

Deutsches Zentrum für Luft- und Raumfahrt German Aerospace Center

Recent progress and new methods for detecting causal relations in large nonlinear time series datasets



Inferring causality: Three strands of modern (Earth) science

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• Real experiments



Bertini fresco of Galileo Galilei and Doge of Venice



Svante Arrhenius, 1909. Print Collector/Getty Images / Getty Images



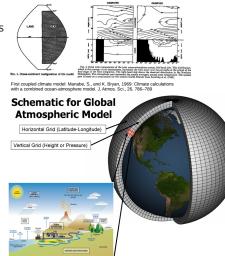
Earth Science Experiments Class Kit





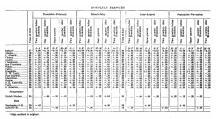
Inferring causality: Three strands of modern (Earth) science

- Real experiments
- Earth system simulation models

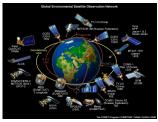




- Real experiments
- Earth system simulation models
- Observational data analysis



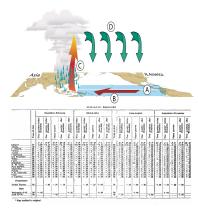
Walker, G T. 1924. "Correlations in Seasonal Variations of Weather." IX. Mem. Ind. Metorol. Dept. 24: 53-84.





Observational (climate) data analysis: 1st attempt

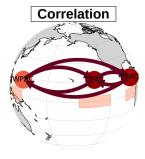
 Walker circulation: Monthly surface pressure anomalies in the West Pacific (WPAC), surface air temperature anomalies in the Central Pacific (CPAC) and East Pacific (EPAC)



Walker (1924)

Observational (climate) data analysis: 1st attempt

- Walker circulation: Monthly surface pressure anomalies in the West Pacific (WPAC), surface air temperature anomalies in the Central Pacific (CPAC) and East Pacific (EPAC)
- All three regions are strongly lag-correlated with each other 'in all directions'



Walker (1924)



Causal inference: 1st attempt

S. Wright, Correlation and Causation, J. of Agricultural Res. 10(7), 1921

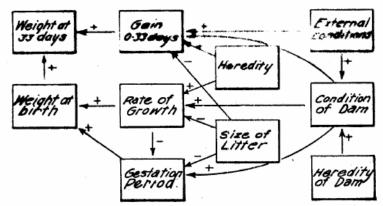


FIG. 1.-- Diagram illustrating the interrelations among the factors which determine the weight of guinea pigs at birth and at weaning (33 days).



Karl Pearson's "Grammar of Science" (1911): "Beyond such discarded fundamentals as 'matter' and 'force' lies still another fetish amidst the inscrutable arcana of modern science, namely, the category of cause and effect."



CONTINGENCY AND CORRELATION 159 B_1 occurs n_{y_1} , B_2 occurs n_{y_2} times, and so on. We thus are able to obtain a general distribution of B's for each

are able to obtain a general distribution of B's for each class of A that we can form, and were we to go through the whole population, N, of A's in this manner we should obtain a table of the following kind :---

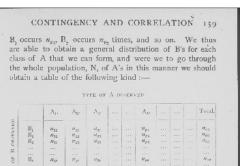
TYPE OF A OUSERVED

| | Λ_0 | Ag | $\Lambda_{\rm P}$ | | A _p . | | Total |
|----------------|-------------|-------|-------------------|--|------------------|--|-------|
| B | 2211 | na | 14.51 | | | | 17.13 |
| B _t | N15 | 11:00 | 34.71 | | 12,15 | | Hay. |
| E ₁ | 1510 | 1721 | 1123 | | 11,2 | | Was. |
| | | | | | | | |
| | | | | | | | |
| B _e | 15.15 | Wer | 1131 | | II ju | | West |
| | | | | | | | |
| | | | | | | | |
| Total | stip | Rep. | 11:50 | | Mak | | N |

Karl Pearson's "Grammar of Science" (1911): "Beyond such discarded fundamentals as 'matter' and 'force' lies still another fetish amidst the inscrutable arcana of modern science, namely, the category of cause and effect." **Correlation is not causation!**

Total Max Has Has

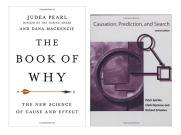






Causality and statistics

Correlation is not causation! Well... not generally, but... [Pearl, 2000, Pearl and Mackenzie, 2018, Spirtes et al., 2000]





Causality and statistics

Causal inference is about identifying assumptions and methods that enable to learn causal relations from observational data

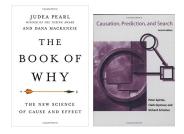


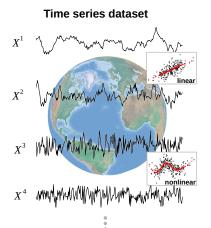


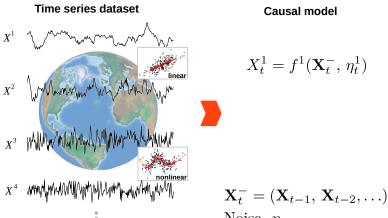
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- 7. Causality benchmark platform

