

# Discharge estimations of rivers from altimetry and datasets by hybrid computational methods

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## Outline

- ▷ The inverse problem to solve.
- ▷ The hybrid (Artificial Neural Network - Variational Data Assimilation) algorithm.

Estimation of the discharge  $Q(x, t) \oplus$  the bathymetry  $b(x)$  and roughness coeff.  $K(x, h)$ .

- ▷ Numerical results : "Pepsi challenge" rivers.

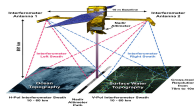
Application of the original HiVDI algo. (VDA w/o ANN) to anabranching river with lateral fluxes :  
see talk presented by L. Pujol, P.-A. Garambois et al.



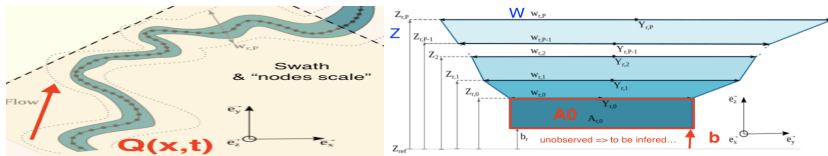
# SWOT-like data & Inverse problem(s)

Forthcoming SWOT mission (NASA-CNES et al., to be launched in 2021)

Swath mapping radar interferometer (2x60 km). 1 to 4 revisits per 21 days repeat cycle



- ▷ **Data** : water elevation  $Z$  & width  $W$  at nodes ( $\sim 200\text{m}$ ) scale  
 $\oplus$  slopes  $S$  at reach ( $\sim 1 - 10 \text{ km}$ ) scale



- ▷ **Inverse problem** : Infer the discharge  $Q_{r,p}$  at "reach"  $r$ , instant  $p$ .  
 $\Rightarrow$  To infer the bathymetry  $b_r$  ( $\Leftrightarrow$  the lowest unobserved wetted cross section  $A_{0,r}$ )  
 $\oplus$  an effective spatially distributed roughness coefficient  $K_r(h)$ .  
 Water depth  $h = (Z - b)$ .

# Hierarchical flow models

- ▷ **Dynamic model : Saint – Venant's equations** 1D SWE set up at nodes scale ( $\approx 200\text{m}$ ).

$$\partial_t(A, Q) + \partial_x(Q, Q^2/A)) + (0, gA\partial_x b) = (0, -gAS_f((K; A, Q)) \oplus Q_{in}(t) \text{ imposed at inflow.}$$

Of course, outflow B.C. are part of the unknowns too (normal depth condition).

**"Parameters" to be identified** :  $Q_{in}(t)$  inflow discharge  $\oplus b(x)$  effective bed elevation  
 $\oplus$  corresponding roughness coeff.  $K(\cdot)$  or  $K(\alpha, \beta; h) = \alpha h^\beta$ .  
 $\Rightarrow$  unknown "parameters"  $c = (Q_{in}(t), b(x); (\alpha, \beta))$ .

- ▷ **Dedicated algebraic (low complexity) 0.5D model.**

Local low Froude equilibriums (Manning-Strickler's laws) set up at reach scale ( $\approx 1 - 10\text{km}$ ).

Considering  $P$  overpasses, the equations read :

$$(\mathcal{M}_2) : c_{r,p} \cdot K_{r,p}^{3/5} A_{r,0} + d_{r,p} \cdot K_{r,p}^{3/5} = Q_{r,p}^{3/5} \quad \forall \text{reach } r \quad \forall \text{pass } p$$

with  $(c_{r,p}, d_{r,p})$  given by the altimetry measurements

If considering the full set of unknowns  $(K_{r,p}, A_{r,0}, Q_{r,p})$  then  $(\mathcal{M}_2)$  is under-determined. But...

**Use 1) Given**  $(Q_{r,p})$  e.g. by a Neural Network (see later)

$(\mathcal{M}_2)$  provides  $(A_{r,0})_r$  with effective low-Froude friction coeff.  $K_{r,p} \quad \forall r \quad \forall p$ .

**Use 2) Given**  $(A_{r,0}, K_{r,p})$  (estimations resulting of the inversions done during the "rivers learning period"),

$(\mathcal{M}_2)$  provides  $Q_{r,p} \quad \forall r \quad \forall p$  in real-time. [Larnier-Monnier et al.] rev., to appear.

# VDA formulation and ill-posedness

Recall. The unknown "control variable" in SWE is  $c = (Q_{in}(t), b(x); (\alpha, \beta))$ .

▷ **The inverse problem** reads :  $\min_c j(c)$  with  $j(c) = \|Z(c) - Z_{obs}\|_*^2$ .

→ Minimization by a gradient-based algorithm (L-BFGS) - adjoint method.

▷ **Probabilistic - physical a-priori introduced via covariance matrices.**

Change of variables :  $k = B^{-1/2}(c - c_{prior})$  with  $B = \text{diag}(B_Q, b_b, B_K)$ .

The covariances matrices may be chosen as :  $(B_{\square})_{i,j} = (\sigma_{\square})^2 \exp(-|x_j - x_i|/L_{\square})$

⇒ Parameters to be set : the 3 amplitudes  $\sigma_{\square}$  and the 3 correlation scales  $L_{\square}$ .

