

# Data quality of Aeolus wind measurements

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Knowledge for Tomorrow



# The Aeolus Data Innovation and Science Cluster (DISC)



DLR



Koninklijk Nederlands  
Meteorologisch Instituut  
Ministerie van Infrastructuur en Milieu



**METEO FRANCE**  
Toujours un temps d'avance



esa



Physics Solutions

OLA

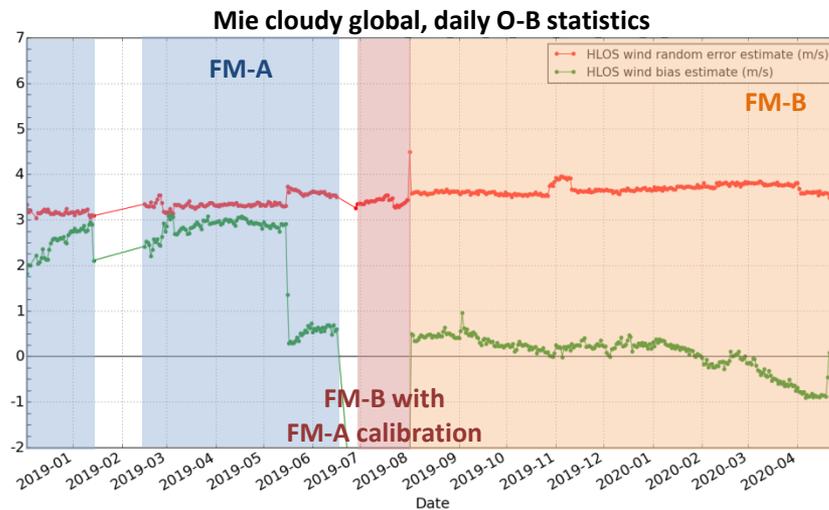
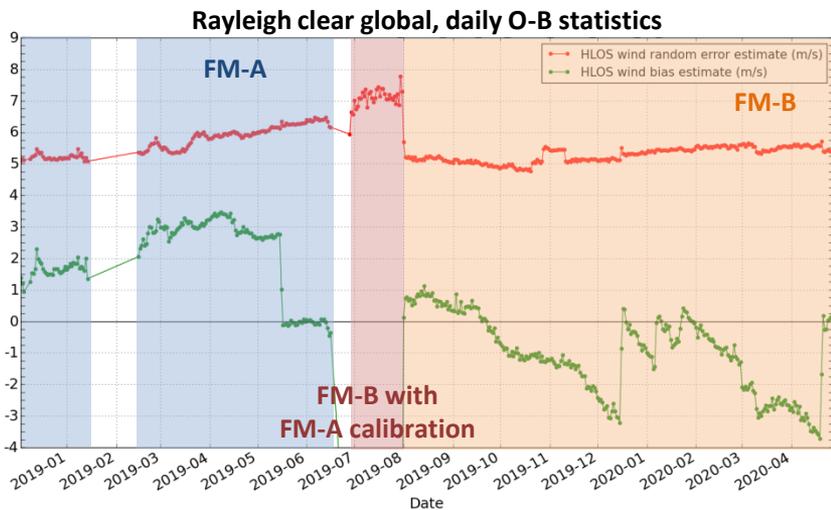


**O-B:**  
 Difference between Aeolus observation and ECMWF forecasted HLOS wind

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# Evolution of Aeolus random and systematic errors

