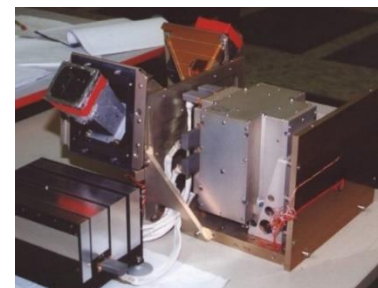
K-Band Ranging



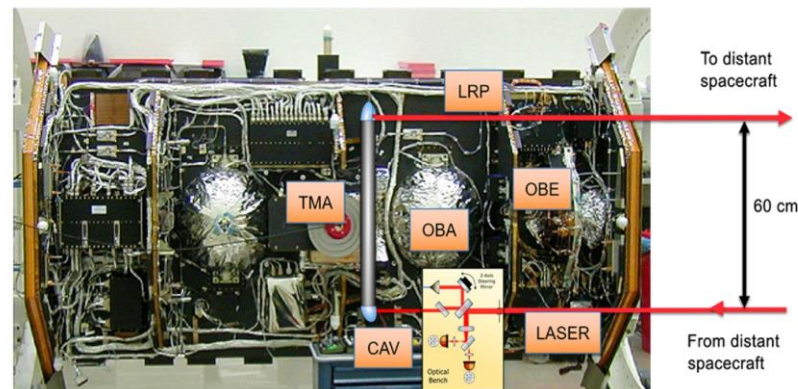
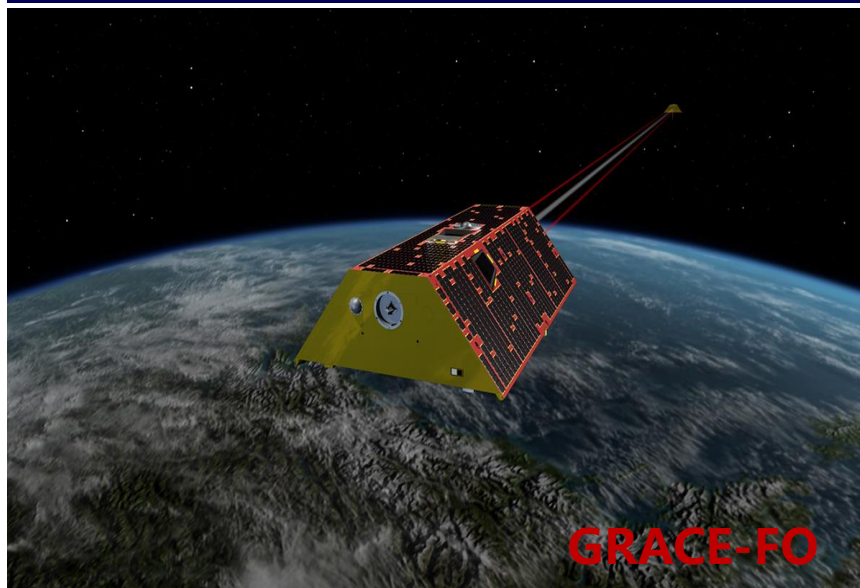
GNSS Receiver



Accelerometer



Star Camera



LRI

Introduction — GRACE/GRACE-FO Solutions

GRACE monthly solutions

Monthly model	Spatial / time res.	Time span
CSR RL06	(60 96) / 30	04/02-06/17
GFZ RL06	(60 96) / 30	04/02-06/17
JPL RL06	(60 96) / 30	04/02-06/17

ITSG-Grace2016	(60 90 120) / 30	04/02-06/17
ITSG-Grace2018	(60 96 120) / 30	04/02-06/17
CNES/GRGS RL05	90 / 30	04/02-06/17
DMT-1	120 / 30	02/03-12/09
DMT-2	120 / 30	02/03-04/12
Tongji-RL01*	60 / 30	01/03-08/11
Tongji-RL02*	60 / 30	01/03-09/15
Tongji-Grace2018*	96 / 30	04/02-06/17
HUST-Grace2016	60 / 30	01/03-04/15
IGG RL01	60 / 30	04/02-07/16
WHU RL01	(60 90 120) / 30	04/02-07/16

GRACE-FO monthly solutions

Monthly model	Spatial / time res.	Time span
CSR RL06	(60 96) / 30	06/18-11/19
GFZ RL06	(60 96) / 30	06/18-11/19
JPL RL06	(60 96) / 30	06/18-11/19
ITSG-Grace2018 (opt.)	(60 96 120) / 30	06/18-10/19

GRACE static solutions

Static model	Spatial res.	Data span
GGM05S	180	~10 yrs.
Tongji-Grace02s*	180	~13.5 yrs.
Tongji-Grace02k*	180	~13.5 yrs.
ITSG-Grace2018s	200	~15 yrs.
AIUB-GRACE03S	160	~6 yrs.
Tongji-GRACE01*	160	~5 yrs.
HUST-Grace2016s	160	~13 yrs.

Method — Modified Short-arc Algorithm

$$\mathbf{r}(\tau) = \mathbf{r}_0(1-\tau) + \mathbf{r}_N(\tau) - T^2 \int_0^1 K(\tau, \tau') \mathbf{a}(\mathbf{r}(\tau'), u, \mathbf{p}(\tau')) d\tau' \rightarrow \text{Orbit Eq.}$$

$$\mathbf{r}(\tau') = \mathbf{r}_k(\tau') + \mathbf{v}_r(\tau') \quad \mathbf{p}(\tau') = C(\mathbf{q}_s + \mathbf{v}_{q_s})^T (\mathbf{S}\mathbf{a}_s + \mathbf{v}_{a_s} + \mathbf{b})$$

1. Co-estimating orbit corrections

2. Acceleration & attitude corrections

3. Temporal acceleration calibration model

$$\dot{\mathbf{r}}(\tau) = (\mathbf{r}_N - \mathbf{r}_0)/T + T \int_0^1 \frac{\partial K(\tau, \tau')}{\partial \tau} \mathbf{a}(\mathbf{r}(\tau'), u, \mathbf{p}(\tau')) d\tau'$$

$$\dot{\rho}(\tau) + v_{\dot{\rho}}(\tau) = (\dot{\mathbf{r}}_B(\tau) - \dot{\mathbf{r}}_A(\tau)) \cdot \mathbf{e}_{AB}(\tau) \rightarrow \text{KBRR Eq.}$$

Tongji-GRACE01 Model: Modelling Orbit and KBR Obs. Errors

Tongji-GRACE02 model: Further Modelling Acc. and Attitude Obs. Errors

Method — Optimized Short-arc Algorithm

➤ Boundary Conditions

$$\mathbf{r}_k(\tau_0) + \mathbf{v}_r(\tau_0) = \mathbf{r}_0 + \delta \mathbf{r}_0$$

$$\mathbf{r}_k(\tau_N) + \mathbf{v}_r(\tau_N) = \mathbf{r}_N + \delta \mathbf{r}_N$$

➤ Obs. Eq. for One Arc

Sat. A: $\mathbf{C}_k^A \mathbf{x}_k + \mathbf{D}_k^A \mathbf{v}_k^A = \mathbf{y}_k^A$, $\mathbf{D}_k^A \rightarrow \text{Sq. Mat.}$

Sat. B: $\mathbf{C}_k^B \mathbf{x}_k + \mathbf{D}_k^B \mathbf{v}_k^B = \mathbf{y}_k^B$, $\mathbf{D}_k^B \rightarrow \text{Sq. Mat.}$

KBRR: $\mathbf{C}_k^{\dot{\rho}} \mathbf{x}_k + \mathbf{D}_k^{\dot{\rho}A} \mathbf{v}_k^A + \mathbf{D}_k^{\dot{\rho}B} \mathbf{v}_k^B - \mathbf{v}_k^{\dot{\rho}} = \mathbf{y}_k^{\dot{\rho}}$