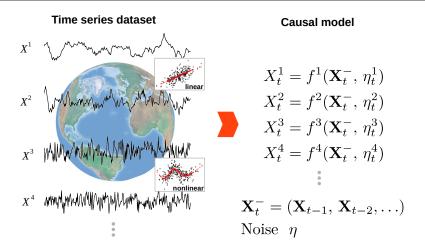
8. Discussion and Conclusions

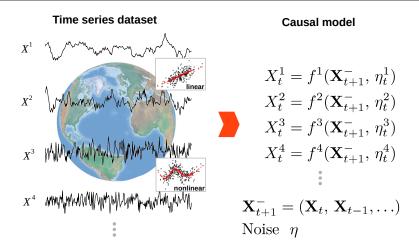


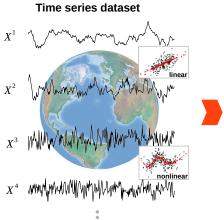




Noise η





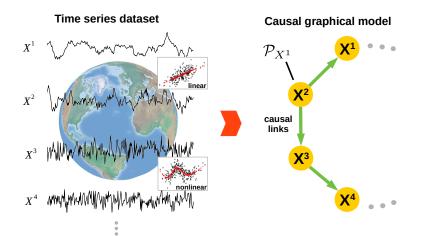


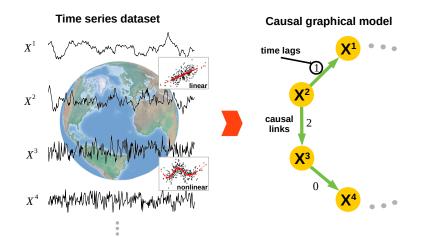
Causal model

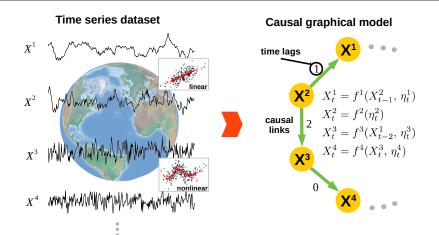
$$X_{t}^{1} = f^{1}(\mathcal{P}_{X_{t}^{1}}, \eta_{t}^{1})$$
$$X_{t}^{2} = f^{2}(\mathcal{P}_{X_{t}^{2}}, \eta_{t}^{2})$$
$$X_{t}^{3} = f^{3}(\mathcal{P}_{X_{t}^{3}}, \eta_{t}^{3})$$
$$X_{t}^{4} = f^{4}(\mathcal{P}_{X_{t}^{4}}, \eta_{t}^{4})$$

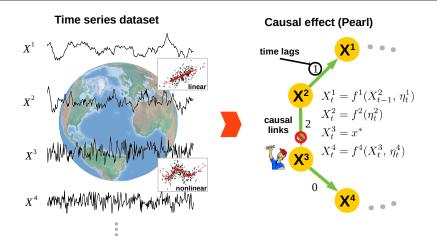
Parents $\mathcal{P} \subset \mathbf{X}_{t+1}^-$ Noise η

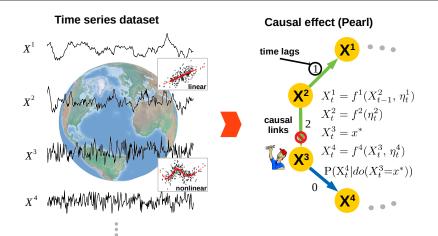


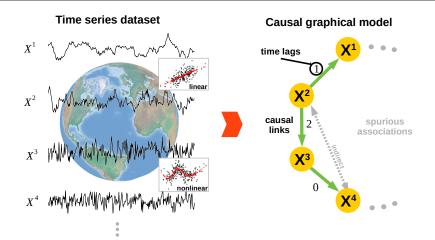


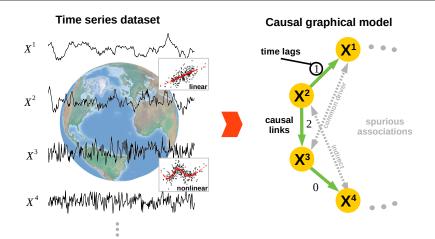


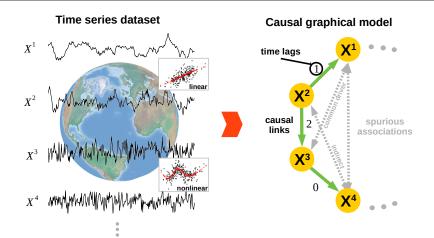








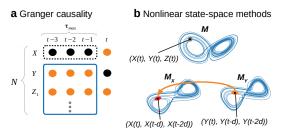


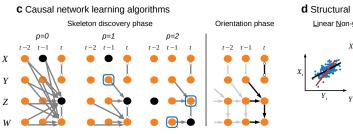


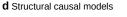
State of the art

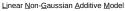


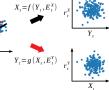
State of the art: Runge et al., NatComm Perspective 2019













Challenges for causal inference

Challenges for causal inference: Runge et al., NatComm 2019

Challenges

Process:

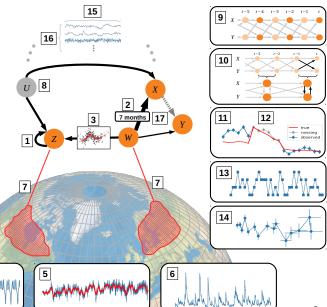
- 1 Autocorrelation
- 2 Time delays
- 3 Nonlinear dependencies
- 4 Chaotic state-dependence
- 5 Different time scales
- 6 Noise distributions

Data:

- 7 Variable extraction
- 8 Unobserved variables
- 9 Time subsampling
- 10 Time aggregation
- 11 Measurement errors
- 12 Selection bias
- 13 Discrete data
- 14 Dating uncertainties

Computational / statistical:

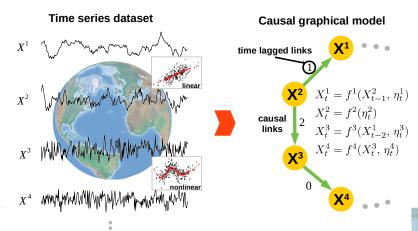
- 15 Sample size
- 16 High dimensionality
- 17 Uncertainty estimation



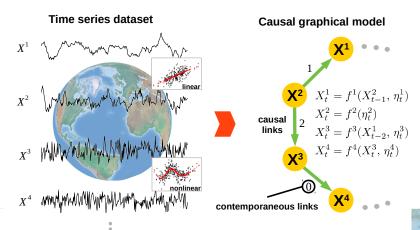




PCMCI: Assumes time-lags (Runge et al. *Science Advances* 2019) Tigramite 4.2 python package

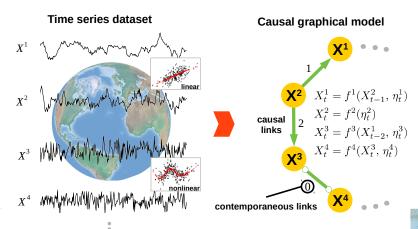


PCMCI+: Allows time-lags and contemporaneous links (Runge (2020) https://arxiv.org/abs/2003.03685)