## ECMWF operational monitoring of Aeolus Rayleigh and Mie winds

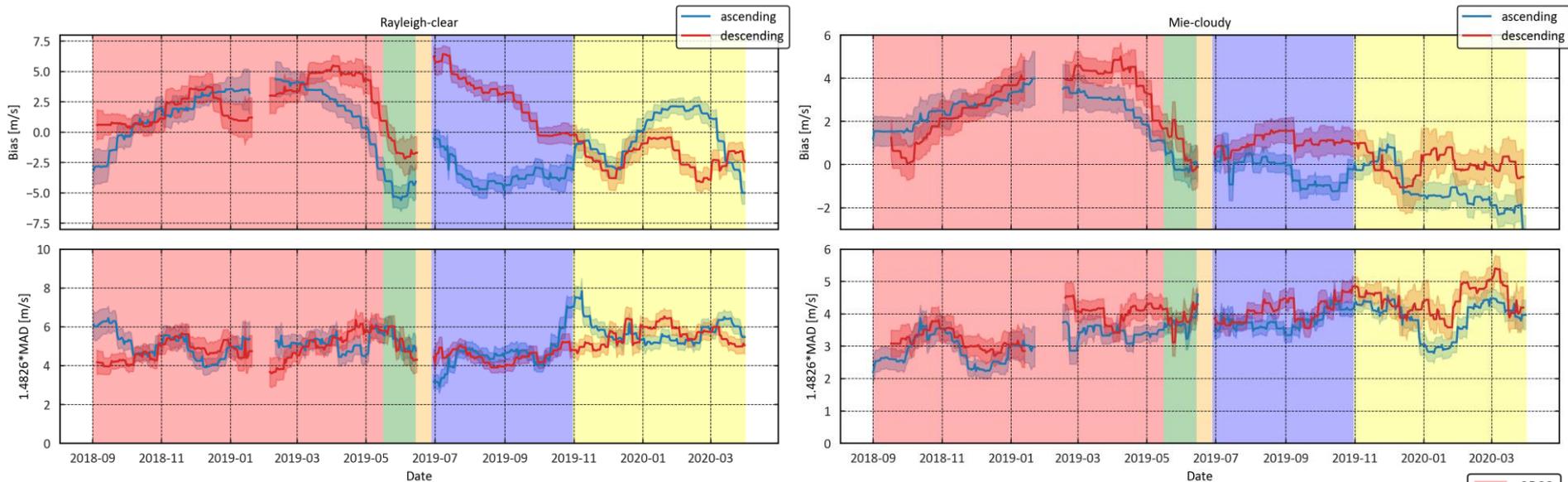


- **Random error of ALADIN Rayleigh winds** is in the order of **5-7 m/s** and **3-4 m/s** for **Mie winds** (mostly clouds): random errors in both channels were increased since launch and did not improve.
- **Systematic errors (bias) for both Mie and Rayleigh winds** were **enhanced since launch** (several m/s), and show **strong temporal variations** (slow drifts), **orbital variations**, **differences for ascending and descending orbits**, and **occurrence in some range-gates**
  - combination of **4 unexpected sources** for the bias identified up to now



# Evolution of Aeolus random and systematic errors

## Comparison of Aeolus Rayleigh and Mie winds with 4 German radar wind-profilers



- Radar wind profilers support error estimates obtained by ECMWF O-B.

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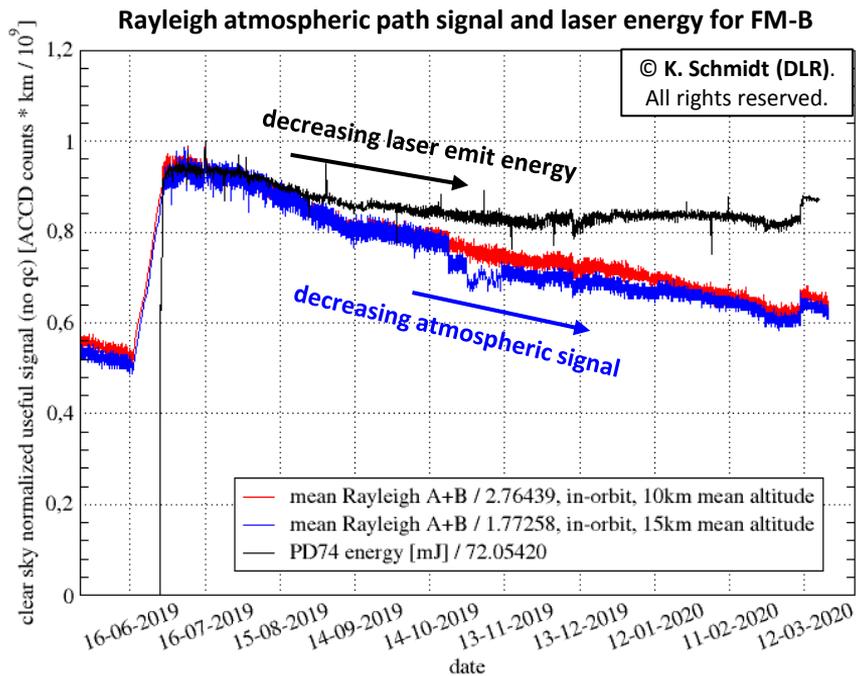
# What drives the random errors?

## 1. Laser emit energy

- ⇒ Lower than expected (60mJ instead of 80mJ)
- ⇒ Negative trend

## 2. Optical signal throughput in receive path for atmospheric signal

- ⇒ Lower than expected (factor 2-3)
- ⇒ Negative trend



Discrepancy between these lines indicates that laser energy is not representative for instrument performance. This hints to a **signal loss in optical emit and/or receive path.**



# What drives the random errors?

## 1. Laser emit energy

- ⇒ Lower than expected (factor 1-2)
- ⇒ Negative trend

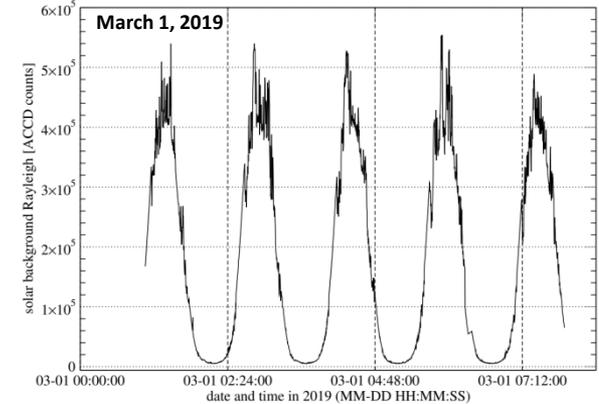
## 2. Optical signal throughput in receive path for atmospheric signal