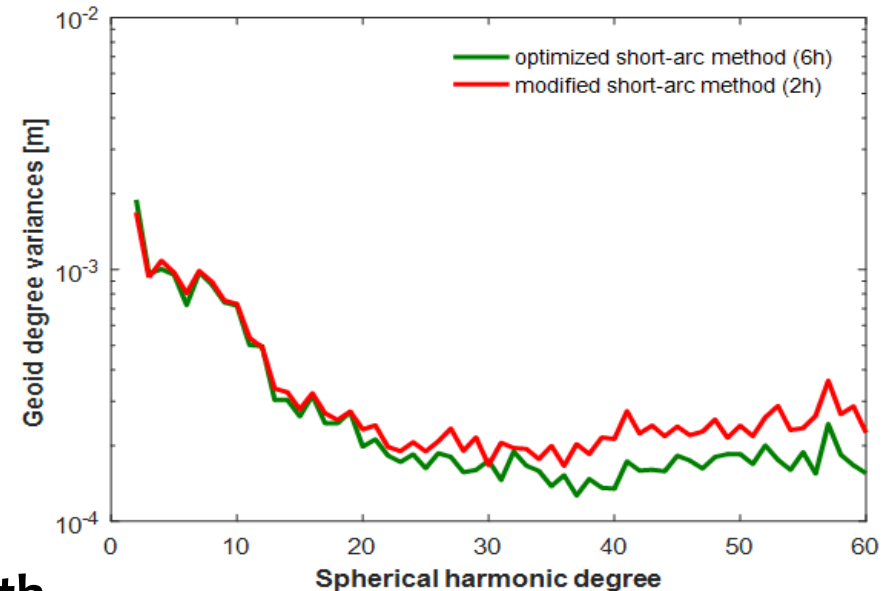
➤ Re-Organized Obs. Equation

$$\mathbf{v}_k^A = -(\mathbf{D}_k^A)^{-1} \mathbf{C}_k^A \mathbf{x}_k + (\mathbf{D}_k^A)^{-1} \mathbf{y}_k^A$$

$$\mathbf{v}_k^B = -(\mathbf{D}_k^B)^{-1} \mathbf{C}_k^B \mathbf{x}_k + (\mathbf{D}_k^B)^{-1} \mathbf{y}_k^B$$

$$\mathbf{v}_j^{\dot{\rho}} = \bar{\mathbf{C}}_j^{\dot{\rho}} \mathbf{x}_j - \bar{\mathbf{y}}_j^{\dot{\rho}}$$

Arc Length	Cond. Num. [log10]	Cond. Num. [log10]
	Mod. Algorithm $\mathbf{D}_k \mathbf{Q}_k \mathbf{D}_k^T$	Opt. Algorithm $\mathbf{D}_k^s (s = A, B)$
2	15.3	3.3
4	15.8	4.2
6	16.4	4.8
8	16.8	5.5
12	*	9.9



Tongji-GRACE2018 model: 6 hour Arc Length

Tongji-GRACE Gravity Field Solutions

Gravity Field Models

- Static Models
- Temporal Models
- Topographic Gravity Field Models

Calculation Service

- Regular grids
- User-defined points

3D Visualisation

- Static Models
- Temporal Models
- Trend & Amplitude
- Spherical Harmonics

Evaluation

- Spectral domain
- GNSS Leveling

Documentation

- FAQ
- Theory



I C G E M

GFZ
Helmholtz Centre
Potsdam

Nr	Model	Year	Degree	Data	References	Download	Calculate	Show	DOI
176	XGM2019e_2159	2019	2190 5540 760	A, G, S(GOC006s), T	Zingerle, P. et al, 2019	gfc zip gfc zip gfc zip	Calculate	Show	✓
175	GO_CONS_GCF_2_TIM_R6e	2019	300	G (Polar), S(Goce)	Zingerle, P. et al, 2019	gfc zip	Calculate	Show	✓
174	ITSG-Grace2018s	2019	200	S(Grace)	Mayer-Gürr, T. et al, 2018	gfc zip	Calculate	Show	✓
173	EIGEN-GRGS.RL04.MEAN-FIELD	2019	300	S	Lemoine et al, 2019	gfc zip	Calculate	Show	✓
172	GOC006s	2019	300	S	Kvas et al., 2019	gfc zip	Calculate	Show	✓
171	GO_CONS_GCF_2_TIM_R6	2019	300	S(Goce)	Brockmann, J. M. et al, 2014	gfc zip	Calculate	Show	✓
170	GO_CONS_GCF_2_DIR_R6	2019	300	S	Bruinsma, S. L. et al, 2014	gfc zip	Calculate	Show	✓
169	IGGT_R1C	2018	240	G, S(Goce), S(Grace)	Lu, B. et al., 2019	gfc zip	Calculate	Show	✓
168	Tongji-Grace02k	2018	180	S(Grace)	Chen, Q. et al, 2018	gfc zip	Calculate	Show	✓
167	SGG-UGM-1	2018	2159	EGM2008, S(Goce)	Liang, W. et al., 2018 & Xu, X. et al. (2017)	gfc zip	Calculate	Show	✓
166	GOSG01S	2018	220	S(Goce)	Xu, X. et al., 2018	gfc zip	Calculate	Show	✓
165	IGGT_R1	2017	240	S(Goce)	Lu, B. et al, 2017	gfc zip	Calculate	Show	✓
164	IE_GOCO05s	2017	250	S	Wu, H. et al, 2017	gfc zip	Calculate	Show	✓
163	GO_CONS_GCF_2_SPW_R5	2017	330	S(Goce)	Gatti, A. et al, 2016	gfc zip	Calculate	Show	✓
162	GAO2012	2012	360	A, G, S(Goce), S(Grace)	Demianov, G. et al, 2012	gfc zip	Calculate	Show	✓
161	XGM2016	2017	719	A, G, S(GOC005s)	Pail, R. et al, 2017	gfc zip	Calculate	Show	✓
160	Tongji-Grace02s	2017	180	S(Grace)	Chen, Q. et al, 2016	gfc zip	Calculate	Show	✓
159	NULP-02s	2017	250	S(Goce)	A.N. Marchenko et al, 2016	gfc zip	Calculate	Show	✓
158	HUST-Grace2016s	2016	160	S(Grace)	Zhou, H. et al, 2016	gfc zip	Calculate	Show	✓

ICGEM Home

- Gravity Field Models
- Static Models
- Temporal Models
- Topographic Gravity Field Models

Calculation Service

- Regular grids
- User-defined points

3D Visualisation

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- Latest Changes
- Discussion Forum

Other Celestial Bodies
(Moon, Venus, Mars)



I C G E M

GRACE and Grace-FO solutions from the Science Data System centers CSR, GFZ and JPL expand all

- + CSR: Center for Space Research at University of Texas, Austin
- + GFZ: Helmholtz Centre Potsdam German Research Centre for Geosciences
- + JPL: Jet Propulsion Laboratory

The processing standards to generate the GRACE Level-2 products of CSR, GFZ and JPL are also available in the Document Section of the GRACE archives at GFZ ISDC or JPL PO.DAAC

COST-G (International Combination Service for Time-variable Gravity Field) expand all

GRACE / CHAMP solutions from other groups expand all

- + AIUB: Astronomical Institute University Bern
- + CNES: Centre national d'études spatiales
- + DMT: Delft University of Technology
- + EGSiEM: European Gravity Service for Improved Emergency Project
- + geo-Q: Leibniz Universität Hannover
- + HUST: Huazhong University of Science and Technology, Wuhan, PR China
- + IGG: Institute of Geodesy and Geophysics, Chinese Academy of Sciences, China
- + ITG: Institute of Geodesy and Geoinformation, Universität Bonn
- + ITSG: Institute of Geodesy at Graz University of Technology (ITSG)
- + LUH: Leibniz Universität Hannover
- + QuantumFrontiers: Leibniz Universität Hannover
- + SWJTU: Faculty of Geosciences and Environmental Engineering, Southwest Jiao-Tong University, PR China

- + Tongji: Tongji University, Shanghai, PR China
 - Release 01: monthly GRACE monthly solutions
 - Release 02 new version: monthly GRACE monthly solutions
 - Release 02 old version: monthly GRACE monthly solutions
 - Tongji-Grace2018: monthly GRACE monthly solutions

- + ULux: University of Luxembourg

Static Solutions — Data input and Model Output

➤ Data Input:

- JPL RL02 KBRR (5s)
- JPL RL02 Acceleration Data(5s)
- JPL RL02 Attitude Data (5s)
- Graz Kinematic Orbit (10s)