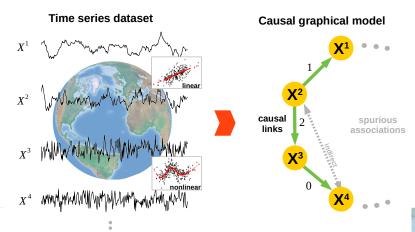




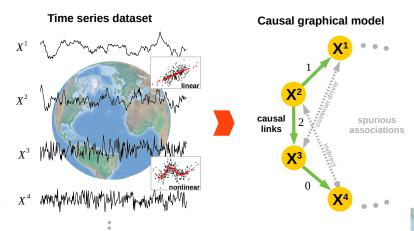
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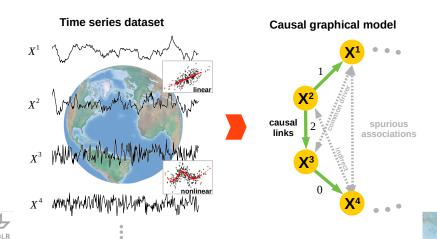
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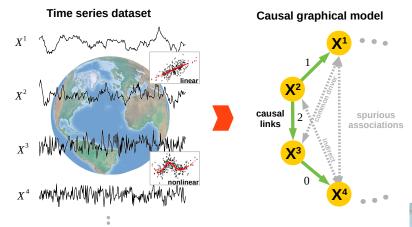
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Enabling assumptions: Faithfulness, Markovity, Causal Sufficiency, no
contemporaneous effects, and stationarity

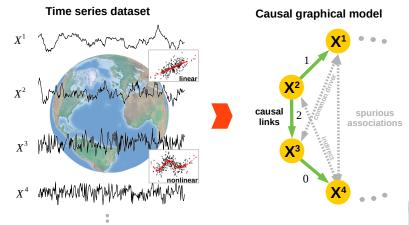




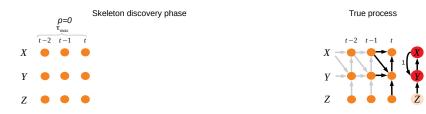
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Enabling assumptions: Faithfulness, Markovity, Causal Sufficiency, no contemporaneous effects, and stationarity

Nonlinearity and noise distributions handled by flexible conditional inde-

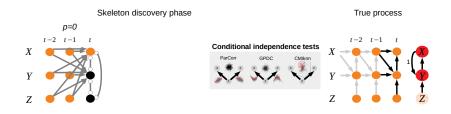


PC algorithm skeleton discovery phase can use different conditional independence (CI) tests: Partial Correlation $\rho(X; Y|\mathbf{S})$, Conditional Mutual Information $I(X; Y|\mathbf{S})$, etc.





Detection power for detecting $X \not\sqcup Y \mid \mathbf{S}$ depends on: Sample size





10

Detection power for detecting $X \not\sqcup Y \mid \mathbf{S}$ depends on: Sample size Significance level α_{PC}





Detection power for detecting $X \not\perp Y \mid \mathbf{S}$ depends on: Sample size Significance level α_{PC} Condition dimension, cardinality of $|\mathbf{S}|$



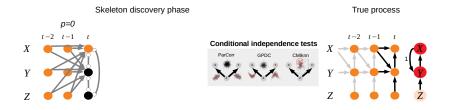


Detection power for detecting $X \not\perp Y \mid \mathbf{S}$ depends on: Sample size Significance level α_{PC} Condition dimension, cardinality of $|\mathbf{S}|$ Effect size, i.e., magnitude of $I(X; Y|\mathbf{S})$



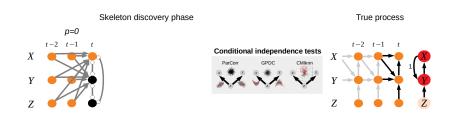


Detection power for detecting $X \not\bowtie Y \mid \mathbf{S}$ depends on: Sample size (given by dataset) Significance level α_{PC} (hyperparameter, difficult to tune) Condition dimension, cardinality of $|\mathbf{S}|$ (PC optimizes this) Effect size, i.e., magnitude of $I(X; Y \mid \mathbf{S})$ (Problem addressed here)



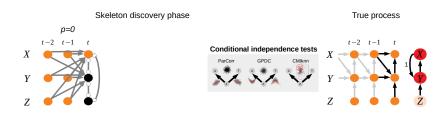


Consider underlying linear model, here
$$I(Y_t; Z_t) = \frac{1}{2} \ln \left(1 + \frac{cVar(Z)}{Var(Y)}\right)$$





Consider underlying linear model, here $I(Y_t; Z_t) = \frac{1}{2} \ln \left(1 + \frac{cVar(Z)}{Var(Y)}\right)$ \implies Effect size is small if $Var(Y) \gg Var(Z)$, and lead to false removal.



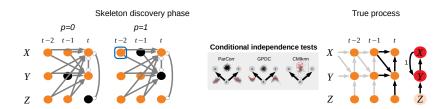


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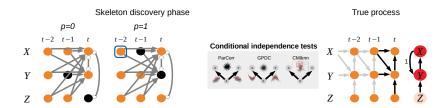


Problem: PC iterates through all adjacent conditions **S** and link is removed if $\left[\min_{\mathbf{S}} I(X; Y | \mathbf{S}) < I_{\alpha_{\mathrm{PC}}} \right]$



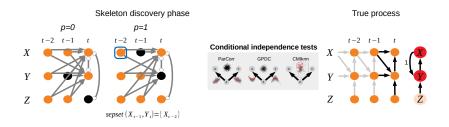


Problem: PC iterates through **all** adjacent conditions **S** and link is removed if $\begin{bmatrix} \min I(X; Y | \mathbf{S}) < I_{\alpha_{\rm PC}} \end{bmatrix}$ Generally: Effect size for a link $X_{t-\tau} \rightarrow Y_t$ is small when conditioning on parents of $X_{t-\tau}$ and large when conditioning on parents of Y_t , i.e., $I(X; Y | \mathcal{P}(X)) \ll I(X; Y | \mathcal{P}(Y))$ [Runge et al., 2012a]



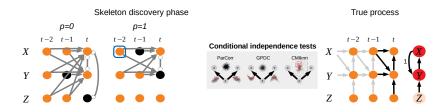


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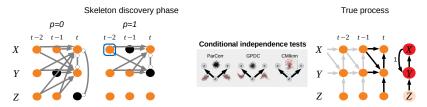
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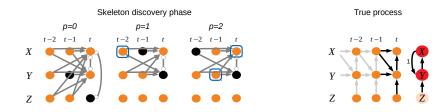
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PC likely iterates through such conditions and removes true links.