- ⇒ Lower than expected (factor 2-3)
- ⇒ Negative trend

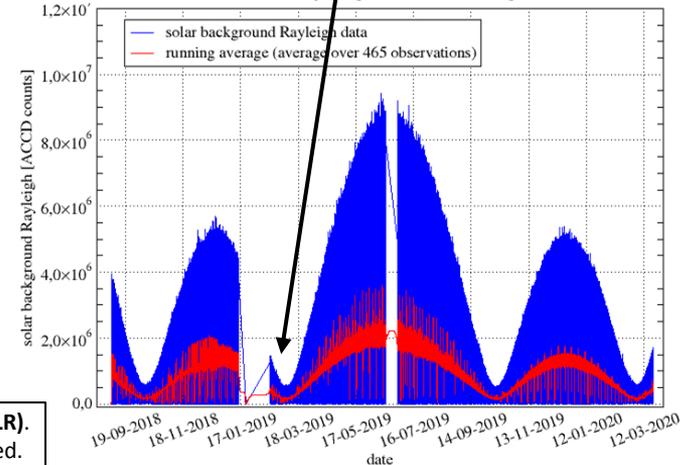
## 3. Solar background noise

- ⇒ Impact higher than expected due to lower atmospheric signal
- ⇒ Seasonal variation of solar background by factor 18: Rayleigh random errors of 7-8 m/s were obtained in summer months for polar regions

Orbital variation of Rayleigh solar background noise



Seasonal variation of Rayleigh solar background noise



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# What causes systematic errors?

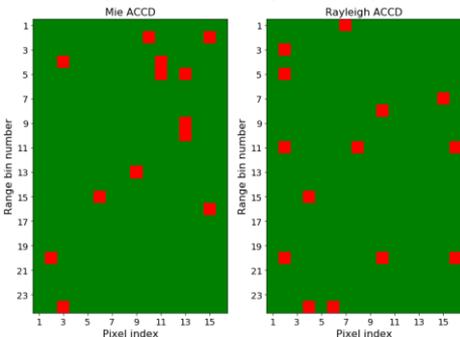
Combination of 4 unexpected error sources with different temporal characteristics

## 1. Higher dark current rates for some “hot pixels”

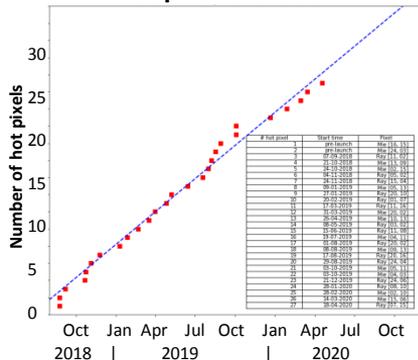
- ⇒ affects specific range gates; currently 13 pixels on Mie ACCD and 14 pixels on Rayleigh ACCD

Systematic dark signal offsets with  $10^{-3}$  to  $10^{-4}$  of signal or 1% -10% of noise

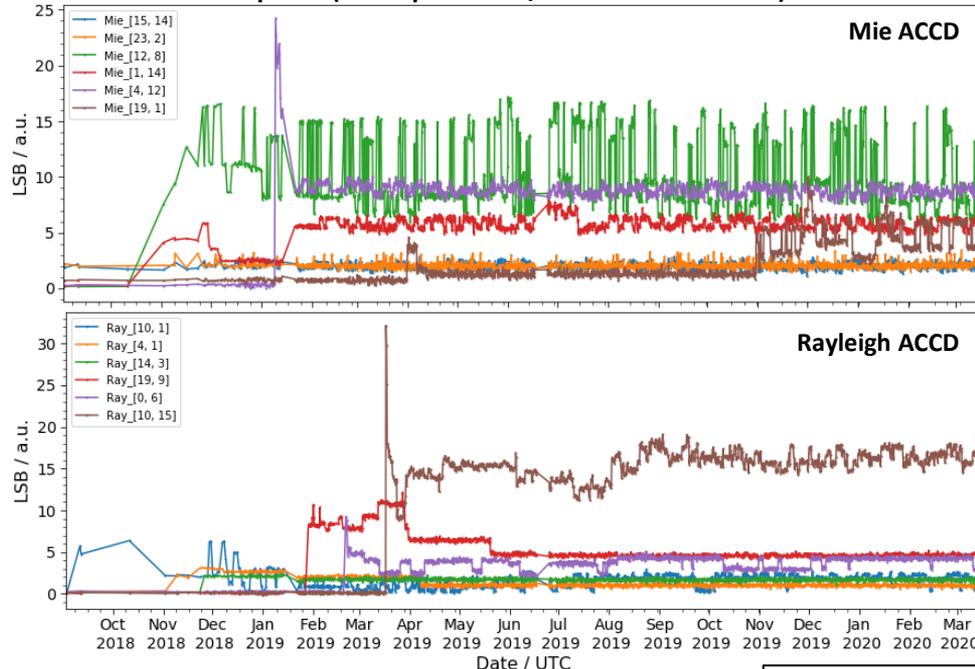
April 2020, Hot pixel map



Hot pixel evolution



Hot pixels (mean per DCMZ/DUDE measurement)