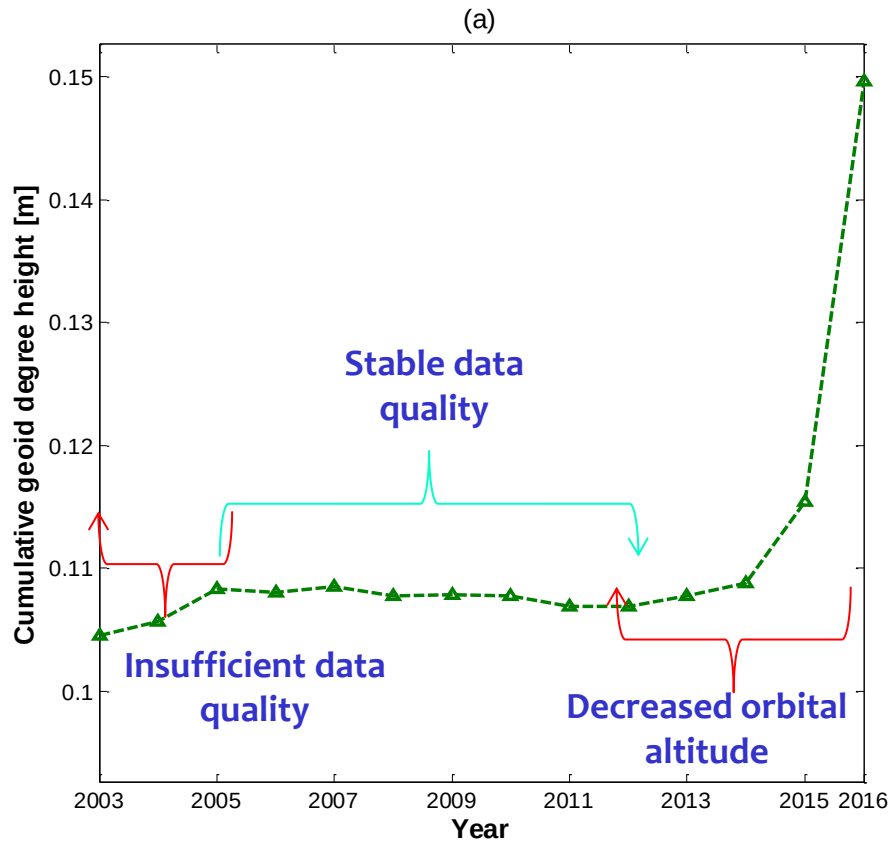
➤ Spatial/Temporal Resolution:

- Temporal Resolution: ~13.5 years (01/2003-03/2016)
- Spatial Resolution: 180 d/o

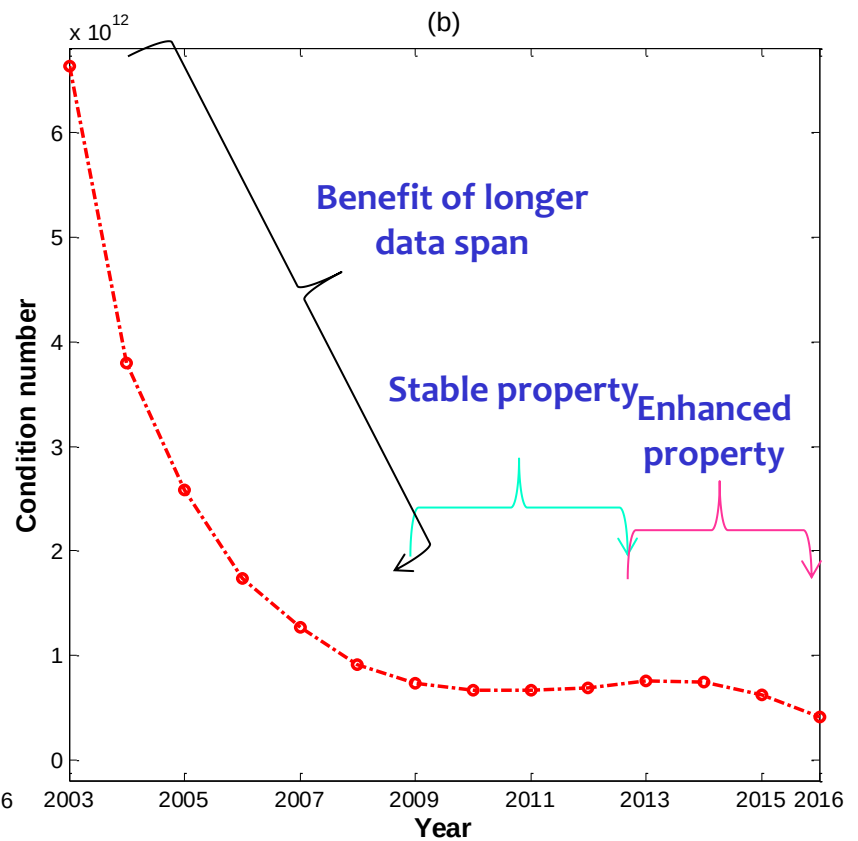
➤ Model Output:

- Tongji-Grace02s Model, Unconstrained Solution
- Tongji-Grace02k Model, Regularized Solution

Static Solutions — Data Contribution



(a) Contributions of GRACE Data



(b) Cond. Num. of Normal Eq.

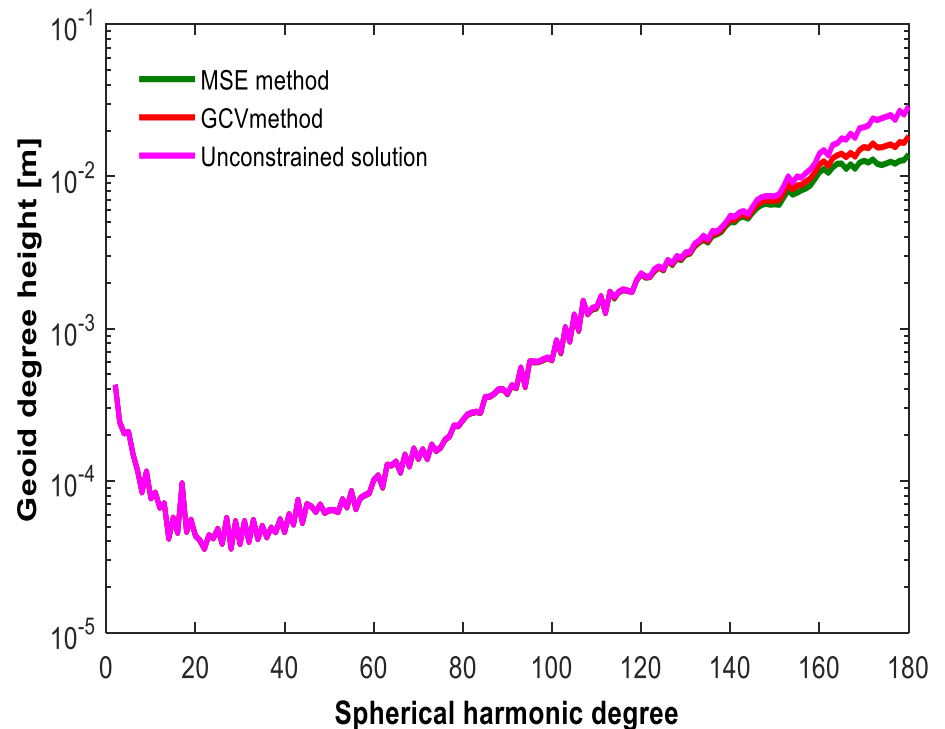
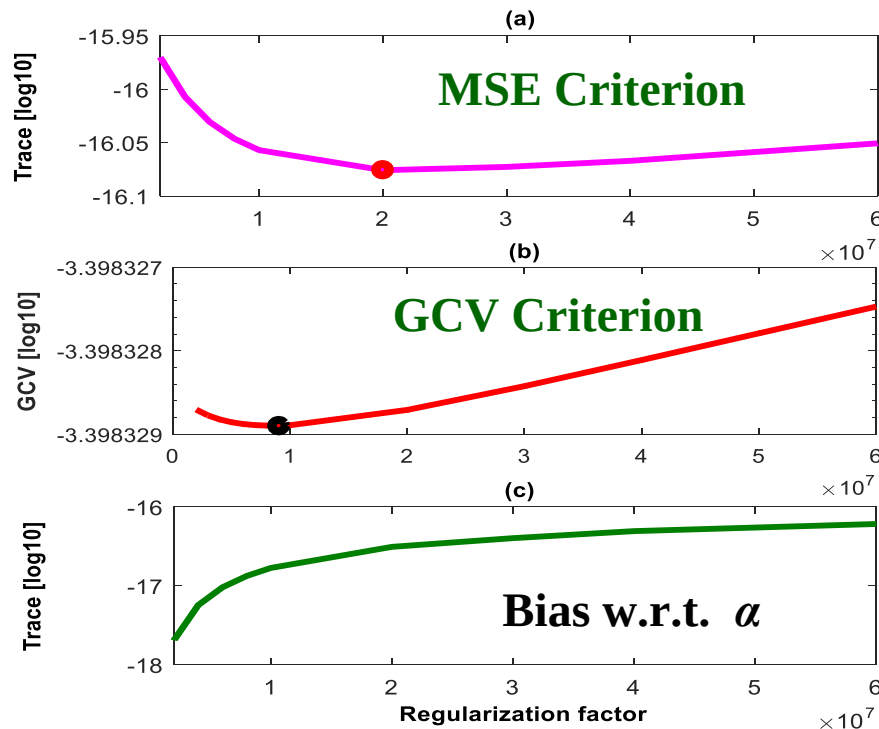
Static Solutions — Regularization Method