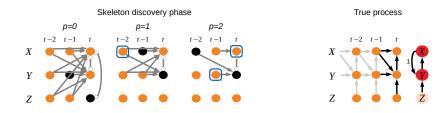


Removed links are not used as conditions for larger *p*.



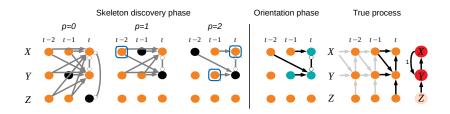


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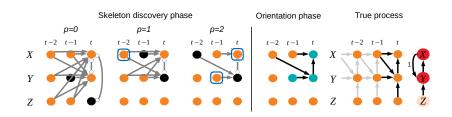




 \implies False positives (incorrect links)! Then orientation phase also suffers from wrong sepsets.



Then orientation phase also suffers from wrong sepsets.



Consider underlying true process graph.

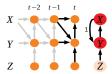
True process





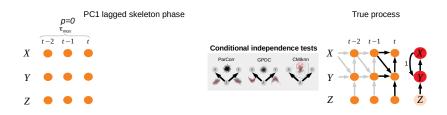
Consider underlying true process graph. Associated time series graph.

True process



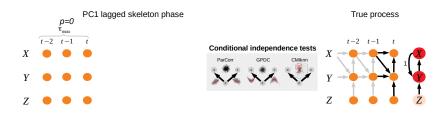


 PCMCI^+ has 3 phases: PC_1 lagged phase, MCI contemporaneous phase, Orientation phase.





PC₁ lagged phase differs from PC algorithm twofold:

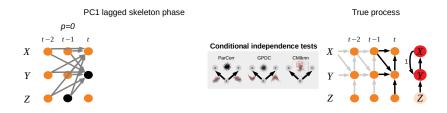




11

PC₁ lagged phase differs from PC algorithm twofold:

(1) S iterates through lagged links only,

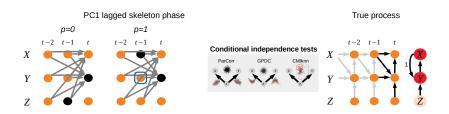




PC₁ lagged phase differs from PC algorithm twofold:

(1) S iterates through lagged links only,

(2) $\mathbf{S} = \{\mathcal{A}(X_t^j)\}_{l=1}^p$ for every cardinality p: lagged conditions with largest association with X_t^j .



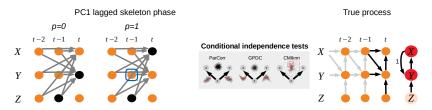


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 \implies much less likely to condition on "effect-size weakening" parents of $X^i_{t-\tau}$



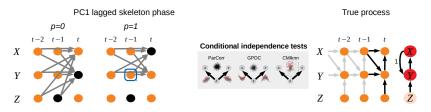


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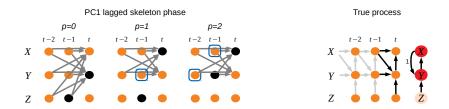
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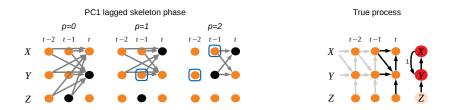
 \implies much less likely to condition on "effect-size weakening" parents of $X^i_{t-\tau}$



 PC_1 converges to lagged parents plus parents of contemporaneous ancestors: $\widehat{\mathcal{B}}^-_t(X^j_t).$



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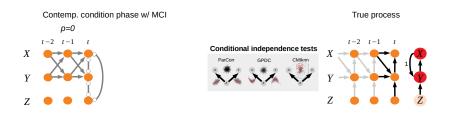


MCI contemporaneous phase is first initialized with lagged links $\hat{\mathcal{B}}_t^-(X_t^j)$ and all contemporaneous links





MCI contemporaneous phase is first initialized with lagged links $\hat{\mathcal{B}}_t^-(X_t^j)$ and all contemporaneous links





11

MCI phase iterates through contemporaneous conditions $S \subseteq A_t(X_t^J)$ with MCI tests:

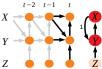
$$X_{t-\tau}^{i} \bot\!\!\!\bot X_{t}^{j} \mid \mathbf{S}, \widehat{\mathcal{B}}_{t}^{-}(X_{t}^{j}) \backslash \{X_{t-\tau}^{i}\}, \widehat{\mathcal{B}}_{t-\tau}^{-}(X_{t-\tau}^{i})$$













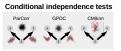
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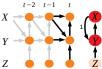
$$X_{t-\tau}^{i} \bot\!\!\!\bot X_{t}^{j} \mid \mathbf{S}, \widehat{\mathcal{B}}_{t}^{-}(X_{t}^{j}) \backslash \{X_{t-\tau}^{i}\}, \widehat{\mathcal{B}}_{t-\tau}^{-}(X_{t-\tau}^{i})$$



True process

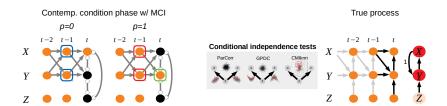






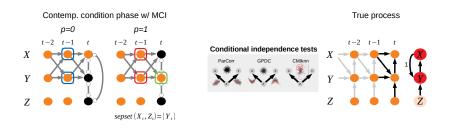


Conditioning on **both** $\widehat{\mathcal{B}}_{t}^{-}(X_{t}^{j})$ and $\widehat{\mathcal{B}}_{t-\tau}^{-}(X_{t-\tau}^{j})$ has two important implications: (1) MCI effect size larger than PC effect size, (2) MCI tests well-calibrated (both discussed in paper)



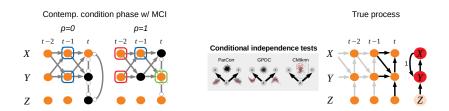


Spurious links due to contemporaneous drivers are removed and sepsets stored; converges much faster than PC algorithm, shorter runtimes.



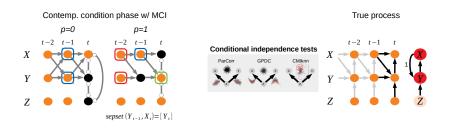


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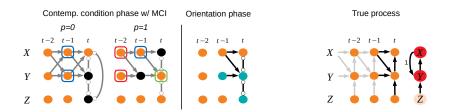


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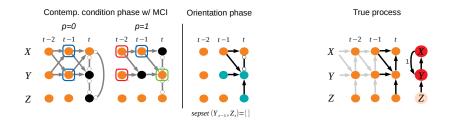
Orientation phase as for PC algorithm.