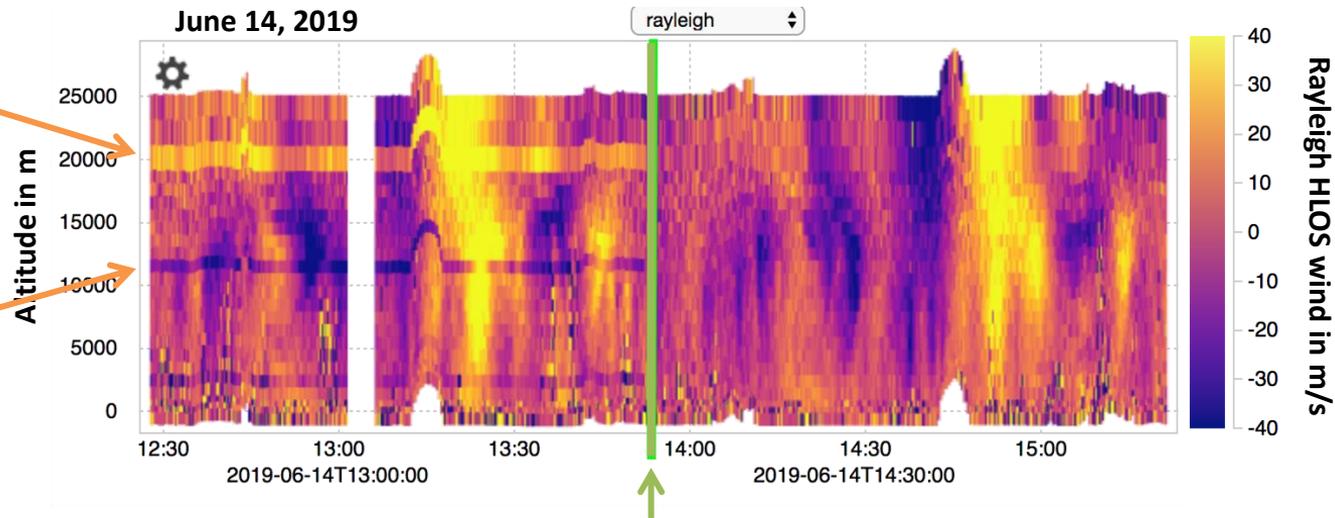
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# Correction of hot pixels implemented in June 2019

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correction developed by  
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Enhanced dark signals  
(hot pixels) cause  
**systematic errors of**  
 **$\pm(1-3 \text{ m/s})$**  for Rayleigh  
winds for some range gates  
=> horizontal stripes



New instrument modes introduced, algorithms developed and implemented in operational processors on **June, 14, 2019** for correction of hot pixels by measuring dark signals **4 times per day** for real-time datasets

**!** Hot pixels appearing in between the dark signal measurements still cause biases in NRT dataset  
(are flagged in L2B winds)



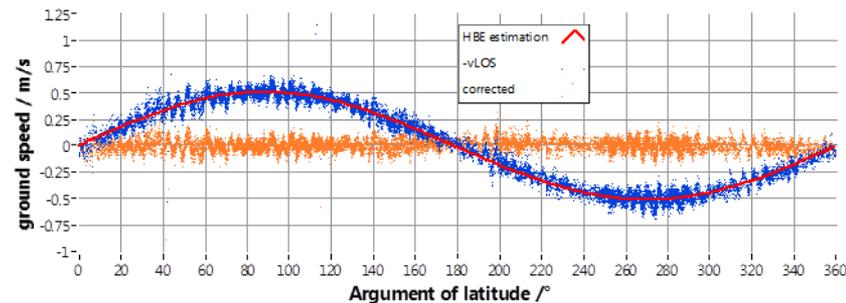
# What causes systematic errors?

Combination of 4 unexpected error sources with different temporal characteristics

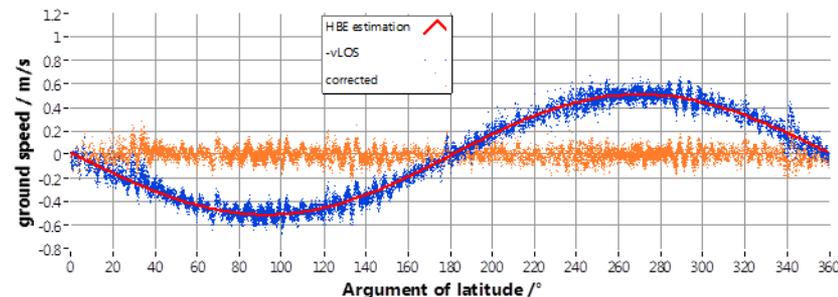
1. Higher dark current rates for some “hot pixels”
2. Error in the on-board software in calculation of residual projection of the **satellite ground speed on the line-of-sight LOS:**

- ⇒ harmonic variation of bias along the orbit
- ⇒ correction with on-board calculated  $v_{SAT}$  in L1B and L2B processors de-activated in summer 2019
- ⇒ correction for on-ground L1A processing identified and implementation envisaged for autumn 2020