➤ Regularization Method

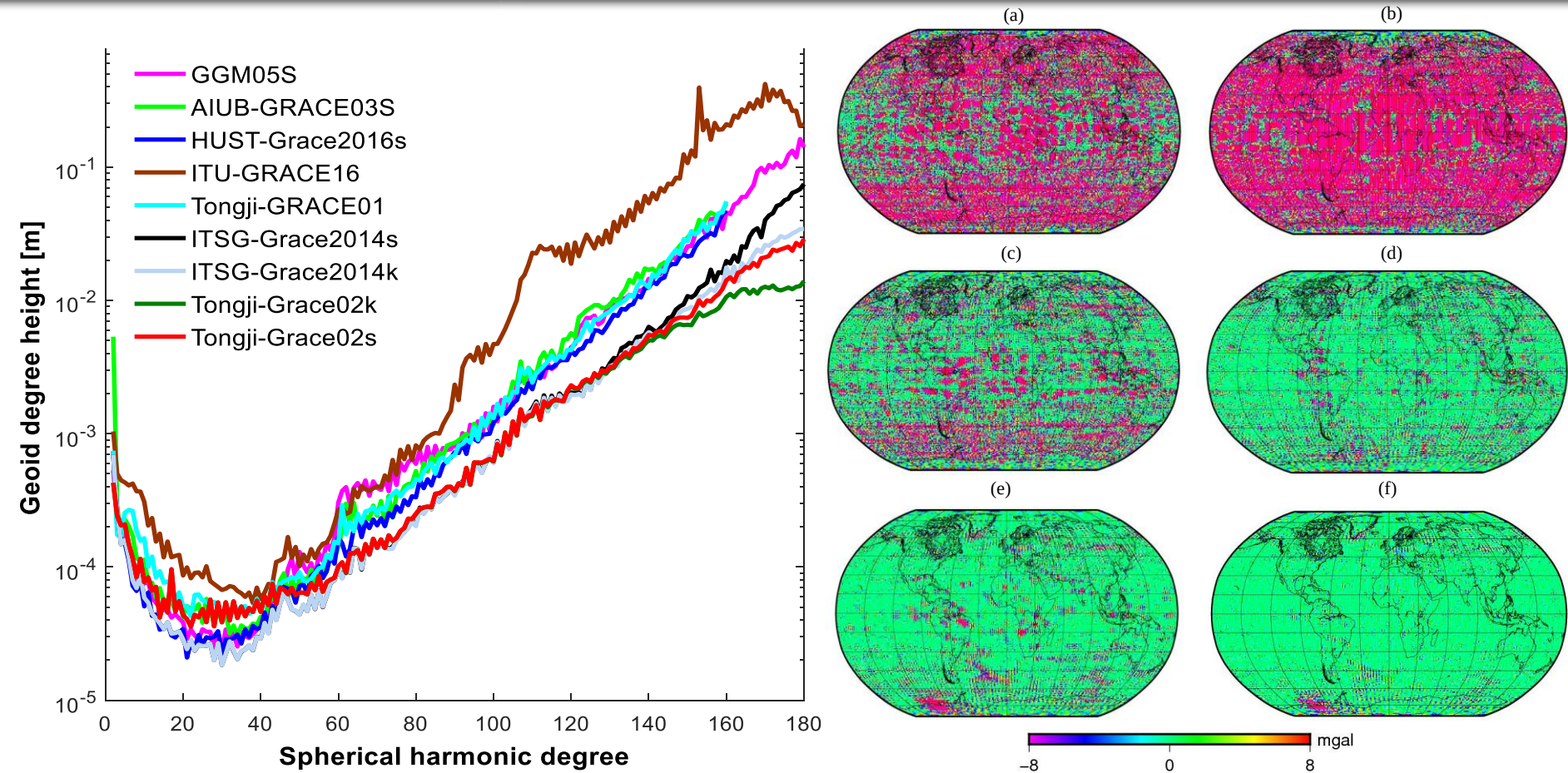
$$\delta \mathbf{u}_\alpha = (\mathbf{N}_{uu} + \alpha \mathbf{K})^{-1} \mathbf{W}_u \quad \mathbf{K} \rightarrow \text{Kaula constraint}$$

**Criterion
to Est. α :**

$$\min: \text{trace}[\text{MSE}(\delta \mathbf{u}_\alpha)] = \sigma_0^2 \text{trace}[\mathbf{Q}_\alpha \mathbf{N}_{uu} \mathbf{Q}_\alpha] + \alpha^2 \text{trace}[\mathbf{Q}_\alpha \mathbf{K} \delta \mathbf{u}_L \delta \mathbf{u}_L^T \mathbf{K} \mathbf{Q}_\alpha]$$



Static Solutions — Tongji-Grace02s/k



Static Solutions — Validation by DTU13 data

A: $[26^{\circ}N, 36^{\circ}N]$, $[255^{\circ}E, 265^{\circ}E]$; B: $[30^{\circ}N, 40^{\circ}N]$, $[165^{\circ}E, 175^{\circ}E]$ (mGal)

Region	Degree	GGM 05S	ITU- GRACE 16	AIUB- GRACE 03S	Tongji- GRACE 01	HUST- Grace 2016s	ITSG- Grace 2014s	ITSG- Grace 2014k	Tongji- Grace 02s	Tongji- Grace 02k
A	60	0.81	0.81	0.81	0.81	0.81	0.81	0.81	0.81	0.81
	90	0.81	0.81	0.81	0.81	0.81	0.81	0.81	0.81	0.81
	120	0.81	1.28	0.82	0.85	0.85	0.81	0.81	0.82	0.82
	160	3.94	34.74	3.51	3.74	3.27	2.31	1.41	2.31	1.39
	180	10.52	72.80	*	*	*	6.79	4.06	4.18	2.42
B	60	2.25	2.25	2.25	2.25	2.25	2.25	2.25	2.25	2.25
	90	2.25	2.25	2.25	2.25	2.25	2.25	2.25	2.25	2.25
	120	2.25	2.29	2.28	2.27	2.25	2.25	2.25	2.26	2.26
	160	3.17	10.62	4.84	4.09	3.29	2.60	2.57	2.47	2.30
	180	10.74	15.07	*	*	*	4.83	4.44	3.05	2.61

Monthly Solutions — Data input and Model Output

➤ Data Input:

- JPL **RL03** KBRR (5s)
- JPL **RL02** Acceleration Data(5s)
- JPL **RL02** Thruster Data(30s)
- JPL **RL03** Attitude Data (5s)
- Graz Kinematic Orbit (10s)