Orientation phase as for PC algorithm.

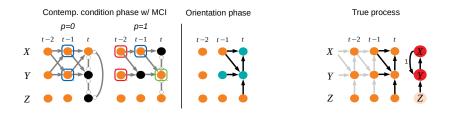
Collider/unshielded triple rule: Y_t is <u>not</u> in $sepset(Y_{t-1}, Z_t) \implies$ orient $Z_t \rightarrow Y_t$





Orientation phase as for PC algorithm. Collider/unshielded triple rule: Y_t is <u>not</u> in $sepset(Y_{t-1}, Z_t) \implies$ orient $Z_t \rightarrow Y_t$

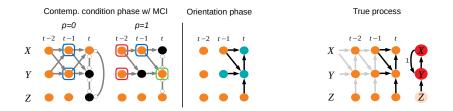
Rule R1: Orient remaining unshielded tripls in other direction



Orientation phase as for PC algorithm.

Collider/unshielded triple rule: Y_t is <u>not</u> in $sepset(Y_{t-1}, Z_t) \implies$ orient $Z_t \rightarrow Y_t$

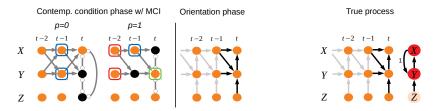
Rule R1: Orient remaining unshielded tripls in other direction Further rules that make use of acyclicity assumption (see paper).



Orientation phase as for PC algorithm.

Collider/unshielded triple rule: Y_t is <u>not</u> in $sepset(Y_{t-1}, Z_t) \implies$ orient $Z_t \rightarrow Y_t$

Rule R1: Orient remaining unshielded tripls in other direction Further rules that make use of acyclicity assumption (see paper). PCMCI⁺ converges, links are repeated by assuming stationarity,



In paper:

• Asymptotical consistency: PCMCI⁺ is sound and complete

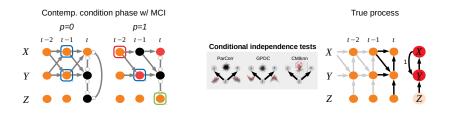




12

In paper:

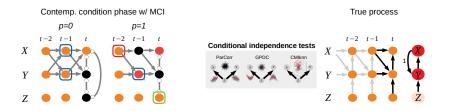
- \bullet Asymptotical consistency: PCMCI^+ is sound and complete
- Order independence (with majority rule in collider phase and conflict resolution)





In paper:

- \bullet Asymptotical consistency: PCMCI^+ is sound and complete
- Order independence (with majority rule in collider phase and conflict resolution)
- Conjecture: Effect size is always greater than that of PC algorithm $\min_{\mathbf{S} \text{ in PCMCI}^+} I(X_{t-\tau}^i ; X_t^j \mid \mathbf{S}, \widehat{\mathcal{B}}_j, \widehat{\mathcal{B}}_i) > \min_{\mathbf{S}' \text{ in PC}} I(X_{t-\tau}^i ; X_t^j \mid \mathbf{S}')$



In paper:

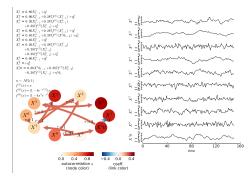
- \bullet Asymptotical consistency: PCMCI^+ is sound and complete
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- Conjecture: Effect size is always greater than that of PC algorithm $\min_{\mathbf{S} \text{ in PCMCI}^+} I(X_{t-\tau}^i; X_t^j \mid \mathbf{S}, \widehat{\mathcal{B}}_i, \widehat{\mathcal{B}}_i) > \min_{\mathbf{S}' \text{ in PC}} I(X_{t-\tau}^i; X_t^j \mid \mathbf{S}')$
- MCI tests are well-calibrated also for autocorrelated data [Runge et al., 2019b]

Contemp. condition phase w/ MCI

True process



- random coupling topologies, time lags, linear/nonlinear
- 30% contemporaneous links, coefficients \pm [0.1..0.5]
- different autocorrelations for variables
- $\tau_{\rm max} = 5$, T = 500, varying N = 2..40
- $\alpha_{\rm PC}$ fixed, can be chosen via AIC





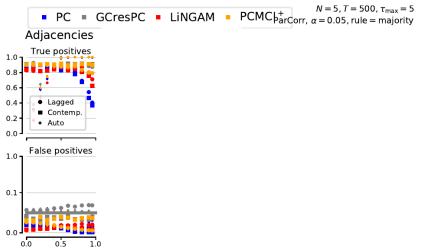
Comparing with PC algo, Granger causality + PC on residuals (GCresPC), LiNGAM

• PC = GCresPC • LiNGAM • PCMC $_{arCorr, \alpha}^{+}$ = 5.00, τ_{max} = 5



Autocorrelation a

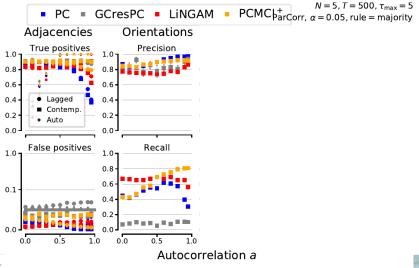
High adjacency detection rate, well-controlled false positives



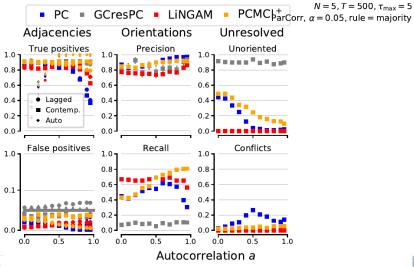


Autocorrelation a

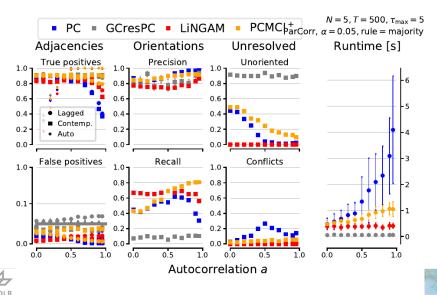
High precision and high recall for strong autocorrelation; LinGAM makes use of non-Gaussianity here, fails for Gaussians