$v_{SAT}$  during Dec 18 – 24, 2018



$v_{SAT}$  during June 29 – Jul 05, 2019



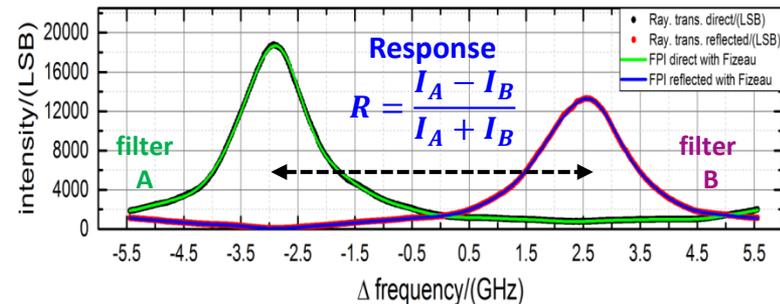
Amplitude of  $v_{LOS}$  is zero at equator and maximum at poles with around 0.6 m/s, but opposite phase as in December



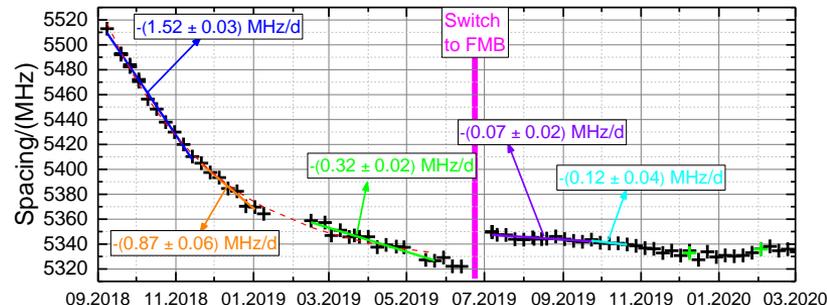
# What causes systematic errors?

Combination of 4 unexpected error sources with different temporal characteristics

1. Higher dark current rates for some “hot pixels”
2. Error in the on-board software in calculation of residual projection of the satellite ground speed on the line-of-sight LOS
3. **Slow drifts** in the illumination of the Rayleigh/Mie spectrometers causing a slowly, linear drifting constant bias



Rayleigh spectrometer filter spacing



Rayleigh filter A and B spectral difference nominal  
 2.3 pm = 5460 MHz  
 => change of 0.4 fm/d ( $2 \cdot 10^{-4}$  /d)  
 => wind speed dependent error

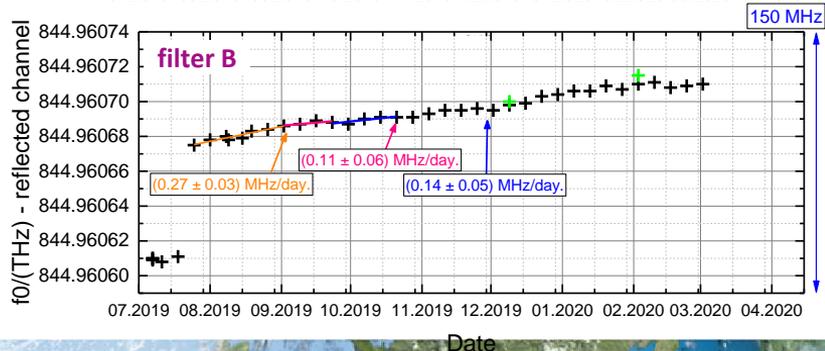
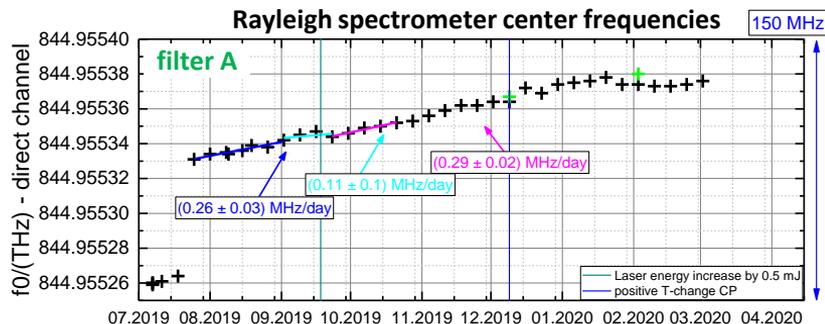
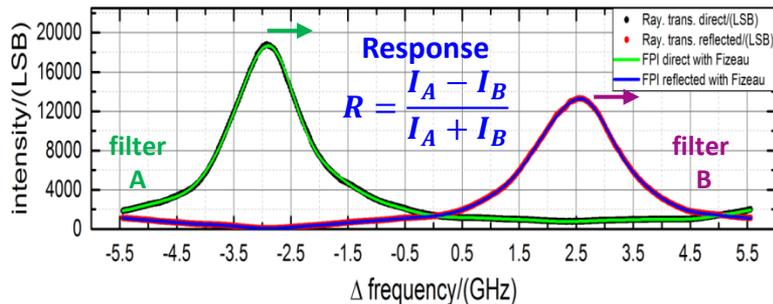
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# What causes systematic errors?