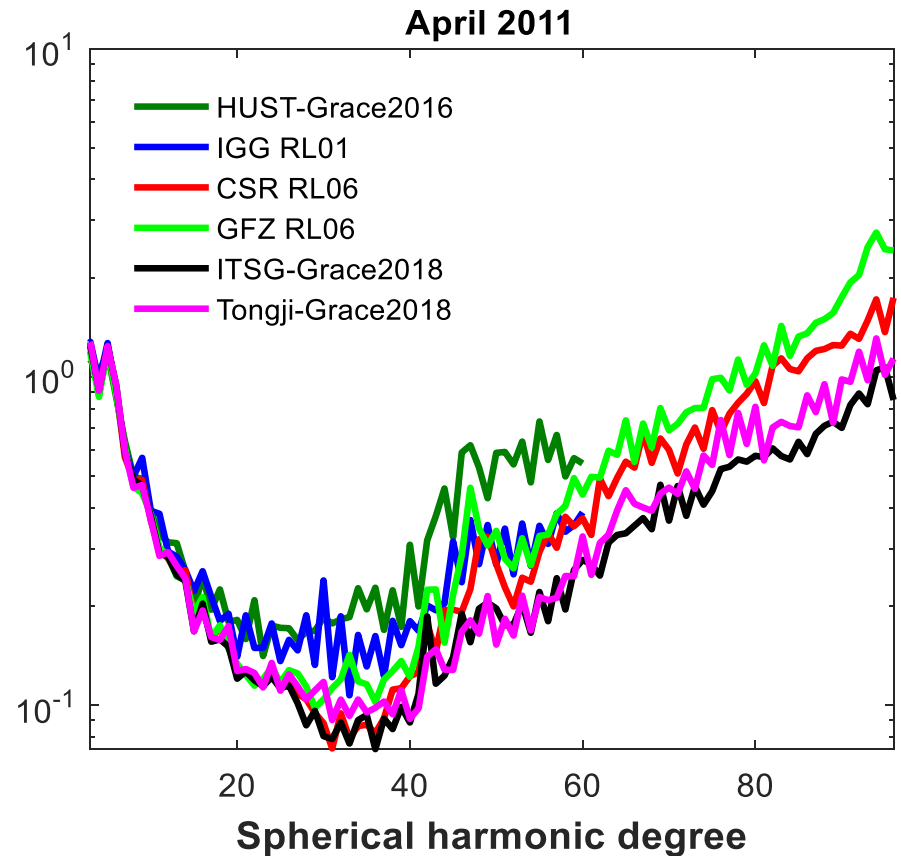
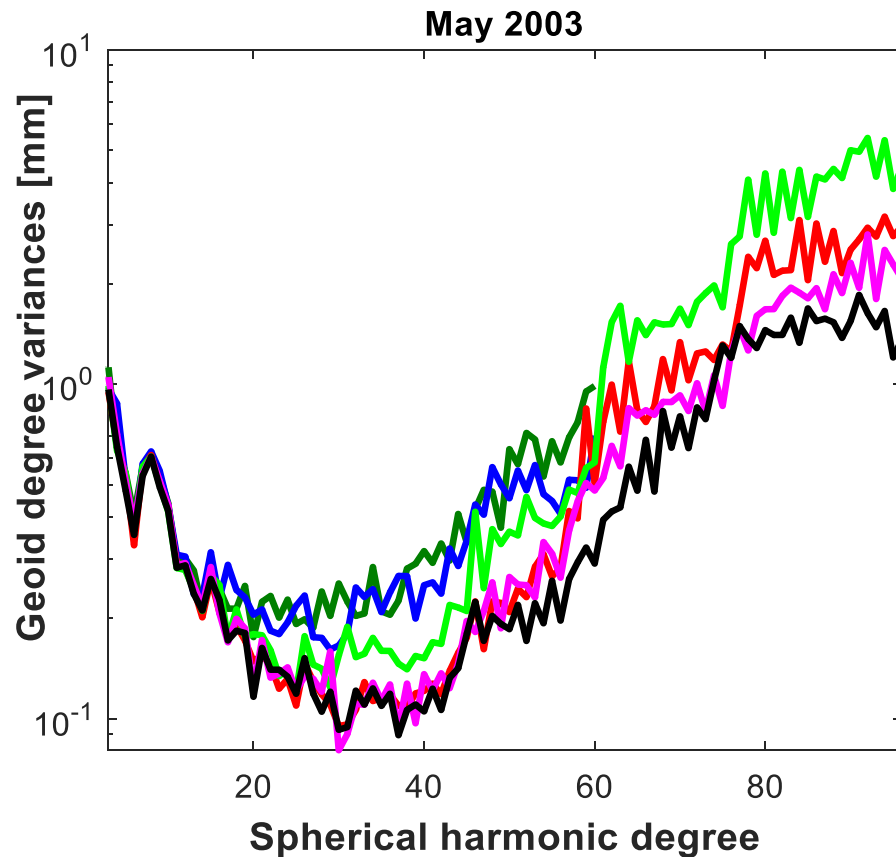
➤ Spatial/Temporal Resolution:

- Temporal Resolution: One **month** (04/2002-06/2017)
- Spatial Resolution: **96 d/o**

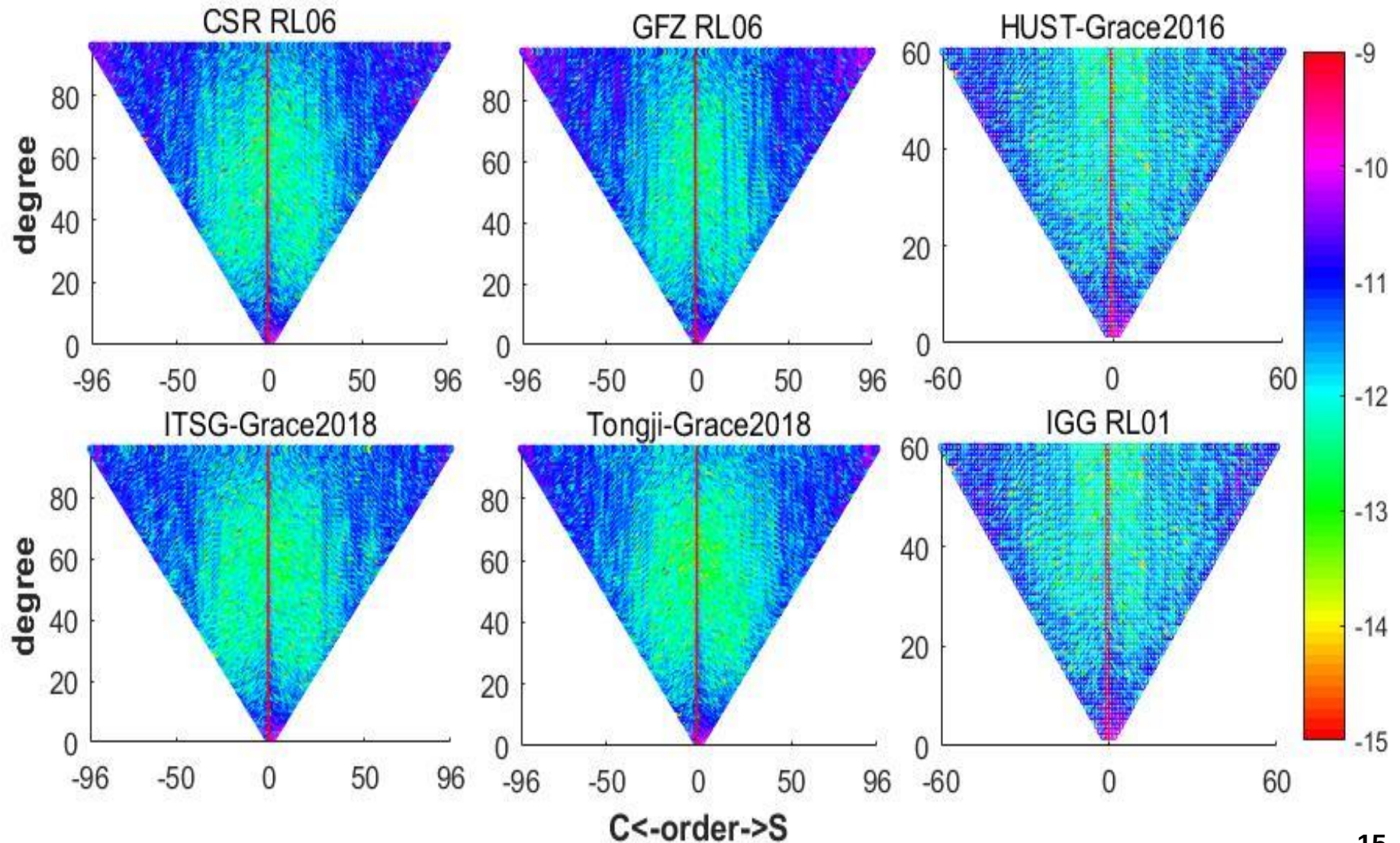
➤ Model Output:

- Tongji-Grace2018s Model, Unconstrained Solution

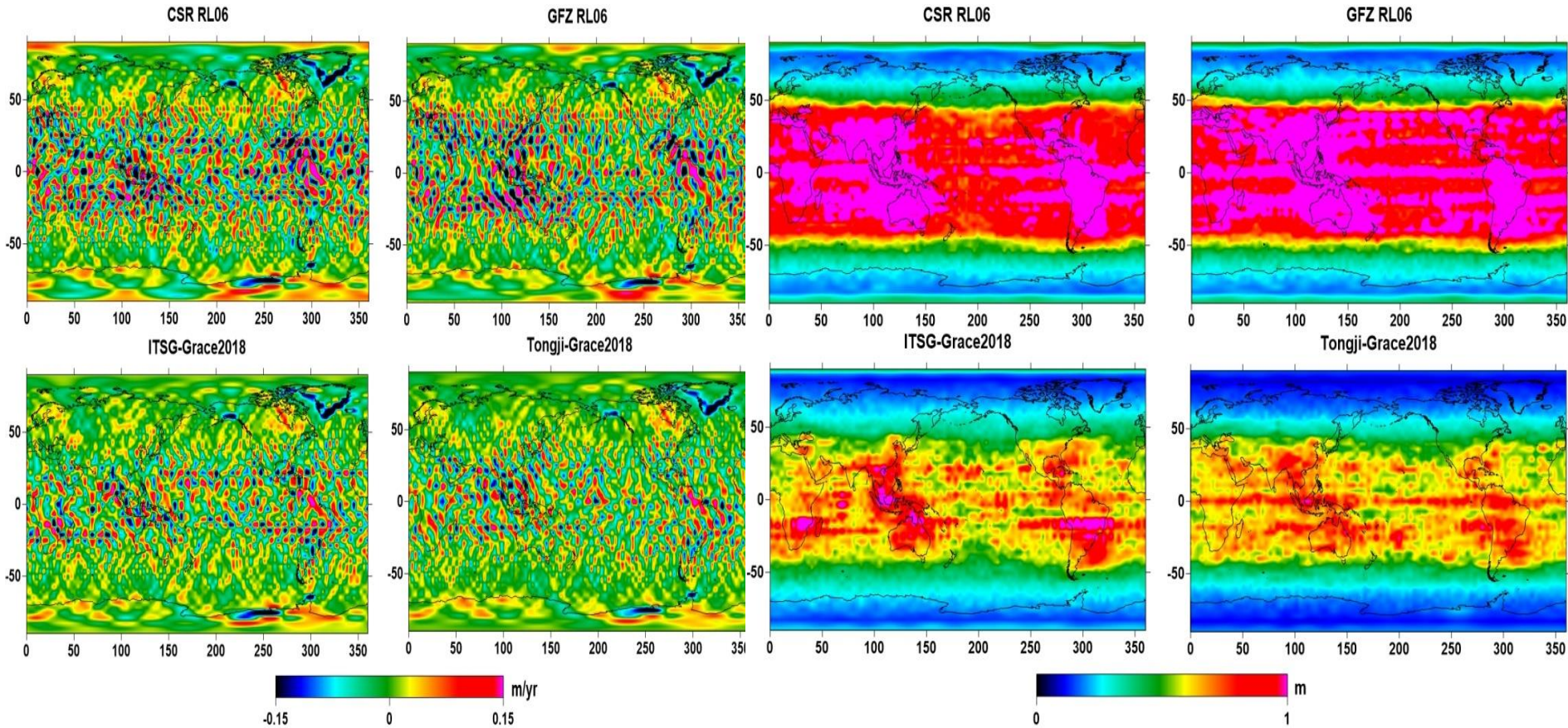
Monthly Solutions — Geoid Degree Variances