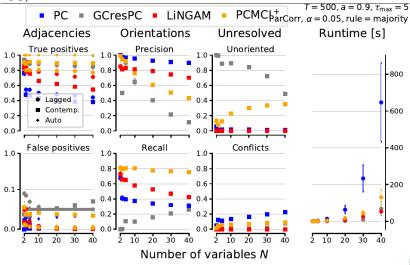
Slightly more unoriented, but also fewer conflicts (majority rule and conflict resolution enabled)



PC takes longer and is more variable

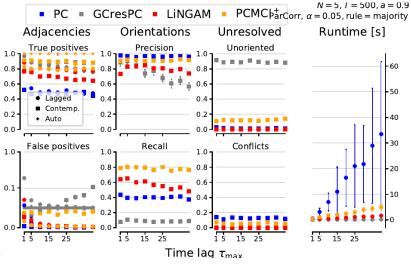


High dimensionality: Still well-calibrated, high recall, less precision (at this α_{PC})

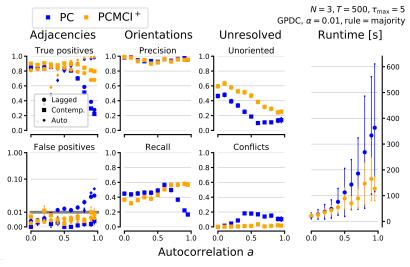




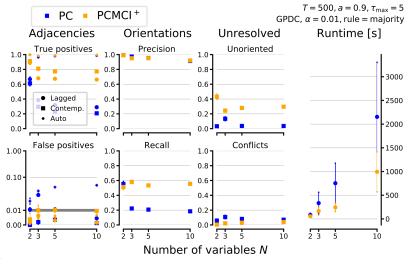
Large time lags: Almost no effect on precision and recall



Nonlinear GPDC test: Higher recall than PC for high autocorrelation



Nonlinear GPDC test: Higher recall than PC for high dimensionality



Application examples



• Testing causal hypotheses

[Runge et al., 2014, Runge et al., 2015b, Kretschmer et al., 2016, Runge et al., 2019b, Kretschmer et al., 2018, Runge et al., 2018, Runge et al., 2019a, Krich et al., 2019]

• Testing causal hypotheses

[Runge et al., 2014, Runge et al., 2015b, Kretschmer et al., 2016, Runge et al., 2019b, Kretschmer et al., 2018, Runge et al., 2018, Runge et al., 2019a, Krich et al., 2019]

• Optimal statistical prediction schemes [Runge et al., 2015a, Kretschmer et al., 2017, Di Capua et al., 2019]

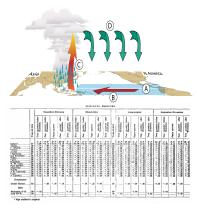
• Testing causal hypotheses

[Runge et al., 2014, Runge et al., 2015b, Kretschmer et al., 2016, Runge et al., 2019b, Kretschmer et al., 2018, Runge et al., 2018, Runge et al., 2019a, Krich et al., 2019]

- Optimal statistical prediction schemes [Runge et al., 2015a, Kretschmer et al., 2017, Di Capua et al., 2019]
- Evaluating climate/physical models [Schleussner et al., 2014, Nowack et al., 2019]

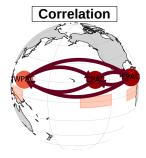
 Monthly surface pressure anomalies in the West Pacific (WPAC), surface air temperature anomalies in the Central Pacific (CPAC) and East Pacific (EPAC)

Runge et al. Nat. Comm. (2019)





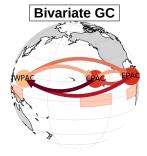
- Monthly surface pressure anomalies in the West Pacific (WPAC), surface air temperature anomalies in the Central Pacific (CPAC) and East Pacific (EPAC)
- Correlation analysis gives a completely connected graph



Runge et al. Nat. Comm. (2019)



- Monthly surface pressure anomalies in the West Pacific (WPAC), surface air temperature anomalies in the Central Pacific (CPAC) and East Pacific (EPAC)
- Correlation analysis gives a completely connected graph
- Also bivariate Granger Causality cannot remove indirect and common driver links

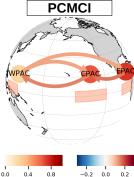


Runge et al. Nat. Comm. (2019)



- Monthly surface pressure anomalies in the West Pacific (WPAC), surface air temperature anomalies in the Central Pacific (CPAC) and East Pacific (EPAC)
- Correlation analysis gives a completely connected graph
- Also bivariate Granger Causality cannot remove indirect and common driver links
- PCMCI [Runge et al., 2019b] better identifies the Walker circulation

Runge et al. Nat. Comm. (2019)

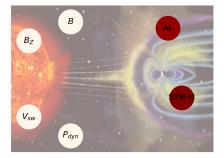


Auto-strength

Link strength



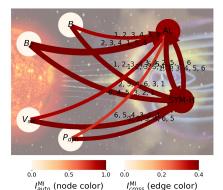
 Hypothesis on interaction between magnetospheric Auroral Electrojet index (AL), magnetospheric ring current strength (SYM-H), and solar wind parameters



Runge et al. *Sci. Rep.* (2018), $\Delta t = 20$ min resolution

- Hypothesis on interaction between magnetospheric Auroral Electrojet index (AL), magnetospheric ring current strength (SYM-H), and solar wind parameters
- Mutual information analysis gives many dependencies

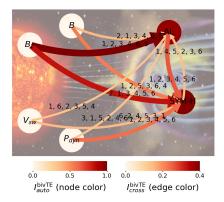
Mutual information



Runge et al. *Sci. Rep.* (2018), $\Delta t = 20$ min resolution

- Hypothesis on interaction between magnetospheric Auroral Electrojet index (AL), magnetospheric ring current strength (SYM-H), and solar wind parameters
- Mutual information analysis gives many dependencies
- Transfer Entropy cannot remove indirect and common driver links

Transfer Entropy

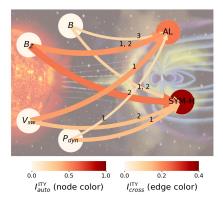


Runge et al. *Sci. Rep.* (2018), $\Delta t = 20$ min resolution

- Hypothesis on interaction between magnetospheric Auroral Electrojet index (AL), magnetospheric ring current strength (SYM-H), and solar wind parameters
- Mutual information analysis gives many dependencies
- Transfer Entropy cannot remove indirect and common driver links
- PCMCI yields novel insight that solar wind is common driver of magnetospheric indices