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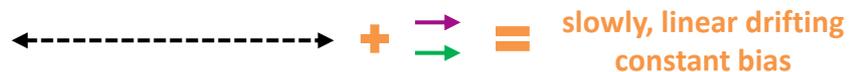
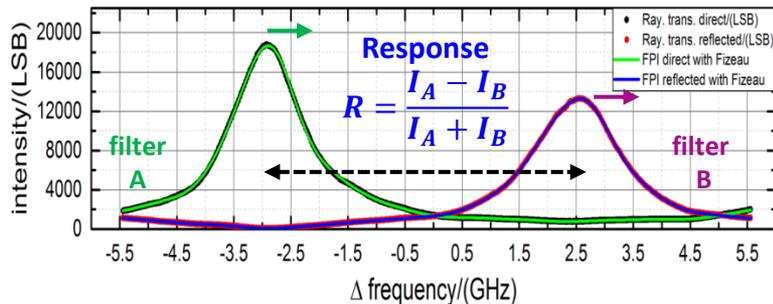
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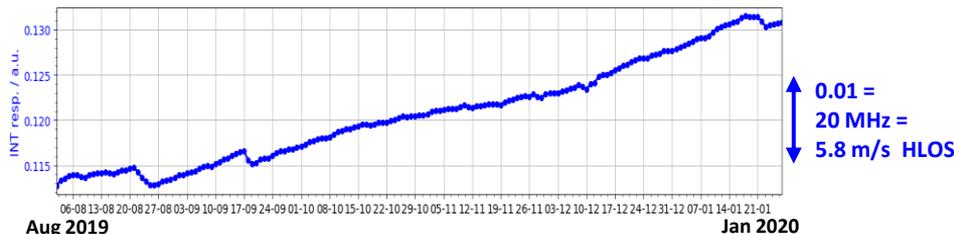
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2. Error in the on-board software in calculation of residual projection of the **satellite ground speed on the line-of-sight LOS**
3. **Slow drifts** in the illumination of the Rayleigh/Mie spectrometers causing a **slowly, linear drifting constant bias**
  - ⇒ Was in the past **corrected manually** by tuning of input parameters for L2B processing
  - ⇒ Now **corrected in real-time products** as part of M1-correction (see next slide)



Temporal evolution of internal Response  $R_{Int}$



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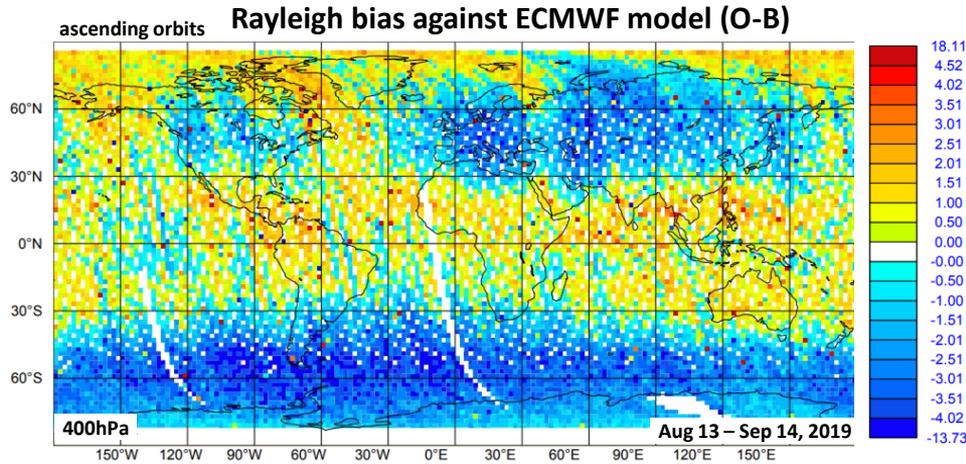
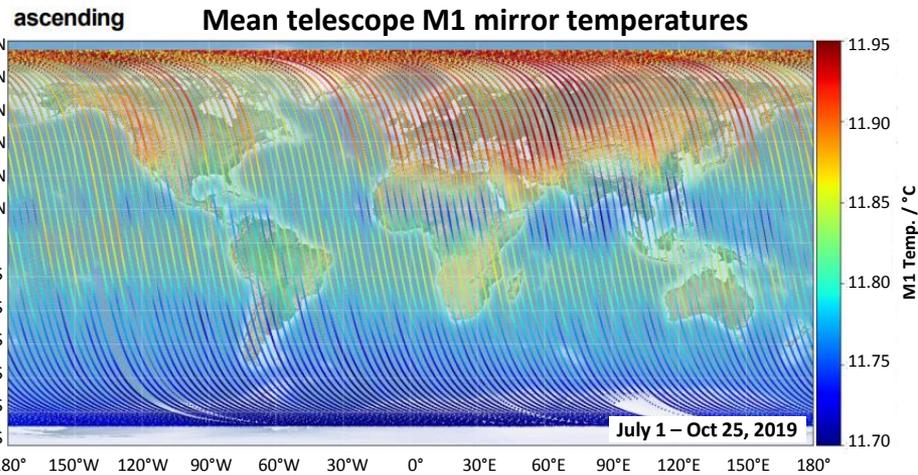


# What causes systematic errors?

Combination of 4 unexpected error sources with different temporal characteristics