Monthly Solutions — Coefficient Difference



Monthly Solutions — Global Trend Comparison



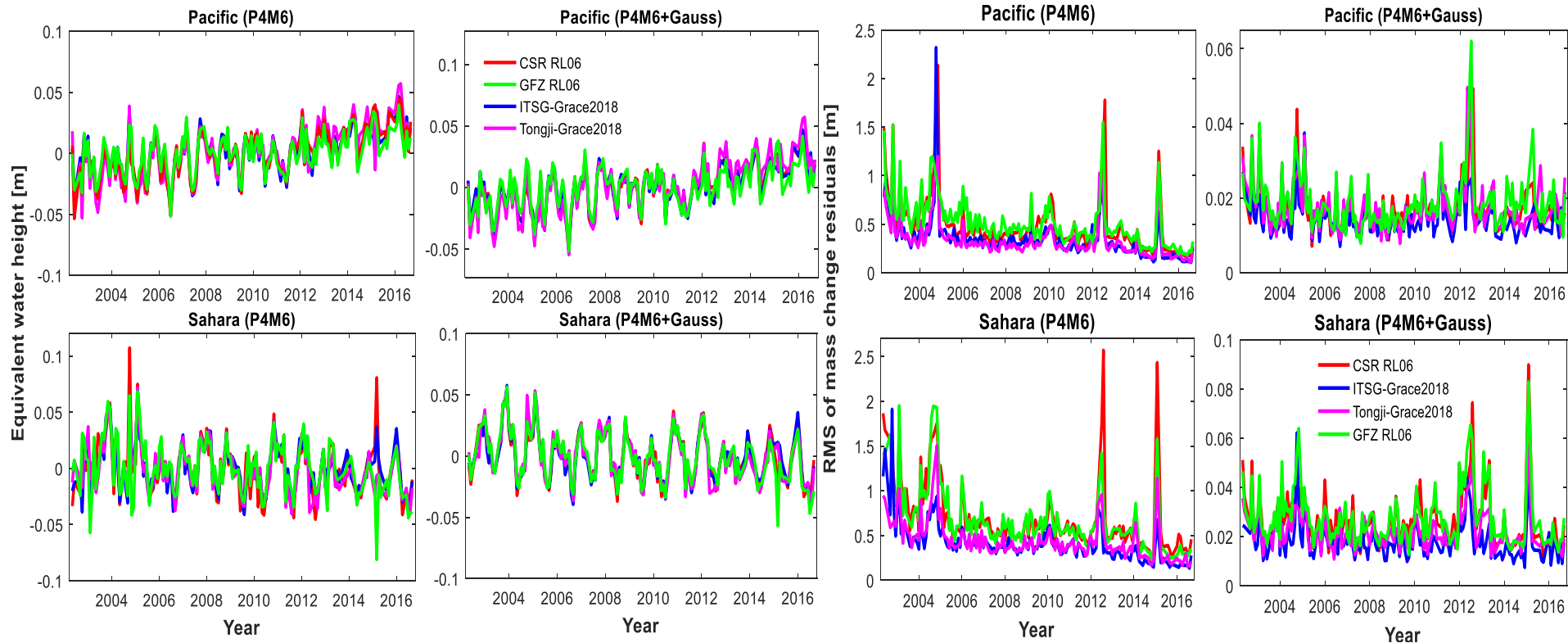
Global Trend

Global RMS

P4M6 Decorrelation

Monthly Solutions — Noise Analyses

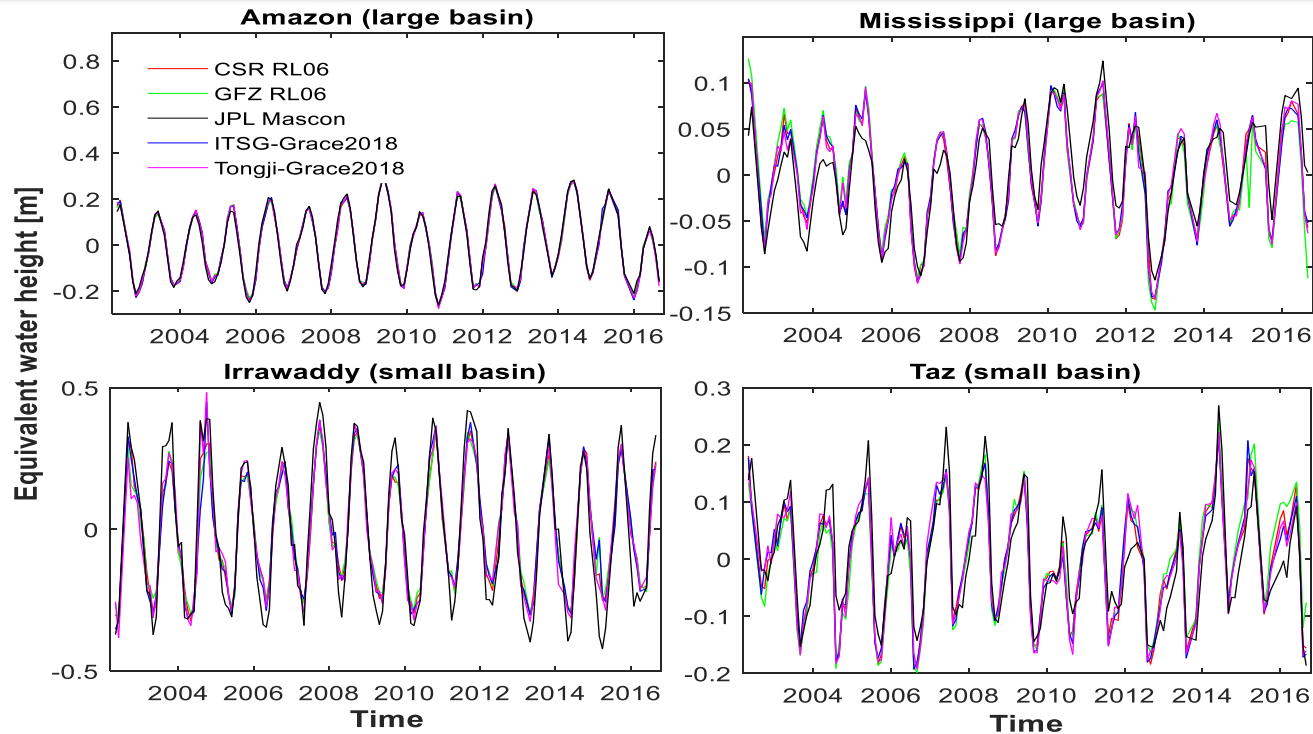
Pacific ($28^{\circ}\text{N}\sim 51^{\circ}\text{N}$, $170^{\circ}\text{E}\sim 220^{\circ}\text{E}$), Sahara ($15^{\circ}\text{N}\sim 35^{\circ}\text{N}$, $0^{\circ}\text{E}\sim 35^{\circ}\text{E}$)



