

## Sharing knowledge of Planetary Datasets through the Web-Based P<sub>RO</sub>GIS

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### Abstract

The large amount of raw and derived data available from various planetary surface missions (e.g. Mars and Moon in our case) has been integrated with co-registered and geocoded orbital image data to provide rover traverses and camera site locations in universal global co-ordinates [1]. This then allows an integrated GIS to use these geocoded products for scientific applications: we aim to create a web interface, P<sub>RO</sub>GIS, with minimal controls focusing on the usability and visualisation of the data, to allow planetary geologists to share annotated surface observations. These observations in a common context are shared between different tools and software (P<sub>RO</sub>GIS, Pro3D, 3D point cloud viewer). Our aim is to use only Open Source components that integrate Open Web Services for planetary data to make available an universal platform with a WebGIS interface, as well as a 3D point cloud and a Panorama viewer to explore derived data. On top of these tools we are building capabilities to make and share

annotations amongst users. We use Python and Django for the server-side framework and Open Layers 3 for the WebGIS client. For good performance previewing 3D data (point clouds, pictures on the surface and panoramas) we employ ThreeJS, a WebGL Javascript library. Additionally, user and group controls allow scientists to store and share their observations. P<sub>RO</sub>GIS not only displays data but also launches sophisticated 3D vision reprocessing (P<sub>RO</sub>VIP) and an immersive 3D analysis environment (P<sub>RO</sub>3D).

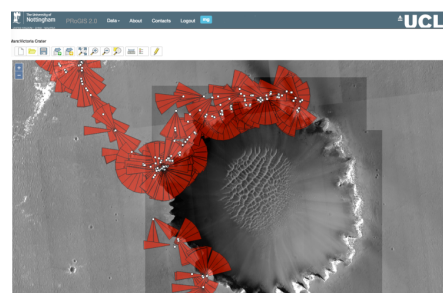


Figure 1. P<sub>RO</sub>GIS displaying camera footprints.

### Acknowledgements

The research leading to these results has received funding from the European Community's Seventh

## References

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