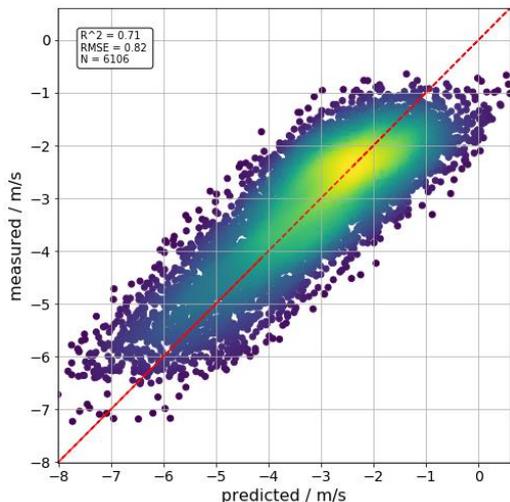
1. Higher dark current rates for some “hot pixels”
2. Error in the on-board software in calculation of residual projection of the **satellite ground speed on the line-of-sight LOS**
3. **Slow drifts** in the illumination of the Rayleigh/Mie spectrometers causing a **slowly, linear drifting constant bias**
4. Thermal variations of the **M1 telescope mirror**
  - ⇒ Rayleigh bias with orbital phase (argument of latitude) and longitude
  - ⇒ Use correlation between M1 temperatures and mean model bias for correction

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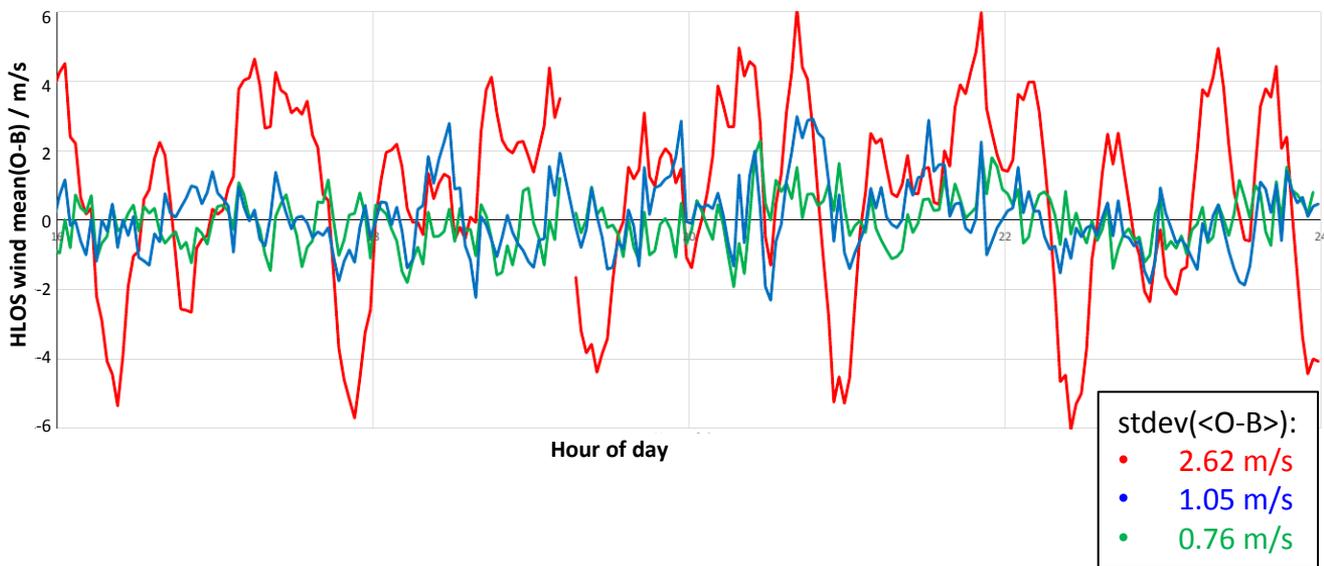


# Correction of bias caused by thermal variations of the M1 mirror

Multiple linear regression (1d of data)



Rayleigh bias versus time on 09/08/2019



## Effects of M1 correction:

1. „flattens out“ orbital variation (M1 telescope mirror) – reduces std. deviation of O-B (here: 2.62 m/s to 0.76 m/s)
2. Corrects for bias drifts (e.g. illumination effects)

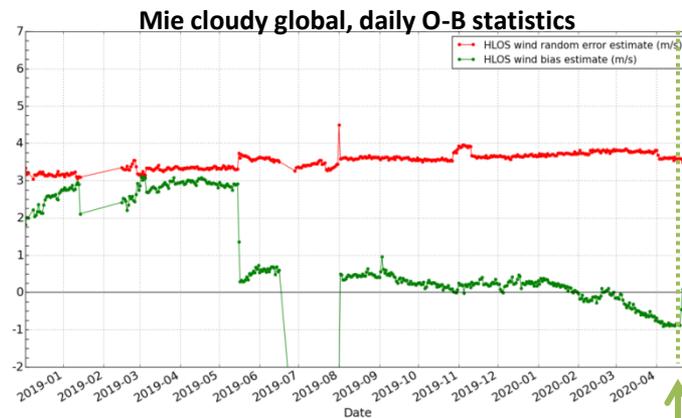
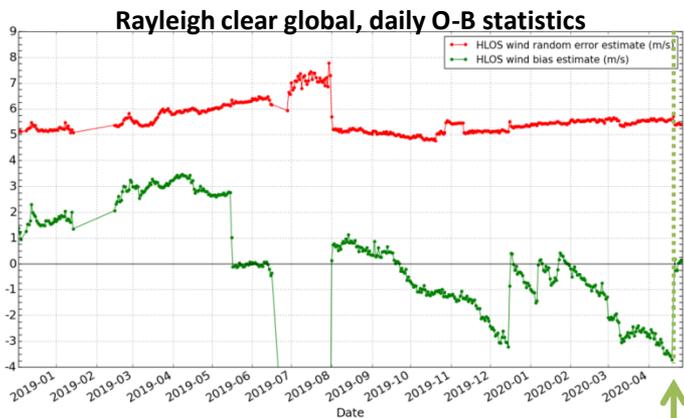
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# Correction of bias caused by thermal variations of the M1 mirror