⇒ **Priors of the VDA formulation :**

- The first guess values :  $c^{(0)} = (Q_{in}^{(0)}(t), b^{(0)}(x); (\alpha, \beta)^{(0)})$ .

- The regularization parameters  $\sigma_{\square}$  and  $L_{\square}$ .

▷ Based on the flow models only, the inverse problems is ill-posed :

**the unknowns  $c = (Q_{in}(t), b(x); (\alpha, \beta))$  may be unique up to a scalar scaling factor only.** [Larnier-Monnier] submitted.

⇒ **Priors of the VDA formulation select the (physically-consistent) solution therefore the estimations of  $Q_{r,p}$  ...**

# Hybrid ANN - VDA inversions

▷ **Stage 1) From datasets (e.g. Pepsi1, 2 and HydroSWOT), train an Artificial Neural Network (ANN) to estimate  $Q_{r,p}$ .**

Case In) Rivers inside the learning flow regimes : excellent estimations.

Case Out) Rivers outside the learning flow regimes, bad estimations but (crucial) space-time variations are captured.

⇒ **First guess value  $Q^{(0)} \equiv Q^{(ANN)}$ .**

▷ **Stage 2)**

a) **Algebraic model** with  $Q^{(ANN)}$  given ⇒ First guess values  $\left(b_r^{(0)}; K_r(h)^{(0)}\right) \forall r$ .

b) **VDA based inversions**

Estimation of the complete set (discharge  $Q_{r,p}$ , bathymetry  $b_r$  and roughness  $K_r(h)$ ).

⇒ **The estimated  $Q_{r,p}$  is accurate, at worse with a low bias.**

Estimations obtained at fine scale i.e. at node scale  $\sim 200$  m. Ref. [Larnier-Monnier] sub.

▷ **Stage 3) Past this river learning period (e.g. one year), given newly acquired SWOT measurements  $(Z, W)_{r,p}$ ,**

⇒ **Estimations of  $Q_{r,p}$  in real-time** using the (low complexity) algebraic system  $(\mathcal{M}_2)$ . Inference obtained at reach scale ( $\sim 1 - 10$  km). Ref. [Larnier-Monnier et al.] Rev., to appear.

NB. Possible to assimilate any existing global-regional database values (if reliable).

# Numerical results

▷ **SWOT-like data only : no additional in-situ information ; fully ungauged rivers.**

Pepsi 1 and 2 datasets : 27 rivers portions presenting very wide ranges of flow regimes.

$Q$  within  $\approx [10^2, 10^5] \text{ m}^3/\text{s}$ .

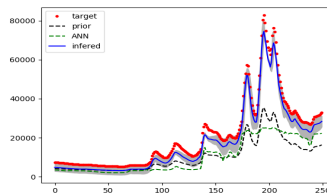
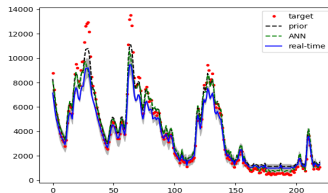
- Cal-Val SWOT frequency : 1 day revisit.
- SWOT-like data = models outputs (from HEC-Ras, DassFlow)

⊕ realistic Gaussian noise  $\Rightarrow$  **Target values.**

▷ **Rivers partly within the ANN-learned flow regimes** e.g. Fig. (Left) : Ohio river.

- The ANN estimation is very good.
- Next, the VDA estimation may be better, similar or slightly less accurate.

Present case : the VDA estimation is a bit less accurate than the ANN one.



▷ **Rivers far outside the ANN-learned flow regimes** e.g. Fig. (Right) : Jamuna river.

- The algebraic flow model  $\mathcal{M}_2$  ("prior" in Fig.) improves the accuracy of  $Q^{(ANN)}$ .
- The VDA estimation ("inferred" in Fig.) provides a relatively good estimation of  $Q(x, t)$ .

All other rivers (27 in total) have been analysed : similar results.

# Conclusion

▷ The (purely physically informed) VDA approach provides accurate space-time variations of  $Q(x, t)$  (at the observations "hours scale") *but up to an intrinsic bias*.

(At least if based on the usual flow models...).

▷ **Combining the VDA inversions with ANN** makes greatly decrease the bias.

⇒ **Much more reliable estimations of  $Q(x, t)$ .**

Accurate space-time variations; if a bias remains it is observed to be relatively low.

▷ Past the "learning period", **real-time estimations of  $Q_{r,p}$**  are possible using the dedicated low-complexity algebraic flow model.

▷ This algorithm (named H2iVDI) can be naturally applied to **multi-satellites data**.

See e.g. PhD T. Malou (IMT-INSA - INRAE - CLS group) in progress.

▷ **The HiVDI algorithm has been applied** by the colleagues from Univ. Strasbourg and INRAE

to anabranching rivers and with coupling to hydrological models. See talk presented by L. Pujol et al.

## References

- K. Larnier, J. Monnier. "Hybrid estimations of river discharges from altimetry". Sub.
- K. Larnier, J. Monnier, P.-A. Garambois, J. Verley. "On the estimation of river discharges from altimetry". In rev. (to appear).
- P. Brisset, J. Monnier, P.-A. Garambois, H. Roux. "On the assimilation of altimetry data in 1D Saint-Venant river models". Adv. Water Res., 2018.

HiVDI algorithms are available in DassFlow, open source computational software. Test it!

<http://www.math.univ-toulouse.fr/DassFlow>