Mean Mass Variation Series

Mean RMS Series

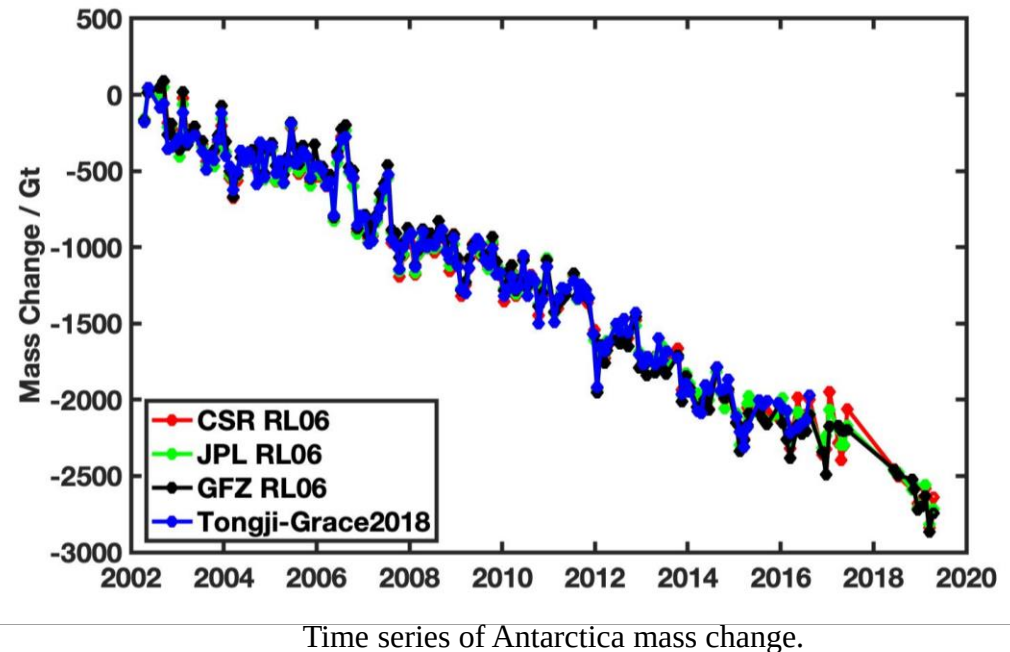
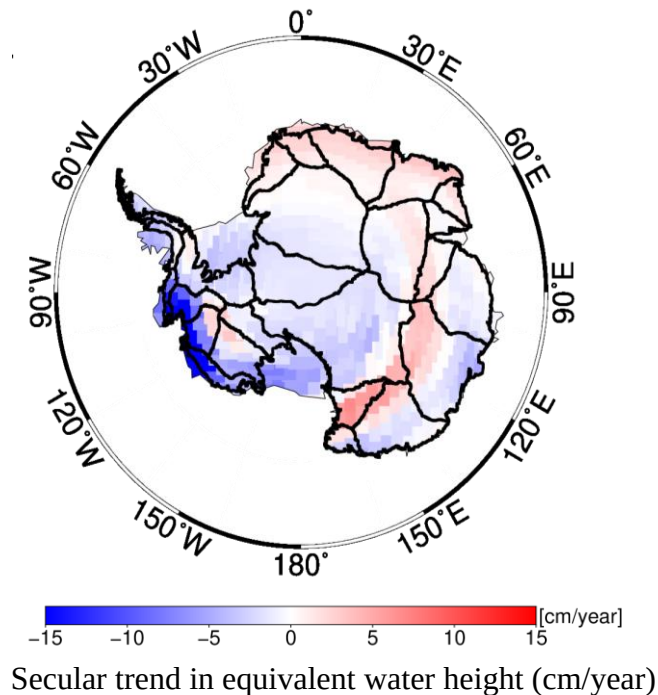
Monthly Solutions — Signal Comparison



⟨Amp|Pha⟩

River Basin	CSR RL06	GFZ RL06	ITSG-Grace2018	Tongji-Grace2018	JPL Mascon
Amazon	⟨22.8cm 96°⟩	⟨22.5cm 96°⟩	⟨23.4cm 98°⟩	⟨23.3cm 96°⟩	⟨24.7cm 111°⟩
Mississippi	⟨6.5cm 112°⟩	⟨6.4cm 111°⟩	⟨6.5cm 113°⟩	⟨6.6cm 111°⟩	⟨6.0cm 100°⟩
Irrawaddy	⟨26.6cm 291°⟩	⟨25.3cm 291°⟩	⟨27.3cm 290°⟩	⟨27.0cm 292°⟩	⟨34.8cm 296°⟩
Taz	⟨10.4cm 126°⟩	⟨10.6cm 126°⟩	⟨10.5cm 128°⟩	⟨10.7cm 128°⟩	⟨10.3cm 103°⟩

Monthly Solutions — Signal in Antarctica by Mascon Modelling



Mass Variations in Antarctica	Trend(Gt/year)	Annual		Semiannual	
		amplitude(Gt)	phase(°)	amplitude(Gt)	phase(°)
CSR Release 06	-151 ± 17	84 ± 27	126 ± 17	15 ± 8	234 ± 78
JPL Release 06	-150 ± 17	73 ± 27	125 ± 21	9 ± 7	228 ± 86
GFZ Release 06	-157 ± 18	89 ± 29	134 ± 21	11 ± 9	243 ± 92
Tongji-Grace2018	-150 ± 18	84 ± 29	131 ± 20	12 ± 8	230 ± 89

Preliminary GRACE-FO Solutions: Data Input and Model Output

➤ Data Input:

- JPL **RL04** KBRR (5s) / LRIRR (2s)
- JPL **RL04** Acceleration Data(1s)
- JPL **RL04** Thruster Data(30s)
- JPL **RL04** Attitude Data (1s)
- Tongji Kinematic Orbit (10s)

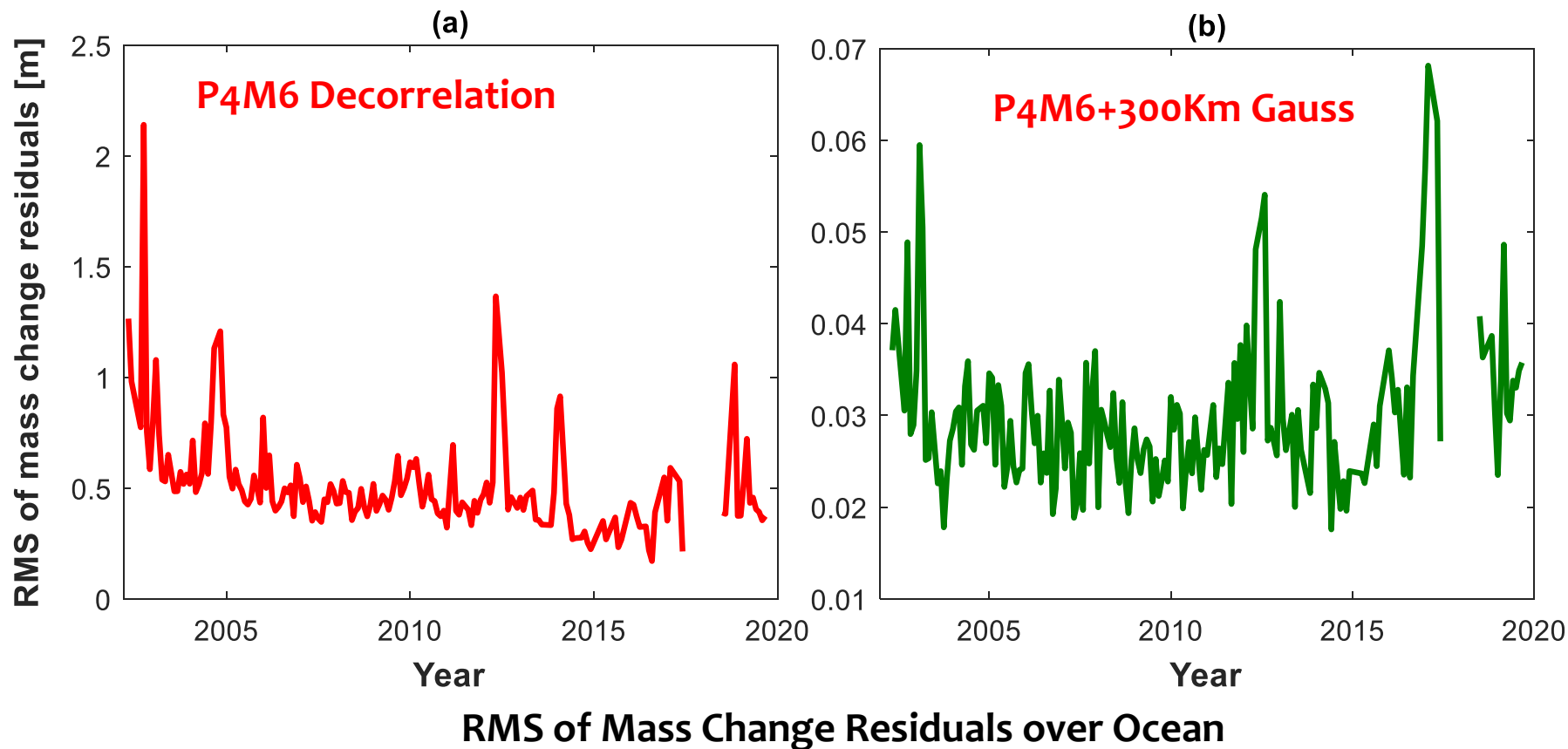
➤ Spatial/Temporal Resolution:

- Temporal Resolution: One **month** (06/2018-10/2019)
- Spatial Resolution: **96 d/o**

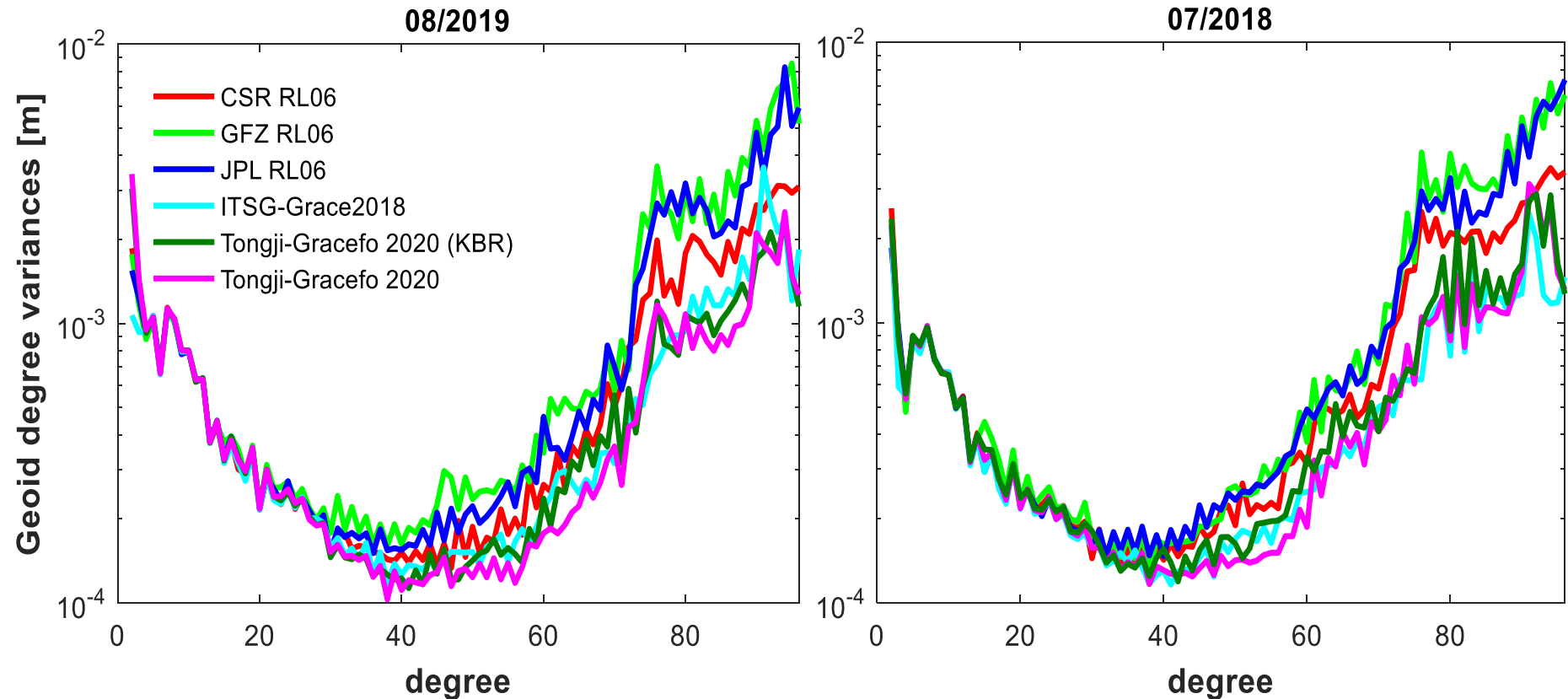
➤ Model Output:

- Tongji-Gracefo2020 Model, Unconstrained Solution

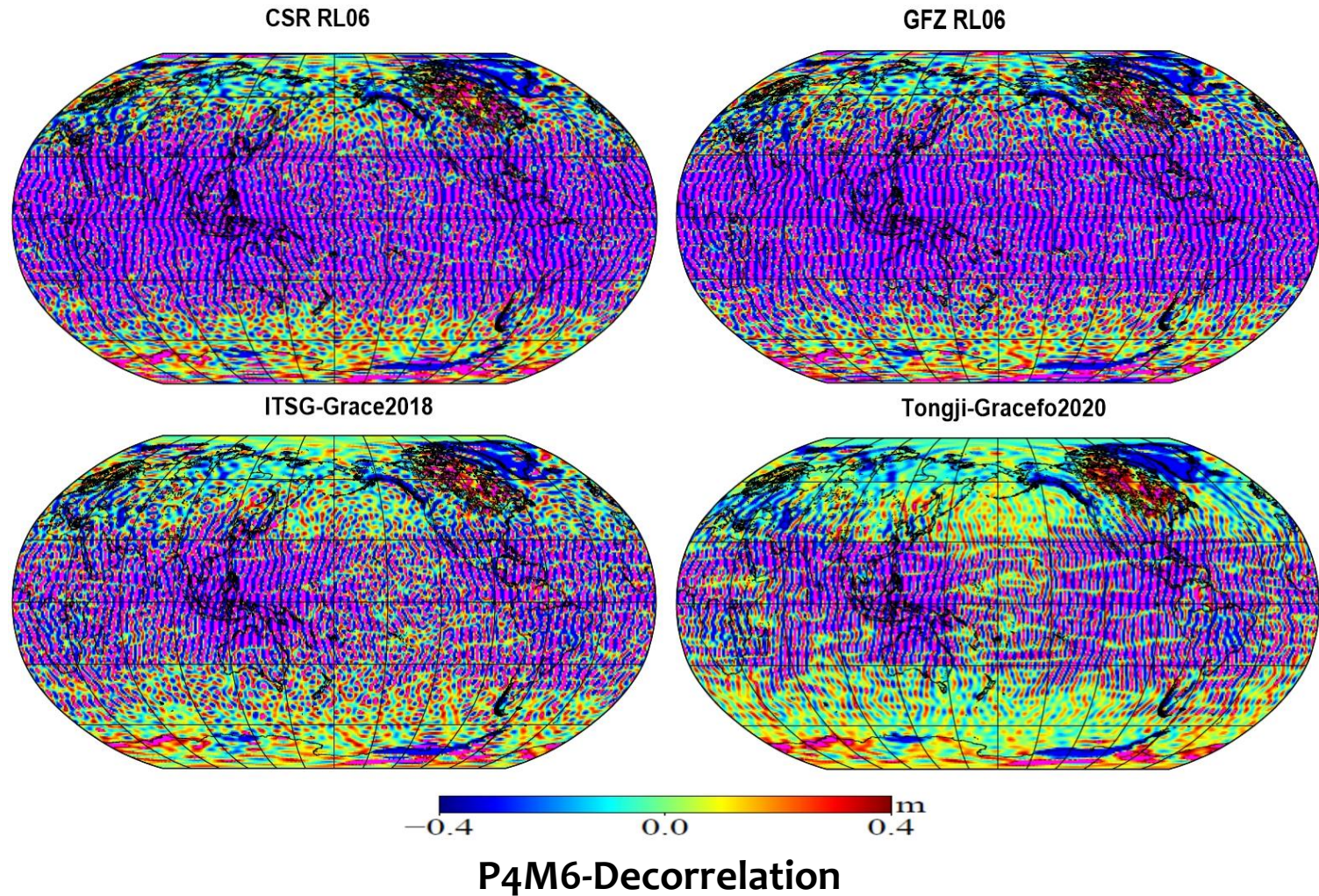
Preliminary GRACE-FO Solutions: KBR-based Models



Preliminary GRACE-FO Solutions: Degree Variances



Preliminary GRACE-FO Solutions: **Spatial Noise**



Concluding remarks

1. High-frequency noise in Tongji-Grace02s/k static gravity field solutions has been reduced.
2. Compared to the officially released RL06 models, Tongji-Grace2018 has comparable signals and improved noise level. Tongji-Grace2018 is closer to ITSG-Grace2018.
3. The noise of preliminary GRACE-FO gravity field solutions from Tongji Uni. has been further reduced. Additional work is still going on...

Thank You for Your Attention!