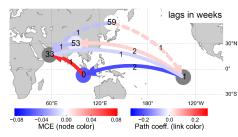
Runge et al. *Sci. Rep.* (2018), $\Delta t = 20$ min resolution

PCMCI



Causal mediation analysis

• Pathway mechanisms by which El Nino influences Indian monsoon through sea-level pressure system

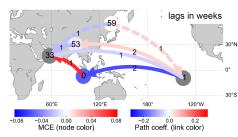


Runge et al. Nat. Comm. (2015)



Causal mediation analysis

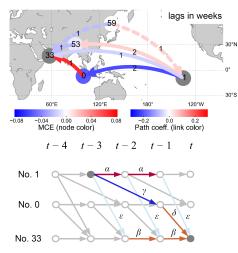
- Pathway mechanisms by which El Nino influences Indian monsoon through sea-level pressure system
- <u>Mediated Causal Effect</u> (MCE) quantifies how much an intermediate variable (node) contributes to a causal effect





Causal mediation analysis

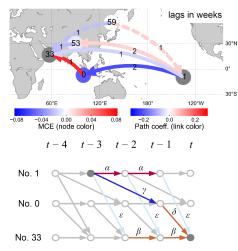
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- Linear path analysis (early approach due to Sewall Wright in 1920s)





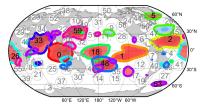
Causal mediation analysis

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- Linear path analysis (early approach due to Sewall Wright in 1920s)
- Nonlinear extension in Runge *Physical Review E* (2015)



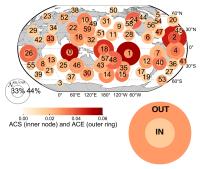


• Complex network measures based on extracted causal network from sea-level pressure system



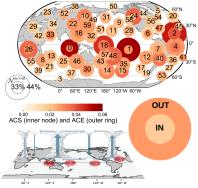


- Complex network measures based on extracted causal network from sea-level pressure system
- Global <u>causal gateways</u> based on <u>Average Causal Effect</u> (ACE)



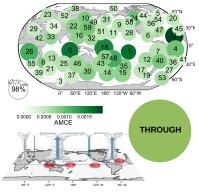


- Complex network measures based on extracted causal network from sea-level pressure system
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- Here well represents tropical atmospheric uplift regions



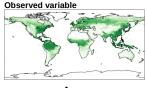


- Complex network measures based on extracted causal network from sea-level pressure system
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- Here well represents tropical atmospheric uplift regions
- Global <u>causal mediators</u> based on Mediated Causal Effect (MCE)



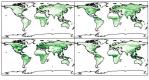


Motivation: Simple statistics (e.g. mean, variance, trends) can be right for the wrong reasons





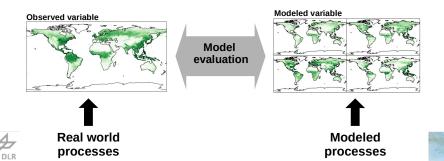
Modeled variable



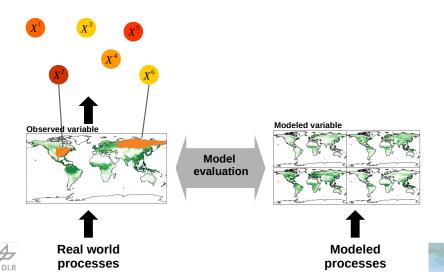


20

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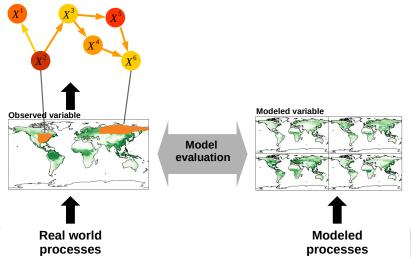


Idea: Compare climate models and observations in terms of causal relationships

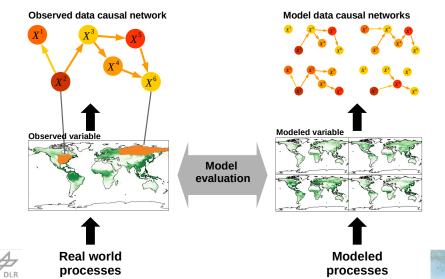


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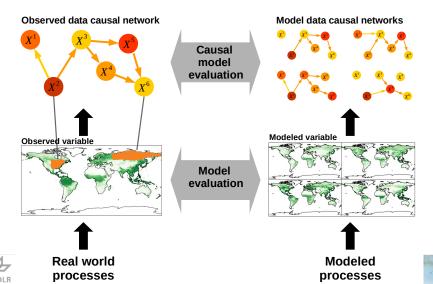
Observed data causal network



Idea: Compare climate models and observations in terms of causal relationships

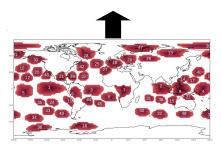


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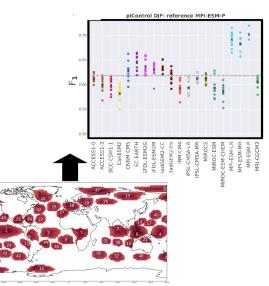
20

First results: CMIP5 simulations (historical and preindustrial) vs NCEP/NCAR reanalysis data of regional 3-day-mean sea level pressure



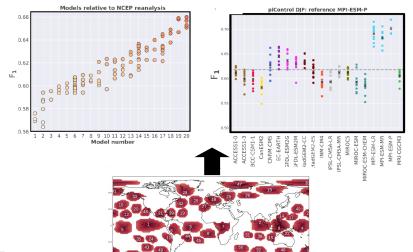


Validation: Similar climate models have similar causal networks; F-score as network comparison metric





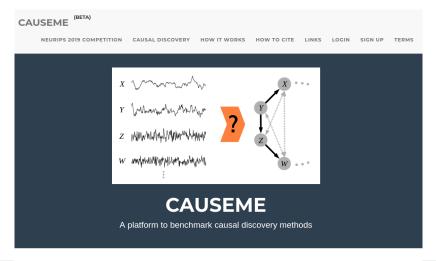
Model evaluation: Significant differences in comparison to reanalysis





Causality benchmark platform

Joint work with Jordi Munoz-Mari and Gustau Camps-Valls (U Valencia)





CALICAL DICCOVEDV

Joint work with Jordi Munoz-Mari and Gustau Camps-Valls (U Valencia)



HOW IT WORKS

Causeme currently covers a wide range of synthetic model data mimicking a number of real world challenges. These cover time delays, autocorrelation, nonlinearity, chaotic dynamics, extreme events, measurement error, and will be extended by many more. Method developers can upload their predictions (matrices of causal connections) and the platform evaluates and ranks the methods according to different metrics of performance. After registering and logging in, more information, datasets, and example code snippets are given.