Activated on April 20, 2020

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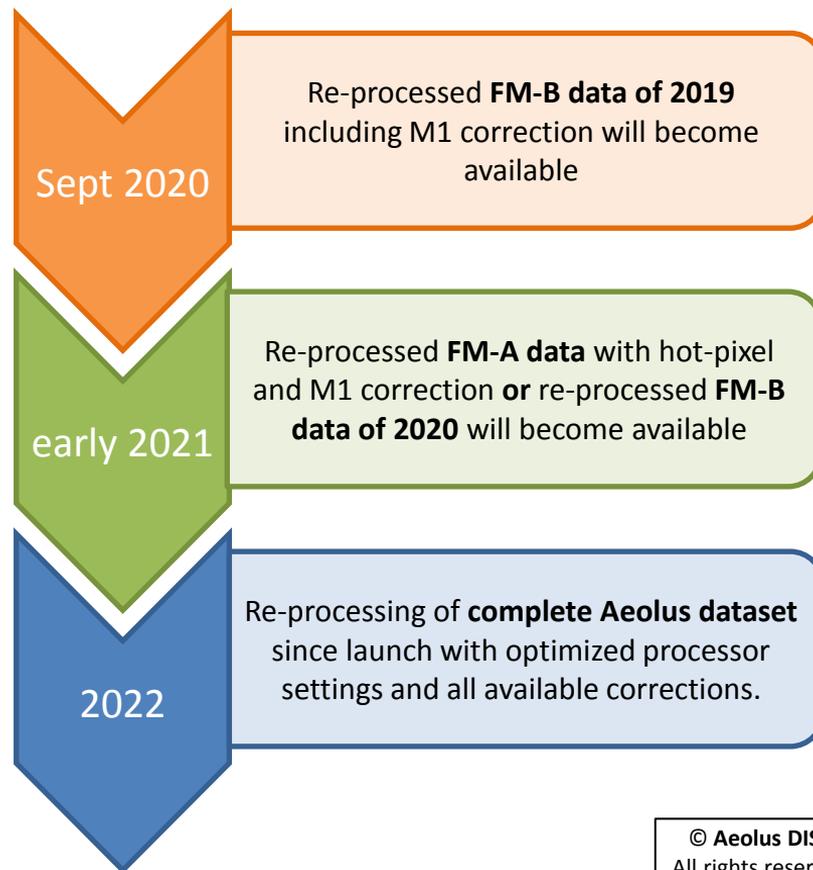
New instrument modes introduced, algorithms developed and implemented in operational processors on **April, 20, 2020** for correction of **M1 temperature biases** and slowly, linear drifting constant biases by using daily mean correlation between ECMWF model bias (O-B) and M1 temperature measurements.

Additional investigations are on-going to use ground measurements instead of ECMWF O-B to regain model independence.



## Re-processing of Aeolus data

- Re-processing activities started beginning of this year
- It involves multiple manual and only semi-automated steps, e.g.
  - Manual production of calibration files and processing up to L1B
  - Correction of hot pixels also in time periods between dark signal measurements
  - Semi-automated processing up to L2B
  - Manual estimation of M1 temperature correction
  - Verification of bias correction and delivery of all calibration files to ESA
  - Re-processing at ESA
  - Validation and quality control of re-processed dataset
- First re-processed dataset is FM-B data from 2019. It will be available in Sept. 2020.



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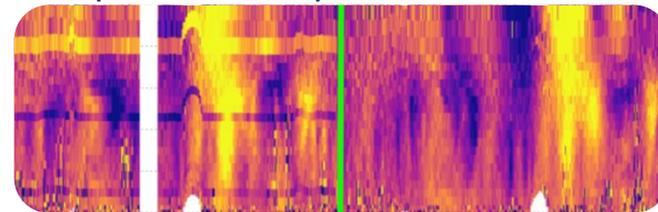




## Summary and Conclusion

- The **Aeolus DISC** consortium is responsible for **calibration, processor evolution, product quality and impact studies**.
- Both **systematic and random errors after launch were higher** than expected
- Precise instrument characterization and use of O-B statistics enabled a **drastic reduction of systematic errors**
- **Hot pixel correction was implemented** in June 2019 for NRT data stream
- **M1 temp. correction was implemented** in April 2020 for NRT data stream and is currently examined by experts.
- **Public data release on May 12, 2020** 😊
- Re-processing started recently and **first re-processed data (June – December 2019) will be available in Sept. 2020**.

Hot pixel correction implemented



M1 bias correction implemented



Public NRT data release

12 May  
2020

Reprocessing

Sept. 2020

early 2021

2022

FM-B 2019 data

FM-A data

Complete  
Aeolus dataset