Challenges Process:

1 Autocorrelation 2 Time delays 3 Nonlinear dependencies 4 Chaotic state-dependence 5 Different time scales 6 Noise distributions

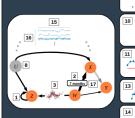
Data:

7 Variable extraction 8 Unobserved variables

9 Time subsampling 10 Time aggregation 11 Measurement errors 12 Selection bias 13 Discrete data 14 Dating uncertainties

Computational / statistical: 15 Sample size

16 High dimensionality 17 Uncertainty estimation







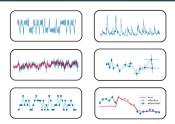


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JAKOB RUNGE

DATA AND MODELS METHODS **I**FRANKING ноwто MY RESULTS

DATA AND MODELS



Below you find a list of available datasets. Currently, they come from dynamical model systems featuring different challenges for causal discovery from time series as discussed in the accompanying Nature Communications Perspective paper. At the end of this page you find information on how to contribute real world datasets or model systems. Clicking on the model name will bring you to a description of the model and a list of experimental datasets. Please see the CauseMe workflow description in HowTo on how to upload your results for these experiments.

You can search through the database by name, description or tags.

Filter models: Name

Long name

LOGOUT

Joint work with Jordi Munoz-Mari and Gustau Camps-Valls (U Valencia)



Below you find a list of methods applied by users of this platform. Clicking on the name will bring you to a description of the method. You can search through the database by name, user, and tags. Register your own methods on My Results!

| Show 10 v entries | | |
|----------------------|-------------|---|
| Filter methods: | | |
| Name | User | Tags |
| adaptive-lasso | Jakob runge | Linear, time delays, high-dimensional |
| correlation | Jakob runge | Linear, time series, non-conditional |
| distance-correlation | Jakob runge | Time delays, nonlinear, non-conditional |
| FullCI-CMIknn | Jakob runge | Time delays, nonlinear |
| FullCI-GPDC | Jakob runge | Time delays, nonlinear |
| FullCI-ParCorr | lakoh runga | Linear time delays |



Joint work with Jordi Munoz-Mari and Gustau Camps-Valls (U Valencia)

JAKOB RUNGE

DATA AND MODELS METHODS ^[]RANKING HOWTO MY RE

MY RESULTS LOGOUT

RANKING

The table below presents a ranking of methods for different experiments and can be social daccording to the different meth role in columns. Optionally, the table can be filtered by metric values above or below a certain trenshold. For example, only methods up only methods and sort these by TPR in decreasing order. In addition, the search field can be used on the whole table to select only particular experiments or particular methods (or both). For example, "winned N+10-150" will ist all methods with "warmout", PLP, and TPR are based on binary link predictions by thresholding uploaded p-values at 0.05 (only available if the "values were uploaded"). Ther example, TPR are based on binary link predictions by thresholding uploaded p-values at 0.05 (only available if the "values were uploaded"). The requires lag predictions:

| ilter: | | | | | | | | | | | | | | | | |
|--------|----------------|------------------------------|-----------------------------------|-------|------|--------|--------|-------|--------------|------------------|-------|-------|---------|------------|-----|----------------|
| Id | User | Experiment | Method (params) | Paper | Code | Valid. | Time 🔱 | AUC 1 | AUC- PR 1 | F- measure ↓↑ | FPR 🕸 | TPR 🕸 | TLR 1 | Boxplot FF | 'R | Boxplot TPR |
| 37 | Jakob Runge | linear- VAR_multirealiz | PCMCI-ParCorr (tau_max=5,pc_ + | * | ~ | ~ | 2.97 | 0.98 | 0.89 | 0.56 | 0.05 | 0.92 | 0.98 | ŀ | 200 | + |
| 145 | Jakob Runge | linear- VAR_multirealiz | adaptive-lasso (tau_max=5,) | * | × | * | 18.99 | 0.96 | 0.86 | 0.75 | 0.02 | 0.92 | 0.99 | ŀ | 200 | ···· |
| 215 | Jakob Runge | linear- VAR_multirealiz | varmodel (maxlags=5,) | * | * | * | 0.48 | 0.95 | 0.69 | 0.50 | 0.05 | 0.76 | 0.98 | ŀ | 200 | • H I H |
| 249 | Jakob Runge | linear- VAR_multirealiz + | FullCI-ParCorr (tau_max=5,) | * | * | * | 11.24 | 0.94 | 0.70 | 0.51 | 0.05 | 0.74 | 0.98 | ŀ | 200 | • H |
| howing | 1 to 4 of 4 | entries (filtered from 1 | ,604 total entries) | | | | | | | | | P | revious | 1 Next | | |

Discussion and Conclusions

• Causal inference = answering causal questions from empirical data



- Causal inference = answering causal questions from empirical data
- Causal inference methods only give you graph

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 - Causal Sufficiency

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 - Time order

- Causal inference = answering causal questions from empirical data
- Causal inference methods only give you graph
- Causal conclusions are based on assumptions
 - Causal Markov Condition
 - Faithfulness
 - Causal Sufficiency
 - Time order
 - Stationarity

- Causal inference = answering causal questions from empirical data
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- And to indicate how conclusions are altered for different assumptions

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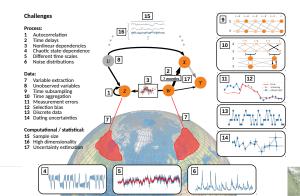


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 - Causal evaluation of physical climate models (Nowack et al., 2020)



Thank you! Questions?

- PCMCI [Runge et al., 2019b] in Science Advances
- PCMCl⁺ Runge (2020) https://arxiv.org/abs/2003.03685
- Conditional independence testing based on CMI [Runge, 2018b] in <u>AISTATS</u>
- Nature Comm. Perspective [Runge et al., 2019a]
- My software: jakobrunge.github.io/tigramite



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